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Images

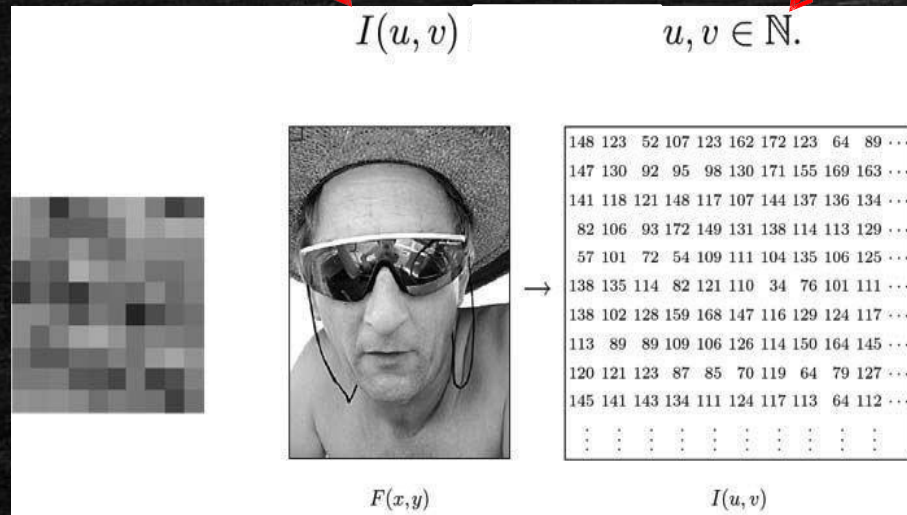


# Representing Images

- 2-dimensional matrix of Intensity (gray or color) values

Set of Intensity values

Image coordinates are integers



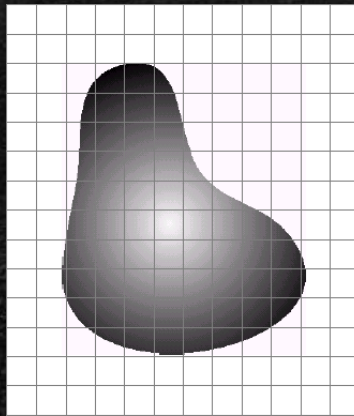
$\mathbb{N}$

is the set of natural numbers. These are whole, non-negative numbers. Therefore  $\mathbb{N} = \{0, 1, 2, 3, \dots\}$

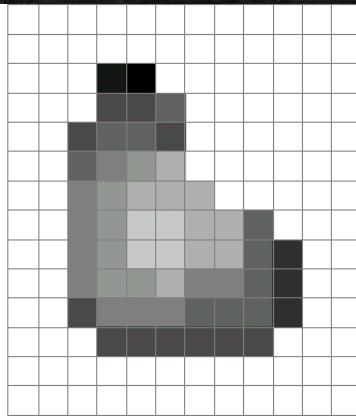


# Digitization

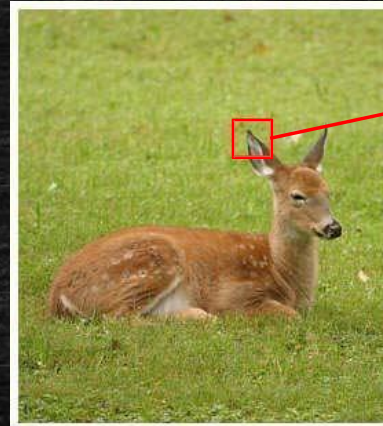
- Remember: *digitization* causes a digital image to become an *approximation* of a real scene



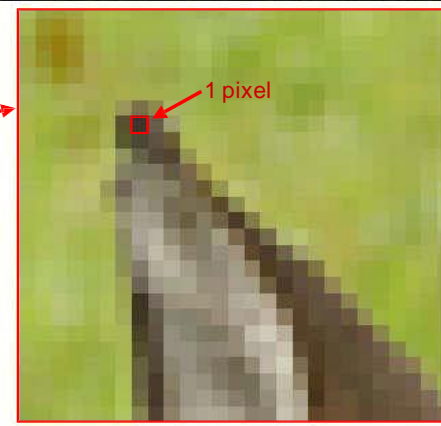
Real image



Digital Image  
(an approximation)



Real image



Digital Image  
(an approximation)



# Common Image Formats

- Common image formats include:
  - 1 values per point/pixel (B&W or Grayscale)
  - 3 values per point/pixel (Red, Green, and Blue)
  - 4 values per point/pixel (Red, Green, Blue, + “Alpha” or Opacity)



Grayscale



RGB

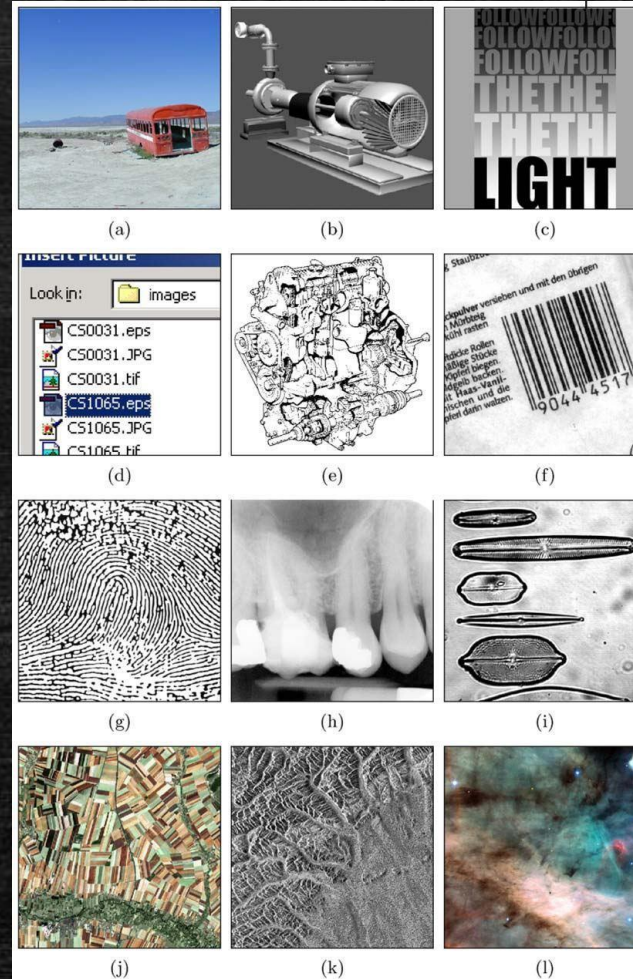


RGBA



# Example of Digital Images

- a) Natural landscape
- b) Synthetically generated scene
- c) Poster graphic
- d) Computer screenshot
- e) Black and white illustration
- f) Barcode
- g) Fingerprint
- h) X-ray
- i) Microscope slide
- j) Satellite Image
- k) Radar image
- l) Astronomical object





# Image File Formats

- Hundreds of image file formats. Examples
  - Tagged Image File Format (TIFF)
  - Graphics Interchange Format (GIF)
  - Portable Network Graphics (PNG)
  - JPEG, BMP, Portable Bitmap Format (PBM), etc
- Image pixel values can be
  - **Grayscale:** 0 - 255 range
  - **Binary:** 0 or 1
  - **Color:** RGB colors in 0-255 range (or other color model)
  - **Application specific** (e.g. floating point values in astronomy)



# How many Bits Per Image Element?

## Grayscale (Intensity Images):

<i>Chan.</i>	<i>Bits/Pix.</i>	<i>Range</i>	<i>Use</i>
1	1	0...1	Binary image: document, illustration, fax
1	8	0...255	Universal: photo, scan, print
1	12	0...4095	High quality: photo, scan, print
1	14	0...16383	Professional: photo, scan, print
1	16	0...65535	Highest quality: medicine, astronomy

## Color Images:

<i>Chan.</i>	<i>Bits/Pix.</i>	<i>Range</i>	<i>Use</i>
3	24	$[0...255]^3$	RGB, universal: photo, scan, print
3	36	$[0...4095]^3$	RGB, high quality: photo, scan, print
3	42	$[0...16383]^3$	RGB, professional: photo, scan, print
4	32	$[0...255]^4$	CMYK, digital prepress

## Special Images:

<i>Chan.</i>	<i>Bits/Pix.</i>	<i>Range</i>	<i>Use</i>
1	16	$-32768...32767$	Whole numbers pos./neg., increased range
1	32	$\pm 3.4 \cdot 10^{38}$	Floating point: medicine, astronomy
1	64	$\pm 1.8 \cdot 10^{308}$	Floating point: internal processing

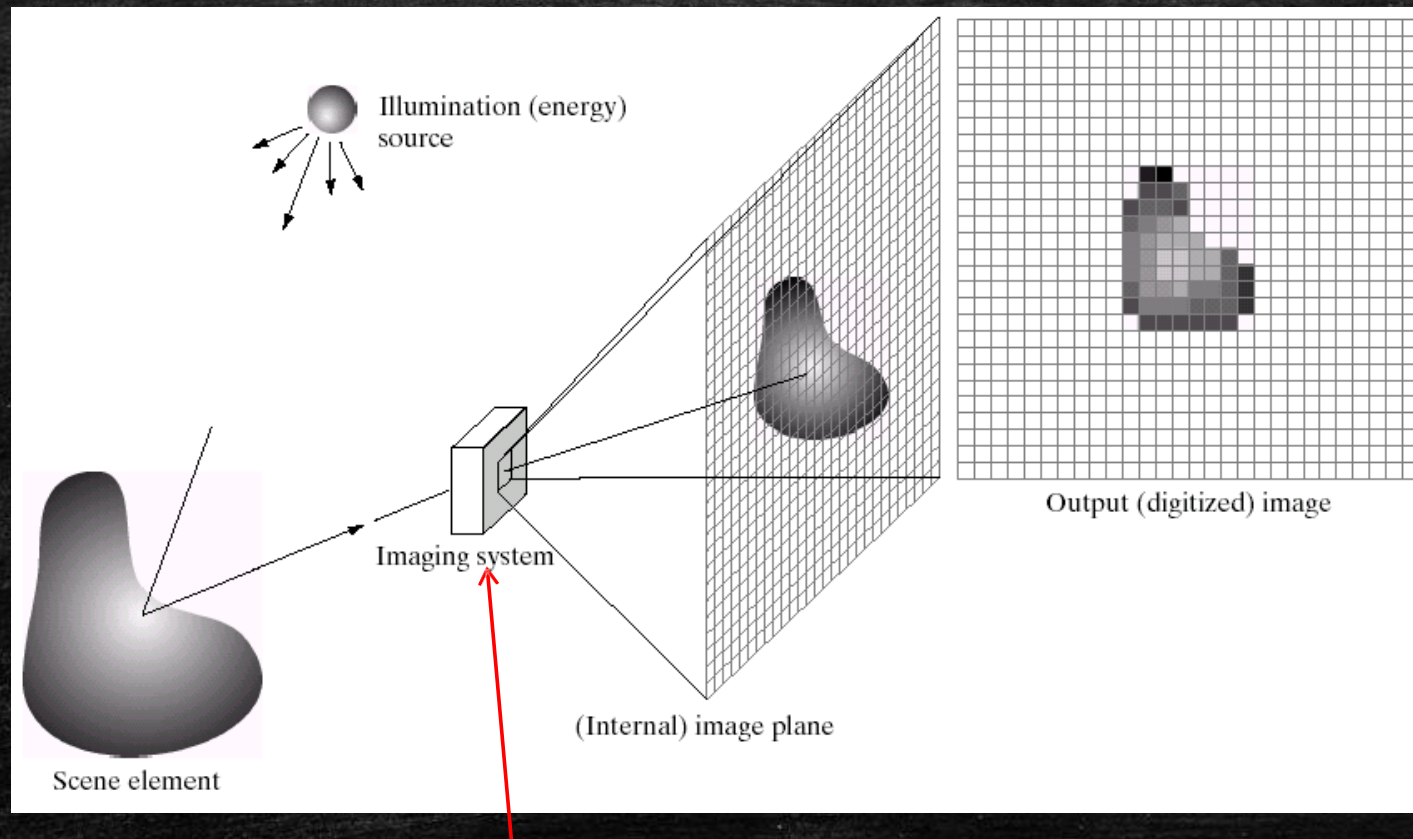


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# Image Acquisition and Imaging Devices



