Please try to follow this developing steps. Starting from the basic map, then add up the functionalities one by another ;-)

## Single object:

- 1. Position / Velocity / Acceleration (optional)
  - → Able to move / stop
- 2. Turn / Decision making
  - → Able to move / stop / turn

## Multiple object:

- 3. Car following / Collision avoidance
  - → Able to move / stop / turn / wait in line
- 4. Behavior / Overtaking
  - → Able to move / stop / turn / wait in line / driving behavior / overtaking ...
- 5. Car Types
  - → Able to move / stop / turn / wait in line / driving behavior / overtaking / set size of car / priority of having the way

I suggest to stat an ideal and simple map like below:

