

Lecture 4: The Poisson Algebra of Observables

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Definition (Lie Algebra)

A **real Lie algebra** is defined to be a real vector space \mathfrak{g} admitting a bilinear map

$$[\cdot, \cdot]: \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$$

called a **Lie bracket**, satisfying the following conditions:

- $[\cdot, \cdot]$ is skew-symmetric.
- $[\cdot, \cdot]$ satisfies the **Jacobi identity**, that is

$$[X, [Y, Z]] + [Z, [X, Y]] + [Y, [Z, X]] = 0 \quad \forall X, Y, Z \in \mathfrak{g}.$$

Lemma

Let M be a smooth manifold. Then $(\mathfrak{X}(M), [\cdot, \cdot])$ is a Lie algebra.

Definition (Algebra of Classical Observables)

Let (M, ω) be a symplectic manifold. Then the commutative real algebra $C^\infty(M)$ of smooth functions on M is called the *algebra of classical observables*.

Definition (Poisson Algebra)

A **Poisson algebra** is defined to be a real commutative algebra \mathfrak{p} together with a Lie bracket $\{\cdot, \cdot\}$ on \mathfrak{p} satisfying the **Leibniz rule**

$$\{f, gh\} = h\{f, g\} + g\{f, h\} \quad \forall f, g, h \in \mathfrak{p}.$$

Lemma

Let (M, ω) be a symplectic manifold. Then $(C^\infty(M), \{\cdot, \cdot\})$ is a Poisson algebra, where

$$\{f, g\} := \omega(X_f, X_g) \quad \forall f, g \in C^\infty(M)$$

*denotes the **Poisson bracket of classical observables**.*

- $X_{\{f,g\}} = [X_f, X_g]$ for all $f, g \in C^\infty(M)$.

Lemma

Let (M, ω) be a symplectic manifold and $\varphi \in \text{Symp}(M, \omega)$. Then

$$\varphi^*\{f, g\} = \{\varphi^*f, \varphi^*g\} \quad \forall f, g \in C^\infty(M).$$

The Evolution Operator

Definition (Evolution Operator)

Let (M, ω, H) be a complete Hamiltonian system. Define the *evolution operator*

$$U_t: C^\infty(M) \rightarrow C^\infty(M), \quad U_t(f) := f \circ \theta_t^{X_H}$$

for all $t \in \mathbb{R}$.

Theorem

Let (M, ω, H) be a complete Hamiltonian system. Then

$$\frac{d}{dt}U_t(f) = U_t\{H, f\} \quad \forall f \in C^\infty(M).$$

Definition (Integral of Motion)

Let (M, ω, H) be a Hamiltonian system. An *integral of motion* is defined to be a function $I \in C^\infty(M)$ such that $\{H, I\} = 0$.

The Lie Algebra of a Lie Group

Definition (Lie Group)

A ***Lie group*** is defined to be a group object in the category of finite-dimensional smooth manifolds.

Given a Lie group G , the tangent space $\mathfrak{g} := T_e G$ to the identity element $e \in G$ is a Lie algebra. Indeed, there is a canonical isomorphism

$$T_e G \cong \mathfrak{X}_L(G),$$

where $\mathfrak{X}_L(G) \subseteq \mathfrak{X}(G)$ denotes the Lie subalgebra of all left-invariant vector fields on G .

As every left-invariant vector field is complete, we can define the *exponential map*

$$\exp: \mathfrak{g} \rightarrow G, \quad \xi \mapsto \gamma_\xi(1),$$

where $\gamma_\xi: \mathbb{R} \rightarrow G$ denotes the unique integral curve of $X_\xi \in \mathfrak{X}_L(G)$ with $X_\xi(e) = \xi$ such that $\gamma_\xi(0) = e$ and $\dot{\gamma}_\xi(0) = \xi$.

