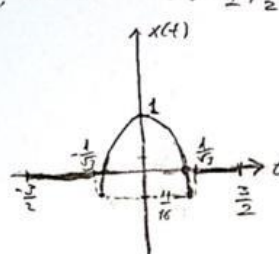


Lab-02

Analytical Part

$T=3, \quad \forall \omega=1.5 \quad t \in (-\frac{3}{2}, \frac{3}{2}), \quad x(t) = \begin{cases} 1-3t^2, & -\frac{3}{4} < t < \frac{3}{4} \\ 0, & \text{o.w.} \end{cases}$



$$X_k = \frac{1}{T} \int_{-T/4}^{T/4} x(t) e^{-j\frac{2\pi k}{T}t} dt = \frac{1}{3} \int_{-3/4}^{3/4} (1-3t^2) e^{-j\frac{2\pi k}{3}t} dt$$

$$= \frac{1}{3} \left[\int_{-3/4}^{3/4} e^{-j\frac{2\pi k}{3}t} dt - 3 \int_{-3/4}^{3/4} t^2 e^{-j\frac{2\pi k}{3}t} dt \right] = \frac{1}{3} \left[-\frac{3}{2\pi k j} e^{-j\frac{2\pi k}{3}t} \Big|_{-3/4}^{3/4} - 3 \left(t^2 \int_{-3/4}^{3/4} e^{-j\frac{2\pi k}{3}t} dt - 2 \int_{-3/4}^{3/4} t e^{-j\frac{2\pi k}{3}t} dt \right) \right]$$

$$= \frac{1}{3} \left[\frac{3}{2\pi k j} \sin\left(\frac{\pi k}{2}\right) - 3 \left(-2jt^2 \sin\left(\frac{\pi k}{2}\right) - \int_{-3/4}^{3/4} 2t \left(-\frac{3}{j2\pi k} \right) e^{-j\frac{2\pi k}{3}t} dt \right) \right]$$

$$\stackrel{*}{\Rightarrow} \frac{3}{j2\pi k} \left[-4tj \sin\left(\frac{\pi k}{2}\right) + \frac{3}{j\pi k} (-2j \sin\left(\frac{\pi k}{2}\right)) \right]$$

$$\frac{1}{3} \left[\frac{3}{\pi k} \sin\left(\frac{\pi k}{2}\right) + 6jt^2 \sin\left(\frac{\pi k}{2}\right) - \frac{9}{j2\pi k} \left[-4tj \sin\left(\frac{\pi k}{2}\right) + \frac{3}{j\pi k} (-2j \sin\left(\frac{\pi k}{2}\right)) \right] \right]$$

$$= \frac{\sin\left(\frac{\pi k}{2}\right)}{\pi k} + 2jt^2 \sin\left(\frac{\pi k}{2}\right) + \frac{6t}{\pi k} \sin\left(\frac{\pi k}{2}\right) + \frac{9j}{\pi^2 k^2} \sin\left(\frac{\pi k}{2}\right)$$

• While computing cosine & sine functions, Matlab has a error margin, because the π in the Matlab is not exactly the real π .


• As k increases, the function has more points to work with so it is a better approximation of the real function. Increased k will increase the likeness of the function. For the discontinuities, we can observe the Gibbs phenomenon.

• Part 4

a-) This operation flips the function on y-axis. But since the function looks even, it does not have much effect on graph.

b-) The 't' in the func. becomes 't-to': time shift to right by t_0 .

c-) This takes the derivative of the func. So it is the speed of change of the func.

d-)  The function goes from min point to peak & flips it, then from peak to min. and flip it again. Then readjusts the zero points. Since this is a periodic signal, it looks like a time-shifted version.

