

# Keys and Total Order Relations

- A **Priority Queue** ranks its elements by *key* with a *total order* relation
- Keys:
  - Every element has its own key
  - Keys are not necessarily unique
- Total Order Relation
  - Denoted by  $\leq$
  - **Reflexive:**  $k \leq k$
  - **Antisymmetric:** if  $k_1 \leq k_2$  and  $k_2 \leq k_1$ , then  $k_1 = k_2$
  - **Transitive:** if  $k_1 \leq k_2$  and  $k_2 \leq k_3$ , then  $k_1 \leq k_3$
- A **Priority Queue** supports these fundamental methods:
  - `insertItem(k, e)` // element  $e$ , key  $k$
  - `removeMinElement()` // return and remove the // item with the smallest key

# Sorting with a Priority Queue

- A **Priority Queue**  $P$  can be used for sorting by inserting a set  $S$  of  $n$  elements and calling **removeMinElement()** until  $P$  is empty:

**Algorithm** PriorityQueueSort( $S, P$ ):

*Input:* A sequence  $S$  storing  $n$  elements, on which a total order relation is defined, and a Priority Queue  $P$  that compares keys with the same relation

*Output:* The Sequence  $S$  sorted by the total order relation

**while** ! $S$ .isEmpty() **do**

$e \leftarrow S$ .removeFirst()

$P$ .insertItem( $e, e$ )

**while**  $P$  is not empty **do**

$e \leftarrow P$ .removeMinElement()

$S$ .insertLast( $e$ )

# The Priority Queue ADT

- A priority queue  $P$  must support the following methods:
  - **size():**  
Return the number of elements in  $P$   
**Input:** None;      **Output:** integer
  - **isEmpty():**  
Test whether  $P$  is empty  
**Input:** None;      **Output:** boolean
  - **insertItem( $k, e$ ):**  
Insert a new element  $e$  with key  $k$  into  $P$   
**Input:** Objects  $k, e$  **Output:** None
  - **minElement():**  
Return (but don't remove) an element of  $P$  with smallest key; an error occurs if  $P$  is empty.  
**Input:** None;      **Output:** Object  $e$

# The Priority Queue ADT (contd.)

- **minKey():**

Return the smallest key in  $P$ ; an error occurs if  $P$  is empty

**Input:** None;      **Output:** Object  $k$

- **removeMinElement():**

Remove from  $P$  and return an element with the smallest key; an error condition occurs if  $P$  is empty.

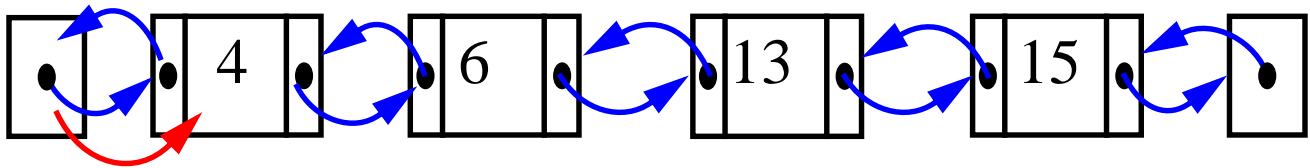
**Input:** None;      **Output:** Object  $e$

# Comparators

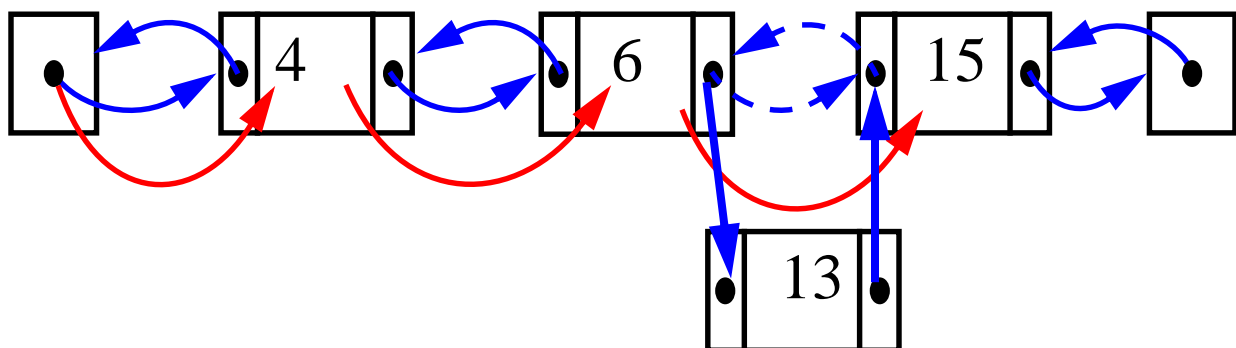
- The most general and reusable form of a priority queue makes use of **comparator** objects.
- Comparator objects are external to the keys that are to be compared and compare two objects.
- When the priority queue needs to compare two keys, it uses the comparator it was given to do the comparison.
- Thus a priority queue can be general enough to store any object.
- The comparator ADT includes:
  - isLessThan( $a, b$ )
  - isLessThanOrEqualTo( $a, b$ )
  - isEqualTo( $a, b$ )
  - isGreaterThan( $a, b$ )
  - isGreaterThanOrEqualTo( $a, b$ )
  - isComparable( $a$ )

# Implementation with a Sorted Sequence

- Another implementation uses a sequence  $S$ , sorted by keys, such that the first element of  $S$  has the smallest key.
- We can implement `minElement()`, `minKey()`, and `removeMinElement()` by accessing the first element of  $S$ . Thus these methods are  $O(1)$  (assuming our sequence has an  $O(1)$  front-removal)



- However, these advantages comes at a price. To implement `insertItem()`, we must now scan through the entire sequence. Thus `insertItem()` is  $O(n)$ .



