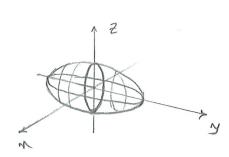
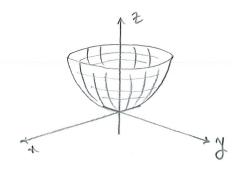


Ellipsoid. 
$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$$
.

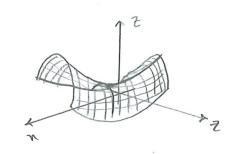


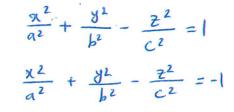
## Elliptic paraboloid:

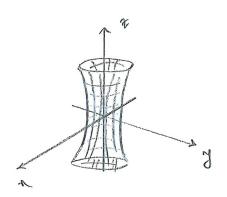
$$\mathcal{Z} = \frac{\chi^2}{a^2} + \frac{y^2}{b^2}$$

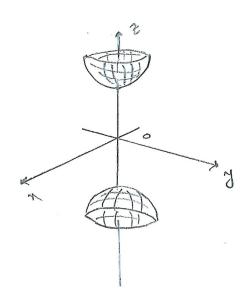


$$\mathcal{Z} = \frac{\chi^2}{a^2} - \frac{y^2}{b^2}$$









(16.4)

Lines

$$\overrightarrow{P}_{0} = t\overrightarrow{V} \quad te(R)$$

$$\overrightarrow{V} = (a_{1}b_{1}C) \quad P_{0} = (\lambda_{0}, y_{0}, \lambda_{0}) \quad P = (\lambda_{1}y_{0}, \lambda_{0})$$

$$(x-x_{0}, y-y_{0}, \lambda_{0}-2c) = (ta_{1}, tb_{1}+C)$$

$$\Rightarrow \begin{cases} x-x_{0} = ta \\ y-y_{0} = tb \end{cases}$$

$$\begin{cases} x = \lambda_{0} + ta \\ \lambda_{0} = \lambda_{0} = tc \end{cases}$$

$$\begin{cases} x = \lambda_{0} + ta \\ \lambda_{0} = \lambda_{0} = \lambda_{0} = \lambda_{0} = \lambda_{0} = \lambda_{0}
\end{cases}$$

$$\begin{cases} \frac{x-x_{0}}{a} = t \\ \frac{y-y_{0}}{b} = t \end{cases}$$

$$\begin{cases} \frac{x-x_{0}}{a} = t \\ \frac{y-y_{0}}{c} = t \end{cases}$$

$$\begin{cases} \frac{x-x_{0}}{a} = t \\ \frac{y-y_{0}}{c} = t \end{cases}$$

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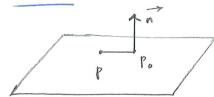
$$\begin{cases} \frac{x-x_{0}}{a} = t \\ \frac{y-y_{0}}{a} = t \end{cases}$$

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$$\begin{cases} \frac{x-x_{0}}{a} = t \\ \frac{y-y_{0}}{a} = t \end{cases}$$

(Standard Form)



$$\overrightarrow{n} = (A, B, C)$$
 (normal)

$$\overrightarrow{PPO} = 0 \qquad \Longrightarrow (A, B, C) \cdot (x - x_{0}, y - y_{0}, z - z_{0}) = 0$$

$$\Longrightarrow Ax + By + Cz - (Ax_{0} + By_{0} + Cz_{0}) = 0$$

$$\Longrightarrow Ax + By + Cz = D$$

A line is the intersection of two planes:

$$\frac{x-x_0}{a} = \frac{y-y_0}{b} = \frac{z-z_0}{c}$$

$$\frac{x-x_0}{a} = \frac{y-y_0}{b} \Rightarrow \frac{x_0}{a} - \frac{x_0}{a} - \frac{y}{b} + \frac{y_0}{b} = 0 \Rightarrow Ax + By + D = 0$$

$$\frac{y-y_0}{b} = \frac{z-z_0}{c} \Rightarrow \frac{y}{b} - \frac{z}{c} + \frac{z_0}{c} = 0 \Rightarrow By + Cz + D' = 0$$

Proof. It is obvious that we have the equality when:  $\overline{U}=\overline{0}$  or  $\overline{V}=\overline{0}$ .

Assume that \$\overline{u}\_{\pm 0}\$ and \$\overline{v}\_{\pm 0}\$.

