

YANNIS BÄHNI

---

DIFFERENTIAL  
TOPOLOGY AND  
DIFFERENTIAL  
GEOMETRY WITH  
APPLICATIONS TO  
GENERAL  
RELATIVITY

---

YANNIS BÄHNI

---

DIFFERENTIAL  
TOPOLOGY AND  
DIFFERENTIAL  
GEOMETRY WITH  
APPLICATIONS TO  
GENERAL  
RELATIVITY

---

## Preface

The process of writing this book started in autumn of 2018. The book is mainly based on the course notes of the course *Differential Geometry I* and *Differential Geometry II* held by *Prof. Dr. Will J. Merry* at *ETH Zurich* in the autumn semester 2018 and spring semester 2019, I visited. They can be found here:

<https://www.merry.io/differential-geometry/>

Moreover, the part concerning general relativity, is freely taken from the course *General Relativity* taught by *Prof. Dr. Renato Renner* at *ETH Zurich* in the autumn semester 2018.

Winterthur,  
September 1, 2018

Yannis Bähni

## Contents

<b>Preface</b> . . . . .	<b>ii</b>
<b>Chapter 1: Differential Topology</b> . . . . .	<b>1</b>
The Category of Smooth Manifolds . . . . .	1
The Tangent Bundle . . . . .	1
Vector Fields . . . . .	1
The Cotangent Bundle . . . . .	2
Tensor Bundles and Tensor Fields . . . . .	2
<b>Chapter 2: Differential Geometry</b> . . . . .	<b>7</b>
<b>Chapter 3: General Relativity</b> . . . . .	<b>8</b>
<b>Bibliography</b> . . . . .	<b>9</b>

## CHAPTER 1

### Differential Topology

#### The Category of Smooth Manifolds

**Example 1.1 ( $n$ -Spheres).** Let  $n \in \omega$ . If  $n = 0$ , we have that  $\mathbb{S}^0 = \{\pm 1\}$ . It is easily seen that  $\mathbb{S}^0$  is a smooth manifold of dimension 0. Let  $n \geq 1$ . Define  $N := e_{n+1}$  and  $S := -e_{n+1}$ , where  $e_{n+1}$  denotes the  $n + 1$ -th standard basis vector of  $\mathbb{R}^{n+1}$ . Moreover, set

$$U_+ := \mathbb{S}^n \setminus S \quad \text{and} \quad U_- := \mathbb{S}^n \setminus N.$$

Then  $U_+$  and  $U_-$  are open subsets of  $\mathbb{S}^n$ , the upper and lower hemisphere, respectively. Then the functions  $\varphi_{\pm} : U_{\pm} \rightarrow \mathbb{R}^n$  defined by

$$\varphi_{\pm}(x) := \frac{1}{1 \pm x_{n+1}}(x_1, \dots, x_n),$$

are homeomorphisms. Indeed, one can check that  $\psi_{\pm} : \mathbb{R}^n \rightarrow U_{\pm}$  defined by

$$\psi_{\pm}(x) := \left( \frac{2x}{1 + |x|^2}, \frac{\pm(1 - |x|^2)}{1 + |x|^2} \right)$$

is a continuous inverse for  $\varphi_+$  and  $\varphi_-$ , respectively. We claim that  $\{(U_{\pm}, \varphi_{\pm})\}$  is a smooth atlas for  $\mathbb{S}^n$ . Clearly,  $\mathbb{S}^n$  is covered by the two charts. Next we have to calculate the transition functions  $\varphi_{\mp} \circ \varphi_{\pm}^{-1} = \varphi_{\mp} \circ \psi_{\pm} : \varphi_{\pm}(U_+ \cap U_-) \rightarrow \varphi_{\mp}(U_+ \cap U_-)$ . It is easy to see that  $\varphi_{\pm}(U_+ \cap U_-) = \mathbb{R}^n \setminus \{0\}$  and that

$$\varphi_{\mp} \circ \psi_{\pm} = \frac{x}{|x|^2},$$

which is smooth. Since  $\mathbb{S}^n$  is Hausdorff as a metric space and as a subspace of a second countable space, itself second countable,  $\mathbb{S}^n$  equipped with the smooth structure induced by the smooth atlas constructed above, is a smooth manifold of dimension  $n$ .