Part 1

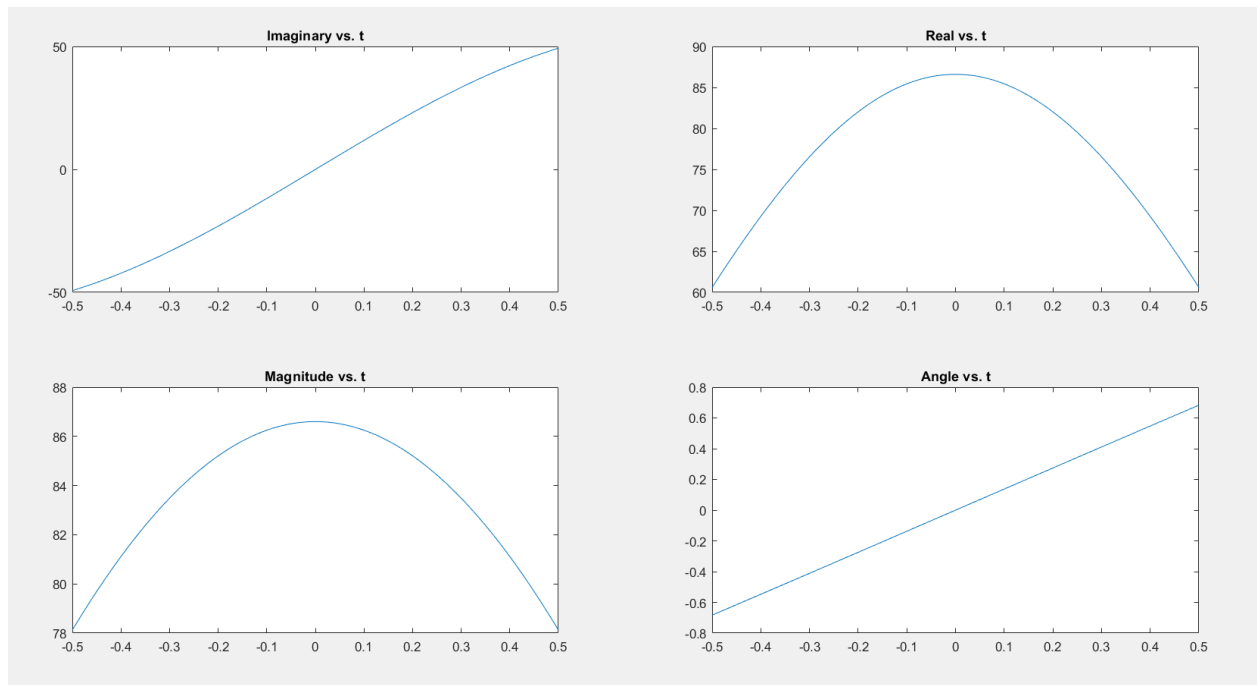


Figure 1- SUMCS Output

Part 3

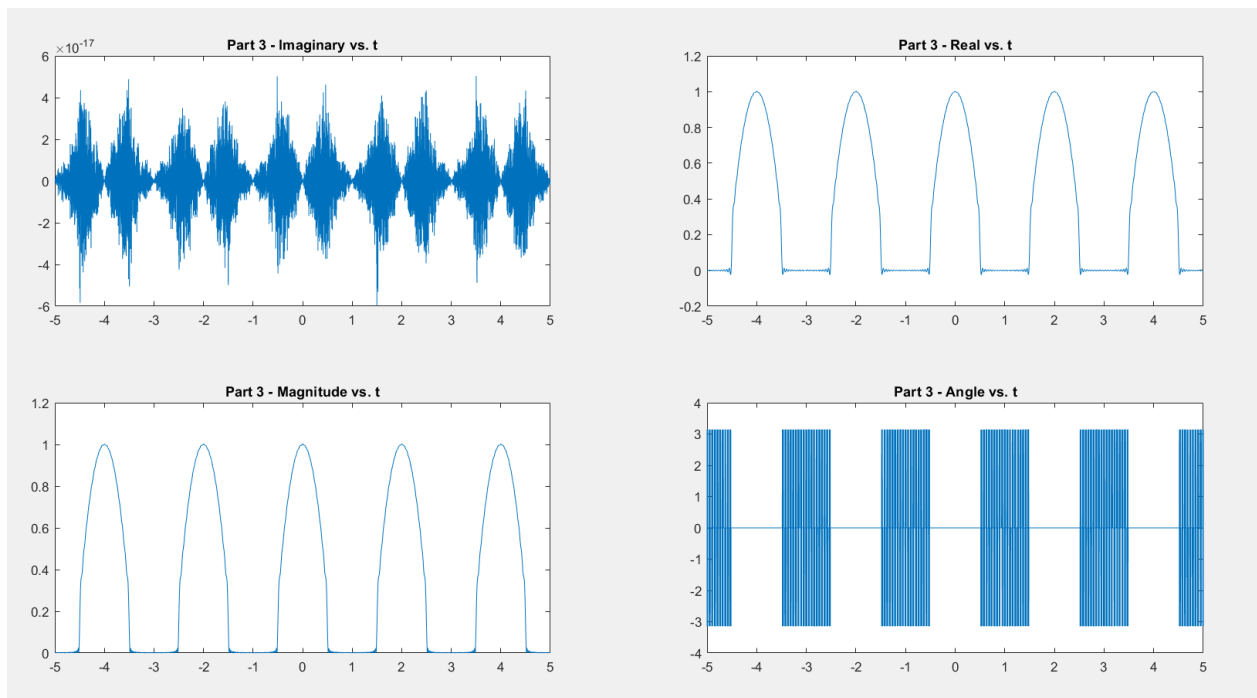


Figure 2- FSWave Output

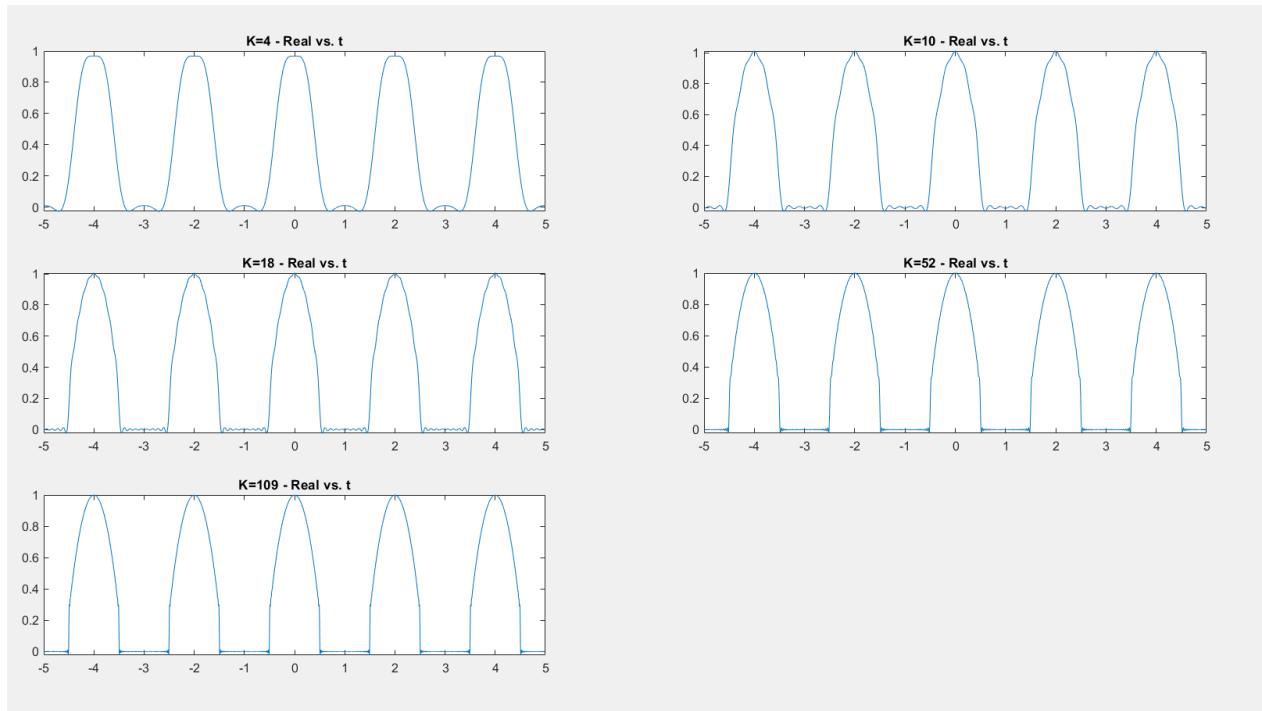


Figure 3- FSWave Output for Differing K 's

Part 4

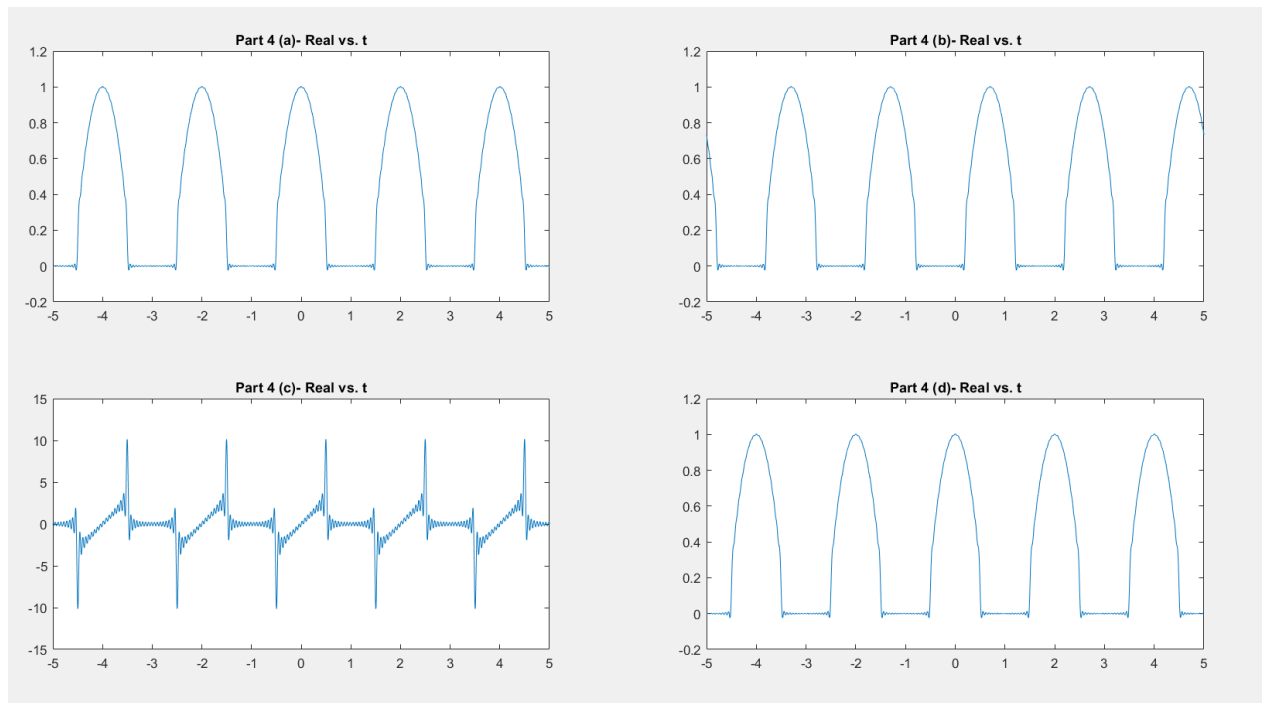


Figure 4- Part 4 Output

MATLAB Code

```
t=[-0.5:0.001:0.5];
t3=[-5:0.001:5];
t4=[-5:0.001:5];
t4b=[-5:0.001:5]-0.7;
A=1+(4).*rand(1,33);
omega=pi.*rand(1,33);
K=37;
K1=4;
K2=10;
K3=18;
K4=52;
K5=109;
K6=34;
T=2;
W=1;
x1=SUMCS(t,A,omega);
x2=FSWave(t3,K,T,W);
x3=FSWave(t4,K1,T,W);
x4=FSWave(t4,K2,T,W);
x5=FSWave(t4,K3,T,W);
x6=FSWave(t4,K4,T,W);
x7=FSWave(t4,K5,T,W);

x8=FSWave(-t4,K6,T,W);

xb=FSWave(t4b,K6,T,W);

xc=FS1Wave(t4,K6,T,W);

xd=FS2Wave(t4,K6,T,W);

