

## List of formulas for the exam in Numerical Methods, 2024

*These formulas will be attached to the exam. The list is not guaranteed to be complete, and the use, meaning, conditions and assumptions of the formulas are purposely left out.*

- **Taylor's formula**

$$f(x) = f(a) + \frac{f'(a)}{1!}(x-a) + \frac{f''(a)}{2!}(x-a)^2 + \dots + \frac{f^{(n)}(a)}{n!}(x-a)^n + \frac{f^{(n+1)}(\xi)}{(n+1)!}(x-a)^{n+1}$$

( $\xi$  between  $x$  and  $a$ )

- **Operation count**

$$1 + 2 + 3 + 4 + \dots + n = \frac{n(n+1)}{2}, \quad 1^2 + 2^2 + 3^2 + 4^2 + \dots + n^2 = \frac{n(n+1)(2n+1)}{6}$$

- **Absolute and relative error**

$$\Delta_x = \tilde{x} - x, \quad \frac{\Delta_x}{x} \approx \frac{\Delta_x}{\tilde{x}}, \quad \Delta_{x+y} = \Delta_x + \Delta_y, \quad \frac{\Delta_{xy}}{xy} \approx \frac{\Delta_x}{x} + \frac{\Delta_y}{y}$$

- **Error propagation formulas, condition number (1D)**

$$\Delta f \approx f'(x)\Delta x, \quad \left| \frac{\Delta f/f}{\Delta x/x} \right| \approx \left| \frac{xf'(x)}{f(x)} \right|$$
$$\Delta f \approx f''(x)\frac{\Delta x^2}{2}$$

- **Correct decimals**

$$|\Delta x| \leq 0.5 \cdot 10^{-t}$$

- **Binary numbers**

$$x = x_m 2^m + x_{m-1} 2^{m-1} + \dots + x_0 + x_{-1} 2^{-1} + \dots = (x_m x_{m-1} \dots x_0 . x_{-1} \dots)_b$$

- **Iterative methods**

Bisection method:

```
c=(a+b)/2;
while (b-a)>2*tol
    if f(c)*f(a)>0
        a=c;
    else
        b=c;
    end
    c=(a+b)/2;
end
```

Newton-Raphson:  $x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}, \quad J(\mathbf{x}_n)(\mathbf{x}_{n+1} - \mathbf{x}_n) + \mathbf{f}(\mathbf{x}_n) = 0$

The secant method:  $x_{n+1} = x_n - f(x_n) \frac{x_n - x_{n-1}}{f(x_n) - f(x_{n-1})},$

$$e_n = x_n - x^*, \quad \lim_{n \rightarrow \infty} \frac{|e_{n+1}|}{|e_n|^p} = c$$

• **Equation systems**

$$A\mathbf{x} = \mathbf{b}, \quad \text{residual } \mathbf{r} = \mathbf{b} - A\tilde{\mathbf{x}}$$

$$\text{LU-factorization:} \quad A = LU, \quad PA = LU$$

$$\text{QR-factorization:} \quad A = QR, \quad Q^T Q = I$$

$$(\text{Iterative methods}) \quad A = D + L + U$$

$$\text{Jacobi methods:} \quad \begin{cases} \mathbf{x}^{(k)} = -D^{-1}(L + U)\mathbf{x}^{(k-1)} + D^{-1}\mathbf{b} \end{cases}$$

$$\text{Gauss-Seidel:} \quad \begin{cases} \mathbf{x}^{(k)} = -(D + L)^{-1}U\mathbf{x}^{(k-1)} + (D + L)^{-1}\mathbf{b} \end{cases}$$

$$\text{Backward: } \|\mathbf{r}\|_\infty, \text{ forward: } \|\mathbf{x} - \tilde{\mathbf{x}}\|_\infty$$

• **Norms and condition numbers**

Let  $\mathbf{x} = (x_1, \dots, x_n)$  be a vector:

$$\|\mathbf{x}\|_p = \left( \sum_{i=1}^n |x_i|^p \right)^{1/p}, \quad \|\mathbf{x}\|_1 = \sum_{i=1}^n |x_i|, \quad \|\mathbf{x}\|_2 = \sqrt{x_1^2 + \dots + x_n^2}, \quad \|\mathbf{x}\|_\infty = \max_i |x_i|.$$

Let  $A$  be a  $n \times n$  matrix:

$$\|A\| = \sup_{\mathbf{x} \neq 0} \frac{\|A\mathbf{x}\|}{\|\mathbf{x}\|}, \quad \|A\mathbf{x}\| \leq \|A\| \cdot \|\mathbf{x}\|, \quad \kappa(A) = \|A\| \cdot \|A^{-1}\|$$

$$A(\mathbf{x} + \delta\mathbf{x}) = \mathbf{b} + \delta\mathbf{b}$$

$$\frac{\|\delta\mathbf{x}\|}{\|\mathbf{x}\|} \leq \kappa(A) \frac{\|\delta\mathbf{b}\|}{\|\mathbf{b}\|}, \quad \frac{\|\delta\mathbf{x}\|/\|\mathbf{x}\|}{\|\delta\mathbf{b}\|/\|\mathbf{b}\|} \leq \kappa(A),$$