# Imaging System

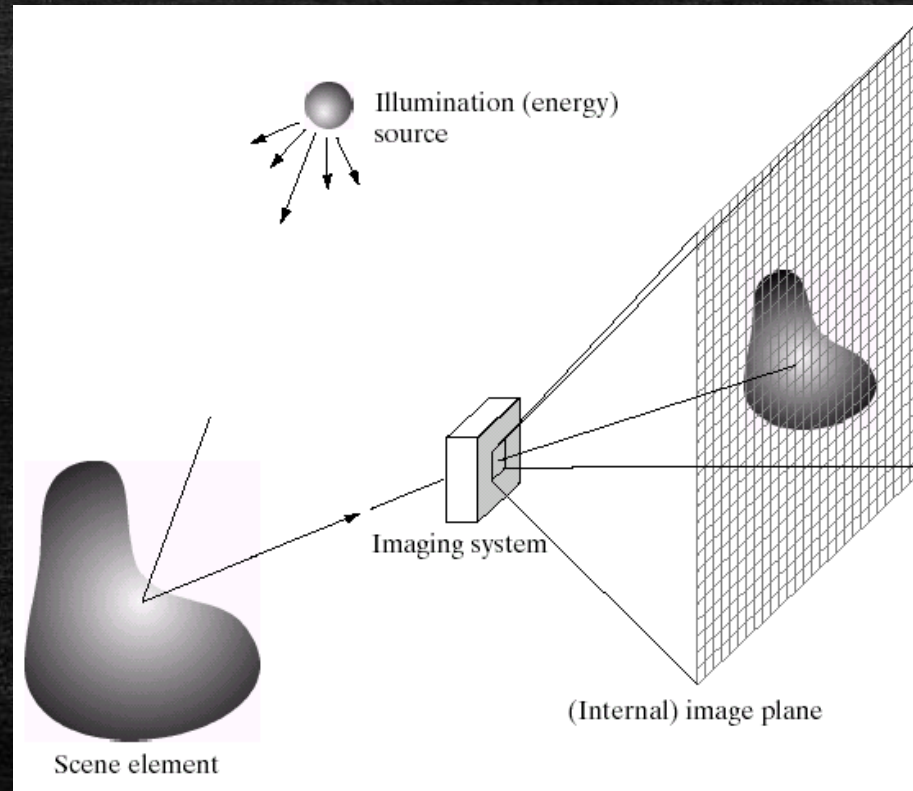


Example: a camera  
Converts light to image



# Image Acquisition

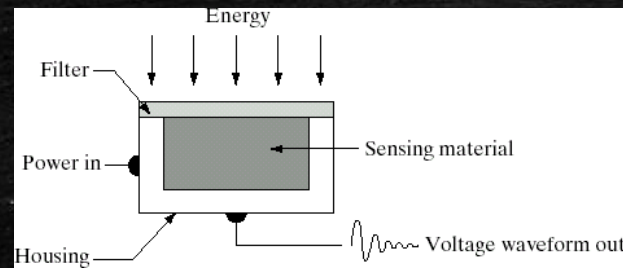
- Images typically generated by *illuminating a scene* and absorbing energy reflected by scene objects





# Image Sensing

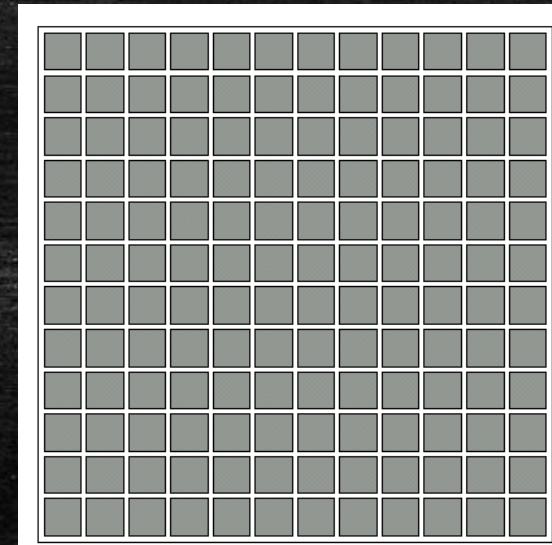
- Incoming energy (e.g. light) lands on a sensor material responsive to that type of energy, generating a voltage
- Collections of sensors are arranged to capture images



Imaging Sensor



Line of Image Sensors

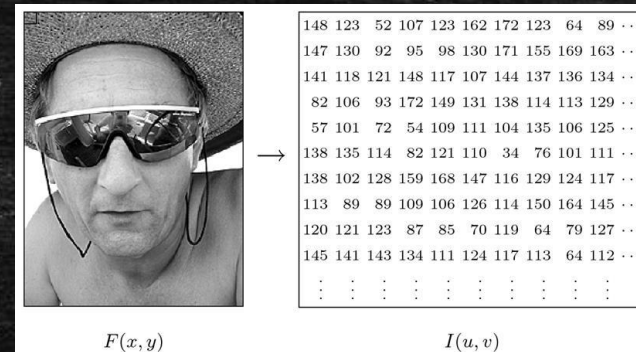
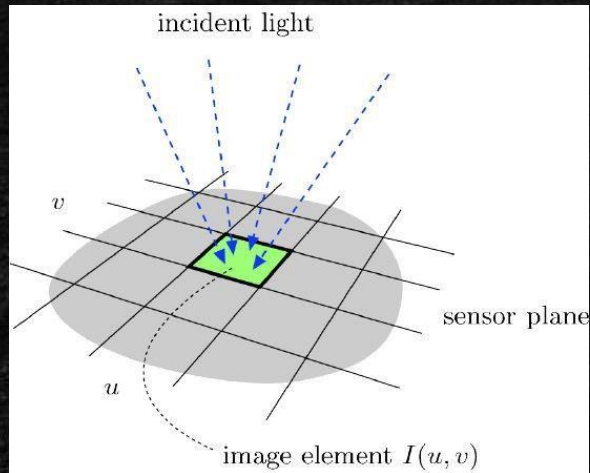


Array of Image Sensors



# Spatial Sampling

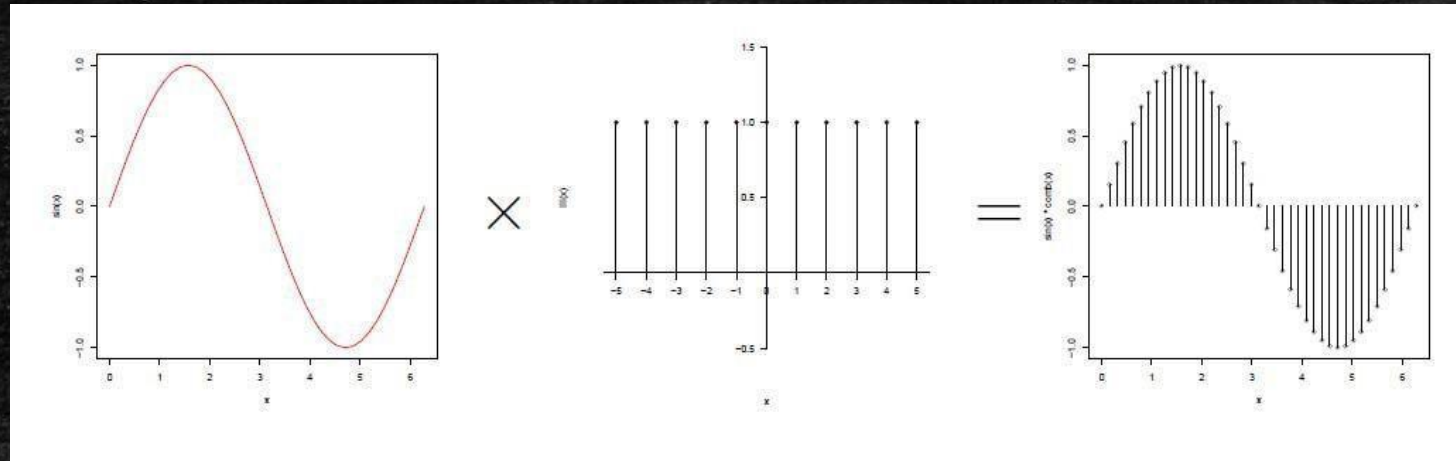
- Cannot record image values for all  $(x,y)$
- Sample/record image values at discrete  $(x,y)$
- Sensors arranged in grid to sample image





# Image (Spatial) Sampling

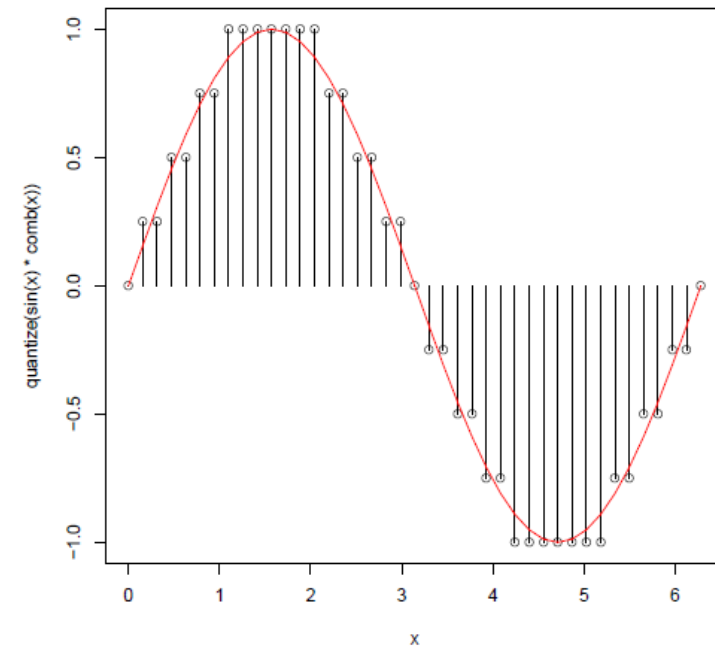
- A digital sensor can only measure a limited number of **samples** at a **discrete** set of energy levels
- **Sampling** can be thought of as:  
Continuous signal  $\times$  comb function





# Image Quantization

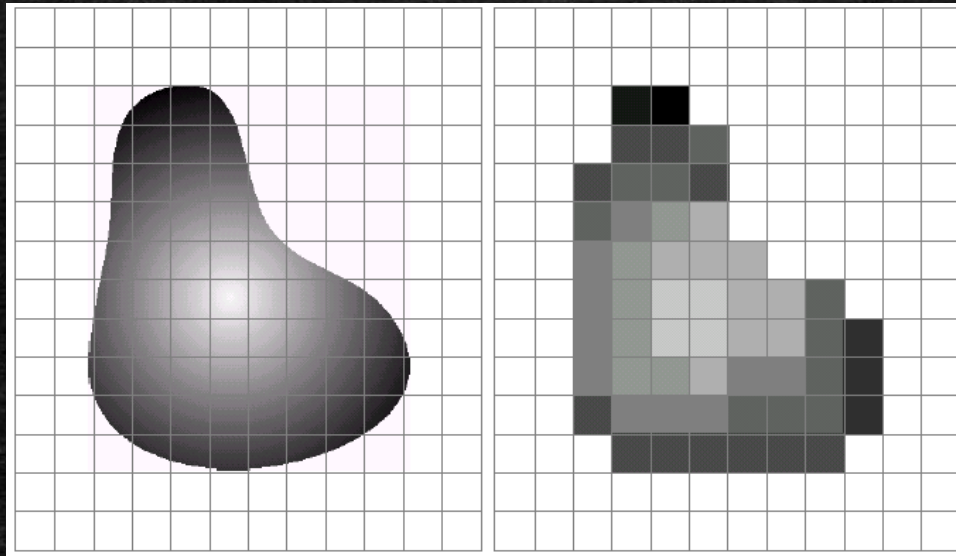
- **Quantization:** process of converting continuous analog signal into its digital representation
- Discretize image  $I(u,v)$  values
- Limit values image can take





# Image Sampling And Quantization

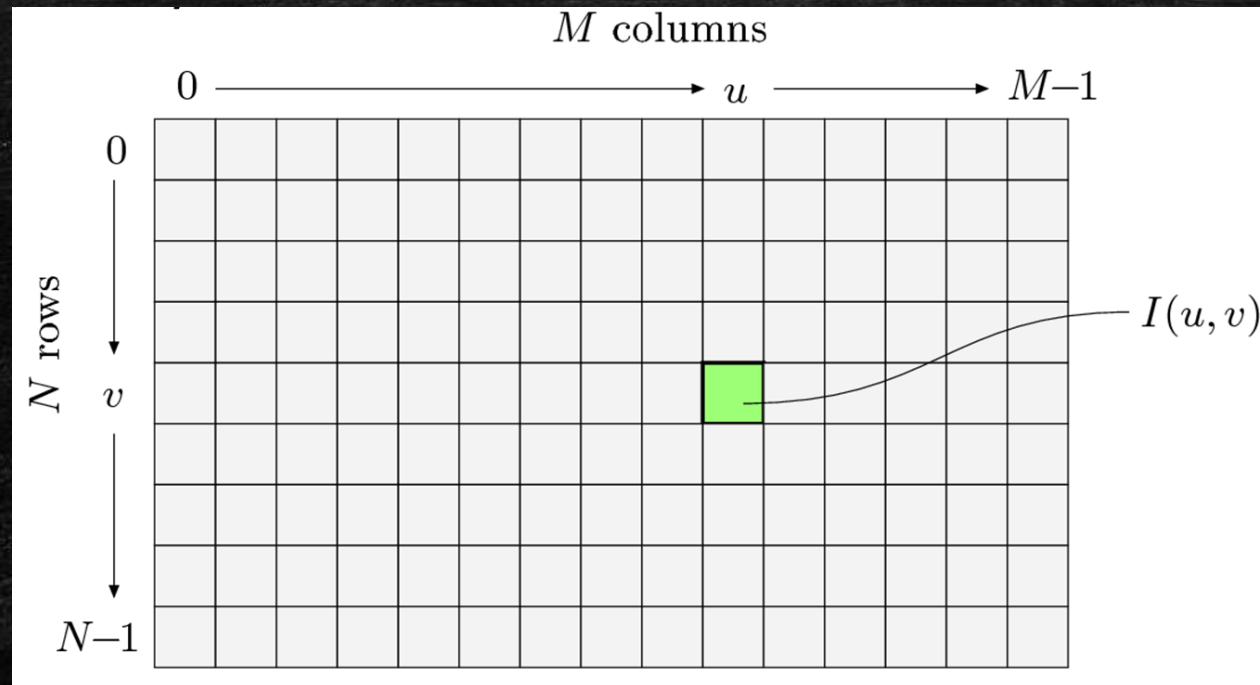
- Sampling and quantization generates **approximation** of a real world scene





# Representing Images

- Image data structure is 2D array of pixel values
- Pixel values are gray levels in range 0-255 or RGB colors
- A numeric datatype (bit, byte, int, float, double, etc.)





