Types, Part II

Programming Languages
CS 214



Review

Recall: A type consists of
The set constructors:
• product: A×B× ×N is the basis for;
• $function: (A) \rightarrow B$ is the basis for; and
• Kleene closure: A* is the basis for
These three provide a formal way to construct types:
\rightarrow Use the <i>product</i> and <i>Kleene closure</i> to represent the;
→ Use the <i>function</i> constructor to represent the
on the type.

Declarations

One purpose of types is to permit objects to be declared.

- A declaration _____ of an object (for the compiler).
- Example: If an object's value may vary, it is a *variable*; otherwise it is a *constant*.
- Issue: Where may declarations occur?
 - Many languages restrict the location of declarations:

```
<ada-program> ::= procedure identifier ; <declaration-section> <block> ;
C++ and Lisp unusual in allowing declarations "anywhere"...
```

- Lisp declarations are functions/expressions,
 and so are permitted anywhere an expression may occur.



Constant Declarations

- Issue: How are constants distinguished from variables?
 - Most imperative languages use a

```
<ada-const-dec> ::= identifier: constant <type> := <expression>;
PI : constant real := 3.1459;
Mass, Energy : real;
```

- C++ is similar, but uses the keyword *const*, and in a prefix form.

```
const double PI = 3.1459;
double mass, energy;
```

– Java is similar to C++, but uses the keyword *final*.

```
final double PI = 3.1459;
double mass, energy;
```

- Lisp constants are declared using the *defconst* function.

```
(defconst PI 3.14159)
(defvar mass 0.0)
```



Imperative Issue

Which approach is preferable?

```
double mass, energy;
```

- 1. The compiler _____
- 2. Each id in the list can be

```
double mass = 1.0,
energy = 0.0;
```

```
mass, energy : real;
```

- 1. The compiler doesn't 'know' the type as it processes the ids.
- 2. Each id must be initialized elsewhere (or else all ids are limited to the same value):

```
mass, energy : real := 0.0;
```



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Fundamental Type Operations

<u>Operation</u>	C++	Ada	Modula-2	Smalltalk	Lisp
+, -, *	+,-,*	+,-,*	+,-,*	+,-,*	+,-,*
	/	/	/	/	/
	/	/	DIV	//	/
	%	mod	MOD	//	mod
		rem		rem:	rem
		**		raisedTo:	expt
		and		&	
	&&	and then	AND	and:	and
		or		1	
	II	or else	OR	or:	or
	!	not	NOT	not	not
	==	=	=	=, ==	=, eq, equal
	!=	/=	#, <>	~=, ~~	/=
uniformly <,>,<=,>=					



Short-Circuit Operators

Logical-and, logical-or operators evaluate both operands.

By contrast:

- -A *short-circuit-or* operator only evaluates its second operand if its first operand is _____; and
- -A *short-circuit-and* operator only evaluates its second operand if its first operand is _____.

Short-circuit behavior is ______, and can be exploited in certain situations:

```
while (ptr != NULL && ptr->value != searchVal)
  ptr = ptr->next;
```

If && were a logical-and instead of short-circuit-and,
 this condition would _____ when searchVal is not in the list

Modeling Real-World Values

Suppose we want to model the seven "ROY G BIV" colors.

```
One approach: const int RED=0, ORANGE=1, YELLOW=2, GREEN=3,
                          BLUE=4, INDIGO=5, VIOLET=6;
                int aColor = BLUE;
```

This approach requires ______to map colors to integers.

Instead:

```
enum Color { RED, ORANGE, YELLOW, GREEN,
             BLUE, INDIGO, VIOLET } ;
Color aColor = BLUE;
```

Most imperative languages support such enumerations...