# Implementation with a Sorted Sequence(contd.)

```
public class SequenceSimplePriorityQueue
implements SimplePriorityQueue {
    //Implementation of a priority queue
    using a sorted sequence
    protected Sequence seq = new NodeSequence();
    protected Comparator comp;
    // auxiliary methods
    protected Object extractKey (Position pos) {
        return ((Item)pos.element()).key();
    }
    protected Object extractElem (Position pos) {
        return ((Item)pos.element()).element();
    }
    protected Object extractElem (Object key) {
        return ((Item)key).element();
    }
    // methods of the SimplePriorityQueue ADT
    public SequenceSimplePriorityQueue (Comparator c) {
        this.comp = c; }
    public int size () {return seq.size(); }
```

# Implementation with a Sorted Sequence(contd.)

```
public boolean isEmpty () { return seq.isEmpty(); }
public void insertItem (Object k, Object e) throws
InvalidKeyException {
    if (!comp.isComparable(k))
        throw new InvalidKeyException("The key is not
valid");
    else
        if (seq.isEmpty())
            seq.insertFirst(new Item(k,e));
        else
            if (comp.isGreaterThan(k,extractKey(seq.last()))
                seq.insertAfter(seq.last(),new Item(k,e));
            else {
                Position curr = seq.first();
                while (comp.isGreaterThan(k,extractKey(curr)))
                    curr = seq.after(curr);
                seq.insertBefore(curr,new Item(k,e));
            }
}
```



# Implementation with a Sorted Sequence(contd.)

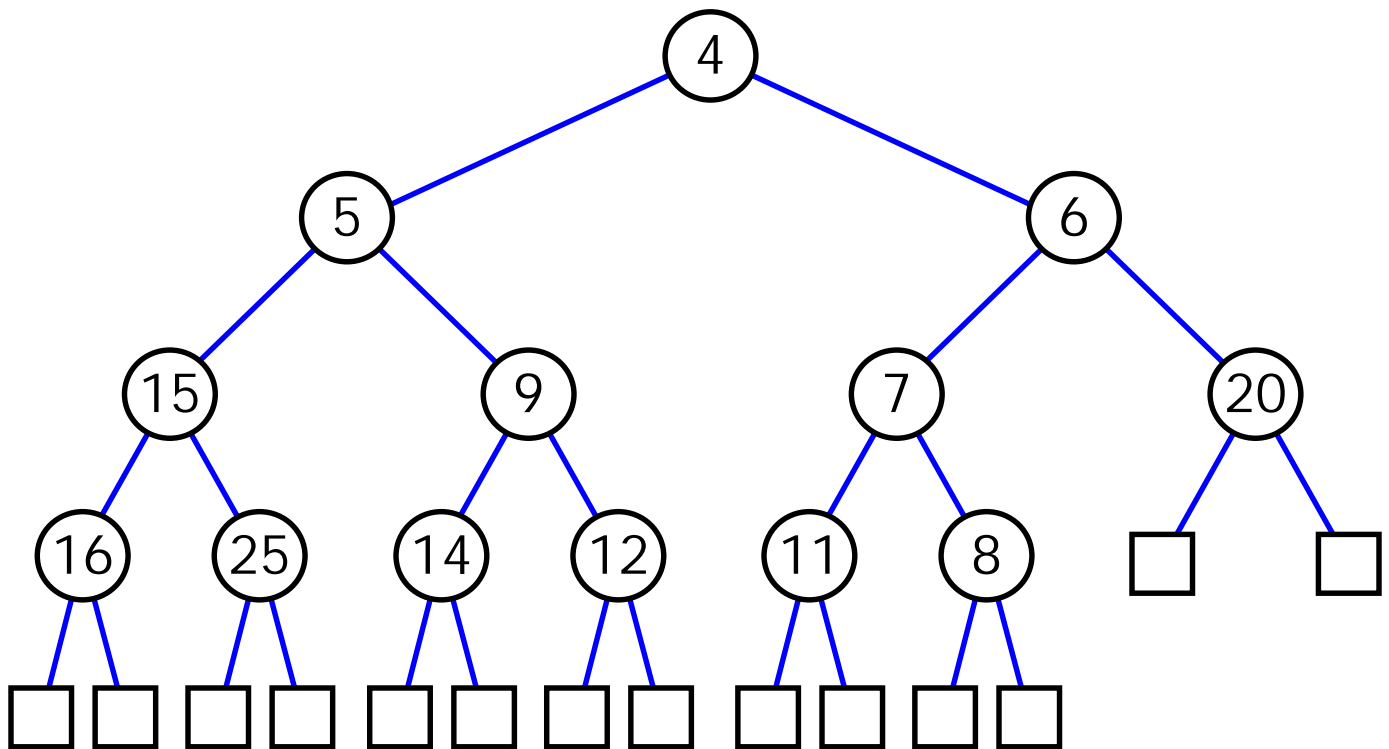
```
public Object minElement () throws  
EmptyContainerException {  
    if (seq.isEmpty())  
        throw new EmptyContainerException("The priority  
            queue is empty");  
    else  
        return extractElem(seq.first());  
}
```

# Heaps

- A **Heap** is a Binary Tree  $H$  that stores a collection of keys at its internal nodes and that satisfies two additional properties:
  - 1) **Heap-Order Property**
  - 2) **Complete Binary Tree Property**
- **Heap-Order Property Property (Relational)**: In a heap  $H$ , for every node  $v$  (except the root), the key stored in  $v$  is greater than or equal to the key stored in  $v$ 's parent.
- **Complete Binary Tree Property (Structural)**: A Binary Tree  $T$  is complete if each level but the last is full, and, in the last level, all of the internal nodes are to the left of the external nodes.