#### The Tangent Bundle

##### Vector Fields.

## The Cotangent Bundle

### Tensor Bundles and Tensor Fields

Let  $M \in \text{Diff}$  and  $(k, l) \in \omega \times \omega$ . Consider

$$T^{(k,l)}M := \coprod_{p \in M} T^{(k,l)}(T_p M).$$

Define  $\pi : T^{(k,l)}M \rightarrow M$  by setting  $\pi(p, A) := p$  for  $A \in T^{(k,l)}(T_p M)$ . Clearly  $\pi$  is surjective. Thus let  $p \in M$  be arbitrary. Then there exists a chart  $(U, \varphi)$  around  $p$

**Lemma 1.2.** *Let  $n, k \in \mathbb{Z}$ ,  $n, k \geq 1$ . Let  $V$  be an  $n$ -dimensional real vector space. Then*

$$V \otimes \underbrace{V^* \otimes \cdots \otimes V^*}_k \cong L(\underbrace{V, \dots, V}_k; V) \quad (1)$$

*canonically. If  $(e_v)$  is a basis of  $V$  and  $(e_v^*)$  the corresponding basis of  $V^*$ , then  $f \in \text{End}(V)$  corresponds to*

$$\sum_{v=1}^n f(e_v) \otimes e_v^*. \quad (2)$$

*Proof.* It is easily checked that

$$\Psi : \begin{cases} V \times V^* \times \cdots \times V^* \rightarrow L(V, \dots, V; V) \\ (v, f_1, \dots, f_k) \mapsto ((v_1, \dots, v_k) \mapsto f_1(v_1) \cdots f_k(v_k)v) \end{cases}$$

is multilinear. Thus by the universal property of the tensor product there exists a unique linear mapping  $\tilde{\Psi} \in \text{Hom}_{\mathbb{R}}(T^{(1,k)}(V); L(V, \dots, V; V))$  such that  $\Psi = \tilde{\Psi} \circ \otimes$ . It is also easily checked that  $\tilde{\Psi}$  is an isomorphism. Let  $f \in \text{End}(V)$ . Then for any  $v \in V$  we have

$$\begin{aligned} \tilde{\Psi} \left( \sum_{v=1}^n f(e_v) \otimes e_v^* \right) (v) &= \sum_{v=1}^n \tilde{\Psi} (f(e_v) \otimes e_v^*) (v) \\ &= \sum_{v=1}^n e_v^*(v) f(e_v) \\ &= f \left( \sum_{v=1}^n e_v^*(v) e_v \right) \\ &= f(v). \end{aligned}$$

□

**Proposition 1.3.** *The bundle of mixed tensors of type  $(k, l)$  has a unique natural structure as a smooth vector bundle of rank  $n^{k+l}$  over  $M$ .*

*Proof.* For each  $p \in M$  let  $E_p := T^{(k,l)}(T_p M)$ . By [Lee13, p. 57] and [Lee13, p. 313]  $\dim E_p = n^{k+l}$ . Furthermore, let  $E := T^{(k,l)}TM$  and  $\pi : E \rightarrow M$  be defined by  $\pi(p, A) := p$ . Let  $\{(U_\alpha, \varphi_\alpha) : \alpha \in A\}$  be an atlas for  $M$ . For each  $\alpha \in A$  define

$$\Phi_\alpha : \begin{cases} \pi^{-1}(U_\alpha) \rightarrow U_\alpha \times \mathbb{R}^{n^{k+l}} \\ (p, A) \mapsto (p, (A_{j_1 \dots j_l}^{i_1 \dots i_k})) \end{cases}$$

