

Lecture 2: Symplectic Manifolds

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Linear Symplectic Geometry

$(V, \langle \cdot, \cdot \rangle)$ inner product space

$\langle \cdot, \cdot \rangle$ bilinear symmetric form which is pos. definite.

\Downarrow
nondegeneracy

Definition (Symplectic Vector Space)

A **symplectic vector space** is defined to be a tuple (V, ω) , where V is a finite-dimensional real vector space and $\omega: V \times V \rightarrow \mathbb{R}$ is a nondegenerate skew-symmetric bilinear form.

- $\omega(v, u) = -\omega(u, v) \quad \forall u, v \in V$

- $V \rightarrow V^*$
 $v \mapsto \iota_v \omega$ is an isomorphism

$$\Leftrightarrow \forall v \in V \setminus \{0\} \exists u \in V \text{ s.t. } \omega(v, u) \neq 0$$

* Every nonzero vector has a "friend."

Theorem

Let (V, ω) be a symplectic vector space. Then there exists a basis (a_i, b_i) of V such that

$$\omega(b_i, a_j) = \delta_{ij} \quad \text{and} \quad \omega(a_i, a_j) = \omega(b_i, b_j) = 0$$

for all i, j . Any such basis is called a **symplectic basis** for V .

$$[\omega] = \begin{pmatrix} 0 & -I \\ I & 0 \end{pmatrix} \Rightarrow \text{Every symplectic vector space is of even dimension!}$$

Proof by induction. $\dim V = 0$ is obvious.

So assume $\dim V \geq 1$. This means, there exists $b_1 \in V \setminus \{0\}$. By nondegeneracy, there exists a find a_1 of b_1 , i.e.

$$\omega(b_1, a_1) = 1.$$

Claim. $\{b_1, a_1\}$ is linearly independent.

Proof of Claim. If not, then $\exists \lambda \in \mathbb{R}$ s.t.

$$a_1 = \lambda b_1.$$

If \dim of S is 1
then $S \subseteq S^\omega$.

But then by skew-symmetry:

$$\omega(b_1, a_1) = \lambda \omega(b_1, b_1) = 0.$$

$$(\downarrow) \quad (= \lambda \|b_1\|^2 \neq 0) \quad \square$$

Now decompose $\{b_1, a_1\}$

$$V = S \oplus S^\omega \stackrel{(+)}{=} \{v \in V : \omega(v, u) = 0 \forall u \in S\}$$

$\omega|_S : S \times S \rightarrow \mathbb{R}$ symplectic complement to S .

$$\bullet \dim S + \dim S^\omega = \dim V \quad [(S^\omega)^\omega = S]$$

$\bullet S$ is symplectic if and only if S^ω is symplectic.

Thus the induction hypothesis applies to the symplectic vector space S^ω . □

Corollary

Every symplectic vector space (V, ω) is of even dimension $2n$ and

canonical / standard form $\omega = \sum_{i=1}^n \beta^i \wedge \alpha^i$ $i_{X_H} \omega = -dH$

in the dual basis (α^i, β^i) of a symplectic basis (a_i, b_i) for V .

$$\omega^n = \left(\sum_{i=1}^n \beta^i \wedge \alpha^i \right)^n = n! (\beta^1 \wedge \alpha^1 \wedge \dots \wedge \beta^n \wedge \alpha^n) \neq 0$$

Corollary

A skew-symmetric bilinear form ω on a real vector space V^{2n} is nondegenerate if and only if $\omega^n \neq 0$.

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$$\underbrace{\omega \wedge \dots \wedge \omega}_n$$

Manifold setting.

Let M be a smooth manifold. A form $\omega \in \Omega^2(M)$ is said to be nondegenerate, iff

$$(T_x M, \omega_x)$$

is a symplectic vector space $\forall x \in M$.

• $\dim M = \dim T_x M \forall x \in M \Rightarrow M$ is even dimensional!!

