

**Written Exam on Numerical Methods, 1MA930, 3 hp (7.5 hp)**

Thursday 2nd of June 2022, 08.00–13.00.

The solutions should be complete, correct, motivated, well structured and easy to follow.  
Aids: Calculator (you may use a scientific calculator but *not* with internet connection).  
*Please begin each question on a new paper.*  
Preliminary grades: 15p-17p⇒E; 18p-20p⇒D; 21p-23p⇒C; 24p-26p⇒B; 27p-30p⇒A.

1. Do the following sums by hand in IEEE double precision computer arithmetic, using the Rounding to Nearest Rule:

(a)  $(1 + 2^{-54}) - 1$ ,

(b)  $2^{-60} + 2^{-75}$ .

- (c) Identify for which values of  $x$  there is subtraction of nearly equal numbers, and find an alternate form that avoids the problem:

$$\frac{1}{1+x} - \frac{1}{1-x}.$$

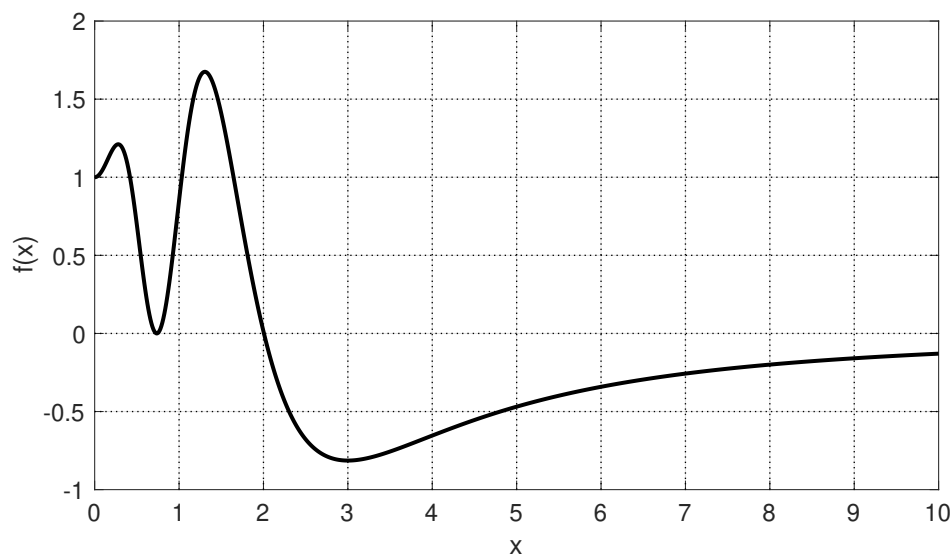
- (d) A derivative  $f'(x)$  is approximated by the central finite difference  $D_{x,h} = \frac{f(x+h)-f(x-h)}{2h}$  in a computer.

Sketch the resulting error  $|D_{x,h} - f'(x)|$ , as a function of  $h$ . It should be a log-log plot (logarithmic scaling on both x-axis and y-axis) for values of  $h$  ranging from  $10^{-20}$  to 1.

*You may assume that  $x \sim \mathcal{O}(1)$ , that  $f(x)$  and its derivatives are well-defined in a neighbourhood around  $x$  and that  $f''(x) \neq 0$ .*

(1p+1p+1p+2p)

2. Assume that you seek the roots to a non-linear equation  $f(x) = 0$ . To get an understanding for the problem, you first plot the function  $f(x)$ . The result is depicted in the figure below (the roots visible in the figure are the only ones that exist for  $x \geq 0$ ):



*Please turn, the questions continue on next page!*

- (a) Without doing any actual calculations, describe what will happen if you use the Newton-Raphson method with (i)  $x_0 = 1$ , (ii)  $x_0 = 2$ , (iii)  $x_0 = 3$  or (iv)  $x_0 = 4$  as initial guess. *Thus, for each initial guess (i-iv): Does the method converge? If it converges – to which root and with what convergence rate? If it does not converge – why not?*
- (b) Find the real solution of  $x^3 + 6x = 3x^2 + 11$ . Answer with 4 correct decimals. (3p)+(2p)
3. Given the following set of points  $(x, y)$ : (1, 2), (3, 6), (4, 5):
- (a) Determine the corresponding interpolating polynomial (of lowest possible degree),
- (b) Evaluate the function value of the interpolating polynomial for  $x = 2$ .
- (c) Assume that the points in (a) were produced by the function  $f(x) = x^3 - 9x^2 + 25x - 15$ . Find an upper bound for the interpolation error at  $x = 2$ .
- (2p+1p+2p)
4. The function values  $y$  are given for a few points according to