# Spatial Resolution

- The *spatial resolution* of an image is determined by how fine/coarse sampling was carried out
- **Spatial resolution:** smallest discernable image detail
  - Vision specialists talk about image resolution
  - Graphic designers talk about *dots per inch* (DPI)





# Spatial Resolution

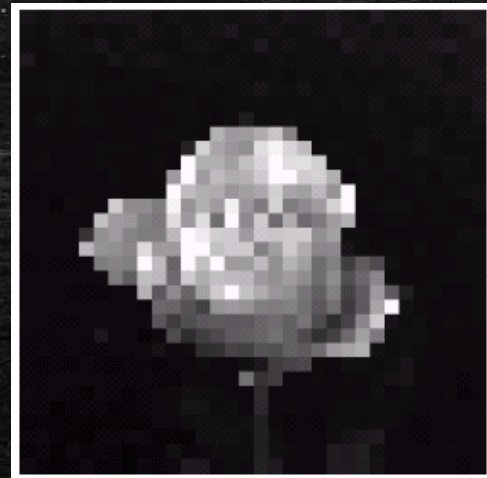
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# Spatial Resolution: Stretched Images

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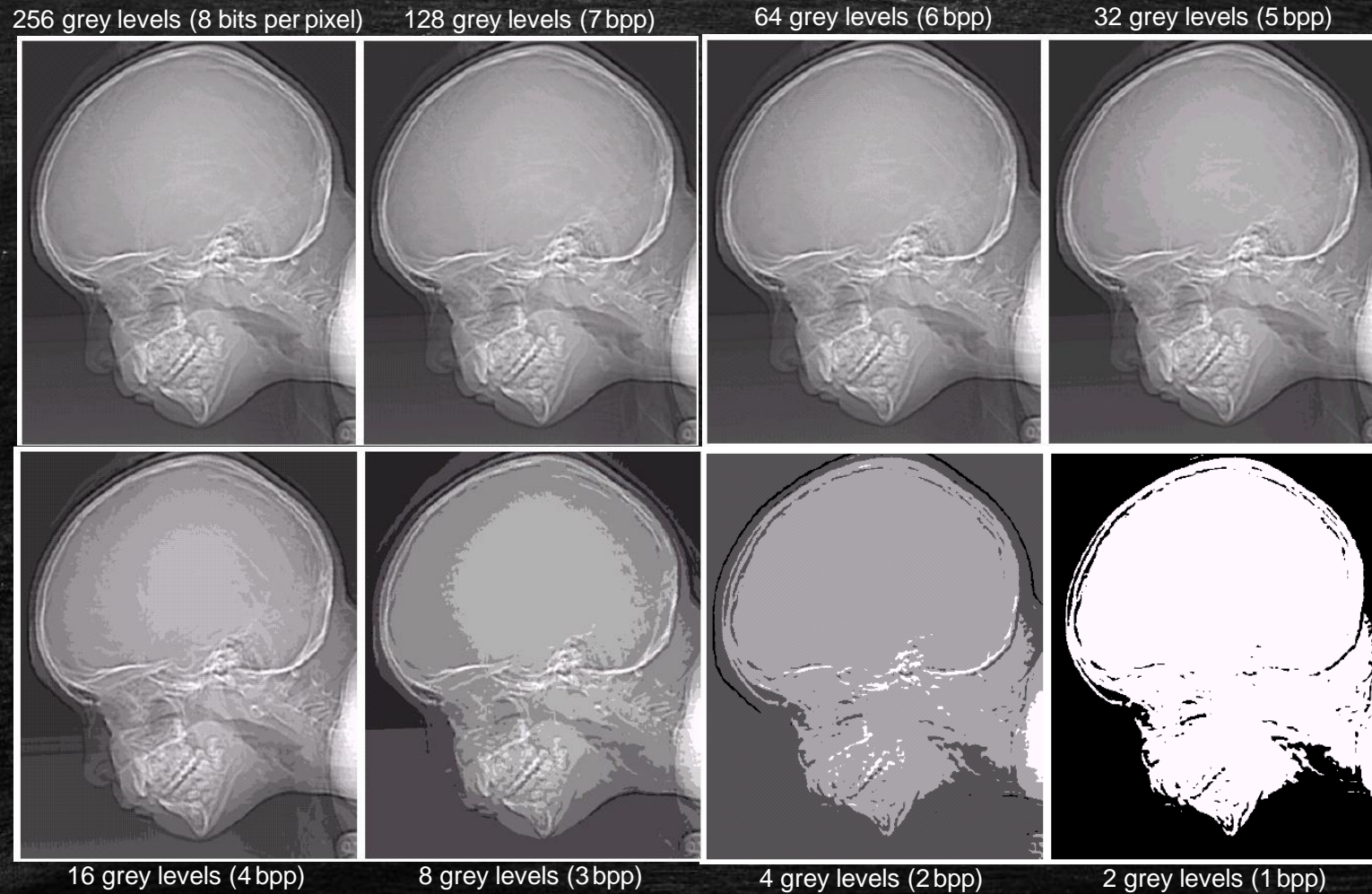
# Intensity Level Resolution

- **Intensity level resolution:** number of intensity levels used to represent the image
  - The more intensity levels used, the finer the level of detail discernable in an image
  - Intensity level resolution usually given in terms of number of bits used to store each intensity level

Number of Bits	Number of Intensity Levels	Examples
1	2	0, 1
2	4	00, 01, 10, 11
4	16	0000, 0101, 1111
8	256	00110011, 01010101
16	65,536	1010101010101010

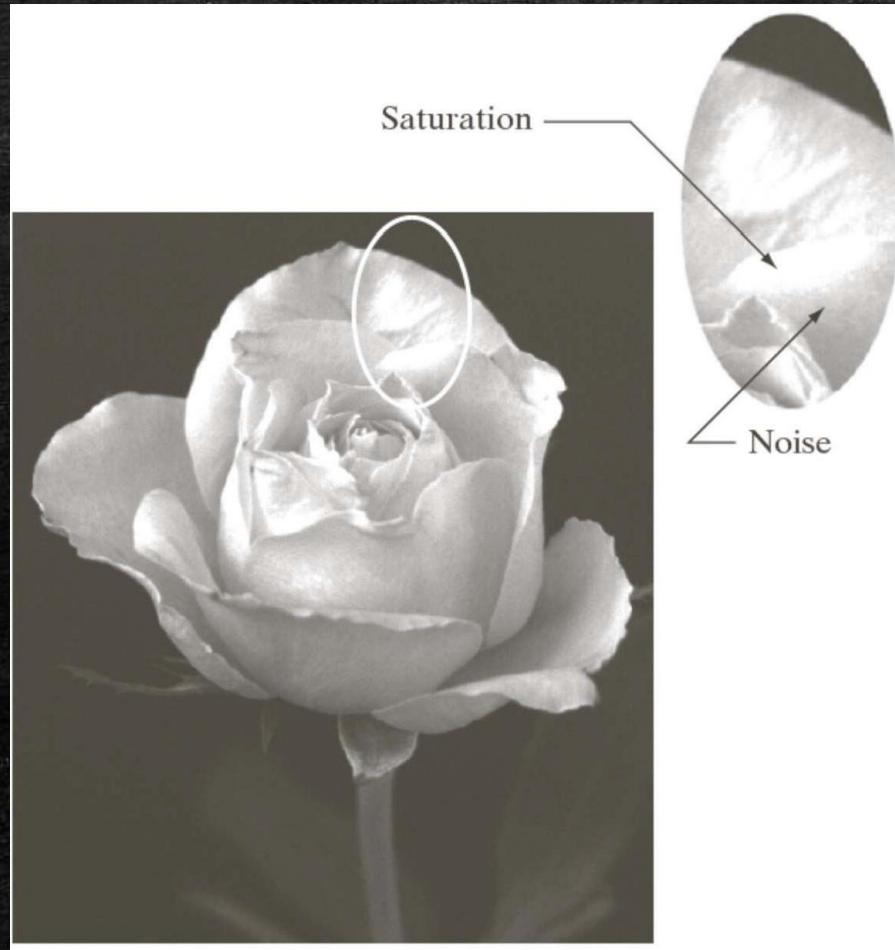


# Intensity Level Resolution





# Saturation & Noise



**Saturation:** highest intensity value above which color is washed out

**Noise:** grainy texture pattern



# Resolution: How Much Is Enough?

- The big question with resolution is always *how much is enough?*
  - Depends on what is in the image (*details*) and what you would like to do with it (*applications*)
  - Key questions:
    - Does image look aesthetically pleasing?
    - Can you see what you need to see in image?



# Resolution: How Much Is Enough?



- **Example:** Picture on right okay for counting number of cars, but not for reading the number plate



# Intensity Level Resolution



Low Detail



Medium Detail



High Detail

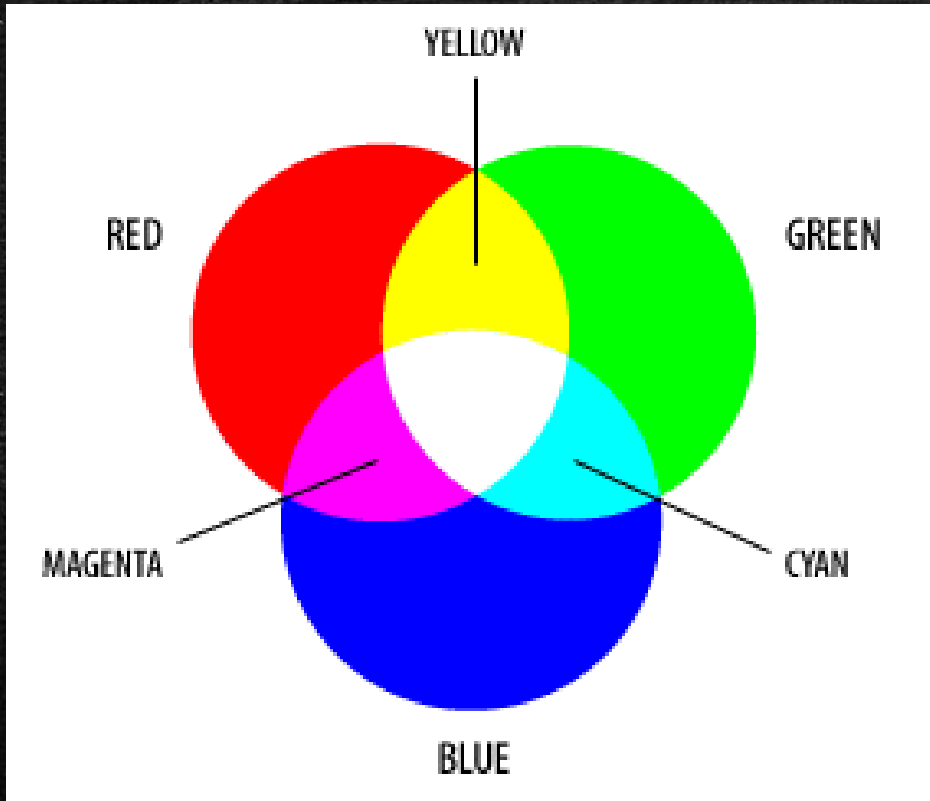


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# Colour Spaces



# RGB (Red, Green, Blue)



*Red, green, and blue are the primary stimuli for human colour perception and are the primary additive colours. The secondary colours produced by the addition of the common parts are Cyan, Magenta and Yellow.*





49	55	56	57	52	53
58	60	60	58	55	57
58	58	54	53	55	55
83	78	72	69	68	69
88	91	91	84	83	82
69	76	83	78	76	75
61	69	73	78	76	76

Red

64	76	82	79	78	78
93	93	91	91	86	86
88	82	88	90	88	89
125	119	113	108	111	110
137	136	132	128	126	120
105	108	114	114	118	113
96	103	112	108	111	107

Green

66	80	77	80	87	77
81	93	96	99	86	85
83	83	91	94	92	88
135	128	126	112	107	106
141	129	129	117	115	101
95	99	109	108	112	109
84	93	107	101	105	102

Blue

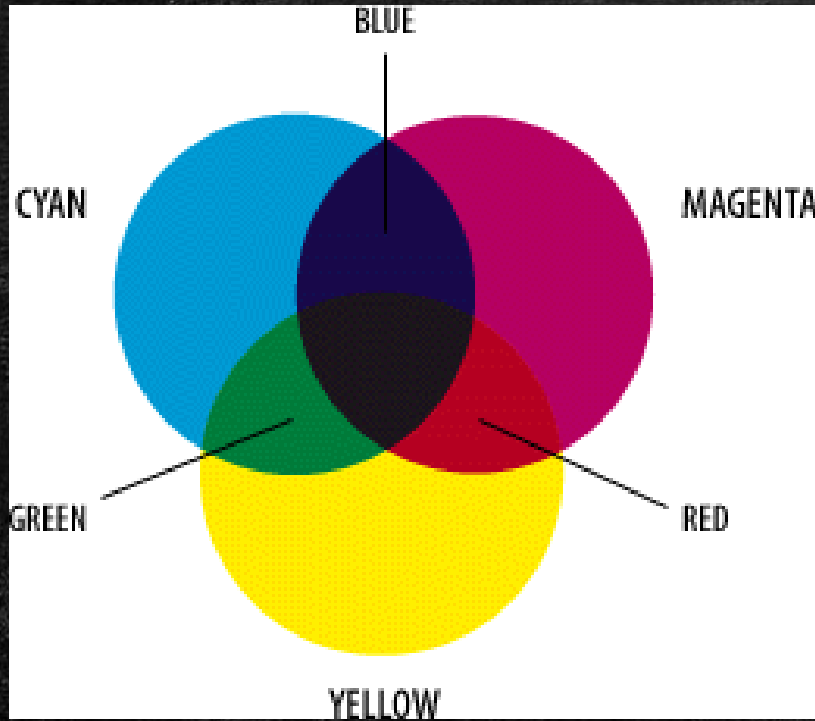


# RGB

- **Additive Colours** are created by mixing spectral light in varying combinations.
- The most common examples of this are television screens and computer monitors, which produce coloured pixels by firing red, green, and blue electron guns at phosphors on the television or monitor screen.
- The total of maximum red, maximum green and maximum blue yields a white colour , whereas the absence of the three colours produces an absence of light i.e. black.
- Note that this colour space **combines** luminance with colour.
- The importance of RGB as a colour model is that it relates very closely to the way we perceive colour with the r g b receptors in our retinas.
- RGB is the basic colour model used in television or any other medium that projects the colour. It is the basic colour model on computers and is used for Web graphics, but it cannot be used for print production.