• M^{2n} is always orientable!

Just observe that $\omega^n \in \Omega^{2n}(M)$ is a volume form on M .

The Category of Symplectic Manifolds

Definition (Symplectic Manifold)

A *symplectic manifold* is defined to be a tuple (M, ω) where M is a smooth finite-dimensional manifold and $\omega \in \Omega^2(M)$ is closed and nondegenerate.

Analytical condition

Definition (Symplectomorphism)

Let (M, ω) and $(\tilde{M}, \tilde{\omega})$ be two symplectic manifolds. A *symplectomorphism* is a diffeomorphism $\varphi: M \rightarrow \tilde{M}$ such that $\varphi^*\tilde{\omega} = \omega$.

if $\varphi \in C^1(K, \mathbb{R})$

• let Σ be an orientable surface.

satisfies

then (Σ, ω) is a symplectic manifold $\varphi^*\tilde{\omega} = \omega$

then φ is an immersion.

bijective for any volume form ω on Σ .
smooth with smooth inverse

Lemma

Let (M, ω) be a compact symplectic manifold. Then $H_{dR}^{2p}(M) \neq 0$. $p \in \mathbb{N}$

Proof. Exercise. Hint: Stoke's theorem.

$(T^*M, d\lambda)$ \Rightarrow Every exact symplectic manifold without boundary is non-compact.
 exact symplectic ω

Assume $(M, d\lambda)$ is exact symplectic manifold.
 Then

$$0 < \int_M \omega^n = \int_M d(\lambda \lrcorner \omega^{n-1})$$

$\xrightarrow{\text{Stokes}} \int_{\partial M} \lambda \lrcorner \omega^{n-1} = 0.$

Liouville domain
 $(M, d\lambda)$ compact.
 $\Rightarrow \partial M \neq \emptyset$.

Observation
 10.5
 twisted
 $\mathbb{R} \neq \mathbb{H}$.

symplectic reduction

Corollary

No even sphere \mathbb{S}^{2n} admits a symplectic form for $n \geq 2$.

The only sphere admitting a symplectic form is \mathbb{S}^2 .

Proof.

$$H_{\mathbb{R}}^k(\mathbb{S}^{2n}) = \begin{cases} \mathbb{R} & k=0, 2n \\ 0 & k \neq 0, 2n \end{cases}$$

□

Lemma

Let M be a smooth manifold. Then $(T^*M, d\lambda)$ is a symplectic manifold with the **Liouville form**

$$\lambda_{(x,\xi)}(v) := \xi(D\pi(v)) \quad \forall (x,\xi) \in T^*M, v \in T_{(x,\xi)}T^*M,$$

where $\pi: T^*M \rightarrow M$ denotes the cotangent bundle projection. The symplectic form $d\lambda$ on T^*M is called the **canonical symplectic form**.

\Rightarrow Every cotangent bundle is orientable!

let (x^i) be coordinates on M . then (x^i, ξ_i)
are coordinates on T^*M .
just write element
in $T^*_x M$
in basis dx^i .

$$\bullet \lambda = \xi_i dx^i.$$

$$\bullet d\lambda = d\xi_i \wedge dx^i.$$

(x^i, ξ_i) are Darboux coordinates!

Lemma

Let $\varphi: M \rightarrow \tilde{M}$ be a diffeomorphism between smooth manifolds M and \tilde{M} .
Then the **cotangent lift**

$$D\varphi^\dagger: T^*M \rightarrow T^*\tilde{M}, \quad D\varphi^\dagger_{(x,\xi)}(\varphi(x), v) := \xi(D\varphi^{-1}(v))$$

is an exact symplectomorphism.

