

## HOMework 2: SYMPLECTIC FORMS VS. AREA AND VOLUME

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**Exercise 1.1.** Let  $(M, \omega)$  be a  $2n$ -dimensional symplectic manifold.

- (a)  $\omega^n$  is a volume form.
- (b) Show that if  $M$  is compact, then  $[\omega^n] \in H_{\text{dR}}^{2n}(M)$  is nonzero.
- (c) Conclude that  $[\omega] \neq 0$ .
- (d)  $\mathbb{S}^{2n}$  does not admit a symplectic structure for  $n > 1$ .

**Solution 1.1.** Part (a) immediately follows from the fact that for each  $p \in M$  we have that  $\omega_p^n \neq 0$ . Thus  $\omega^n$  is a nonvanishing form of top degree, hence a volume form.

For proving (b), assume that  $[\omega^n] = 0$ . Hence  $\omega^n$  is exact. Thus there exists  $\mu \in \Omega^{2n-1}(M)$  such that  $\omega^n = d\mu$ . But then Stoke's theorem [Lee13, p. 411] together with positivity [Lee13, p. 407] yields

$$0 < \int_M \omega^n = \int_M d\mu = \int_{\partial M} \mu = \int_{\emptyset} \mu = 0$$

since  $M$  is oriented by part (a) and  $\omega^n$  is a positively oriented orientation form (see [Lee13, p. 381]).

For proving (c), observe that  $[\omega^n] = [\omega] \cup \dots \cup [\omega]$ , where  $\cup$  is the so-called cup product (see [Lee13, p. 464]). So if  $[\omega] = 0$ , we have by bilinearity also  $[\omega^n] = 0$ , which contradicts part (b).

For proving (d), by [Lee13, p. 450] we have that

$$H_{\text{dR}}^p(\mathbb{S}^n) \cong \begin{cases} \mathbb{R} & p = 0 \text{ or } p = n, \\ 0 & 0 < p < n, \end{cases}$$

for  $n \geq 1$ . Let  $n > 1$ . Assume that  $(\mathbb{S}^n, \omega)$  is a symplectic manifold. Since  $\mathbb{S}^n$  is compact, part (c) implies that  $[\omega] \neq 0$ . But  $[\omega] \in H_{\text{dR}}^2(\mathbb{S}^{2n}) \cong 0$ .

**Example 1.1.** Consider the symplectic manifold  $(\mathbb{R}^{2n}, \omega_0)$ , where  $\omega_0$  is the standard symplectic structure on  $\mathbb{R}^{2n}$ . Clearly,  $\mathbb{R}^{2n}$  is not compact and  $\omega_0$  is exact since

$$d\left(\sum_{i=1}^n x^i dy^i\right) = \sum_{i=1}^n dx^i \wedge dy^i = \omega_0.$$

**Example 1.2.** Let  $M$  be a smooth manifold. Then  $(T^*M, \omega)$  is a symplectic manifold, where  $\omega$  is the canonical symplectic form on  $T^*M$ . It is an exact form, since  $\omega = -d\alpha$ , where  $\alpha$  is the tautological 1-form. Moreover,  $T^*M$  is not compact by problem 10-19 [Lee13, p. 271].

**Exercise 1.2.** Let  $(M, \omega)$  be a  $2n$ -dimensional symplectic manifold.

(a)

**Solution 1.2.** For proving (a), we have using [Lee13, p. 117]

$$T_p\mathbb{S}^n = \{v \in \mathbb{R}^{n+1} : \langle v, p \rangle = 0\}$$

for each  $p \in \mathbb{S}^n$ . Consider the *Euler vector field*  $V$  defined by

$$V := x^i \frac{\partial}{\partial x^i}.$$

Then  $V$  is a unit normal vector field along  $\mathbb{S}^n$ . Indeed, if  $p \in \mathbb{S}^n$  and  $v \in T_p\mathbb{S}^n$  we have that

$$\langle p, v \rangle_{\bar{g}} = \langle p, v \rangle = 0$$

and

$$|p|_{\bar{g}} = |p| = 1.$$

Hence by [Lee13, p. 390], the volume form  $\omega_{\bar{g}}$  on  $(\mathbb{S}^n, \bar{g})$  is given by

$$\omega_{\bar{g}} = \iota_{\mathbb{S}^n}^*(i_V \omega_{\bar{g}}).$$

More precisely, in the case  $n = 2$  we have

$$\begin{aligned} i_V \omega_{\bar{g}} &= i_V(dx \wedge dy \wedge dz) \\ &= (i_V dx) \wedge dy \wedge dz - dx \wedge i_V(dy \wedge dz) \\ &= (i_V dx) \wedge dy \wedge dz - dx \wedge (i_V dy) \wedge dz + dx \wedge dy \wedge (i_V dz) \\ &= x dy \wedge dz + y dz \wedge dx + z dx \wedge dy. \end{aligned}$$