Clearly, the inverse is given by

$$\Phi_\alpha^{-1} : \begin{cases} U_\alpha \times \mathbb{R}^{n^{k+l}} \rightarrow \pi^{-1}(U_\alpha) \\ (p, (A_{j_1 \dots j_l}^{i_1 \dots i_k})) \mapsto (p, A) \end{cases}.$$

Hence each  $\Phi_\alpha$  is bijective. Now we have to check, that  $\Phi_\alpha|_{E_p}$  is an isomorphism. So let  $\lambda \in \mathbb{R}$  and  $B \in E_p$ . Then

$$\begin{aligned} \Phi_\alpha|_{E_p}(p, \lambda A + B) &= (p, (\lambda A + B)_{j_1 \dots j_l}^{i_1 \dots i_k}) \\ &= (p, \lambda (A_{j_1 \dots j_l}^{i_1 \dots i_k}) + (B_{j_1 \dots j_l}^{i_1 \dots i_k})) \\ &= \lambda \Phi_\alpha|_{E_p}(p, A) + \Phi_\alpha|_{E_p}(p, B). \end{aligned}$$

Now let  $\alpha, \beta \in A$  such that  $U_\alpha \cap U_\beta \neq \emptyset$ . We consider the mapping

$$\Phi_\alpha \circ \Phi_\beta^{-1} : (U_\alpha \cap U_\beta) \times \mathbb{R}^{n^{k+l}} \rightarrow (U_\alpha \cap U_\beta) \times \mathbb{R}^{n^{k+l}}.$$

Define  $\tau_{\alpha\beta} : U_\alpha \cap U_\beta \rightarrow \text{GL}(n^{k+l}, \mathbb{R})$  by

$$\tau_{\alpha\beta} := (\delta_j^i).$$

Then we have that

$$(\Phi_\alpha \circ \Phi_\beta^{-1})(p, (A_{j_1 \dots j_l}^{i_1 \dots i_k})) = (p, (A_{j_1 \dots j_l}^{i_1 \dots i_k})) = (p, \tau_{\alpha\beta}(p)(A_{j_1 \dots j_l}^{i_1 \dots i_k})).$$

Since  $\tau_{\alpha\beta}$  is constant, it is smooth (see [Lee13, p. 36]). Hence we can apply the vector bundle chart lemma [Lee13, p. 253] and the result follows.  $\square$

**Proposition 1.4 (Smoothness Criteria for Tensor Fields).** *Let  $M$  be smooth manifold and let  $A : M \rightarrow T^{(1,k)}TM$  be a rough section. Then the following are equivalent:*

- (a)  $A \in \Gamma(T^{(1,k)}TM)$ .
- (b) In every smooth coordinate chart, the component functions of  $A$  are smooth.
- (c) For all  $X_1, \dots, X_k \in \mathfrak{X}(M)$ , the rough section  $A(X_1, \dots, X_k) : M \rightarrow TM$  defined by

$$A(X_1, \dots, X_k)(p) := A_p(X_1|_p, \dots, X_k|_p) \tag{3}$$

is a smooth vector field.

- (d) If  $X_1, \dots, X_k$  are smooth vector fields on some open subset  $U \subseteq M$ , then also  $A(X_1, \dots, X_k)$  is a smooth vector field on  $U$ .

*Proof.* We prove (a) $\Leftrightarrow$ (b) and (b) $\Rightarrow$ (c) $\Rightarrow$ (d) $\Rightarrow$ (b).