Every diffeomorphism can be lifted to a symplectomorphism u.r.t. the canonical symplectic forms on the cotangent bundles.

$$\begin{array}{ccc} M & \xrightarrow{\varphi} & \tilde{M} \\ \uparrow & \cong & \uparrow \\ T^*M & \xrightarrow{D\varphi^\dagger} & T^*\tilde{M} \end{array}$$

Good exercise to get used to tangent bundles of cotangent bundles!
i.e. check $(D\varphi^\dagger)^*\tilde{\omega} = \omega$.

Definition (Lagrangian Submanifold)

Let (M, ω) be a symplectic manifold. An embedded submanifold L of M is said to be **Lagrangian**, iff $\dim L = \frac{1}{2} \dim M$ and $\iota_L^* \omega = 0$.

Lemma

Let $\varphi: M \rightarrow \tilde{M}$ be a diffeomorphism between symplectic manifolds (M, ω) and $(\tilde{M}, \tilde{\omega})$. Then φ is a symplectomorphism if and only if its graph

$$\Gamma_{\varphi} \subseteq (M \times \tilde{M}, -\omega \oplus \tilde{\omega})$$

is a Lagrangian submanifold. $\dim \Gamma_{\varphi} = \frac{1}{2} \dim (M \times \tilde{M})$

Proof. Exercise.

The Darboux Theorem and Moser's Trick

Nonlinear analogue of the canonical form Thm.

Theorem (Darboux Theorem) (Weinstein)

Let M^{2n} be a smooth manifold and $\omega \in \Omega^2(M)$ nondegenerate. Then ω is closed if and only if for every $x \in M$ there exists a chart $(U, (x^i, y^i))$ about x such that

$$\omega|_U = \sum_{i=1}^n dy^i \wedge dx^i. \quad (\text{Darboux Coordinates})$$

Symplectic manifolds are locally indistinguishable!

Proof. Let $x \in M$. By the canonical form theorem there exists a chart such that

$$\omega_x = \sum_{i=1}^n dy^i \wedge dx^i|_x$$

only at one point!

$$\omega_1 := \sum_{i=1}^n dy^i \wedge dx^i \quad \omega_0 := \omega|_U$$

Moser's Trick the theorem is proven, if
 we find a diffeomorphism (U, φ) about x s.t.
 $\varphi^* \omega_1 = \omega_0$ $\leftarrow \varphi: U \rightarrow \varphi(U) \subseteq \mathbb{C}^n$

Show existence of such a φ by letting
 it be the time-1 map of a time-
 dependent vector field,

$$\varphi = \varphi_1,$$

$$\cdot \frac{d}{dt} \varphi_t = X_t \circ \varphi_t,$$

$$\cdot \varphi_0 = \text{id}.$$

For $t \in \mathbb{R}$, set

$$\omega_t := (1-t)\omega_0 + t\omega_1$$

$\omega_t|_x = \omega_x$
 by
 construction.

- ω_t is closed.
- ω_t is nondegenerate for some compact interval around $[0, 1]$ in some neighborhood

We compute improved Fisher's formula -dη by Poincaré

$$\frac{d}{dt} \psi_t^* \omega_t = \psi_t^* \left(L_{X_t} \omega_t + \frac{d}{dt} \omega_t \right) = \psi_t^* \left(L_{X_t} \omega_t + \omega_t'' - \omega_t \right)$$

$$= \psi_t^* \left(\cancel{i_{X_t} d\omega_t} + d i_{X_t} \omega_t - d\eta \right) = d\psi_t^* \left(\cancel{i_{X_t} \omega_t} - \eta \right)$$

Cartan's
magic
formula

Need $\frac{d}{dt} \psi_t^* \omega_t = 0$, because then

$$\psi_t^* \omega_t = \psi_1^* \omega_1 = \psi_0^* \omega_0 = \omega_0.$$

Why does such an X_t even exist?

$$i_{X_t} \omega_t = \eta \Rightarrow X_t := \hat{\omega}_t^{-1}(\eta)$$

due to nondegeneracy of $\omega_t \forall t \in]\geq [0,1]$.

"Symplectic version of ϵ - δ proof!"

□