For  $v, w \in T_p\mathbb{S}^2$ ,  $p \in \mathbb{S}^2$ , we have that

$$\omega_{\bar{g}}|_p(v, w) = (i_V \omega_{\bar{g}})_{\iota(p)}(d\iota_p(v), d\iota_p(w)) = (i_V \omega_{\bar{g}})|_p(v, w)$$

under the usual identification of  $T_p\mathbb{S}^n$  as a linear subspace of  $T_p\mathbb{R}^{n+1}$ . Finally

$$\begin{aligned} \omega_{\bar{g}}(v, w) &= (x dy \wedge dz + y dz \wedge dx + z dx \wedge dy)(v, w) \\ &= x \det \begin{pmatrix} dy(v) & dz(v) \\ dy(w) & dz(w) \end{pmatrix} + y \det \begin{pmatrix} dz(v) & dx(v) \\ dz(w) & dx(w) \end{pmatrix} + z \det \begin{pmatrix} dx(v) & dy(v) \\ dx(w) & dy(w) \end{pmatrix} \\ &= x(v^2 w^3 - w^2 v^3) + y(v^3 w^1 - w^3 v^1) + z(v^1 w^2 - w^1 v^2) \\ &= \langle p, v \times w \rangle \end{aligned}$$

for  $p := (x, y, z) \in \mathbb{S}^2$  using [Lee13, p. 356].

For proving (b), consider cylindrical polar coordinates  $(\theta, z)$  on  $\mathbb{S}^2$  given by

$$(x, y, z) = (\sqrt{1-z^2} \cos \theta, \sqrt{1-z^2} \sin \theta, z).$$

Then we get

$$\begin{aligned} i_V \omega_{\bar{g}} &= \text{id}^*(i_V \omega_{\bar{g}}) \\ &= \text{id}^*(x dy \wedge dz + y dz \wedge dx + z dx \wedge dy) \\ &= \sqrt{1-z^2} \cos \theta d(\sqrt{1-z^2} \sin \theta) \wedge dz + \sqrt{1-z^2} \sin \theta dz \wedge d(\sqrt{1-z^2} \cos \theta) \\ &\quad + z d(\sqrt{1-z^2} \cos \theta) \wedge d(\sqrt{1-z^2} \sin \theta) \\ &= \sqrt{1-z^2} \cos \theta \left( \sqrt{1-z^2} \cos \theta d\theta - \frac{z}{\sqrt{1-z^2}} \sin \theta dz \right) \wedge dz \\ &\quad - \sqrt{1-z^2} \sin \theta dz \wedge \left( \sqrt{1-z^2} \sin \theta d\theta + \frac{z}{\sqrt{1-z^2}} \cos \theta dz \right) \\ &\quad - z \left( \sqrt{1-z^2} \sin \theta d\theta + \frac{z}{\sqrt{1-z^2}} \cos \theta dz \right) \\ &\quad \wedge \left( \sqrt{1-z^2} \cos \theta d\theta - \frac{z}{\sqrt{1-z^2}} \sin \theta dz \right) \\ &= (1-z^2) \cos^2 \theta d\theta \wedge dz - (1-z^2) \sin^2 \theta dz \wedge d\theta + z^2 \sin^2 \theta d\theta \wedge dz \\ &\quad - z^2 \cos^2 \theta dz \wedge d\theta \\ &= d\theta \wedge dz. \end{aligned}$$

For proving (c), just observe that

$$\text{Vol}(\mathbb{S}^2) = \int_{\mathbb{S}^2} \omega_{\bar{g}} = \int_{(0,2\pi) \times (-1,1)} d\theta \wedge dz = 4\pi.$$

**Exercise 1.3.** Let  $(M, \omega)$  be a  $2n$ -dimensional symplectic manifold.

(a)

**Solution 1.3.** For (a), observe that by exercise 1.1, the manifold must be orientable. Thus surfaces like the sphere, torus and connected sums of these (classification theorem) do possess a symplectic structure, whereas the non-orientable surfaces like the real projective plane and the Möbius strip do not possess any symplectic structures.