Ada:

```
type Color = ( RED, ORANGE, YELLOW, GREEN,
               BLUE, INDIGO, VIOLET ) ;
aColor : Color := BLUE;
```

An enumeration is a type _



Enumerations: Compiler Side

An enumeration's values must be valid *identifiers*:

```
<enumeration-type> ::= enum identifier { <id-list> };
```

and the compiler treats a declaration:

```
enum NewType { id_0, id_1, id_2, ..., id_{N-1} };
```

as being (approximately) equivalent to:

```
const int id_0 = 0, id_1 = 1, id_2 = 2, ..., id_{N-1} = N-1;
```

Thus, after processing

so far as the compiler is concerned:

```
RED == _ && ORANGE == _ && YELLOW == _ && ... && VIOLET == _
```



Enumerations: User Side

Enumerations thus provide an automatic means of mapping: (identifier) \rightarrow int

whose chief benefit is

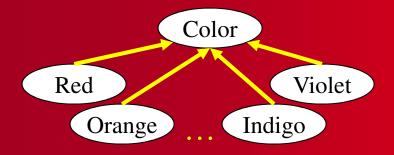
Enumerations allow real-world 'values' to be represented using

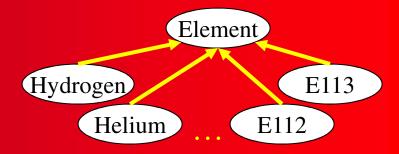
instead of (arbitrary) integer codes.



Enumerations and OO

OO purists replace enums with class hierarchies:





This permits the creation of real-world ______:

```
// Smalltalk
aColor := new Blue.
```

```
// Smalltalk
anElement := new Helium.
```

as opposed to real-world values provided by an enumeration.

For this reason, "pure" OO languages like Smalltalk don't provide an enumeration mechanism.



Subranges

Many imperative languages let us declare a *subrange*: a type whose values are

If a subrange variable is declared:

WeekDay today;

and assigned an invalid value:

today := Saturday;

then an exception occurs that, if not caught, halts the system.

is an essential feature for *life-critical systems*...

Sequence Types

There are to	wo common structi	ures for storing sequences:
•The	(and/or) that stores values in
contiguo	us memory location	ns;
•The	, that stores value	ues anywhere there's room.
Arrays are		: any value in
the array c	an be accessed in t	the same amount of time
-The add	lress of the value at in	idex i can be computed in O(1):
(arrayB	aseAddress + $(i - first)$	tIndex) × ElementSize)
Once declar	red, the size of an	array is usually
A vector is	an array-like struc	ture whose size can

Arrays

Most languages let us build arrays and/or vectors:

```
double anArray[8];
                                            // C++
double * aVector = new double[n];
vector<double> anotherVector(n);
type ArrayType is array(1..8) of real;
                                            -- Ada
anArray : ArrayType;
type Vector is array(integer range <>) of real;
type VectorAccess is access Vector;
aVector : VectorAccess;
begin
    aVector := new Vector(1..n);
(setq anArray (vector 0 1 2 3 4 5 6 7 8)) "Lisp"
| anArray aVector |
                                            "Smalltalk"
anArray := Array new: 8.
aVector := OrderedCollection new: n.
```



Array Indexing

Arrays/vectors are random-access indexed structures: the value stored at index i can be accessed in O(1) time:

The default *firstIndex* is different in different languages:

```
- C/C++: 0
```

- Ada: 1, can be programmer-specified

- Lisp: 0

– Smalltalk: 1

At Issue: There is an efficiency-vs-convenience tradeoff:

Programmer-specified index values can be very

```
type LetterCounter is array(CapitalLetter) of integer;
type DailySales is array(WeekDay) of real;
```



Array Access

An important array operation is to access the value at index *i*.

There are two different flavors to this operation:

```
- the read version _____ the value at index i;
```

- the write version lets us _____ the value at index i.

Most languages use the same syntax for both operations:

```
- C/C++: oldValue = anArray[i]; // read anArray[i] = newValue; // write
```

-Ada: oldValue = anArray(i); -- read anArray(i) = newValue; -- write

```
(setq oldValue (aref anArray i)) "read"
(setq (aref anArray i) newValue) "write"
```

Other languages provide distinct operations for the two:

- Smalltalk:

```
oldValue := anArray at: i. "read"
anArray at: i put: newValue. "write"
```

Array Access (ii)

Although C++ uses the same syntax for both read and write, the operations are implemented as

The compiler links a given call to the proper function:



Aggregates: Records/Structs

Like an array, an _____ type can store multiple values; but (unlike an array) it can store values of _____.

```
struct Student {    // C++
    int id;
    bool fTime;
    double gpa;
};
```

type Student is -- Ada
 record
 id : integer;
 fTime: boolean;
 gpa : float;
 end record;