• **Interpolation**

Let  $(x_0, y_0), \dots, (x_n, y_n)$  be  $n + 1$  points in the  $xy$ -plane.

$$\text{Monomial:} \quad P(x) = a_0 + a_1x + \dots + a_nx^n$$

$$\text{Lagrangre:} \quad P(x) = \sum_{j=0}^n y_j \ell_j(x), \quad \ell_j(x) = \prod_{\substack{0 \leq m \leq n \\ m \neq j}} \frac{x - x_m}{x_j - x_m}$$

Newton's divided differences:

$$P(x) = f[x_1] + f[x_1 x_2](x - x_1) + \dots + f[x_1 \dots x_{k+1}](x - x_1)(x - x_2) \dots (x - x_k). \\ f[x_1] = f(x_1), \quad f[x_1 x_2] = \frac{f(x_2) - f(x_1)}{x_2 - x_1}, \quad f[x_1 x_2 x_3] = \frac{f[x_2 x_3] - f[x_1 x_2]}{x_3 - x_1}, \dots$$

Interpolation remainder:

$$f(x) - P(x) = (x - x_1)(x - x_2) \dots (x - x_n) \frac{f^{(n)}(\xi)}{(n)!}, \quad x_1 < \xi < x_n,$$

• **Least squares, normal equations**  $A^T A \mathbf{x} = A^T \mathbf{b}$ , residual  $\mathbf{r} = \mathbf{b} - A\mathbf{x}$

- **Finite differences**

$$\begin{aligned}\frac{f(x+h) - f(x)}{h} &= f'(x) + f''(\xi) \frac{h}{2} & \xi \in [x, x+h] \\ \frac{f(x) - f(x-h)}{h} &= f'(x) - f''(\xi) \frac{h}{2} & \xi \in [x-h, x] \\ \frac{f(x+h) - f(x-h)}{2h} &= f'(x) + f^{(3)}(\xi) \frac{h^2}{6} & \xi \in [x-h, x+h] \\ \frac{f(x+h) - 2f(x) + f(x-h)}{h^2} &= f''(x) + f^{(4)}(\xi) \frac{h^2}{12} & \xi \in [x-h, x+h]\end{aligned}$$

- **Trapezoidal rule, Simpson's rule**

$$\begin{aligned}\int_a^b f(x)dx &= \frac{h}{2} \left( f(x_0) + 2 \sum_{k=1}^{n-1} f(x_k) + f(x_n) \right) - \frac{(b-a)h^2}{12} f''(\xi), & h = \frac{b-a}{n} \\ \int_a^b f(x)dx &= \frac{h}{3} \left( f(x_0) + 4 \sum_{k=1}^n f(x_{2k-1}) + 2 \sum_{k=1}^{n-1} f(x_{2k}) + f(x_{2n}) \right) - \frac{(b-a)h^4}{180} f^{(4)}(\xi), & h = \frac{b-a}{2n}\end{aligned}$$

$$a < \xi < b$$

- **Richardson extrapolation**

$$Q = F(h) + Kh^n + \mathcal{O}(h^{n+1}), \quad Q = \frac{2^n F(h/2) - F(h)}{2^n - 1} + \mathcal{O}(h^{n+1})$$

- **Romberg**  $R_{i,1} = T(h/2^{i-1})$ ,  $R_{ij} = \frac{4^{j-1}R_{i,j-1} - R_{i-1,j-1}}{4^{j-1} - 1}$

- **Numerical solutions of differential equations**

Differential equation  $y' = f(x, y)$  with initial condition  $y(x_0) = y_0$

$$\begin{aligned}\text{Euler forward } (g_i \sim \mathcal{O}(h)) &: & y_{n+1} &= y_n + hf(x_n, y_n) \\ \text{Euler backward } (g_i \sim \mathcal{O}(h)) &: & y_{n+1} &= y_n + hf(x_{n+1}, y_{n+1}) \\ \text{RK4 } (g_i \sim \mathcal{O}(h^4)) &: & \begin{cases} y_{n+1} = y_n + \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4) \\ k_1 = hf(x_n, y_n) \\ k_2 = hf(x_n + h/2, y_n + k_1/2) \\ k_3 = hf(x_n + h/2, y_n + k_2/2) \\ k_4 = hf(x_n + h, y_n + k_3) \end{cases}\end{aligned}$$

where  $x_{n+1} = x_n + h$ .

- **Boundary value problems**

Two-point boundary problem  $y'' = f(x, y, y')$  with initial condition  $y(a) = \alpha$  and  $y(b) = \beta$ .

Shooting method: The BVP is rewritten as a IVP. Vary the modified initial condition until the boundary conditions are satisfied with desired accuracy.

Finite difference method: Derivatives are approximated by finite difference quotients. Exact solution  $y$  is replaced by  $y_i$  such that  $y_i \approx y(x_i)$