To prove (a) $\Leftrightarrow$ (b), let  $(U, (x^i))$  be a smooth chart. Actually, we can prove this for general tensor fields of type  $(k, l)$ . Proposition 1.3 together with the proof of the vector bundle chart lemma [Lee13, pp. 253–254] implies, that the corresponding chart on  $T^{(k,l)}TM$  is given by  $(\pi^{-1}(U), \tilde{\varphi})$ , where  $\tilde{\varphi} : \pi^{-1}(U) \rightarrow \varphi(U) \times \mathbb{R}^{n^{k+l}}$  is defined by

$$\tilde{\varphi} := (\varphi \times \text{id}_{\mathbb{R}^{n^{k+l}}}) \circ \Phi$$

where  $\Phi : \pi^{-1}(U) \rightarrow U \times \mathbb{R}^{n^{k+l}}$  is given as in the proof of proposition 1.3. Now we consider the coordinate representation  $\hat{A}$  in the given charts (see [Lee13, p. 35]). Since  $A$  is a rough section, we have that

$$A^{-1}(\pi^{-1}(U)) = (\pi \circ A)^{-1}(U) = \text{id}_M^{-1}(U) = U.$$

Hence  $\varphi(U \cap A^{-1}(\pi^{-1}(U))) = \varphi(U)$ , which is open, and  $\hat{A} : \varphi(U) \rightarrow \tilde{\varphi}(\pi^{-1}(U))$  is given by

$$\begin{aligned} \hat{A}(x) &= (\tilde{\varphi} \circ A \circ \varphi^{-1})(x) \\ &= (\varphi \times \text{id}_{\mathbb{R}^{n^{k+l}}})(\Phi(\varphi^{-1}(x), A_{\varphi^{-1}(x)})) \\ &= (\varphi \times \text{id}_{\mathbb{R}^{n^{k+l}}})(\varphi^{-1}(x), (A_{j_1 \dots j_l}^{i_1 \dots i_k}(\varphi^{-1}(x)))) \\ &= (x, (\hat{A}_{j_1 \dots j_l}^{i_1 \dots i_k}(x))). \end{aligned}$$

By [Lee13, p. 35]  $A$  is smooth if and only if in any chart  $\hat{A}$  is smooth. This is furthermore equivalent to that each  $\hat{A}_{j_1 \dots j_l}^{i_1 \dots i_k}$  is smooth and thus equivalent to that  $A_{j_1 \dots j_l}^{i_1 \dots i_k}$  is smooth (see [Lee13, p. 33]).

To prove (b) $\Rightarrow$ (c), let  $(U, (x^i))$  be a smooth chart. Then write  $X_1, \dots, X_k \in \mathfrak{X}(M)$  as

$$X_v = X_v^{\mu_v} \frac{\partial}{\partial x^{\mu_v}}.$$

for  $v = 1, \dots, k$ . For  $p \in U$  lemma 1.2 implies

$$\begin{aligned} A(X_1, \dots, X_n)(p) &= A_p(X_1|_p, \dots, X_k|_p) \\ &= A_p \left( X_1^{\mu_1}(p) \frac{\partial}{\partial x^{\mu_1}} \Big|_p, \dots, X_k^{\mu_k}(p) \frac{\partial}{\partial x^{\mu_k}} \Big|_p \right) \\ &= X_1^{\mu_1}(p) \cdots X_k^{\mu_k}(p) A_p \left( \frac{\partial}{\partial x^{\mu_1}} \Big|_p, \dots, \frac{\partial}{\partial x^{\mu_k}} \Big|_p \right) \\ &= X_1^{\mu_1}(p) \cdots X_k^{\mu_k}(p) A_{\mu_1 \dots \mu_k}^i(p) \frac{\partial}{\partial x^i} \Big|_p. \end{aligned}$$

By the smoothness criterion for vector fields [Lee13, p. 175] we have that each component function  $X_v^{\mu_n}$  is smooth. Thus if  $A$  is smooth, we have by that each  $A_{j_1 \dots j_k}^i$  is smooth and



since  $C^\infty(M)$  is an  $\mathbb{R}$ -algebra (see [Lee13, p. 33]), we have that

$$X_1^{\mu_1} \cdots X_k^{\mu_k} A_{\mu_1 \dots \mu_k}^i$$

is smooth for  $i = 1, \dots, n$ . Thus again by the smoothness criterion together with the localness of smoothness [Lee13, p. 35] we get that  $A(X_1, \dots, X_k) \in \mathfrak{X}(M)$ .