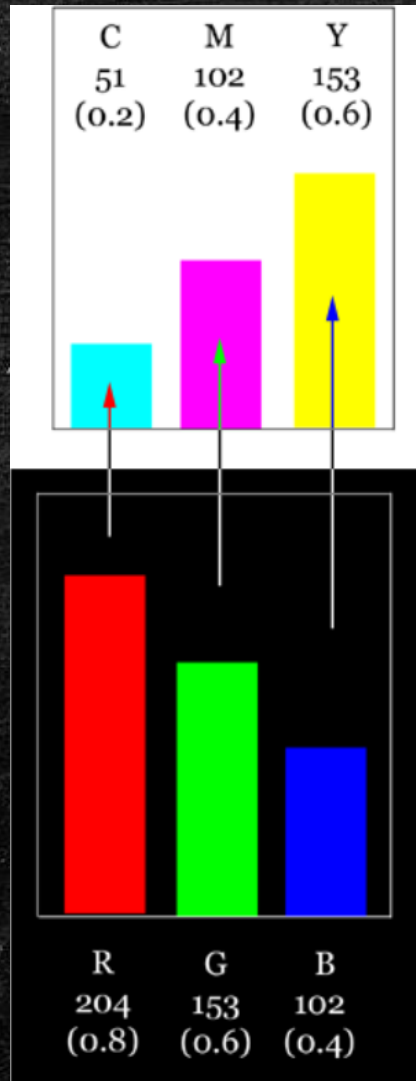
# CMY (Cyan , Magenta, Yellow)



*In CMY space, the same RGB colours are considered as subtractive mixtures of varying quantities of cyan (C), magenta (M) and yellow (Y) colourants. The resulting cubic space is identical to RGB space, apart from the fact that the origin of the C, M and Y axes is at the point representing white instead of black*



# CMY



- *To convert from CMY to RGB*

$$C = 255 - R \text{ (or } 1 - r \text{)}$$

$$M = 255 - G \text{ (or } 1 - g \text{)}$$

$$Y = 255 - B \text{ (or } 1 - b \text{)}$$

- *Note that C,M and Y behave as ideal subtractive colourants complementary to the particular R,G and B additive primaries.*



# CMY

- **Subtractive Colours** are seen when pigments in an object absorb certain wavelengths of white light while reflecting the rest.
- Any coloured object, whether natural or man-made, absorbs some wavelengths of light and reflects or transmits others; the wavelengths left in the reflected/transmitted light make up the colour we see.
- It is used mostly for print.



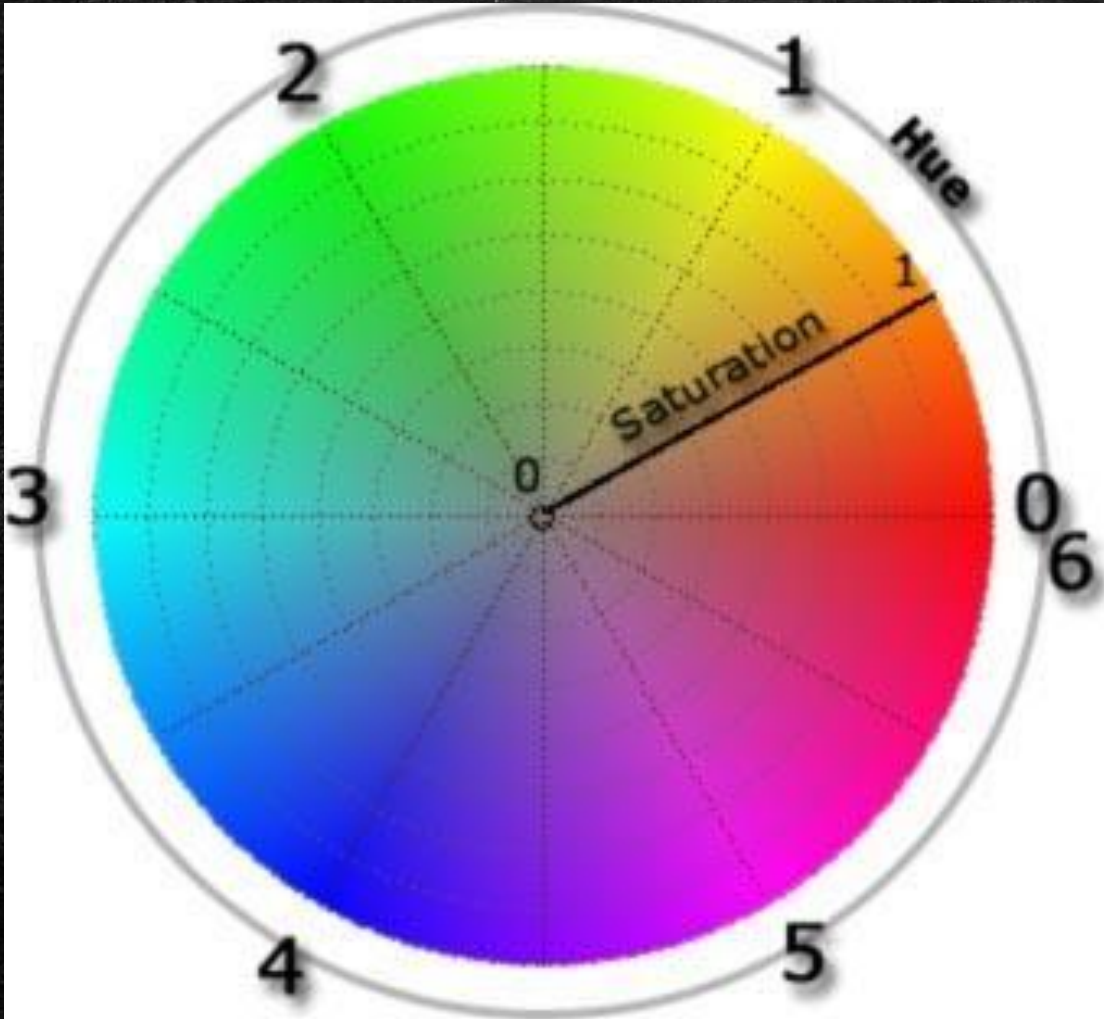
# HSL (Hue, Saturation, Luminance)

*HSL stands for Hue, Saturation and Luminance (or brightness).*

*The HSL colour space defines colours more naturally: Hue specifies the base colour, the other two values then let you specify the saturation of that colour and how bright the colour should be.*



# HSL



Hue specifies the colour

Hue is normally specified as degrees ranging from  $0^{\circ}$  to  $360^{\circ}$  or as numbers from 0 to 6



































































Saturation is a measure between 0 (less saturated i.e. grey) and 100% (more saturated i.e. colourful)

Hue	Hue (degree)	Color
0	$0^{\circ}$	red
1	$60^{\circ}$	yellow
2	$120^{\circ}$	green
3	$180^{\circ}$	cyan
4	$240^{\circ}$	blue
5	$300^{\circ}$	magenta
6	$360^{\circ}$	red



# HSL

- The third parameter (luminance) lets you specify how "bright" the color should be.
- 0% means, the brightness is 0, and the colour is black.
- 100% means maximum brightness, and the colour is white.

	Hue	0 / 0°	1 / 60°	2 / 120°	3 / 180°	4 / 240°	5 / 300°
Luminance							
100%							
90%							
80%							
70%							
60%							
50%							
40%							
30%							
20%							
10%							
0%							



# HSL

- Unlike RGB, HSL separates *luminance*, from colour
- When doing histogram equalization of a colour image, it would be ideal to apply it on the intensity component only.
- In computer vision we often want to separate colour components from intensity for various reasons, such as robustness to lighting changes, or removing shadows.



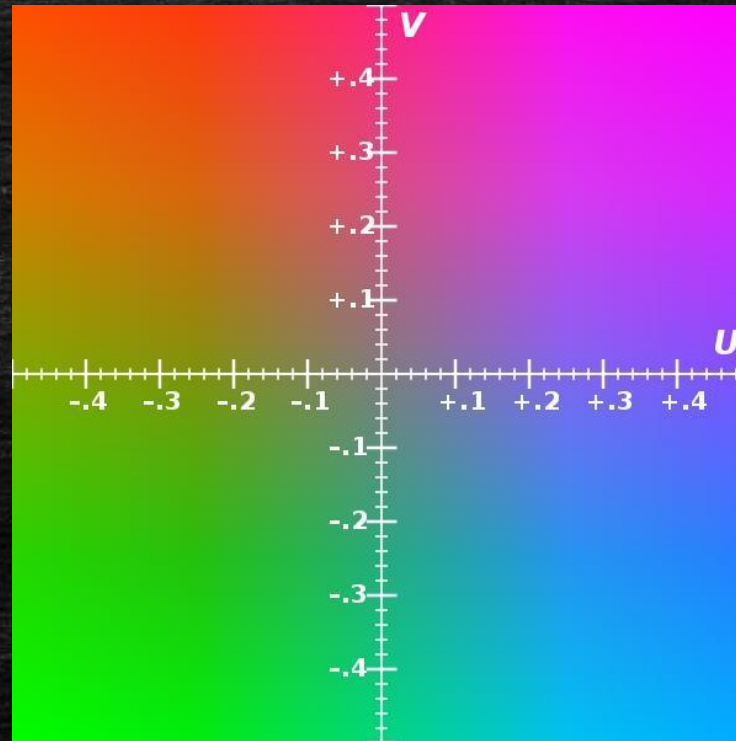
# YUV

*YUV is a colour space typically used as part of a colour image pipeline. It encodes a colour image or video taking human perception into account, allowing reduced bandwidth for chrominance components. This enables transmission errors or compression artefacts to be more efficiently masked by the human perception than using a "direct" RGB-representation.*



# YUV (Chrominance, Luminance)

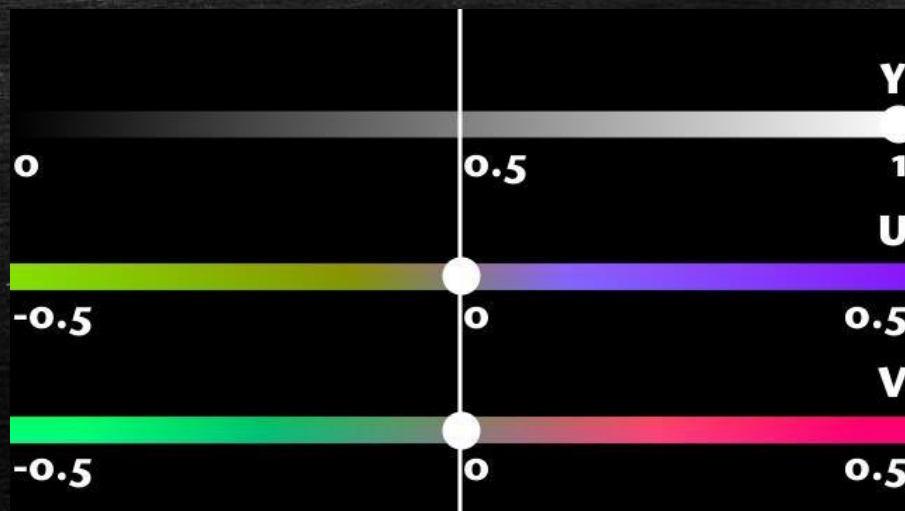
- YUV is built up out of 3 components:
  - Y - luminance (brightness)
  - U and V - chrominance (color)
- The Y component indicates how bright the picture is.
  - Y = 0 - black
  - Y = 0.5 - grey
  - Y = 1 - white
- U and V are a matrix of colors as seen on the right:





# YUV

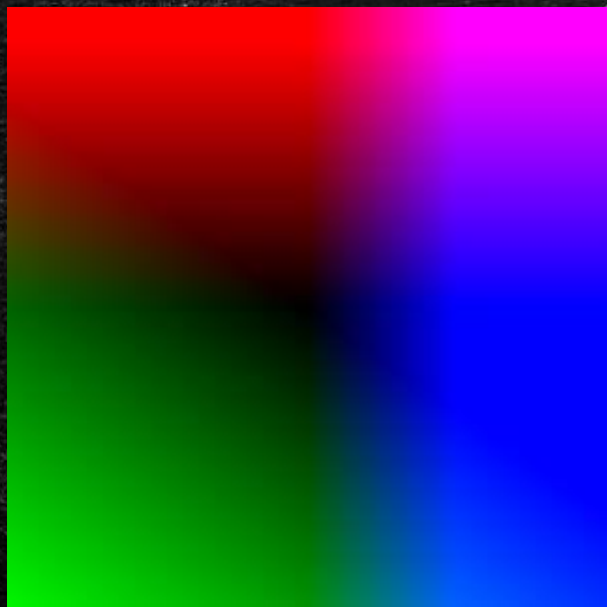
- When working in grey-scale, U and V are in the middle ( $U = 0$  and  $V = 0$ )
- Y would provide you with all the shades between black and white ( $Y = 0$  to  $Y = 1$ )