Smalltalk has no records/structs, as its classes can do anything a record/struct can do...

```
"Lisp"
(defstruct Student
id fTime gpa)
```

Once we have an aggregate type, we can build variables:

```
// C++
Student stu;
```

```
-- Ada
stu : Student;
```

```
"Lisp"
(setq stu make-Student)
```



Record/Struct Projection

We can then

of the record/struct:

```
// C++
stu.id = 1234;
stu.fTime = true; stu.fTime:=true;
stu.qpa = 3.0;
```

```
-- Ada
stu.id:= 1234;
stu.gpa:= 3.0;
```

```
"Lisp"
(setq (Student-id stu) 1234)
(setq (Student-fTime stu) t)
(setq (Student-qpa stu) 3.0)
```

Most languages use similar syntax to ____

```
// C++
cout
 << stu.id;
 << stu.fTime
 << stu.gpa;
```

```
-- Ada
put(stu.id);
put(stu.fTime);
put (stu.gpa);
```

```
"Lisp"
(princ (Student-id stu))
(princ (Student-fTime stu))
(princ (Student-qpa stu))
```

These represent the operation in each language.

Pointers

Most languages permit a programmer to define variables that can store _____: also known as *pointer variables*.

These can be used to build lists of linked nodes:

```
// C++
struct Node {
    SomeType value;
    Node * next;
};
```

```
-- Ada
type Node;
type NodePtr is access Node;
type Node is record
  value: SomeType;
  next: NodePtr;
end record;
```

Smalltalk and Java have no pointer types because _____ is actually a pointer variable.

Lisp variables are also pointers:

```
"Lisp"
(defstruct Node value next)
```



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Dynamic Allocation & Deallocation

Each language supports _____ operation:

```
// C++
Node * nPtr = new Node;

"Smalltalk"
| nPtr |
nPtr := Node new.
```

```
-- Ada
nPtr: NodePtr := new Node;

"Lisp"
(setq nPtr (make-Node))
```

Many languages also provide a _____ operation:

```
// C++
delete nPtr;
```

Ada, Lisp, and Smalltalk instead provide a
that eliminates memory
leaks by automatically reclaiming unused
memory (i.e., when no pointers to it exist).

Pointer Assignment and Copying

Each language provides a means of assigning pointer values:

```
// C++
Node * tempPtr;
tempPtr = nPtr;

"Smalltalk"
| nPtr tempPtr|
...
tempPtr := nPtr.
```

```
-- Ada
tempPtr: NodePtr;
tempPtr := nPtr;

"Lisp"
(setq tempPtr nPtr)
```

Most languages also allow copying of the object pointed to:

```
// C++
tempPtr = new Node;
*tempPtr = *nPtr;

"Smalltalk"
tempPtr := nPtr copy;
```

```
-- Ada
tempPtr := new Node;
tempPtr.all := nPtr.all;

"Lisp"
(setq tempPtr (copy-Node nPtr))
```



Other Pointer Operations

Languages provide a notation for

```
// C++
nPtr = NULL;

"Smalltalk"
nPtr := nil.
```

```
-- Ada
nPtr:= null;

"Lisp"
(setq nPtr nil)
```

Most languages also permit the fields of an aggregate to be via a pointer:

```
// C++
nPtr->value = 1234;
nPtr->next = new Node;
```

Smalltalk "fields" are accessed via accessor and mutator methods

```
-- Ada
nPtr.value:= 1234;
nPtr.next:= new Node;
```

```
"Lisp"
(setq (Node-value nPtr) 1234)
(setq (Node-next nPtr) (make-Node))
```



Type Systems

A type system is a	set of rules	by which a	language	associates
with		<u>.</u>		

The system generates a *type-error* when its rules do not permit a type to be associated with an expression.

Example: Early Fortran versions had only integers and reals.