To prove (c) $\Rightarrow$ (d), we use that smoothness is a local property (see [Lee13, p. 35]). Let  $p \in U$ . Then by [Cat17, p. 14] we find a smooth bump function  $\psi$  supported in  $U$  and identically equal to 1 on some neighbourhood  $V$  of  $p$ . Set

$$\widetilde{X}_v|_p := \begin{cases} \psi(p)X_v|_p & p \in \text{supp } \psi \\ 0 & p \in M \setminus \text{supp } \psi \end{cases}.$$

Then the gluing lemma for smooth maps [Lee13, p. 35] implies  $\widetilde{X}_1, \dots, \widetilde{X}_k \in \mathfrak{X}(M)$ .

Hence by (c) we get that  $A(\widetilde{X}_1, \dots, \widetilde{X}_k) \in \mathfrak{X}(M)$  and so the restriction  $A(\widetilde{X}_1, \dots, \widetilde{X}_k)|_V$  is smooth. But  $A(\widetilde{X}_1, \dots, \widetilde{X}_k)|_V = A(X_1, \dots, X_k)$  and so we are done.

Lastly to prove (d) $\Rightarrow$ (b), each vector field locally defined by

$$X_{j_v} = \delta_{j_v}^{\mu_v} \frac{\partial}{\partial x^{\mu_v}}.$$

is smooth. Thus by

$$A(X_1, \dots, X_n)(p) = \delta_{j_1}^{\mu_1} \cdots \delta_{j_k}^{\mu_k} A_{\mu_1 \dots \mu_k}^i(p) \frac{\partial}{\partial x^i} \Big|_p = A_{j_1 \dots j_k}^i(p) \frac{\partial}{\partial x^i} \Big|_p$$

we get that  $A_{j_1 \dots j_k}^i$  is smooth and hence by (b) also  $A$ . □

**Theorem 1.5 (Tensor Characterization Lemma).** *A mapping*

$$\underbrace{\mathfrak{X}(M) \times \cdots \times \mathfrak{X}(M)}_k \rightarrow C^\infty(M) \quad \text{or} \quad \underbrace{\mathfrak{X}(M) \times \cdots \times \mathfrak{X}(M)}_k \rightarrow \mathfrak{X}(M)$$

*is induced by an element of  $\Gamma(T^{(0,k)}TM)$  or  $\Gamma(T^{(1,k)}TM)$ , respectively, if and only if they are multilinear over  $C^\infty(M)$ .*

*Proof.* We are proving only the second statement. Any element in  $\Gamma(T^{(1,k)}TM)$  induces a mapping  $\mathfrak{X}(M) \times \cdots \times \mathfrak{X}(M) \rightarrow \mathfrak{X}(M)$  by part (c) of the smoothness criteria for tensor fields 1.4. Thus we have to show that  $\mathcal{A}$  is multilinear over  $C^\infty(M)$ . Let  $f \in C^\infty(M)$  and  $X_v, \widetilde{X}_v \in \mathfrak{X}(M)$ ,  $v = 1, \dots, k$ . Then for any  $p \in M$  we have that

$$\begin{aligned} \mathcal{A}(X_1, \dots, fX_v + \widetilde{X}_v, \dots, X_k)_p &= A_p(X_1|_p, \dots, (fX_v + \widetilde{X}_v)|_p, \dots, X_k|_p) \\ &= A_p(X_1|_p, \dots, f(p)X_v|_p + \widetilde{X}_v|_p, \dots, X_k|_p) \\ &= f(p)A_p(X_1|_p, \dots, X_v|_p, \dots, X_k|_p) \\ &\quad + A_p(X_1|_p, \dots, \widetilde{X}_v|_p, \dots, X_k|_p) \\ &= f(p)\mathcal{A}(X_1, \dots, X_v, \dots, X_k)_p \end{aligned}$$

$$\begin{aligned}
 & + \mathcal{A}(X_1, \dots, \widetilde{X}_v, \dots, X_k)_p \\
 & = (f \mathcal{A}(X_1, \dots, X_v, \dots, X_k))_p \\
 & + \mathcal{A}(X_1, \dots, \widetilde{X}_v, \dots, X_k)_p.
 \end{aligned}$$