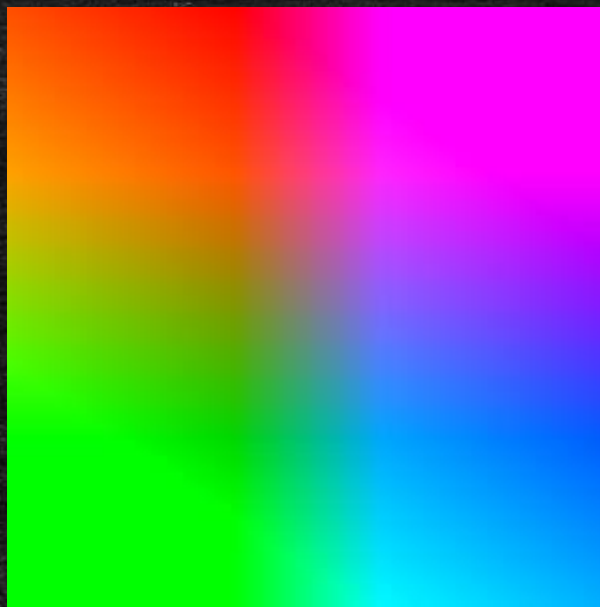


# YUV

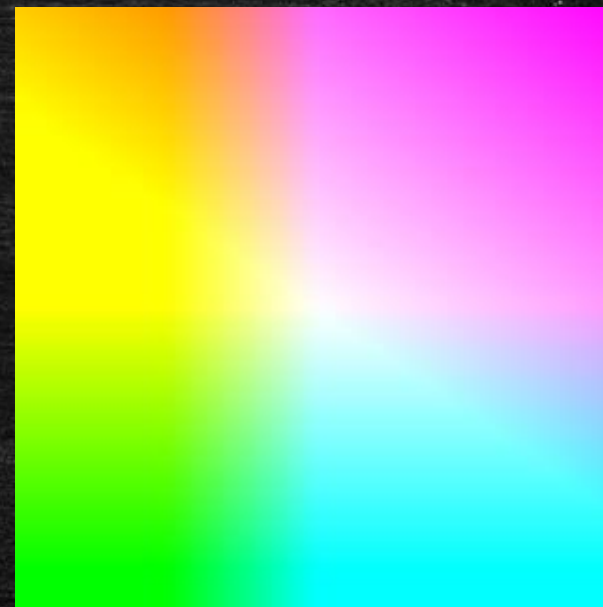
- The U-V matrix colors change depending on how bright the Y value is. The higher the Y value, the brighter the colors



$Y = 0$



$Y = 0.5$

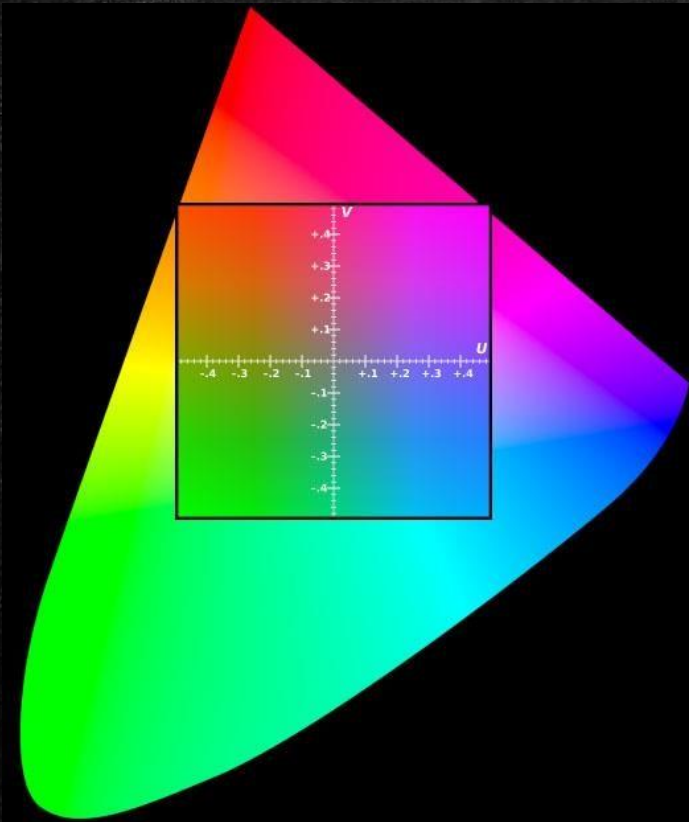


$Y = 1$



# YUV

- YUV color space **cannot** represent all colours available in the RGB color space.



An (NTSC) approximation to convert RGB to YUV gives:

$$Y = 0.299 \times R + 0.587 \times G + 0.114 \times B$$

$$U = -0.147 \times R - 0.289 \times G + 0.436 \times B$$

$$V = 0.615 \times R - 0.515 \times G - 0.100 \times B$$

This is in line with the sensitivity of the human eye for these different colours



# YUV

- image/video codecs use YUV in favour of compression while retaining good image quality.
- Like HSL , YUV separates the colour channels from the luminosity hence it makes it an ideal format when manipulation is required on the luminosity.
- Chrominance (UV) is kept to a minimum
- Luminance (Y) is kept as high as possible



# Some Applications of CV based on Colour

## Skin Detection





# Some Applications of CV based on Colour

## Red Eye Detection and Removal



A pair of red eyes.



The corrected eyes.



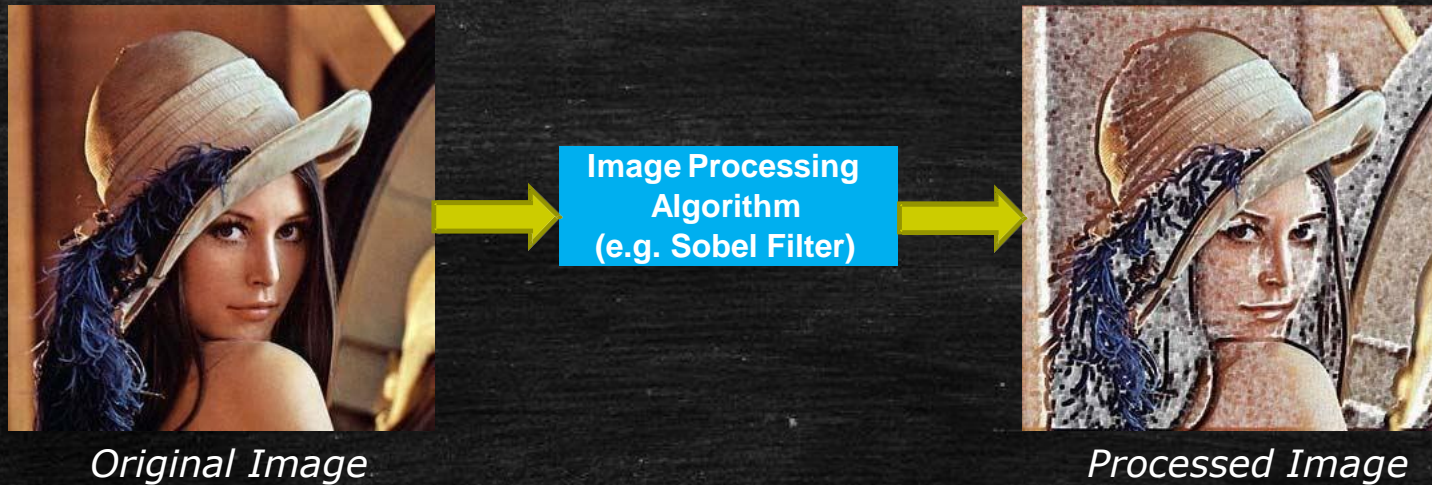
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# Image Processing



# Image Processing: Definition

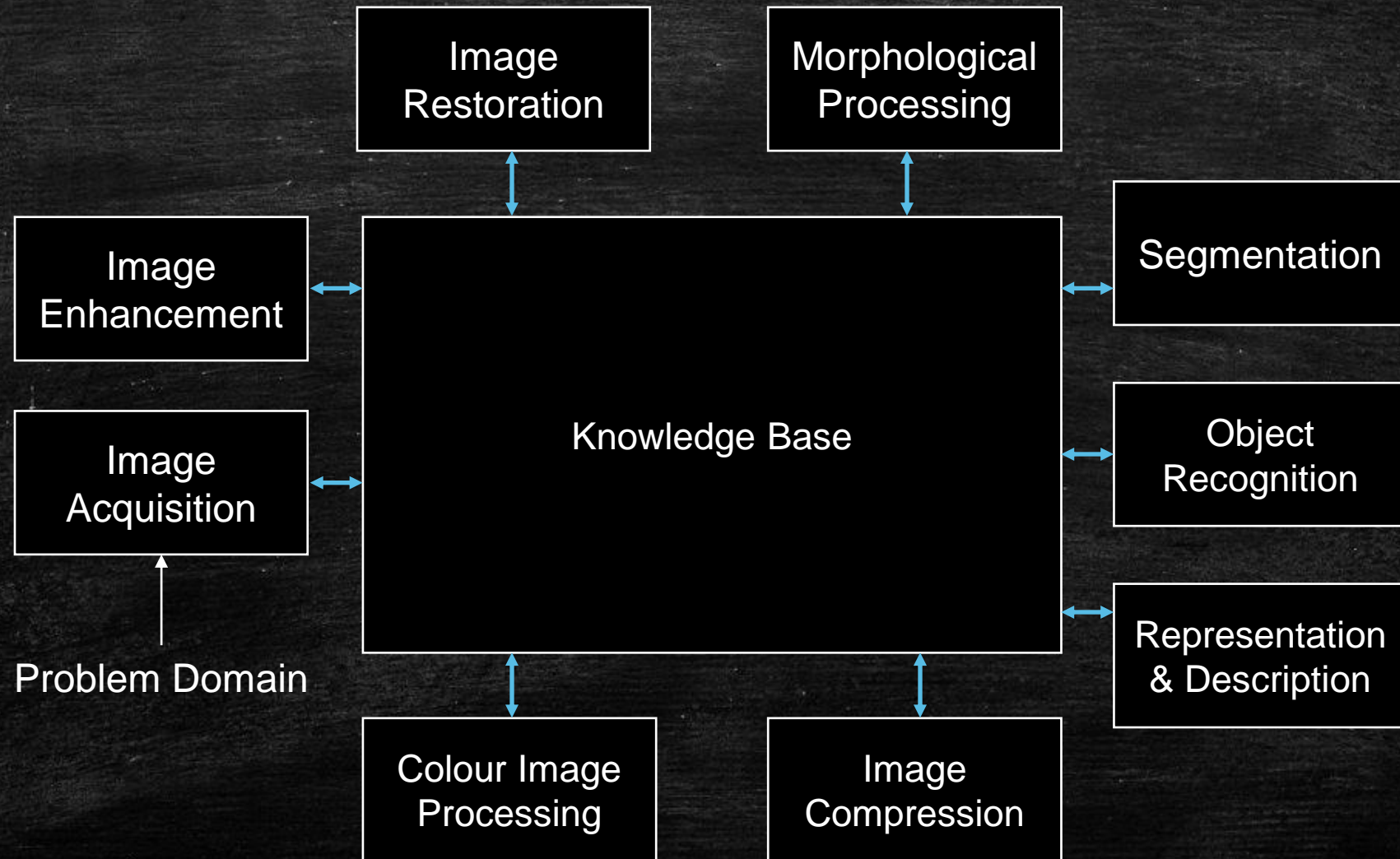
- Algorithms that alter an input image to create new image
- Input is image, output is image



- Improves an image for human interpretation in ways including:
  - Image display and printing
  - Image editing
  - Image enhancement
  - Image compression
- Some Examples follow....