# Heaps (contd.)

- An Example:

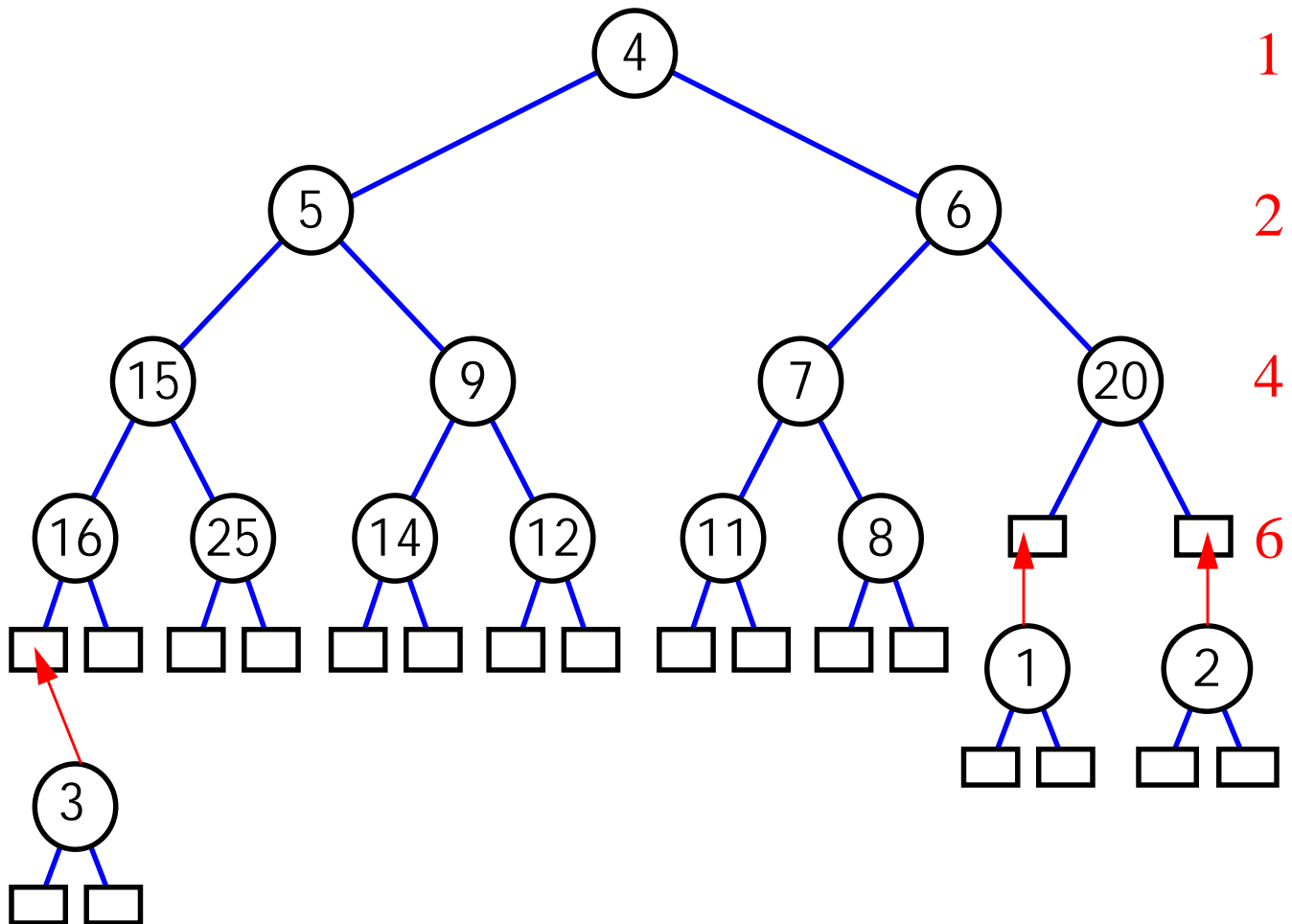


# Height of a Heap

- **Proposition:** A heap  $H$  storing  $n$  keys has height  
$$h = \lceil \log(n+1) \rceil$$
- Justification: Due to  $H$  being complete, we know:
  - #  $i$  of internal nodes is at least :  
$$1 + 2 + 4 + \dots 2^{h-2} + 1 = 2^{h-1} - 1 + 1 = 2^{h-1}$$
  - #  $i$  of internal nodes is at most:  
$$1 + 2 + 4 + \dots 2^{h-1} = 2^h - 1$$
  - Therefore:  
$$2^{h-1} \leq n \text{ and } n \leq 2^h - 1$$
  - Which implies that:  
$$\log(n + 1) \leq h \leq \log n + 1$$
  - Which in turn implies:  
$$h = \lceil \log(n+1) \rceil$$
  - Q.E.D.