We set: 
$$\widehat{x} = \widehat{\hat{u}} = \frac{\overline{u}}{|\overline{u}|}$$
,  $\widehat{y} = \widehat{v} = \frac{\overline{v}}{|\overline{v}|}$ 

$$\Rightarrow |\bar{x}| = |\bar{\hat{u}}| = |$$
 and  $|\bar{y}| = |\bar{\hat{v}}| = |$ .

Now: 
$$0 \le |\bar{x} - \bar{y}|^2 = (\bar{x} - \bar{y}) \cdot (\bar{x} - \bar{y})$$

$$\Rightarrow \frac{\overline{a}}{|\overline{a}|} \cdot \frac{\overline{V}}{|\overline{V}|} \leq 1 \Rightarrow \overline{a} \cdot \overline{V} \leq |\overline{a}||\overline{V}||_{L^{\infty}}(*)$$

If we replace a by (-a) in (x), we get:

#

Consequence 1 & From the Cauchy-Schwarz inequality, we know that  $\frac{|\overline{u}.\overline{v}|}{|\overline{u}||\overline{v}|} \le 1$ . It means  $\frac{|\overline{u}.\overline{v}|}{|\overline{u}||\overline{v}|}$  is a

number between (-1) and (1).

On the other side Coo is an invertible function on  $Cor\bar{n}$ ), like A So, for every number between (-1) and (1) Ythere exists a conigne angle  $\Theta \in (0,\bar{n})$  such that  $A = Cos \Theta$ .

$$\Rightarrow \overline{u.v}$$

$$\overline{|u||v|} = 659$$

Consequence 2: The triangle inequality  $|\bar{u}+\bar{v}| \leq |\bar{u}| + |\bar{v}|$ 

 $\frac{\text{Proof}}{|u+v|^{2}} = (u+v) \cdot (u+v) = u \cdot u + v \cdot u + v \cdot v + u \cdot v$   $= |u|^{2} + 2u \cdot v + |v|^{2}$   $\leq |u|^{2} + 2|u||v| + |v|^{2}$   $= (|u|+|v|)^{2}$ 

$$=$$
)  $|\overline{u}+\overline{v}| \leq |\overline{u}|+|\overline{v}|$ .

#

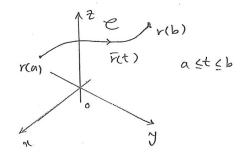
## Vector valued functions (12.1)

A vector-valued function is a mathematical function of one or more variables whose range is a set of multidimensional vectors or infinite dimensional vectors.

Here, we discuss vector-valued functions of a single variable:

$$\overline{Y}: \mathbb{IR} \longrightarrow \mathbb{IR}^3$$

$$\overline{F}(t) = (\chi(t), \chi(t), \overline{Z}(t)) = \chi(t)\overline{i} + \chi(t)\overline{j} + \overline{Z}(t)\overline{k} \qquad (Curres in \mathbb{IR}^3)$$



It is natural to interpret  $\bar{r}(t)$  as giving the position at time tof a particle moving around in space.

If z(t) = 0, then the curve is in the my-plane.

$$F(t)$$
 is Continuous  $\iff$   $\begin{cases} x(t) \\ y(t) \end{cases}$  are Continuous.

Velocity: 
$$\overline{V}(t) = \frac{d}{dt} \overline{r}(t) = (\eta'(t), \eta'(t), \overline{z}'(t)) = r'(t)$$

Acceleration: 
$$\bar{a}(t) = \frac{d\bar{v}}{dt} = \frac{d^2\bar{r}}{dt^2} = r''(t)$$

Theorem. Let  $\bar{u}(t)$  and  $\bar{v}(t)$  be differentiable vector-valued functions and let A(t) be a differentiable scalar-valued function. Then  $\bar{u}(t)+\bar{v}(t)$ ,  $A(t)\bar{u}(t)$ ,  $\bar{u}(t)$ .  $\bar{v}(t)$ ,  $\bar{u}(t)$   $x\bar{v}(t)$ , and  $\bar{u}(A(t))$  are differentiable, and

(a) 
$$\frac{d}{dt} \left( \overline{u}(t) + \overline{V}(t) \right) = \overline{u}(t) + \overline{V}(t)$$

Product 
$$\Rightarrow$$

(b)  $\frac{d}{dt}(\lambda(t)) = \lambda'(t) \overline{u}(t) + \lambda(t) \overline{u}'(t)$ 