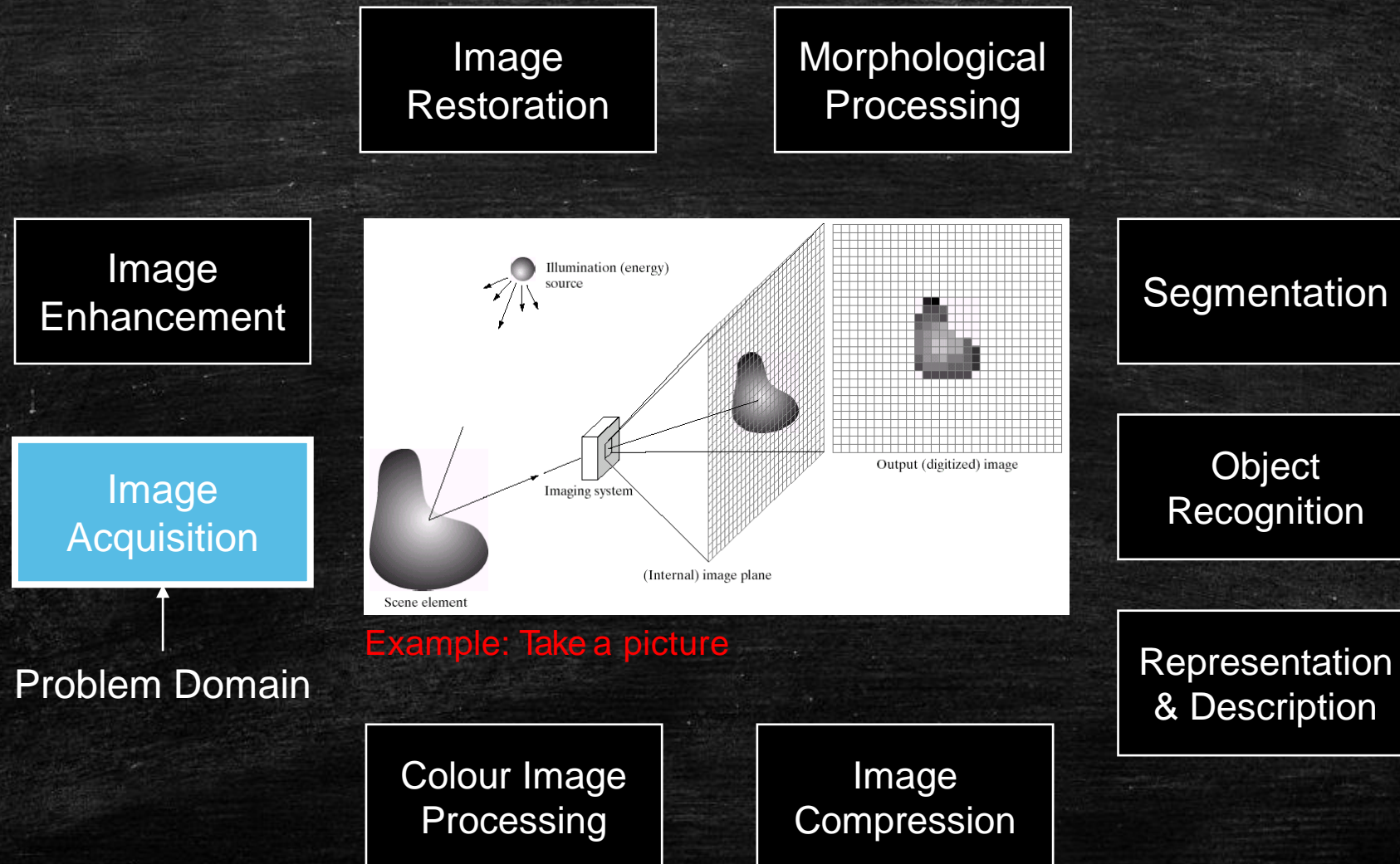


# Key Stages in Digital Image Processing



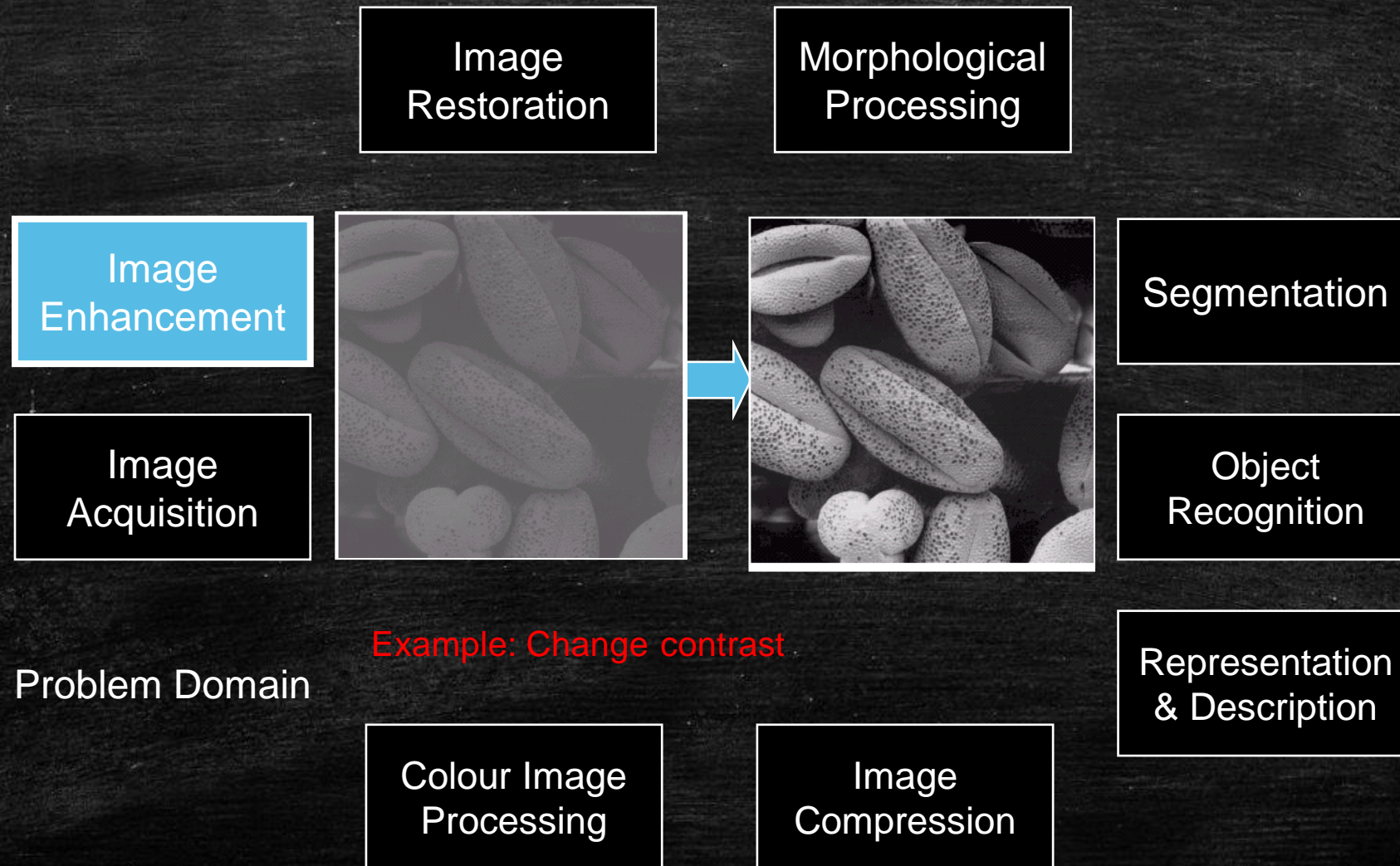


# Key Stages in Digital Image Processing: Image Aquisition



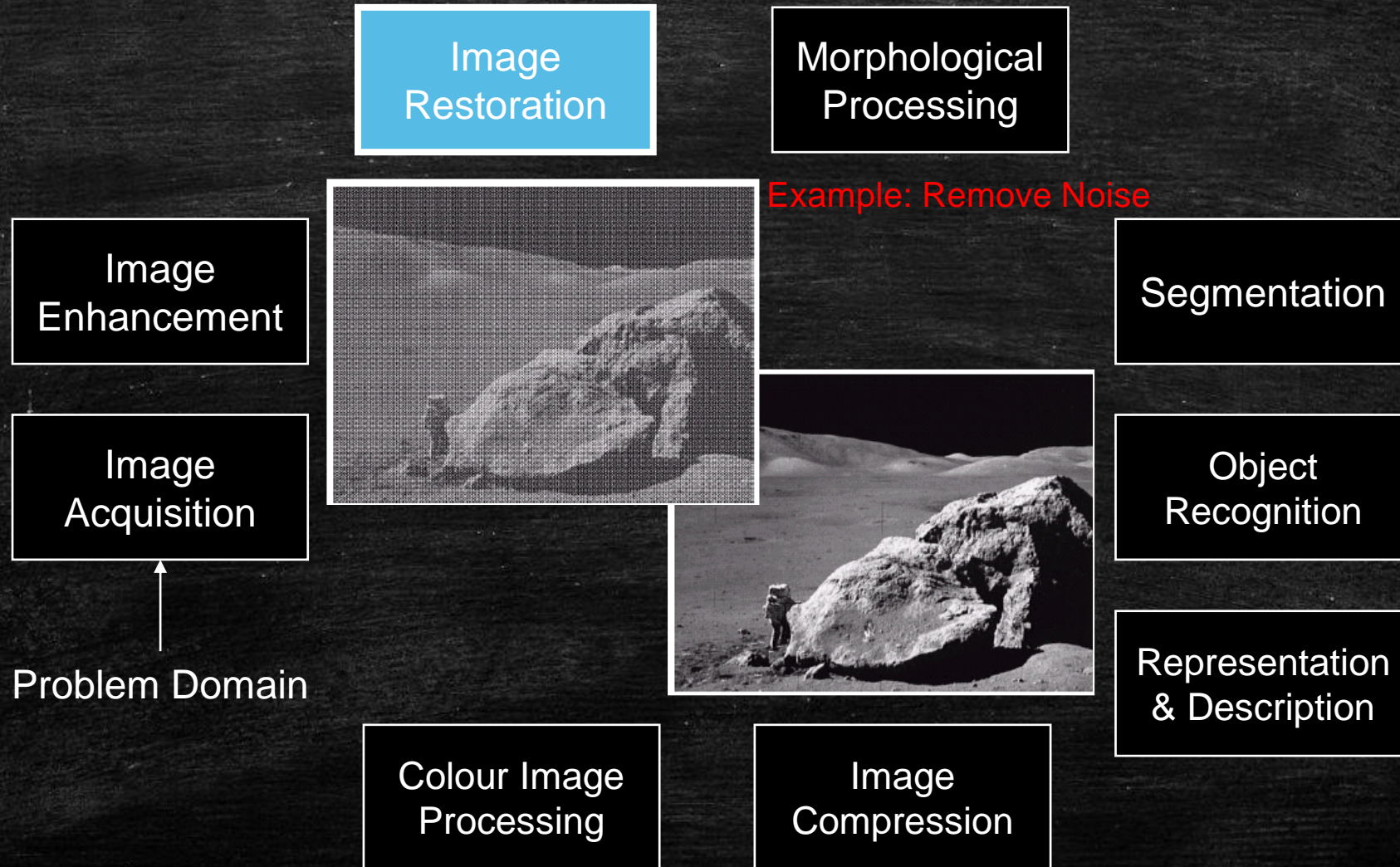


# Key Stages in Digital Image Processing: Image Enhancement





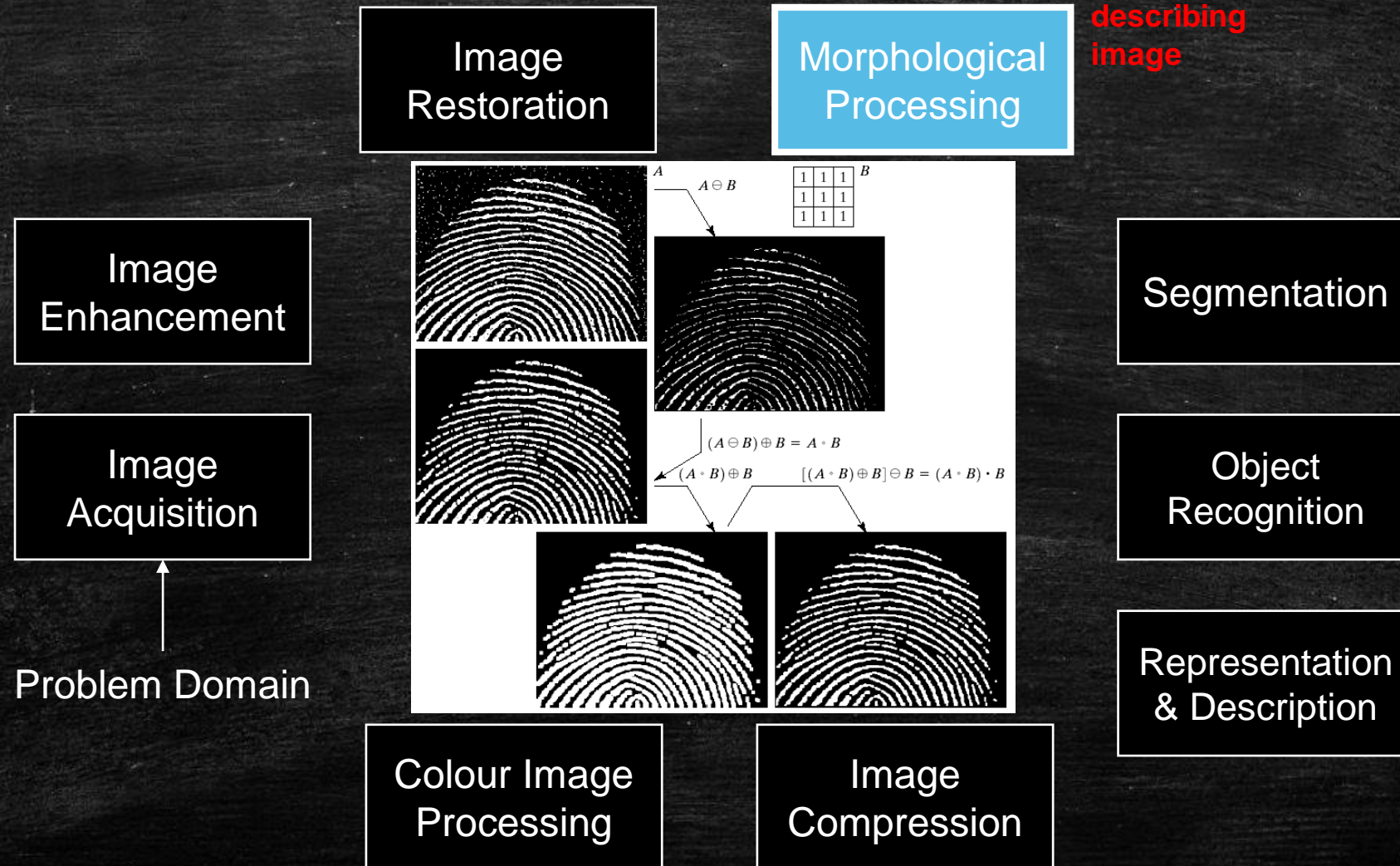
# Key Stages in Digital Image Processing: Image Restoration