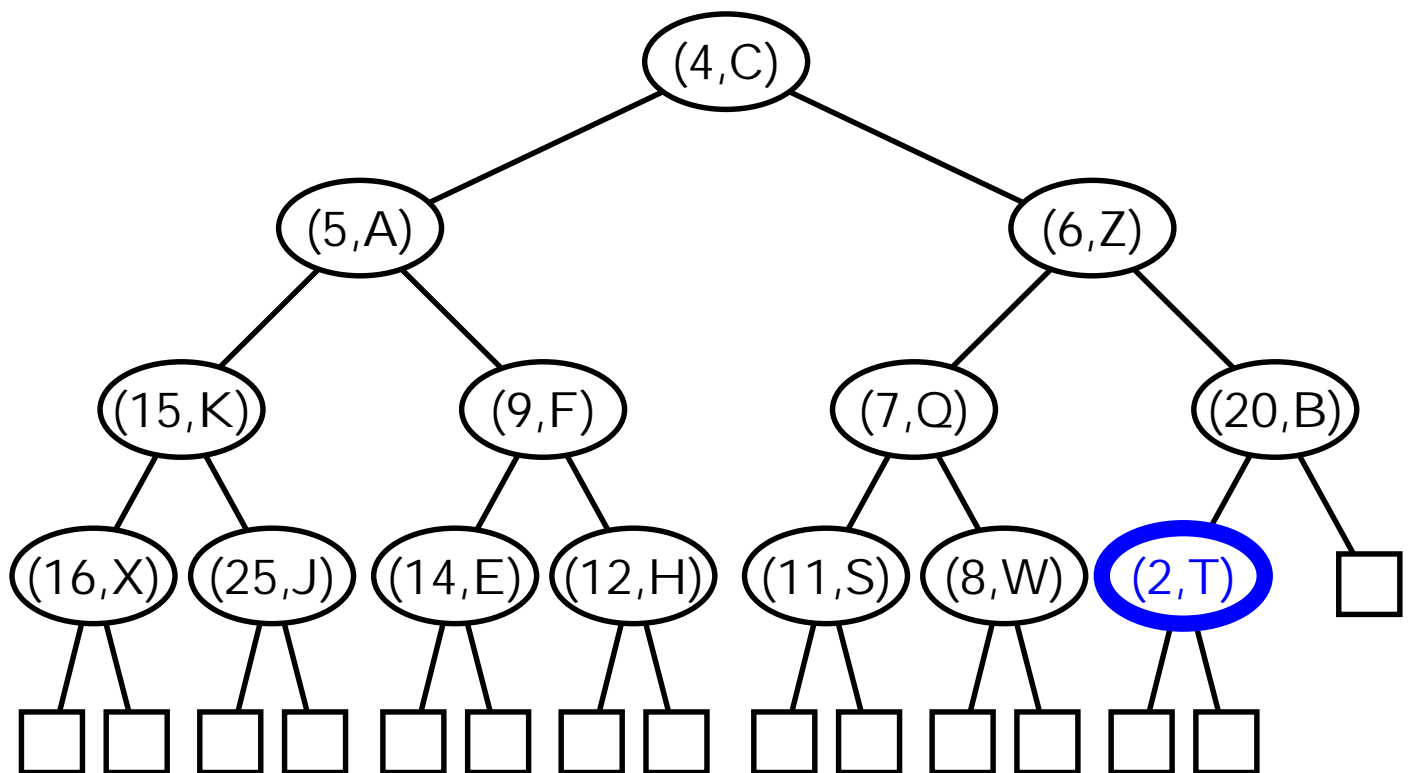
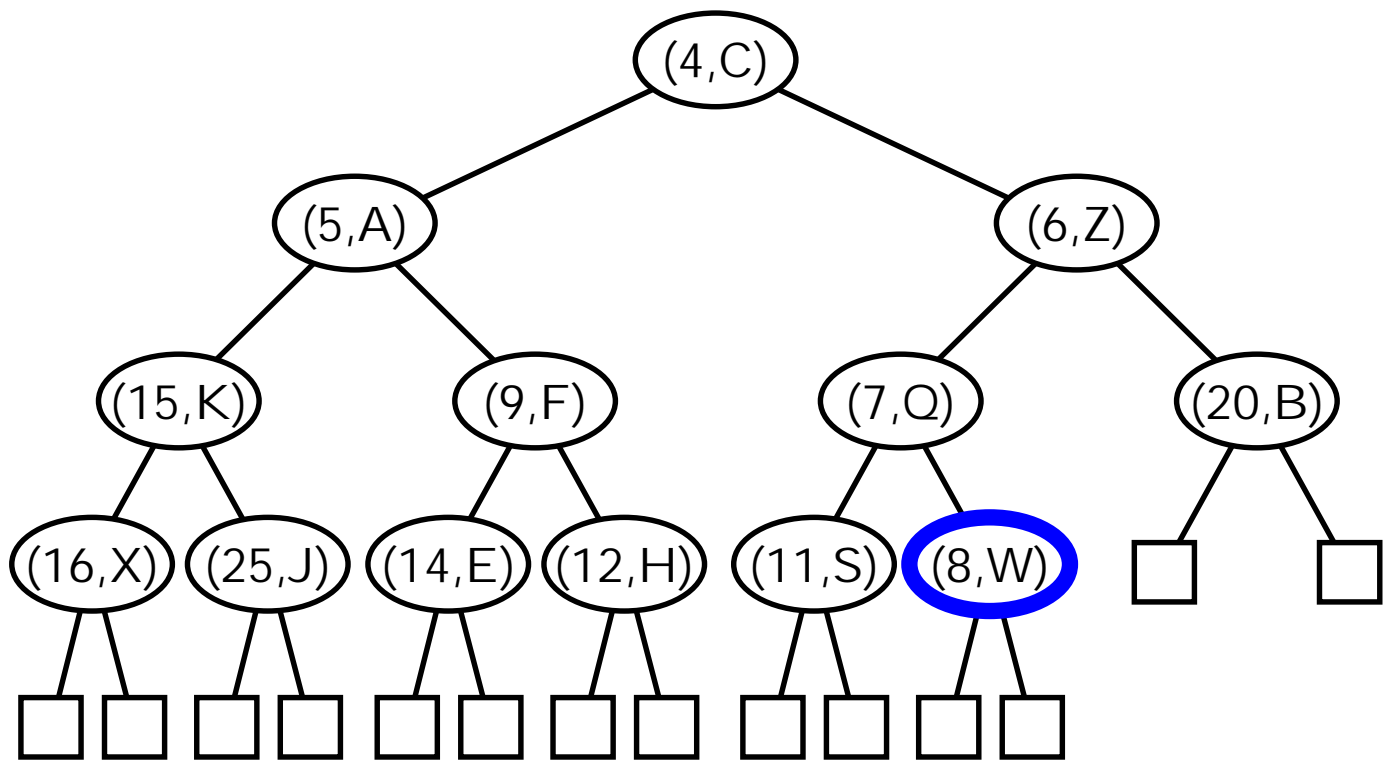
# Heigh of a Heap (contd.)

