

Lab-session week 16 (1MA930/1MA931, VT2024)

Recall that for help with a MATLAB command, you write `help commandname` or `doc` in the command window. Here `commandname` could for example be `legend` or `polyfit`.

1. Interpolation.

- To get a feeling for the methods used to compute interpolating polynomials, solve (by hand) Exercise 3.1.1(c) and the corresponding 3.1.2 exercise on page 149.
 - Use Newton's divided differences to find the polynomial $p(x)$ of degree 3 that interpolates the function $f(x) = \sin(x)$ at 4 equally spaced points on $[0, \pi/2]$. *Either done by hand (exact) or in MATLAB (e.g., page 146).*
 - Plot the functions $f(x)$ and $p(x)$ from 1(b) for $x \in [-\pi, \pi]$ in the same figure window (recall the command `hold on`). Learn how to use the commands `legend`, `xlabel` and `ylabel` to make the figure informative.
 - Check if your polynomial $p(x)$ is correct by comparing with the book of Sauer (Example 3.7, p. 147-149).
 - The interpolation error is $f(x) - p(x) = \frac{(x-x_1)(x-x_2)\cdots(x-x_n)}{n!} f^{(n)}(c)$. Since c is unknown, we use $|f^{(n)}(c)| \leq \max_{x \in [0, \pi/2]} |f^{(n)}(x)|$ to estimate the worst possible error (on $[0, \pi/2]$). Do this (for example) for $x = 1$. Compare with the true error $|f(1) - p(1)|$.
 - Check if you got it right by comparing with the book of Sauer (p. 152).
2. Test MATLAB's function `polyfit` to find a degree 8 polynomial that fits the data

x	-4	-3	-2	-1	0	1	2	3	4
y	1	1	1	1	2	1	1	1	1

Evaluate the polynomial for $x \in [-5, 5]$ using the MATLAB function `polyval` and plot the result together with the set of points. Use enough x -values such that the resulting curve looks smooth.

What happens if you use a smaller degree? A larger? Read the documentation for `polyfit` to understand what it does.

3. The least square method.

- Fit the data points $(1, 0.6)$, $(0.5, 0.8)$ and $(0.4, -0.9)$ as good as possible (in the least square sense) to the form of an ellipse

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1, \quad a, b > 0.$$

Hint: You need to re-formulate the problem as a (overdetermined) linear system of equations. (Re-formulate by hand, solve it using MATLAB.)

Make a figure in MATLAB, plotting the 3 points together with the ellipse using your best values of a and b using (for example) the commands:

```
plot([1 0.5 0.4],[0.6 0.8 -0.9],'b*')  
hold on  
theta=2*pi*(0:0.01:1);  
plot(a*cos(theta),b*sin(theta),'r-')
```

b) Solve the problem from (a) using QR-factorization. Find Q and R using the command `[Q,R]=qr(A)`; Thereafter you can follow the steps from the lecture or Example 4.14 on page 217.

Hint: To pick out the first two rows and columns from R , use the vector notation in MATLAB as `R(1:2,1:2)`. Alternatively: Write "help qr" to see how you can make MATLAB return the reduced QR-factors \tilde{Q} and \tilde{R} .

4. If you have time left, solve computer problems 3.2.3 and 3.2.4.