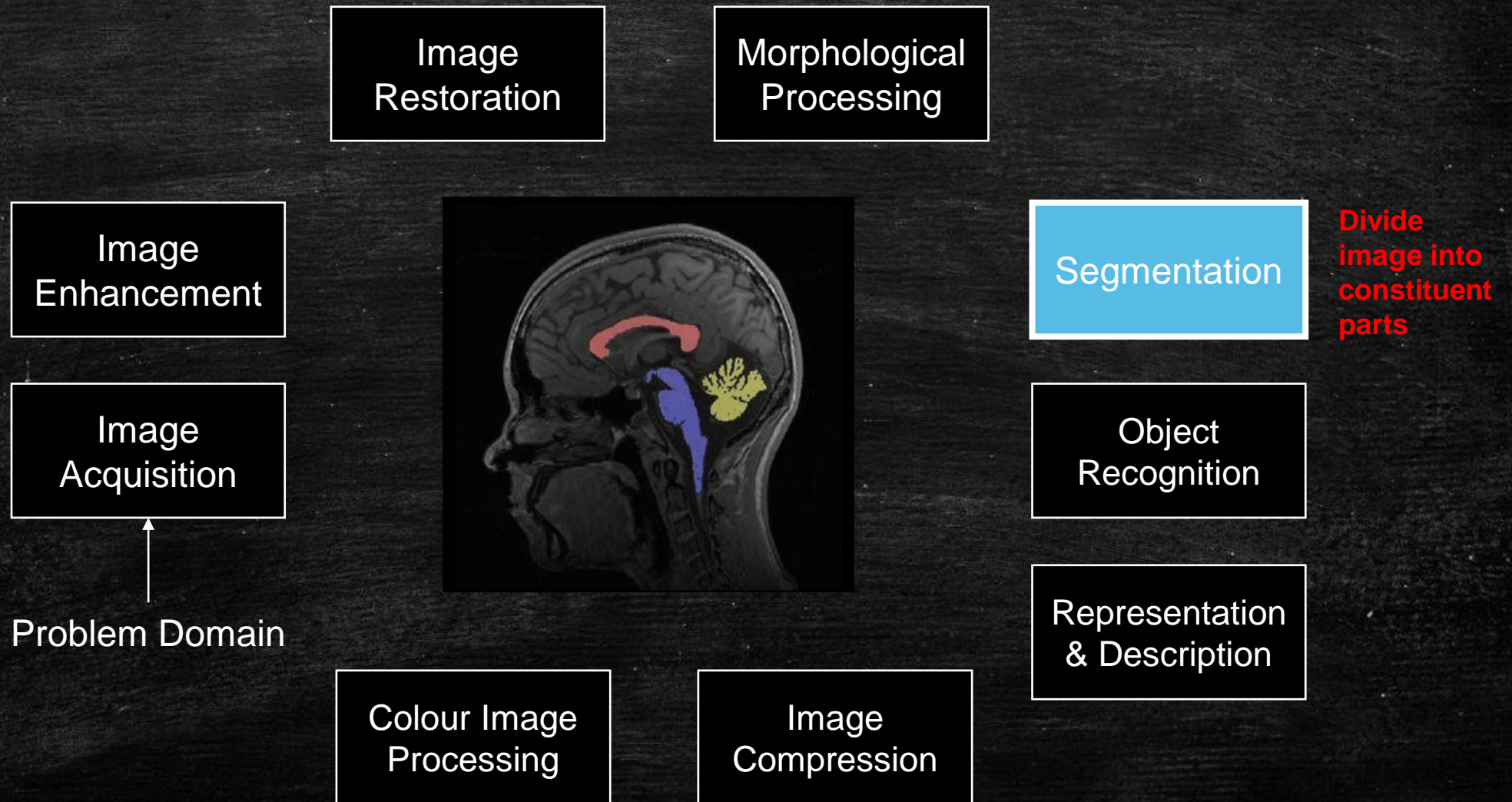
# Key Stages in Digital Image Processing: Morphological Processing

Extract  
attributes  
useful for  
describing  
image



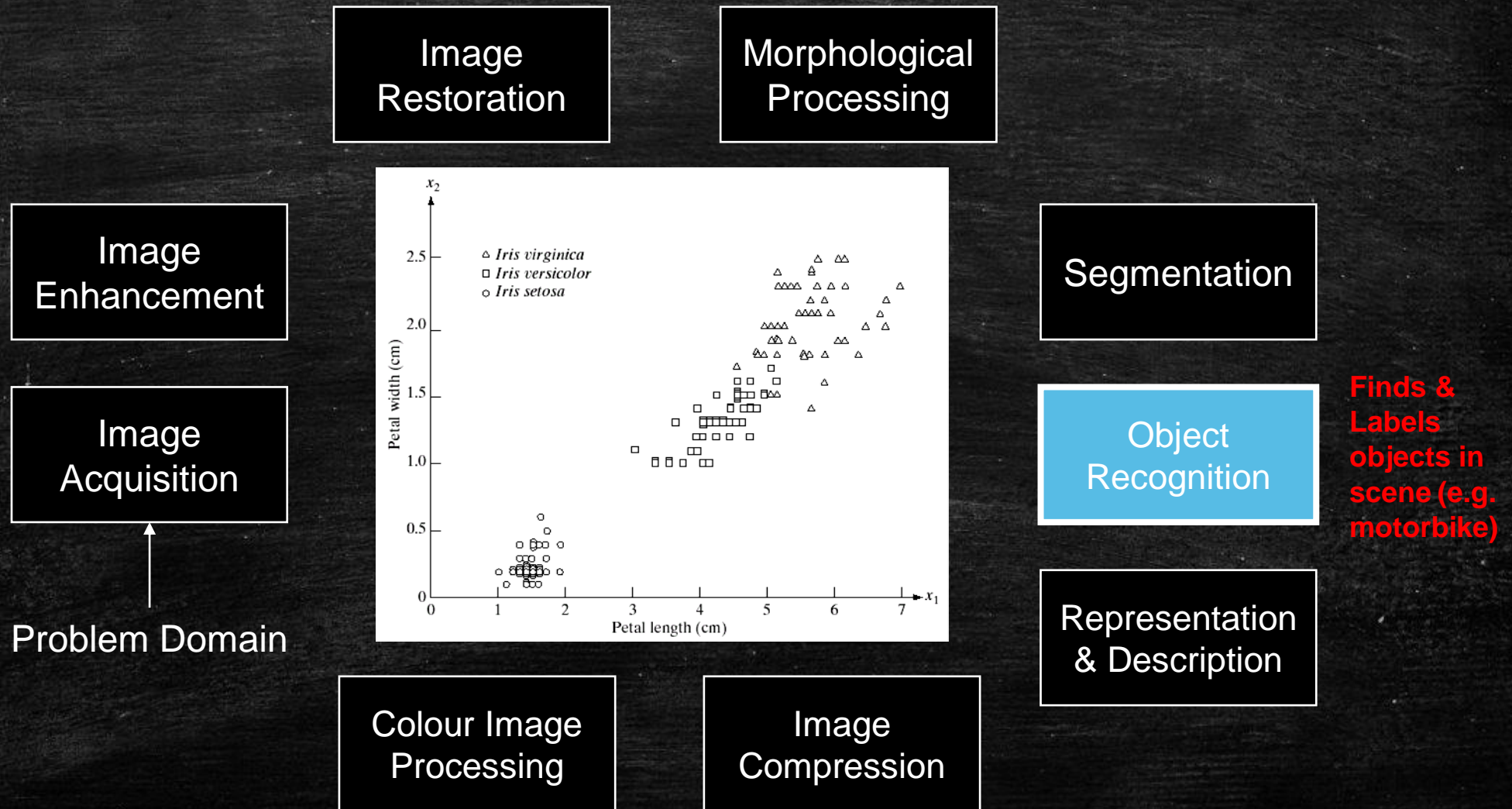


# Key Stages in Digital Image Processing: Segmentation





# Key Stages in Digital Image Processing: Object Recognition





# Key Stages in Digital Image Processing: Representation & Description

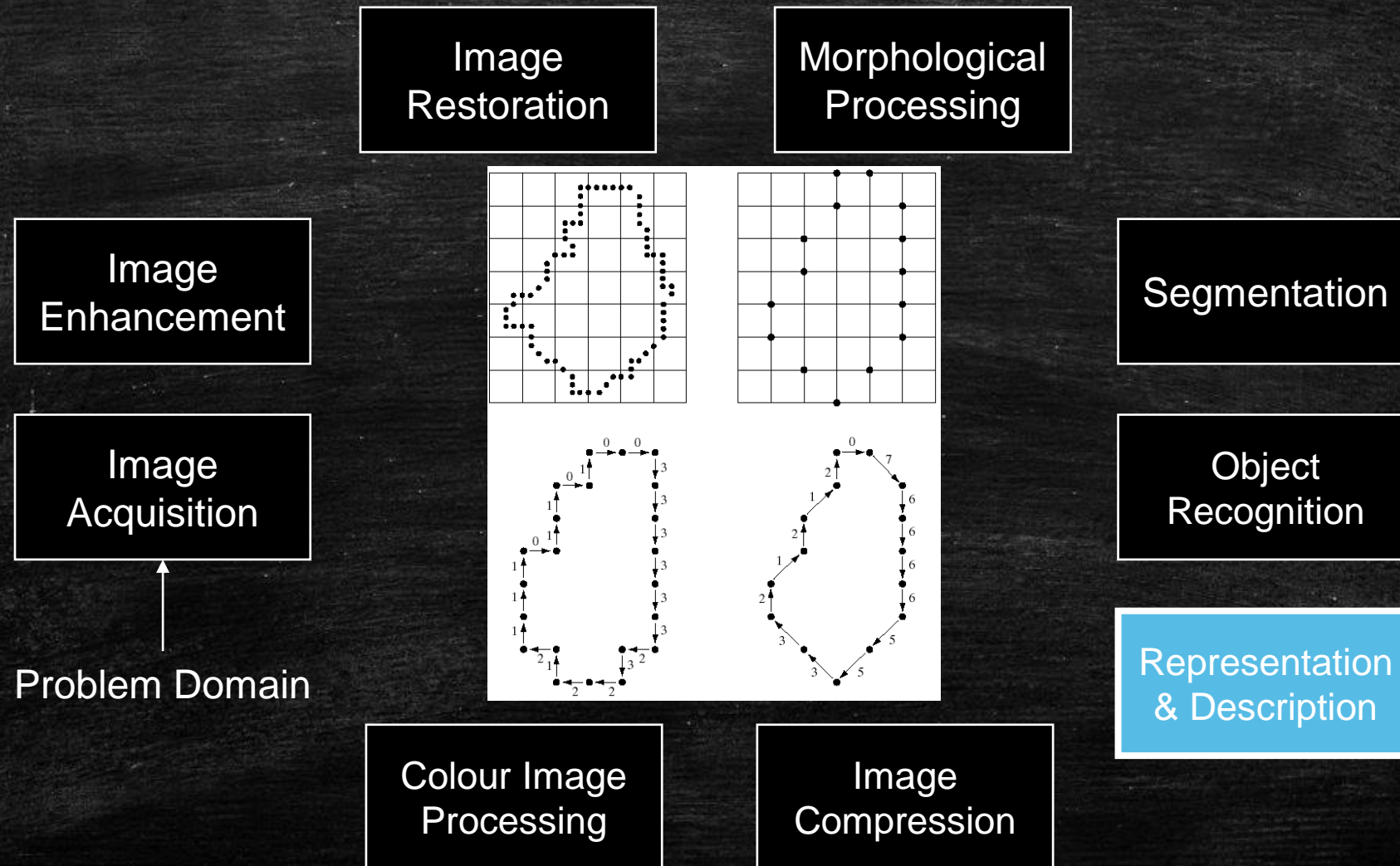
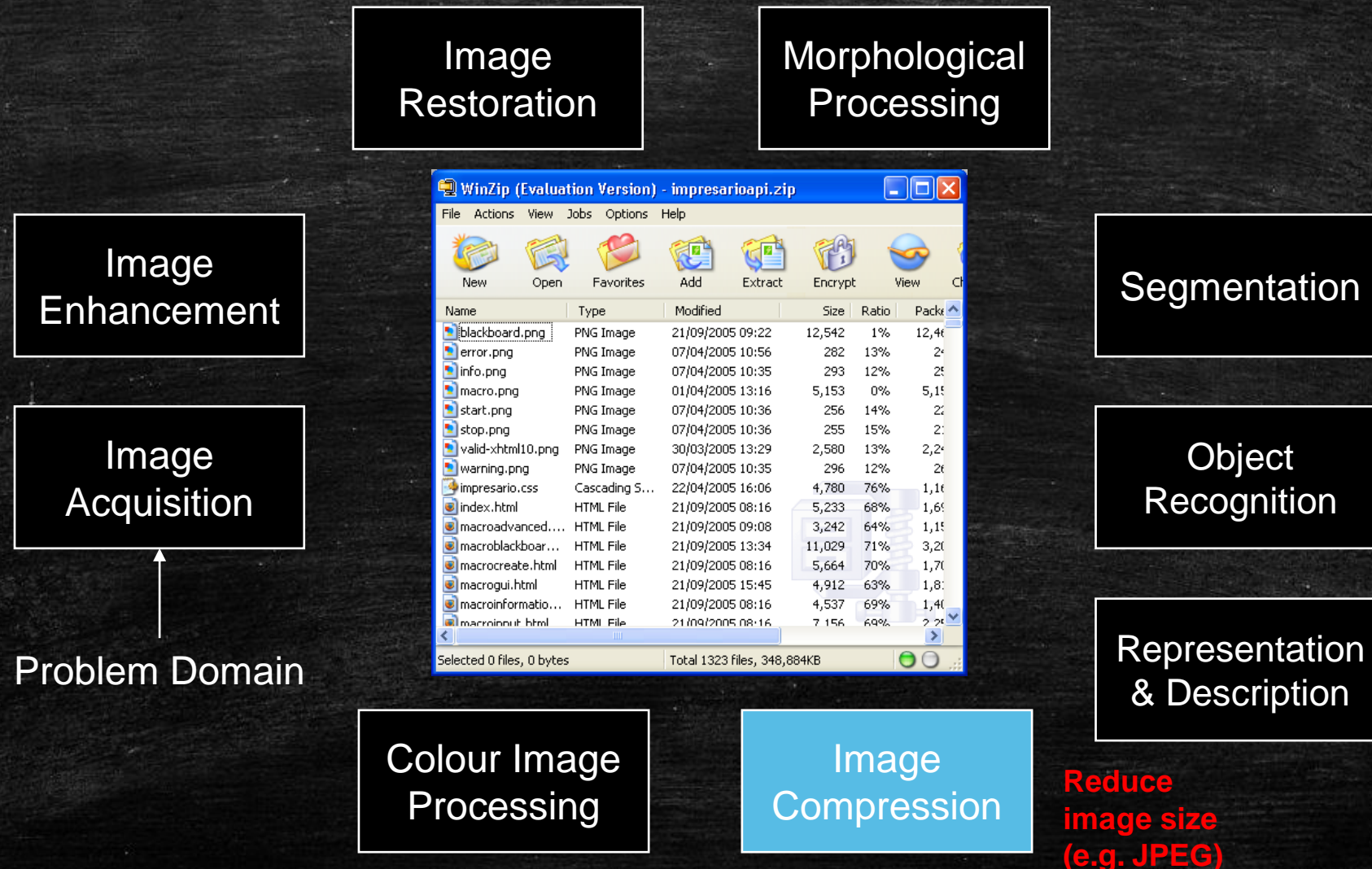