figure(1)
subplot(2,2,1);
plot(t,imag(x1))
title('Imaginary vs. t')

subplot(2,2,2);
plot(t,real(x1))
title('Real vs. t')

subplot(2,2,3);
plot(t,abs(x1))
```

```

title('Magnitude vs. t')

%((imag(x1)).^2+(real(x1)).^2).^(1/2)

subplot(2,2,4);
plot(t,angle(x1))
title('Angle vs. t')


figure(2)
subplot(2,2,1);
plot(t3,imag(x2))
title('Part 2 - Imaginary vs. t')

subplot(2,2,2);
plot(t3,real(x2)),
title('Part 2 - Real vs. t')

subplot(2,2,3);
plot(t3,abs(x2))
title('Part 2 - Magnitude vs. t')

subplot(2,2,4);
plot(t3,angle(x2))
title('Part 2 - Angle vs. t')


figure(3)
subplot(3,2,1);
plot(t4,real(x3))
title('K=4 - Real vs. t')

subplot(3,2,2);
plot(t4,real(x4))
title('K=10 - Real vs. t')

subplot(3,2,3);
plot(t4,real(x5))
title('K=18 - Real vs. t')

subplot(3,2,4);
plot(t4,real(x6))
title('K=52 - Real vs. t')

subplot(3,2,5);
plot(t4,real(x7))

```

```
title('K=109 - Real vs. t')
```

```
figure(4)
```

```
subplot(2,2,1)
```

```
plot(t4,real(x8))
```

```
title('Part 4 (a)- Real vs. t')
```

```
subplot(2,2,2)
```

```
plot(t4,real(xb))
```

```
title('Part 4 (b)- Real vs. t')
```

```
subplot(2,2,3)
```

```
plot(t4,real(xc))
```

```
title('Part 4 (c)- Real vs. t')
```

```
subplot(2,2,4)
```

```
plot(t4,real(xd))
```

```
title('Part 4 (d)- Real vs. t')
```

```
function xs = SUMCS(t,A,omega)
```

```
    xs=zeros(1,length(t));
```

```
    for i=1:length(omega)
```

```
        xs= xs+A(i)*exp(1j*omega(i)*t);
```

```
    end
```

```
end
```

```