Conversly, suppose that  $\mathcal{A} : \mathfrak{X}(M) \times \dots \times \mathfrak{X}(M) \rightarrow \mathfrak{X}(M)$  is multilinear over  $C^\infty(M)$ . Let  $p \in M$ . First we show that  $\mathcal{A}$  acts locally, i.e. if  $X_v = \widetilde{X}_v$  in some neighbourhood  $U$  of  $p$  implies that also

$$\mathcal{A}(X_1, \dots, X_v, \dots, X_k) = \mathcal{A}(X_1, \dots, \widetilde{X}_v, \dots, X_k)$$

on  $U$ . By the multilinearity of  $\mathcal{A}$  it is enough to show that if  $X_v$  vanishes on  $U$  then so does  $\mathcal{A}$ . There exists a smooth bump function  $\psi$  for  $\{p\}$  supported in  $U$  (see [Lee13, p. 44]). Hence  $\psi X_v = 0$  on  $M$  and  $\psi(p) = 1$ . Thus

$$0 = \mathcal{A}(X_1, \dots, \psi X_v, \dots, X_k)_p = \psi(p) \mathcal{A}(X_1, \dots, X_v, \dots, X_k)_p.$$

and since  $\psi(p) = 1$  we have that

$$\mathcal{A}(X_1, \dots, X_v, \dots, X_k)_p = 0$$

for any  $p \in U$ .

Next we show that  $\mathcal{A}$  actually acts pointwise, i.e. if  $X_v|_p$  vanishes so does  $\mathcal{A}$ . Let  $(U, (x^i))$  be a chart containing  $p$  and  $X_v = X_v^i \frac{\partial}{\partial x^i}$  on  $U$ . The same construction as used showing the implication (c) $\Rightarrow$ (d) in the proof of proposition 1.4 yields the existence of  $f^1, \dots, f^n \in C^\infty(M)$  and  $\widetilde{X}_1, \dots, \widetilde{X}_n \in \mathfrak{X}(M)$  such that  $f^i = X_v^i$  and  $\widetilde{X}_i = \frac{\partial}{\partial x^i}$  on a neighbourhood  $V \subseteq U$  of  $p$ . Thus by the previous localization, we get that

$$\mathcal{A}(X_1, \dots, X_v, \dots, X_k) = \mathcal{A}(X_1, \dots, f^i \widetilde{X}_i, \dots, X_k) = f^i \mathcal{A}(X_1, \dots, \widetilde{X}_i, \dots, X_k)$$

in  $U$ . Since  $0 = X_v^i(p) = f^i(p)$ ,  $\mathcal{A}$  vanishes at  $p$ . Hence  $\mathcal{A}$  depends only on the value of  $X_v$  at  $p$ . Thus define a rough section  $A : M \rightarrow T^{(1,k)}TM$  by

$$A_p(v_1, \dots, v_k) := \mathcal{A}(V_1, \dots, V_k)(p)$$

where  $V_1, \dots, V_k \in \mathfrak{X}(M)$  are any extensions of  $v_1, \dots, v_k \in T_p M$  (see [Lee13, p. 177]). By the above, the choice of the extensions does not matter and the resulting rough section is smooth by proposition 1.4 part (c), hence  $A \in \Gamma(T^{(1,k)}TM)$ .  $\square$

## CHAPTER 2

# **Differential Geometry**

## CHAPTER 3

### **General Relativity**

## Bibliography

- [Cat17] Alberto S. Cattaneo. “Notes on Manifolds”. 2017. URL: <http://user.math.uzh.ch/cattaneo/manifoldsFS15.pdf>.
- [Lee13] John M. Lee. *Introduction to Smooth Manifolds*. Second Edition. Graduate Texts in Mathematics. Springer, 2013.