- Let's look at that graphically:

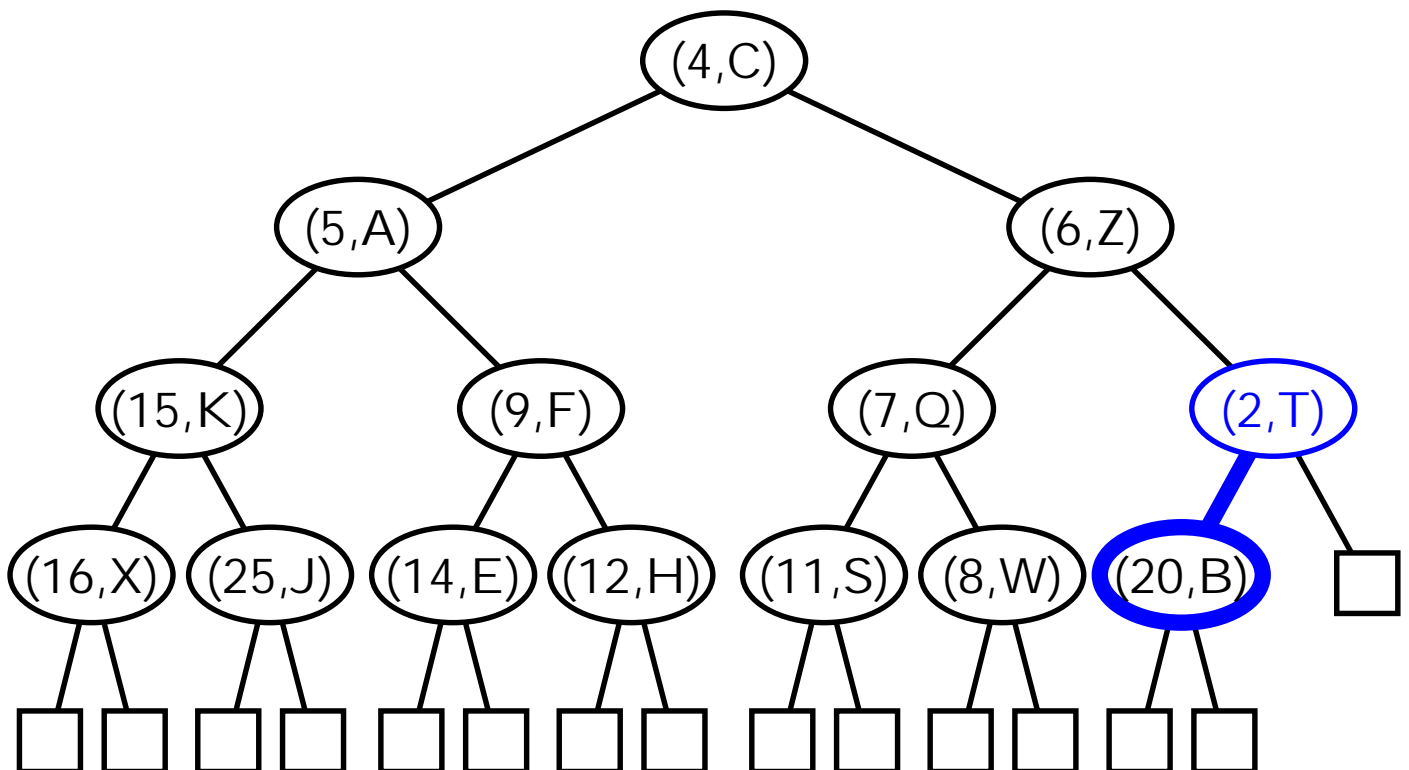
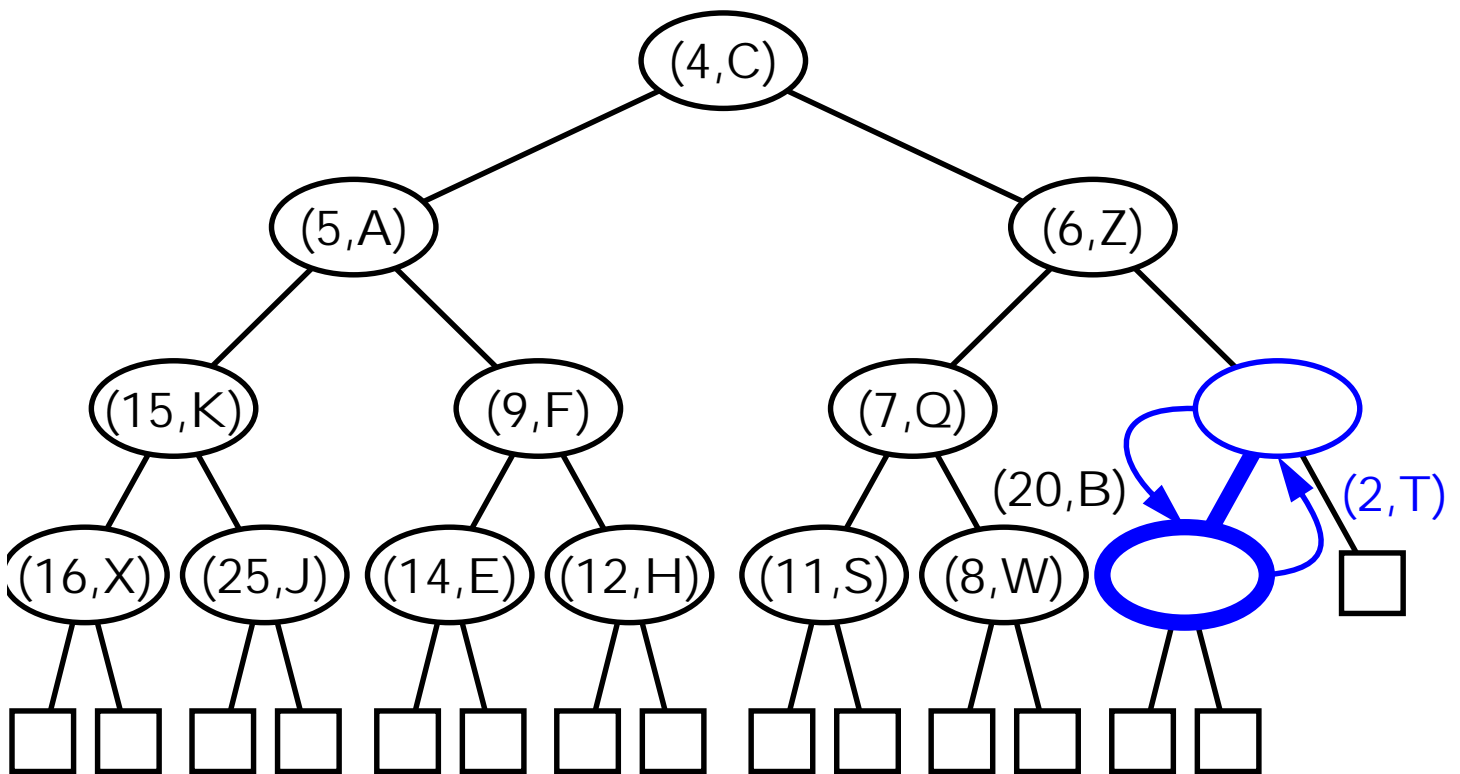