function xt= FSWave(t,K,T,W)
```

```
    k0=[-K:K];
```

```
    fun=@(x) exp(-1j*2*pi/T*k0*x).*(1-3*x.^2);
```

```
    xk=1/T*integral(fun,-W/2, W/2,'ArrayValued',true);
```

```
    xt=SUMCS(t,xk,2*pi*k0/T);
```

```
end
```

```
function xt= FS1Wave(t,K,T,W)
```

```
    k0=[-K:K];
```

```
    fun=@(x) exp(-1j*2*pi/T*k0*x).*(1-3*x.^2);
```

```
    xkz=1/T*integral(fun,-W/2, W/2,'ArrayValued',true);
```

```
    xk=(-1j*2*pi/T*k0).*xkz;
```

```
    xt=SUMCS(t,xk,2*pi*k0/T);
```

```
end
```

```
function xt= FS2Wave(t,K,T,W)
```

```
    k1=[-K:-1];
```

```
k2=[1:K];
k1=flip(k1);
k2=flip(k2);
k0=[k1 0 k2];
fun=@(x) exp(-1j*2*pi/T*k0*x).*(1-3*x.^2);
xk=1/T*integral(fun,-W/2, W/2,'ArrayValued',true);
xt=SUMCS(t,xk,2*pi*k0/T);
end
```