Product  $\Rightarrow$ 

(c)  $\frac{d}{dt}(\overline{u}(t) \cdot \overline{v}(t)) = \overline{u}'(t) \cdot \overline{v}(t) + \overline{u}(t) \cdot \overline{v}'(t)$ 

(d)  $\frac{d}{dt}(\overline{u}(t) \times \overline{v}(t)) = \overline{u}'(t) \times \overline{v}(t) + \overline{u}(t) \times \overline{v}'(t)$ 

Also, at any point where a(t) =0;

$$\frac{d}{dt} \left| \bar{u}(t) \right| = \frac{\bar{u}(t) * \bar{u}'(t)}{\left| \bar{u}(t) \right|}$$

$$\Rightarrow \text{ for } t \in |R| \langle 0 \rangle : \frac{d}{dt} | \bar{u}(t) | = \frac{\bar{u}(t) \cdot \bar{u}'(t)}{|\bar{u}(t)|}$$

$$|\bar{u}(t)| = \sqrt{4t^2+9t^2+t^4} = \sqrt{13t^2+t^4} \implies |S| = \frac{d}{dt} |\bar{u}(t)| = \frac{26t+4t^3}{2\sqrt{13t^2+t^4}} = \frac{13t+2t^3}{\sqrt{13t^2+t^4}}$$

$$\overline{U}(t).\overline{U}(t) = (2t,3t,t^2).(2,3,2t) = 4t + 9t + 2t^3 = 13t + 2t^3$$

$$\Rightarrow RS = \frac{\overline{u(t)}.\overline{u'(t)}}{|\overline{u(t)}|} = \frac{13t + 2t^3}{\sqrt{13t^2 + t^4}} \Rightarrow RS = LS$$

Example. Show that the speed of a moving particle remains constant over an interval of time to the acceleration is perpendicular to the relocity throughout that interval.

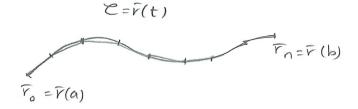
We have:

$$\frac{d}{dt}(\overline{V}(t).\overline{V}(t)) = \overline{V}'(t).\overline{V}(t) + \overline{V}(t).\overline{V}'(t)$$

$$= 2\overline{V}(t).\overline{V}(t) = 2\alpha(t).\overline{V}(t)$$

(12.3)





We calculate the length of a curve by approximation.

Approximation by a polygon path.

$$t_0 = a < t_1 < t_2 < \cdots < t_{n-1} < t_n = b$$
  $\overline{r(t_j)} = \overline{r_j}$ 

Polygon length: 
$$S_n = \sum_{j=1}^n |\vec{r_j} - \vec{r_{j-1}}| = \sum_{j=1}^n |\Delta \vec{r_j}|$$

A curve is rectifiable if there exists a constant A>0 such that  $S_n \subseteq A$  for all  $\{tj\}_{j=0}^n$  and all n. The smallest possible A>0 is the length 5 of the curve.

$$S_{n} = \sum_{j=1}^{n} |\Delta r_{j}| = \sum_{j=1}^{n} |\Delta r_{j}| \Delta t_{j}$$

$$\Delta t_{j} = t_{j} - t_{j-1}$$

$$S = \lim_{n \to \infty} S_n = \int_a^b \left( \frac{d\overline{r}}{dt} \right) dt = \int_a^b |\overline{v}(t)| dt = \int_c^b ds$$
, where max  $\delta tj \to 0$ 

 $\mathcal{E}$  is the curve, and  $ds = \left| \frac{dr}{dt} \right| dt$  is the arc length element.

\* S does not depend on parametrization of the curve.

Example. We have a line along the intersection of the planes (3,2,10) y=2x-4, Z=3x+1. Find the length of the curve (line) by two parametrizations. (A line is a straight curve.)

Parametrization 1 : We set y=t.

$$\Rightarrow x = \frac{t+4}{2} = x + \frac{t}{2}$$
 and  $z = 3(2+\frac{t}{2})+1 = 7+\frac{3}{2}t$ 

$$\Rightarrow F(t) = (\eta(t), y(t), z(t)) = (2 + \frac{1}{2}, t, 7 + \frac{3}{2}t)$$

$$= (2, 0, 7) + t(\frac{1}{2}, 1, \frac{3}{2}) \quad o(t \le 2)$$

Parametrization 2 ? We set n=t

$$\Rightarrow$$
 y=2t-4 and Z=3t+1

$$\Rightarrow \overline{V}(t) = (t, 2t-4, 3t+1) = (09-4, 1) + t(1, 2, 3)$$
 2ct  $\leq 3$ 

· Parametrization of a curve is not unique.