- Consider this heap which has height  $h = 4$  and  $n = 13$
- Suppose two more nodes are added. To maintain completeness of the tree, the two external nodes in level 4 will become internal nodes: i.e.  
 $n = 15, h = 4 = \log(15+1)$
- Add one more:  $n = 16, h = 5 = \lceil \log(16+1) \rceil$

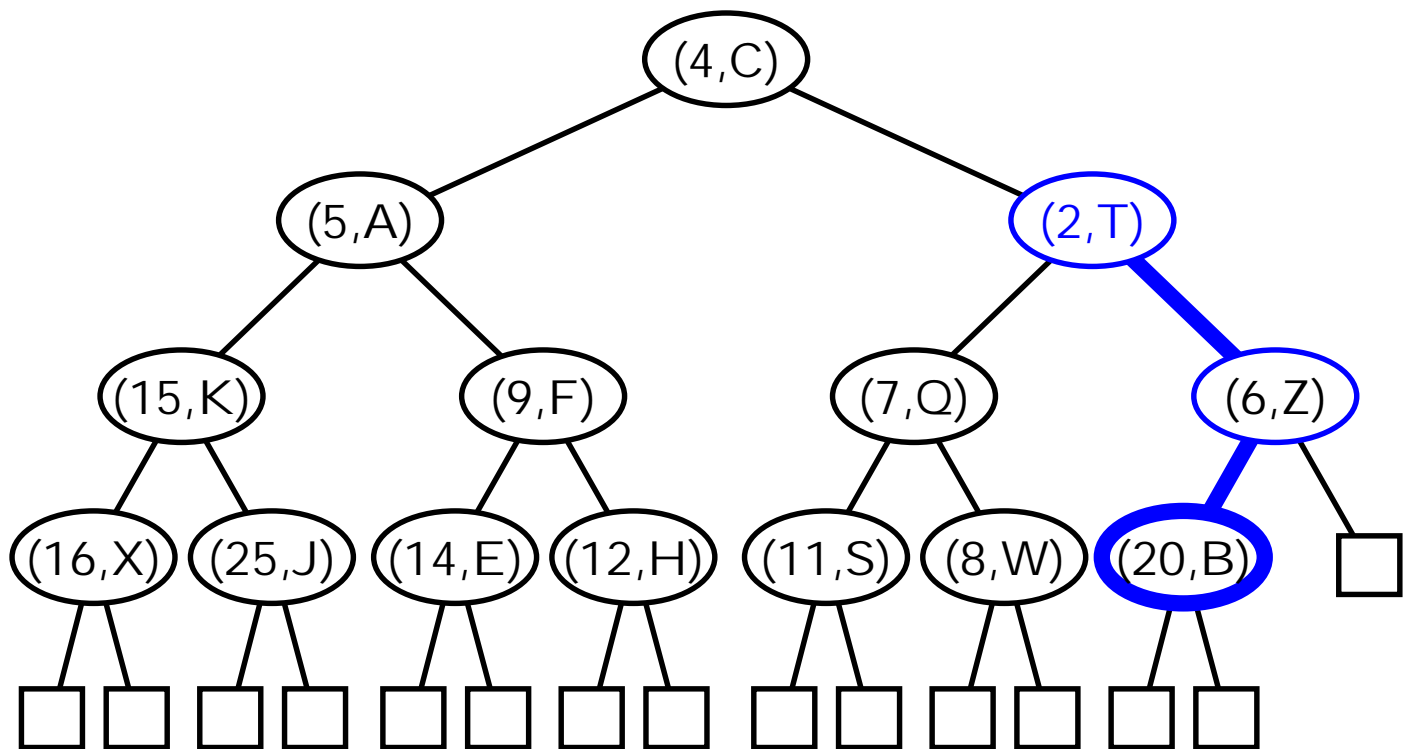
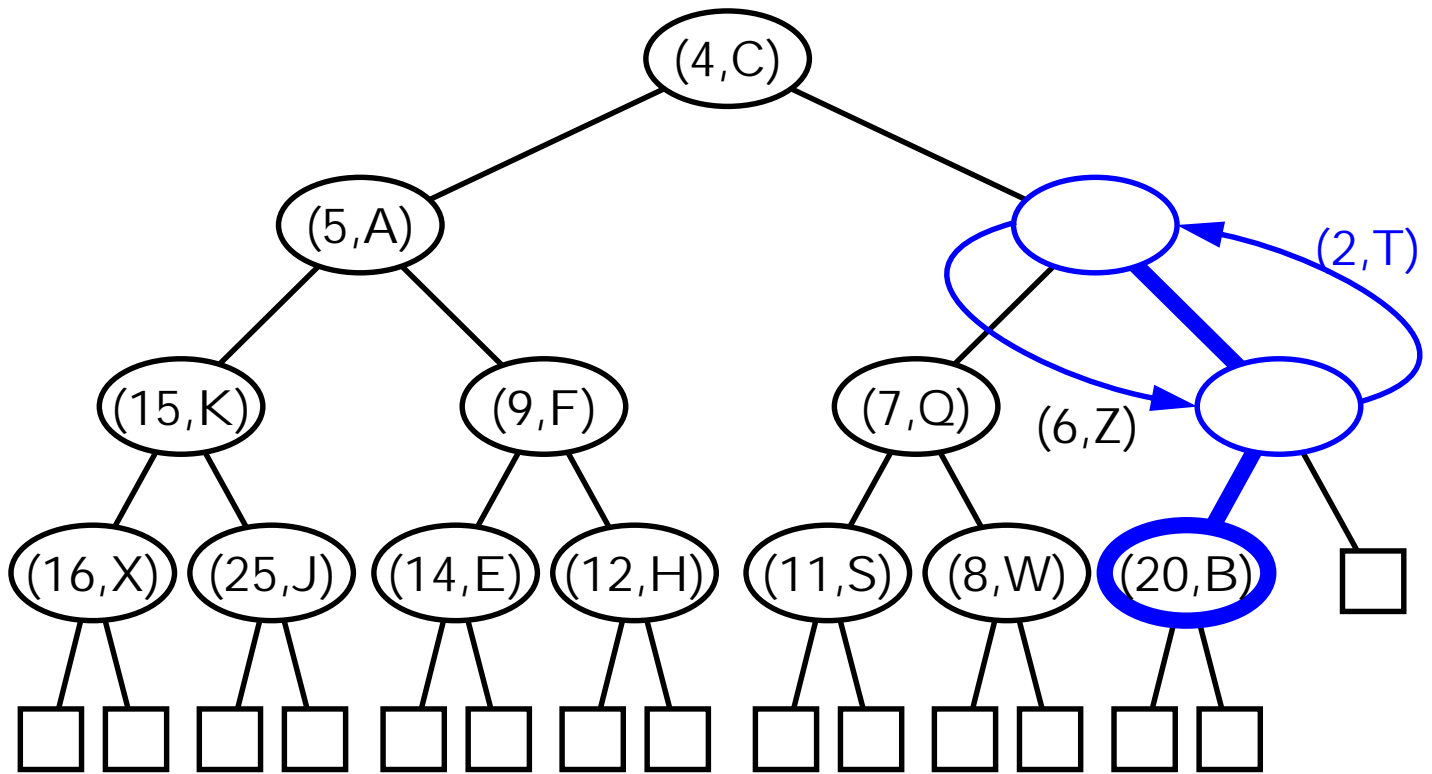
# Insertion into a Heap