$x$	1	1.25	1.5	1.75	2
$y(x)$	0.1250	0.8350	1.0280	0.5740	-1.1630

- (a) Compute an approximation to the integral  $\int_1^2 y(x)dx$  using Simpson's method. All available function values must be used.
- (b) Compute an approximation of  $\int_1^2 y(x)dx$  using Simpson's method again, but now with the step length  $h$  doubled. Approximately how large is the error obtained in (b) compared to the error obtained in (a)? Motivate your answer.
- (c) Use Richardson extrapolation on the values obtained in (a) and (b) in order to find an improved approximation of the integral  $\int_1^2 y(x)dx$ . (2p+2p+1p)
5. Let  $y(x)$  be the solution of  $y'(x) = x - xy$  for which  $y(0) = 2$ .
- (a) Find an approximation of  $y(2)$  using Euler forward with step length  $h = 1$  and another approximation using  $h = 0.5$ . Answer using 4 correctly rounded decimals.
- (b) Using Richardson extrapolation, calculate an improved approximation of  $y(2)$  using the results obtained in (a).
- (c) What are the advantages and drawbacks when comparing Euler forward with Euler backward? (3p+1p+1p)
6. Consider the boundary value problem

$$\frac{d^2 y}{dx^2} = \frac{-15}{x+1}, \quad x \in [0, 6]$$

$$y(x=0) = -8$$

$$y(x=6) = 3$$

- (a) Approximate the boundary value problem described above as a finite difference problem with step size  $\Delta x = h = 2$ , and present the resulting system of equations in matrix form.
- (b) Solve the system and plot the solution in an appropriate coordinate system. (3p+2p)

*Good luck!*

## List of formulas for the exam in Numerical Methods, 2022

*These formulas will be attached to the exam. The list is not guaranteed to be complete, and the use, meaning, conditions and assumptions of the formulas are purposely left out.*

- **Taylor's formula**

$$f(x) = f(a) + \frac{f'(a)}{1!}(x-a) + \frac{f''(a)}{2!}(x-a)^2 + \dots + \frac{f^{(n)}(a)}{n!}(x-a)^n + \frac{f^{(n+1)}(\xi)}{(n+1)!}(x-a)^{n+1}$$

( $\xi$  between  $x$  and  $a$ )

- **Absolute and relative error**

$$\Delta_x = \tilde{x} - x, \quad \frac{\Delta_x}{x} \approx \frac{\Delta_x}{\tilde{x}}, \quad \Delta_{x+y} = \Delta_x + \Delta_y, \quad \frac{\Delta_{xy}}{xy} \approx \frac{\Delta_x}{x} + \frac{\Delta_y}{y}$$

- **Error propagation formulas, condition number (1D)**

$$\Delta f \approx f'(x)\Delta x, \quad \left| \frac{\Delta f/f}{\Delta x/x} \right| \approx \left| \frac{x f'(x)}{f(x)} \right|$$
$$\Delta f \approx f''(x) \frac{\Delta x^2}{2}$$

- **Correct decimals**

$$|\Delta x| \leq 0.5 \cdot 10^{-t}$$

- **Numbers in base  $B$**

$$x = x_m B^m + x_{m-1} B^{m-1} + \dots + x_0 B^0 + x_{-1} B^{-1} + \dots = (x_m x_{m-1} \dots x_0 . x_{-1} \dots)_B$$

- **Iterative methods**

Bisection method:

```
c=(a+b)/2;
while (b-a)>2*tol
    if f(c)*f(a)>0
        a=c;
    else
        b=c;
    end
    c=(a+b)/2;
end
```

Newton-Raphson: 
$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}, \quad J(\mathbf{x}_n)(\mathbf{x}_{n+1} - \mathbf{x}_n) + \mathbf{f}(\mathbf{x}_n) = 0$$