- Declarations not required: implicit typing of identifiers
 - o Identifiers beginning with I-N are integers; all others are reals.
- Literals with decimal points are real; others are integers.
- Type System Rule: If E1 and E2 are expressions of the same type T, then E1+E2, E1-E2, E1*E2, and E1/E2 produce a result of type T.
 - o I+N produces a value of type _____; X+Y produces a value of type _____;
 - Expressions like X+I (e.g., 0.5+1)or N-Y generate ______.

Type System Formalism

If f is a function from $(S) \to T$, and $s \in S$, then $f(s) \in T$.

Ada defines: $+(int \times int) \rightarrow int$

and $+(real \times real) \rightarrow real$

but neither $+(\text{real} \times \text{int}) \rightarrow \text{real nor } +(\text{int} \times \text{real}) \rightarrow \text{real}$

so both 2 + 3 and 2.0 + 3.0 are valid expressions;

but neither 2.0 + 3 nor 2 + 3.0 are valid expressions.

Arithmetic expressions _____ cause type errors.

Ada's other arithmetic operators behave the same way.

Why would Ada's designers choose such a type system?

Ada's type system is perhaps ______ of any HLL.

Ada compilers ______ that slip by in other languages.



Coercion

Ada is unusual in rejecting mixed-type arithmits goal is to prevent	metic expressions:
Most HLLs permit arithmetic types to be fre	ely intermixed.
To prevent information loss,	
such languages take an expression:	2 + 1.5
"expand" theoperand:	2.0 + 1.5
and then perform the operation:	$+(real \times real)$
The automatic conversion of an operand's ty rejection by the type system is called a	pe to prevent
Some languages use the term	to describe this;
others describe it as	

Overloading

Note: operators like +, -, *, ... are _____. In a + b: + means "perform integer addition" if a and b are integers; + means "perform real addition" if a and b are reals. symbols have different meanings in different contexts. Formally: For any function $f(D) \rightarrow R$: - The set of all possible arguments D is the function's domain; - The set of all possible results R is the function's range. An overloaded function is ____ +, -, *, / are overloaded in most HLLs To process such operations, the compiler must check the context (operand types) and find a definition with the matching domain. A occurs when no definition with that domain is found.

Type Checking

A type system enforces its rules by type checking:

- Analyzing the code, looking for type errors
- Only permitting programs without type errors to execute.
- A program with no type errors is described as ______.

Type checking is accomplished at two levels:

1	: check for type-errors at	
7	check for type errors at	

Ada performs both static and dynamic checking, but the language is designed to maximize the number of errors that can be detected _______ (i.e, by the compiler).

Static Checking Examples

a. In C++ expressions of the form: x % y
the compiler looks up the types of x and y
(in a data structure called the
and rejects the expression if both are not of type int.

- b. In C++ expressions of the form: sqrt(x) the symbol table contains both the type T of argument x and the domain-set D for which sqrt() is defined, allowing the compiler to reject the expression if $T \notin D$.
 - Original (K&R) C did not require that function prototypes contain parameter types, making it impossible for the compiler to typecheck function calls (ANSI-C corrected this).

Dynamic Checking Examples

Dynamic checking is checking for errors only detectable at run-time by inserting checks before an expression's code.

Expression: x / y

```
// without dynamic checks
mov x, R0
div R0, y
```

```
-- with dynamic checking
mov x, R0
mov y, R1
cmp R1, #0
be DivideByZero
div R0, R1
```

A[i]

```
// without dynamic checks
    mov A, R0
    add R0, i
```

```
-- with dynamic checking
mov A, R0
mov i, R1
cmp R1, firstIndex
blt IndexTooLow
cmp R1, lastIndex
bgt IndexTooHigh
add R0, R1
```



Type Strength

A language is	if it has a	strict ty	pe syst	tem.
A language is	if it has a	loose ty	pe sys	tem.
From this perspective, languated continuum, based on the the				m:
Lisp C (pre-ANSI)	C++	Smalltalk	Java	Ada
weaker			stror	nger
Fortran-I, -II Fortran-IV Fortran-77 Fortran-90 Language type systems have tended to				
as they evolve through different versions.				
 The importance of type-strength has increased as the systems being built have increased in 				

Type Compatibility

What determines if two types *T1* and *T2* are compatible (e.g., can *T1* arguments be passed to *T2* parameters)?

```
typedef int IntArray[32];
                              int x[32];
IntArray x, y;
                              void f(int y[32]);
// Are x, y compatible?
                              // Are x, y compatible?
struct Student {
                            struct Employee {
  int id;
                               int id;
  string name;
                               string name;
};
                            };
                            Employee emp;
Student stu;
// Are stu, emp compatible?
struct Student {
                            struct Employee {
  int studentID;
                               int empID;
  string studentName;
                               string empName;
Student stu;
                            Employee emp;
// Are stu, emp compatible?
```



Equivalence

Compatibility depends on whether a language views two types as *equivalent*.