Arc length.

$$(2) \vec{r}(t) = (t, 2t-4, 3t+1)$$
 25t 63  $\frac{d\vec{r}}{dt} = (1, 2, 3)$ 

$$S = \int_{2}^{3} \left| \frac{d\overline{r}}{dt} \right| dt = \sqrt{14} \int_{2}^{3} dt = \sqrt{14} \int_{2}^{3} dt$$

\* A particular curve: The graph of a function.

$$y = f(n)$$

$$a \qquad b$$

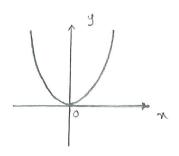
 $= \int_{0}^{b} |(1, f(n))| dn$ = 5 b VI+(f'(x))21 dx.

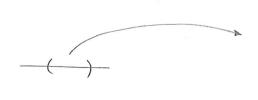
> the length of the graph of a function.

## Functions of several variables (13.1)

Known concepts:

functions IR -> IR, e.g. F(x)=x2





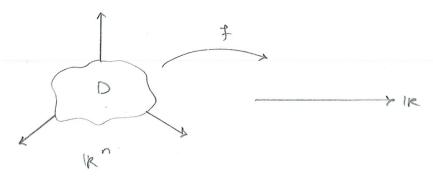
parametrized > n

New Concept:

Let DCIR. A Runction of several variables & is a map F. D-XIR.

D is called domain.

The set frix1, neDy EIR is called the range of f.



Mostly we study n=2 or n=3.

F(x,y) = x2+3y2, D=1k2 Examples : g(n,y) = 2 x /y , D = { (x,y) : x elk, y > 0}

I = f(n,y)

independent variables

dependent Vanable

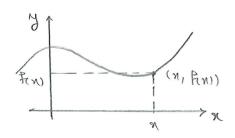
Notation: n=2, fix,y)

n=3: fix,y,Z)

n general: P(x1, x2,--, xn)

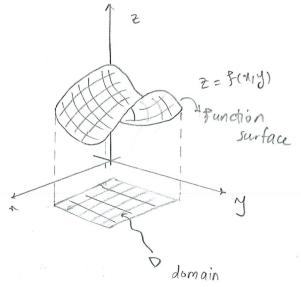
Graphs

The graph of a function File - IR is {(n, Fin)), n ∈ D} = IR2.

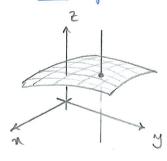


Similarly for f: IR -> IR, the graph is defined by {(x, fix)), xeD} SIR!

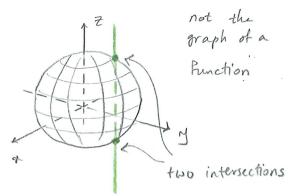
For n=2, the graph  $\{(n,y,f(n,y)): (n,y) \in D\} \subseteq \mathbb{R}^3$  can be visualized as a surface.



Each line perpendicular to the my-plane intersects the surface in at most one point.



Runction surface



two functions

Example:  $f(x_1y) = \frac{1}{3} \sqrt{36-9x^2-4y^2}$ 

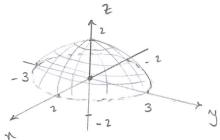
(Is it a function?)

$$Z = f(n_1y_1) \ge 0$$
  $Z^2 = \frac{1}{9} (36 - 9x^2 - 4y^2)$ 

$$\Rightarrow$$
 92<sup>2</sup>= 36-9x<sup>2</sup>-4y<sup>2</sup>  $\Rightarrow$  9x<sup>2</sup>+4y<sup>2</sup>+92<sup>2</sup>=36

=> 
$$\frac{x^2}{4} + \frac{y^2}{9} + \frac{z^2}{4} = 1$$
 ellip soid

The graph of f is the upper half of the ellipsoid. f(x,y) is a function.



Example What is the domain for Rn,y) = Vy-n2) 62

We must exclude  $\{(x,y): y \in \mathbb{N}^2\}$  and (x,y) = (0,1) from  $\mathbb{R}^2$ 