The secant method: 
$$x_{n+1} = x_n - f(x_n) \frac{x_n - x_{n-1}}{f(x_n) - f(x_{n-1})},$$

$$e_n = x_n - x^*, \quad |x_{n+1} - x^*| < \bar{c} |x_n - x^*|^p, \quad \lim_{n \rightarrow \infty} \frac{|e_{n+1}|}{|e_n|^p} = c$$

- **Equation systems**

$$A\mathbf{x} = \mathbf{b}, \quad \text{residual } \mathbf{r} = \mathbf{b} - A\tilde{\mathbf{x}}$$

$$\text{LU-factorization:} \quad A = LU, \quad PA = LU$$

$$\text{QR-factorization:} \quad A = QR, \quad Q^T Q = I$$

$$(\text{Iterative methods}) \quad A = D + L + U$$

$$\text{Jacobi methods:} \quad \begin{cases} \mathbf{x}^{(k)} = -D^{-1}(L + U)\mathbf{x}^{(k-1)} + D^{-1}\mathbf{b} \\ \mathbf{x}^{(k)} = -(D + L)^{-1}U\mathbf{x}^{(k-1)} + (D + L)^{-1}\mathbf{b} \end{cases}$$

$$\text{Gauss-Seidel:}$$

$$\text{Backward: } \|\mathbf{r}\|_\infty, \text{ forward: } \|\mathbf{x} - \tilde{\mathbf{x}}\|_\infty$$

### • Norms and condition numbers

Let  $\mathbf{x} = (x_1, \dots, x_n)$  be a vector:

$$\|\mathbf{x}\|_p = \left( \sum_{i=1}^n |x_i|^p \right)^{1/p}, \quad \|\mathbf{x}\|_1 = \sum_{i=1}^n |x_i|, \quad \|\mathbf{x}\|_2 = \sqrt{x_1^2 + \dots + x_n^2}, \quad \|\mathbf{x}\|_\infty = \max_i |x_i|.$$

Let  $A$  be a  $n \times n$  matrix:

$$\|A\| = \sup_{\mathbf{x} \neq 0} \frac{\|A\mathbf{x}\|}{\|\mathbf{x}\|}, \quad \|A\mathbf{x}\| \leq \|A\| \cdot \|\mathbf{x}\|, \quad \kappa(A) = \|A\| \cdot \|A^{-1}\|$$

$$A(\mathbf{x} + \delta\mathbf{x}) = \mathbf{b} + \delta\mathbf{b}$$

$$\frac{\|\delta\mathbf{x}\|}{\|\mathbf{x}\|} \leq \kappa(A) \frac{\|\delta\mathbf{b}\|}{\|\mathbf{b}\|}, \quad econd(A) = \frac{\|\delta\mathbf{x}\|/\|\mathbf{x}\|}{\|\delta\mathbf{b}\|/\|\mathbf{b}\|} \leq \kappa(A),$$

### • Interpolation

Let  $(x_0, y_0), \dots, (x_n, y_n)$  be  $n + 1$  points in the xy-plane.

$$\text{Monomial:} \quad P(x) = a_0 + a_1x + \dots + a_nx^n$$

$$\text{Lagrangre:} \quad P(x) = \sum_{j=0}^n y_j \ell_j(x), \quad \ell_j(x) = \prod_{\substack{0 \leq m \leq n \\ m \neq j}} \frac{x - x_m}{x_j - x_m}$$

Newton's divided differences:

$$P(x) = [y_0] + [y_0, y_1](x - x_0) + \dots + [y_0, \dots, y_k](x - x_0)(x - x_1) \dots (x - x_{n-1}).$$

$$[y_0] = f(x_0), \quad [y_0, y_1] = \frac{f(x_1) - f(x_0)}{x_1 - x_0}, \quad [y_0, y_1, y_2] = \frac{[y_1, y_2] - [y_0, y_1]}{x_2 - x_0}, \dots$$

Interpolation errors:

$$R(x) = f(x) - P(x) = (x - x_0)(x - x_1) \dots (x - x_n) \frac{f^{n+1}(\xi)}{(n+1)!}, \quad x_0 < \xi < x_n,$$

### • Least squares, normal equations $A^T A \mathbf{x} = A^T \mathbf{b}$ , residual $\mathbf{r} = \mathbf{b} - A\mathbf{x}$