Image regions transformed suitable for computer processing

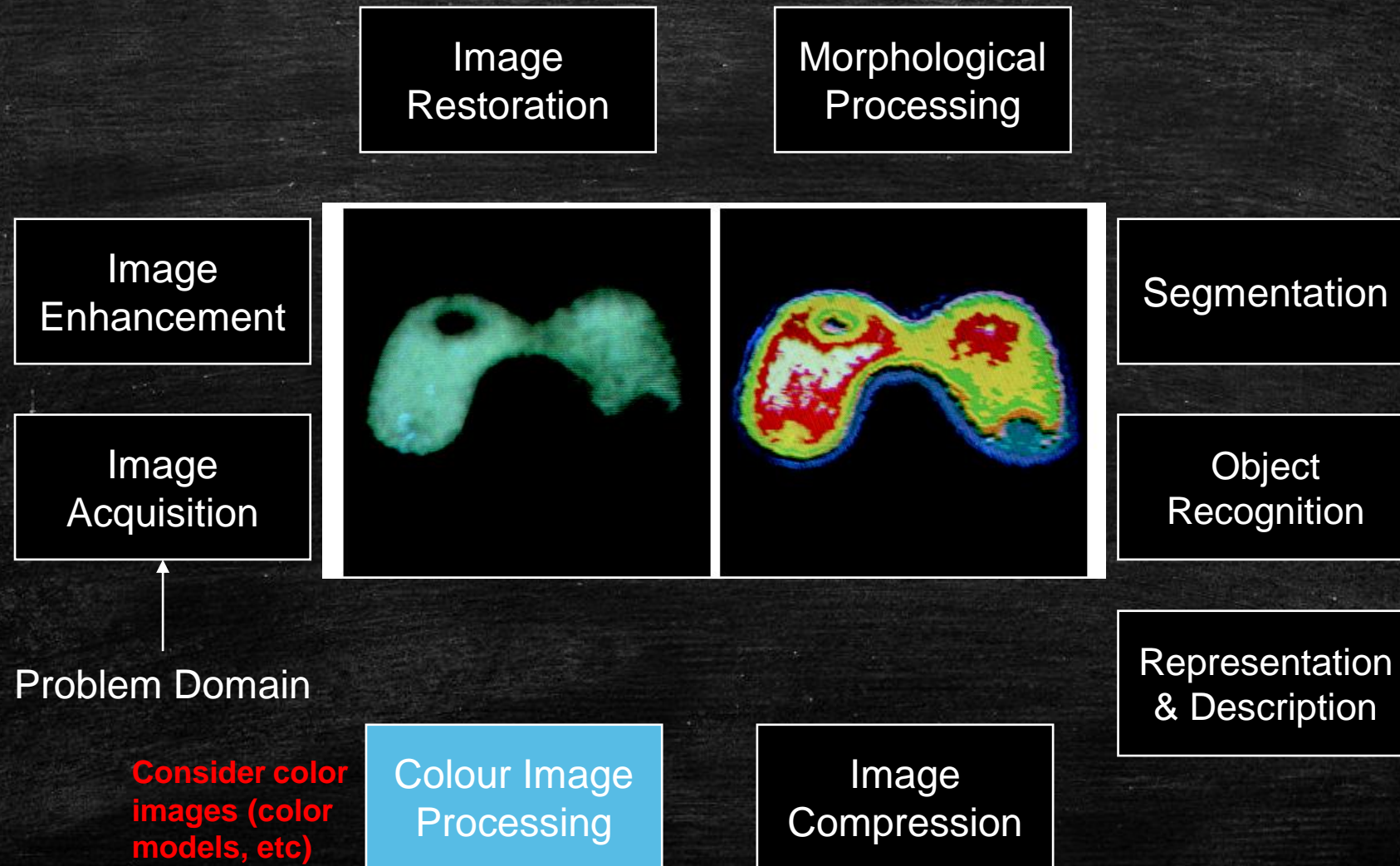


# Key Stages in Digital Image Processing: Image Compression





# Key Stages in Digital Image Processing: Colour Image Processing





# Loading and Displaying Colour Images

Color images are loaded as a  $h * w * 3$  array. Following code loads an image called “fruits.jpg”. Then it zeros-out the red plane and the green plane. As a result the image becomes blue.

```
close all
```

```
im = imread ( 'fruits.jpg' );
```

```
imshow( im)
```

```
pause
```

```
im ( :, :, 1 ) = 0;
```

```
im ( :, :, 2 ) = 0;
```

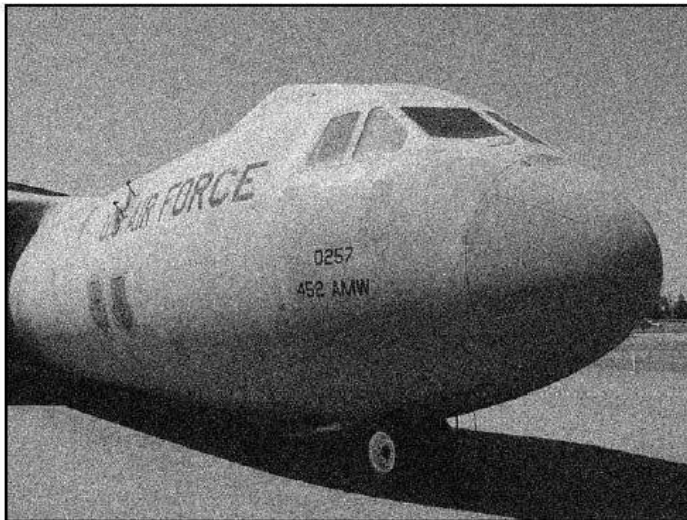
```
figure
```

```
imshow( im)
```



# Image Processing: Noise Removal

Noisy Image



Denoised Image

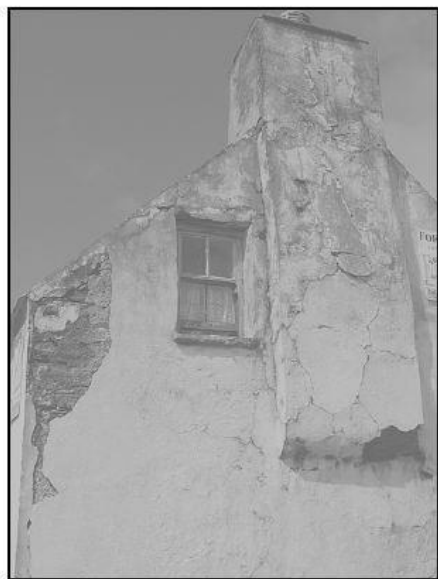


Think of noise as white specks on a picture (random or non-random)



# Image Processing: Contrast Adjustment

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Low Contrast



Original Contrast



High Contrast



# Image Processing: Blurring



Original Image

Blurred Image



# Image Processing: Compression

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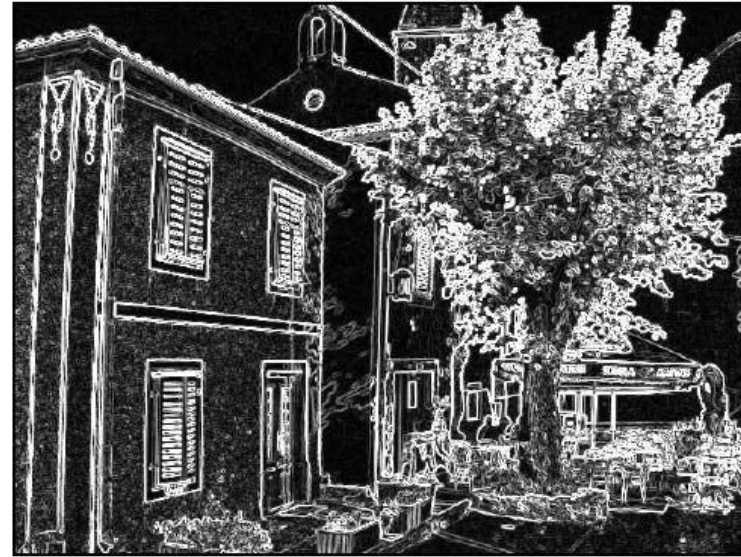
Original, 2.1MB



JPEG Compression, 308KB (15%)



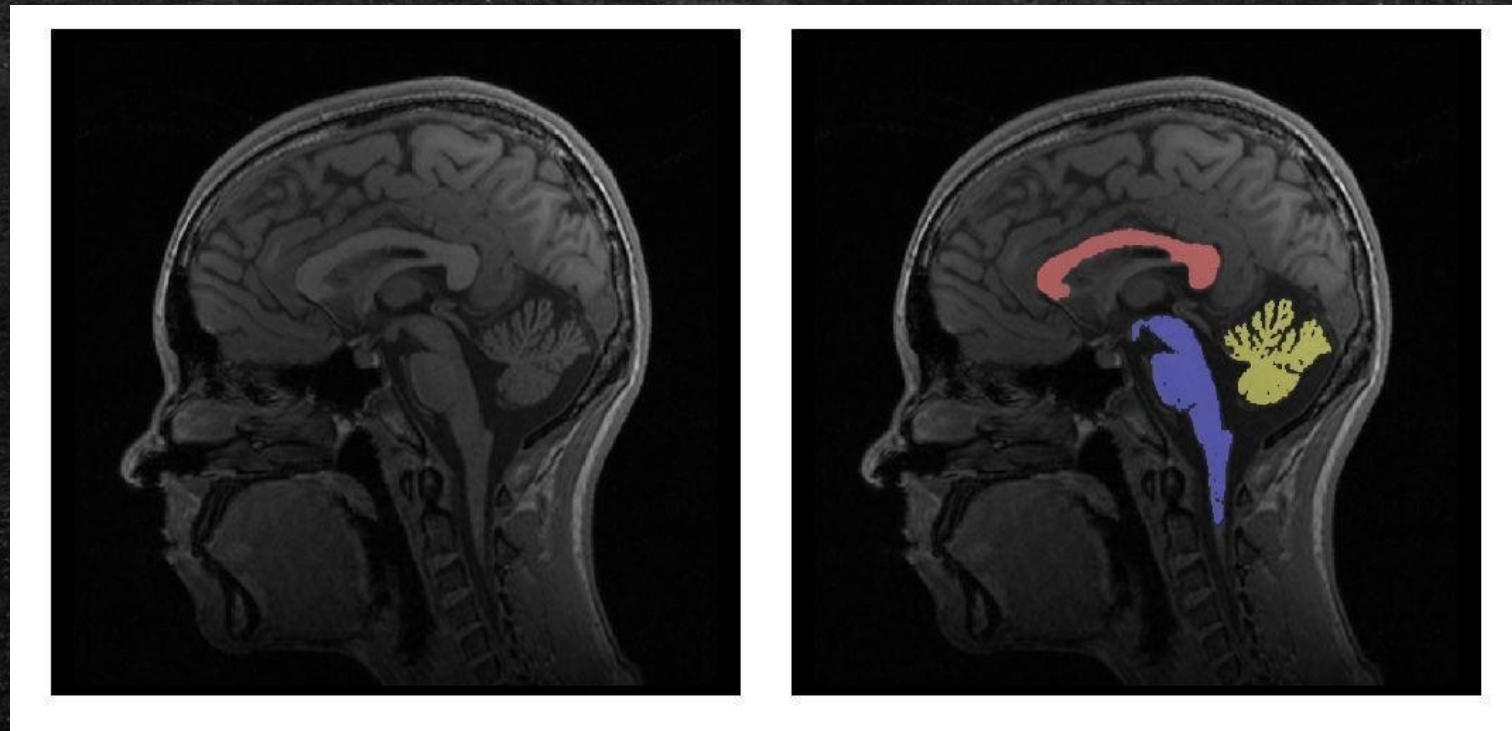
# Image Analysis: Edge Detection





# Segmentation

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# Relating IP, IA, CV



High-level

## Computer Vision

Object detection, recognition, shape analysis, tracking  
Use of Artificial Intelligence and Machine Learning

## Image Analysis

Segmentation, image registration, matching

Low-level

## Image Processing

Image enhancement, noise removal, restoration,  
feature detection, compression