There are two broad categories of equivalence:

-Languages that use	view two types as
equivalent if they have	
–Languages that use	view two types as
equivalent if they are	

To illustrate, suppose that we have these declarations:



Structural Equivalence (SE)

Structural equivalence relies on three "rules":

•SE1: A type name is structurally equivalent to itself.

```
Student stu1; \rightarrow Since their types ______ stu1 and stu2 are structurally equivalent.
```

•SE2: Two types formed by applying the same constructor to SE types are structurally equivalent.

```
Student stu;
Employee emp;
```

•SE3: If one type is an alias of another, the two types are structurally equivalent.

```
typedef Student Transfer;
Student stu;
Transfer trans;
```

→ Since *Transfer* is _____ *Student*, stu and trans are structurally equivalent.

Name Equivalence (NE)

There are different varieties of name equivalence:

• Pure NE: To be equivalent, types ____

```
-- Ada uses pure name equivalence
type IntArray is array(1..32) of Integer;
type IntList is array(1..32) of Integer;
                                             \rightarrow Since a1 and a3
a1: IntArray;
a2: IntList;
                                              are declared with
a3: IntArray;
a4: array(1..32) of Integer;
                                              they are equivalent.
a5: array(1..32) of Integer;
→ If we declare: procedure print(IntArray anArray);
 then Ada's type system will only accept _____ as arguments.
\rightarrow a2's type has a name, but it is a different name from the others.
\rightarrow a4 and a5's types have no name: in Ada.
```

Name Equivalence (ii)

: A type name is equivalent to itself (pure NE), plus it can be declared equivalent to other type names.

```
-- C++ uses transitive name equivalence
                                   struct Employee {
struct Student {
  int idNumber;
                                       int idNumber;
  string name;
                                       string name;
};
                                    };
typedef Student Transfer;
Student stu;
                                   Employee emp;
Transfer trans;
```

- \rightarrow stu and trans are compatible; emp is not compatible to either.
- → If we declare: void print (Student aStudent); then the type system will only accept stu or trans as arguments, but will reject *emp* as an argument.



Which is better?

- Consider type-checking on aggregates:
 - -Type-checking is much _____ under name equivalence, as the type-checker just has to do _____
 - -Under structural equivalence, the type-checker must do _____ (e.g., nested records??).
- •Name equivalence encourages _____:
 - NE encourages detail-hiding (ADT) by rejecting anonymous types:

```
procedure Put(seq: Sequence);  → Any Sequence accepted.
```

```
procedure Put(seq: array(1..32) of Integer); \rightarrow Nothing accepted.
```

- SE discourages abstraction by accepting anonymous types:
 - o SE may permit programs to be written faster (abstraction takes time).
 - o Such programs may be harder to maintain; may be type-unsafe.



Summary

A type consists of	<u>.</u> .
The set constructors: product, function, a provide a formal way to represent type of	
using product and Kleene closure to repr	resent the,
and function to represent the	on the new type.
let us use real-world	values for type data.
constrain the values of ex	isting data types.
	s stored in adjacent
memory locations that permit $O(1)$ time	access to any value.
are sequences stored in dynamical	ally allocated nodes,
that require $O(n)$ time (on average) to according	ccess a value.

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Summary (ii)

store multiple valu	ues of arbitrary types.
store addresses, per	rmit us to build linked nodes.
A type system performs type-che	cking using
equivalence or a version of	equivalence.
Type-checking may be:	
• Static: done at	; and/or
• Dynamic: done at	·
The more type-checking a langu	age requires, the
its type-system, and the fewer ty	ype-errors slip past.
has a very strong type-sys	stem.