### • Finite differences

$$\frac{f(x+h) - f(x)}{h} = f'(x) + f''(\xi) \frac{h}{2} \quad \xi \in [x, x+h]$$

$$\frac{f(x) - f(x-h)}{h} = f'(x) - f''(\xi) \frac{h}{2} \quad \xi \in [x-h, x]$$

$$\frac{f(x+h) - f(x-h)}{2h} = f'(x) + f^{(3)}(\xi) \frac{h^2}{6} \quad \xi \in [x-h, x+h]$$

$$\frac{f(x+h) - 2f(x) + f(x-h)}{h^2} = f''(x) + f^{(4)}(\xi) \frac{h^2}{12} \quad \xi \in [x-h, x+h]$$

- **Trapezoidal rule, Simpson's rule**

$$\int_a^b f(x)dx = \frac{h}{2} \left( f(x_0) + 2 \sum_{k=1}^{n-1} f(x_k) + f(x_n) \right) - \frac{(b-a)h^2}{12} f''(\xi), \quad h = \frac{b-a}{n}$$

$$\int_a^b f(x)dx = \frac{h}{3} \left( f(x_0) + 4 \sum_{k=1}^n f(x_{2k-1}) + 2 \sum_{k=1}^{n-1} f(x_{2k}) + f(x_{2n}) \right) - \frac{(b-a)h^4}{180} f^{(4)}(\xi), \quad h = \frac{b-a}{2n}$$

$$a < \xi < b$$

- **Richardson extrapolation**

$$Q = F(h) + kh^n + \mathcal{O}(h^{n+1}), \quad Q = \frac{2^n F(h/2) - F(h)}{2^n - 1} + \mathcal{O}(h^{n+1})$$

- **Romberg**  $R_{i,1} = T(h/2^{i-1})$ ,  $R_{ij} = \frac{4^{j-1}R_{i,j-1} - R_{i-1,j-1}}{4^{j-1} - 1}$

- **Numerical solutions of differential equations**

Differential equation  $y' = f(x, y)$  with initial condition  $y(x_0) = y_0$

Euler forward ( $g_i \sim \mathcal{O}(h)$ ):	$y_{n+1} = y_n + hf(x_n, y_n)$
Euler backward ( $g_i \sim \mathcal{O}(h)$ ):	$y_{n+1} = y_n + hf(x_{n+1}, y_{n+1})$
Heun's method ( $g_i \sim \mathcal{O}(h^2)$ ):	$\begin{cases} y_{n+1} = y_n + \frac{1}{2}(k_1 + k_2) \\ k_1 = hf(x_n, y_n) \\ k_2 = hf(x_n + h, y_n + k_1) \end{cases}$
RK4 ( $g_i \sim \mathcal{O}(h^4)$ ):	$\begin{cases} y_{n+1} = y_n + \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4) \\ k_1 = hf(x_n, y_n) \\ k_2 = hf(x_n + h/2, y_n + k_1/2) \\ k_3 = hf(x_n + h/2, y_n + k_2/2) \\ k_4 = hf(x_n + h, y_n + k_3) \end{cases}$

where  $x_{n+1} = x_n + h$ .

- **Boundary value problems**

Two-point boundary problem  $y'' = f(x, y, y')$  with initial condition  $y(a) = \alpha$  and  $y(b) = \beta$ .

Shooting method: The BVP is rewritten as a IVP. Vary the modified initial condition until the boundary conditions are satisfied with desired accuracy.

Finite difference method: Derivatives are approximated by finite difference quotients. Exact solution  $y$  is replaced by  $y_i$  such that  $y_i \approx y(x_i)$

- **Eigenvalue problems**

The power method:  $\mathbf{v}_{k+1} = A\mathbf{v}_k / \|A\mathbf{v}_k\|$  and  $\lambda_1 \approx \mathbf{v}_k^T A \mathbf{v}_k$ .

The QR-method. Let  $A = Q_0 R_0$  be a QR-decomposition of a real matrix  $A$ . Set  $A_1 = R_0 Q_0$  and inductively (if  $A_{n-1} = Q_{n-1} R_{n-1}$  is a QR-decomposition)  $A_n = R_{n-1} Q_{n-1}$ .