Filters 1

What is filtering?

- Filtering is a technique for modifying or enhancing an image.
- For example, you can filter an image to emphasize certain features or remove other features.
- Image processing operations implemented with filtering include smoothing, sharpening, and edge enhancement.

Examples (sharpening)



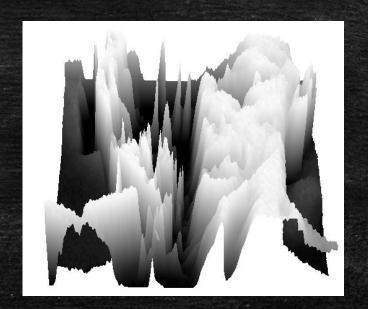
Examples (blurring)



Images as functions

- We can think of a (grayscale) image as a **function**, where
 - f(x,y) gives the **intensity** at position (x,y)





 A digital image is a discrete (sampled, quantized) version of this function

Image transformations

As with any function, we can apply operators to an image







$$g(x,y) = f(x,y) + 20$$





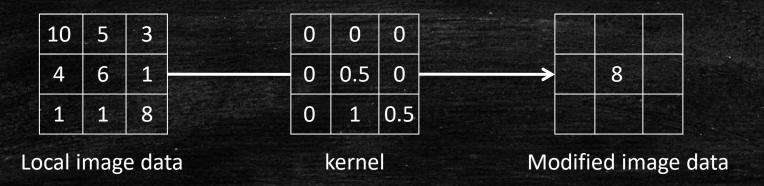


$$g(x,y) = f(-x,y)$$

Kernel Transformations

Replace each pixel by a linear combination of its neighbors

- The prescription for the linear combination is called the "kernel" (or "mask", "filter")
- Involves sliding a kernel (filter) across an image.
- A mask should always be in odd number, because other wise you cannot find the mid of the mask.



Calculation

Assume original image is H. Filter is F. G is the resultant image. Each resultant pixel in G is calculated by:

$$G[i,j] = \sum_{u=-k}^{k} \sum_{v=-k}^{k} H[u,v]F[i-u,j-v]$$

How to do it

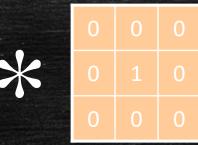
In order to perform a filter on an image, following steps should be taken.

- 1) Slide the mask onto the image.
- 2) Multiply the corresponding elements and then add them
- 3) Repeat this procedure until all values of the image have been calculated.

Linear filters: examples



Original



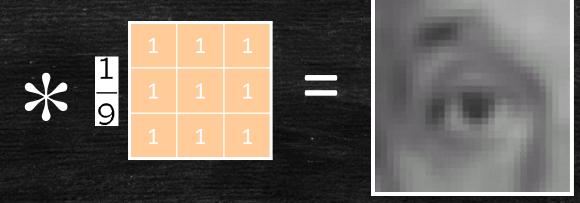


Identical image

Linear filters: examples



Original



Blur (with a mean filter)

We just did blurring with a 3x3 mask.

Consider a 5x5 mask:

- 1) What would the effect on blurring be?
- 2) What would the values of the mask need to be?

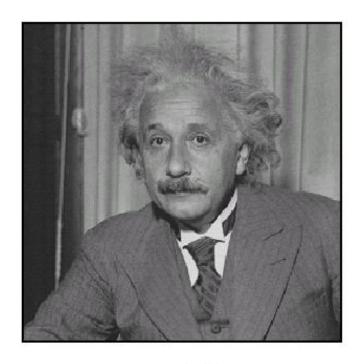
It is also possible to have masks that are 7x7, 9x9, etc... Try it out!

Python Implementation

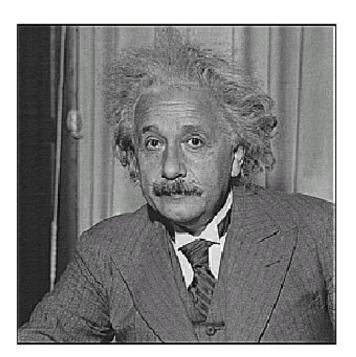
```
img = cv2.imread('images/lena.jpg')
img = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)
#kernel = np.ones((5,5),np.float32)/25 or
kernel = np.array([[1, 1, 1], [1, 1, 1], [1, 1, 1]])
dst = cv2.filter2D(img,-1,kernel)
```

Try implementing different levels of blurring!

High-pass filters - Sharpening



before



after

Sharpening

What does blurring take away?



Let's add it back:



Source: S. Lazebnik

Questions?