# Insertion into a Heap (cont.)

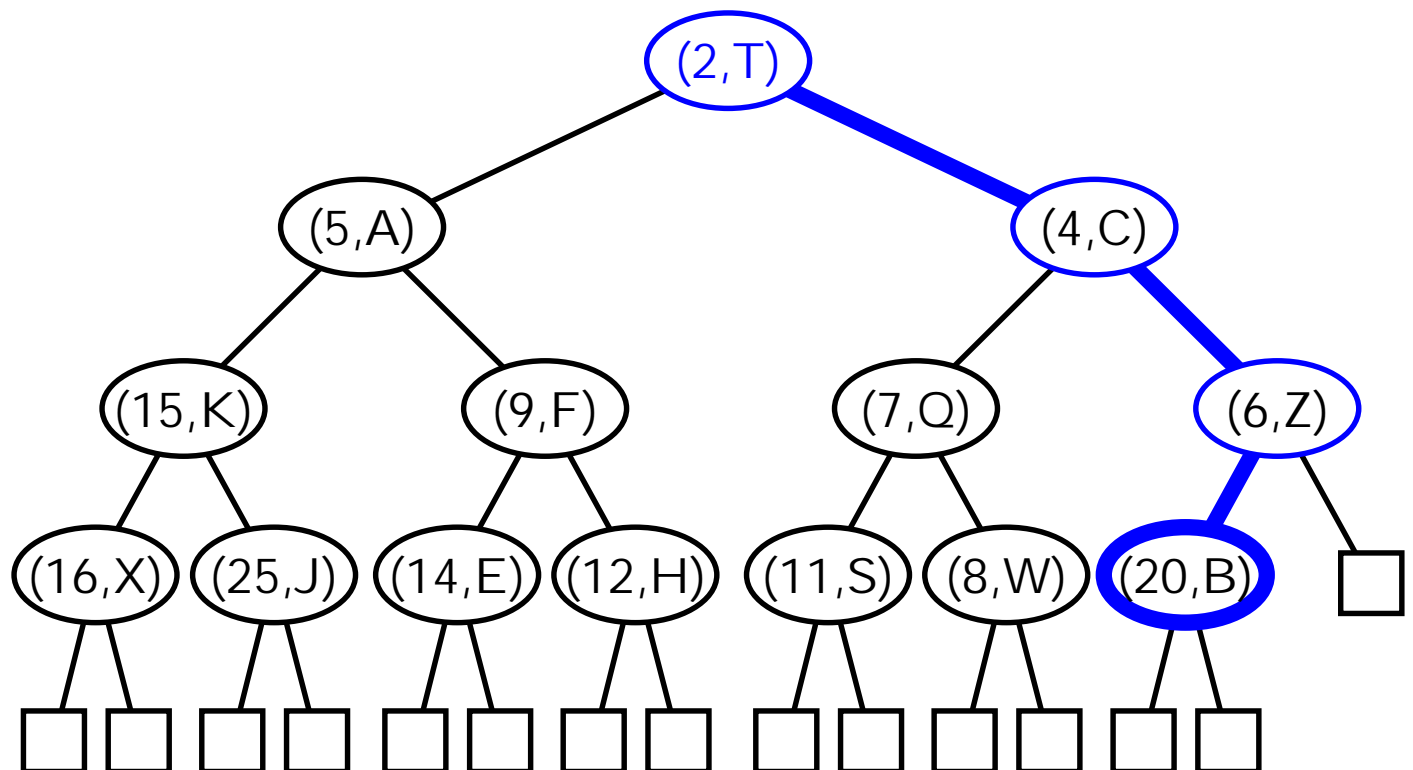
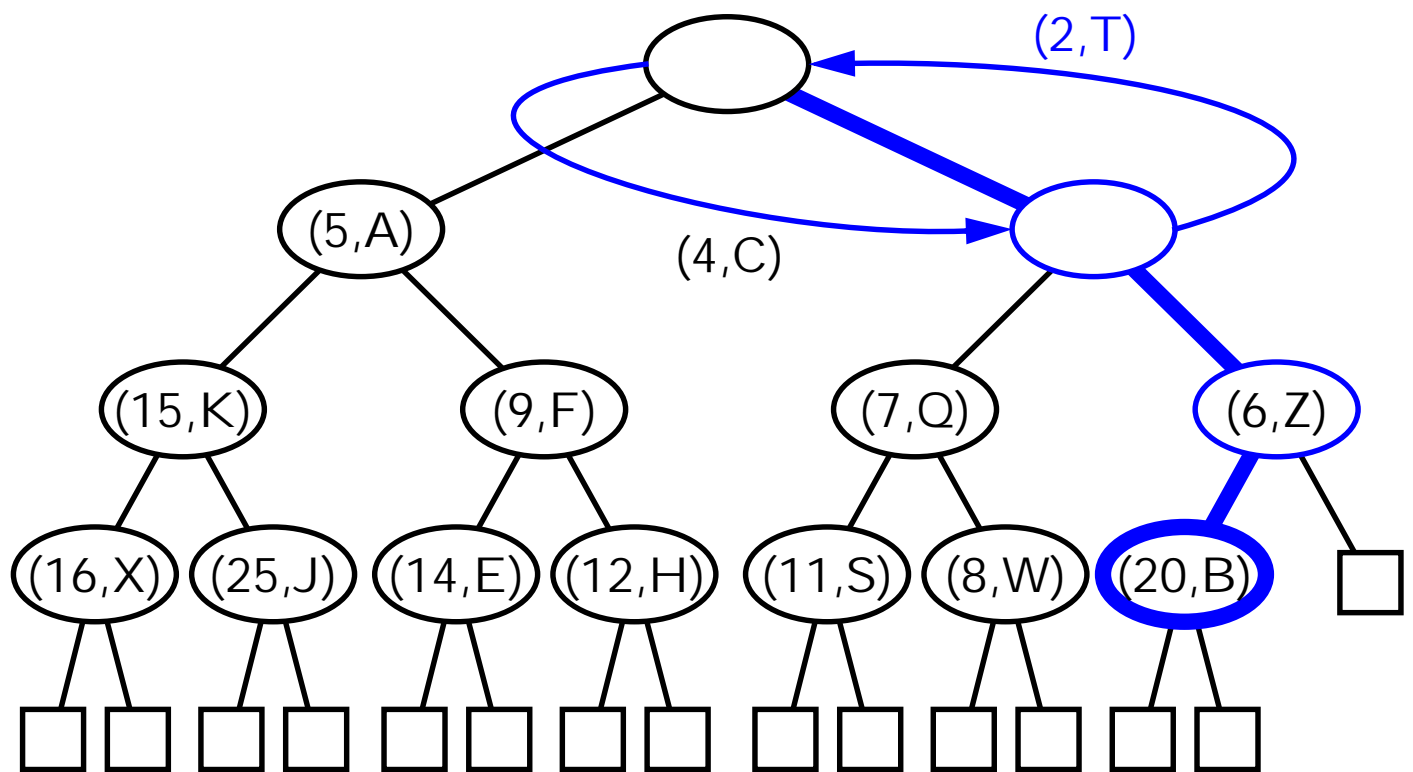


# Insertion into a Heap (cont.)

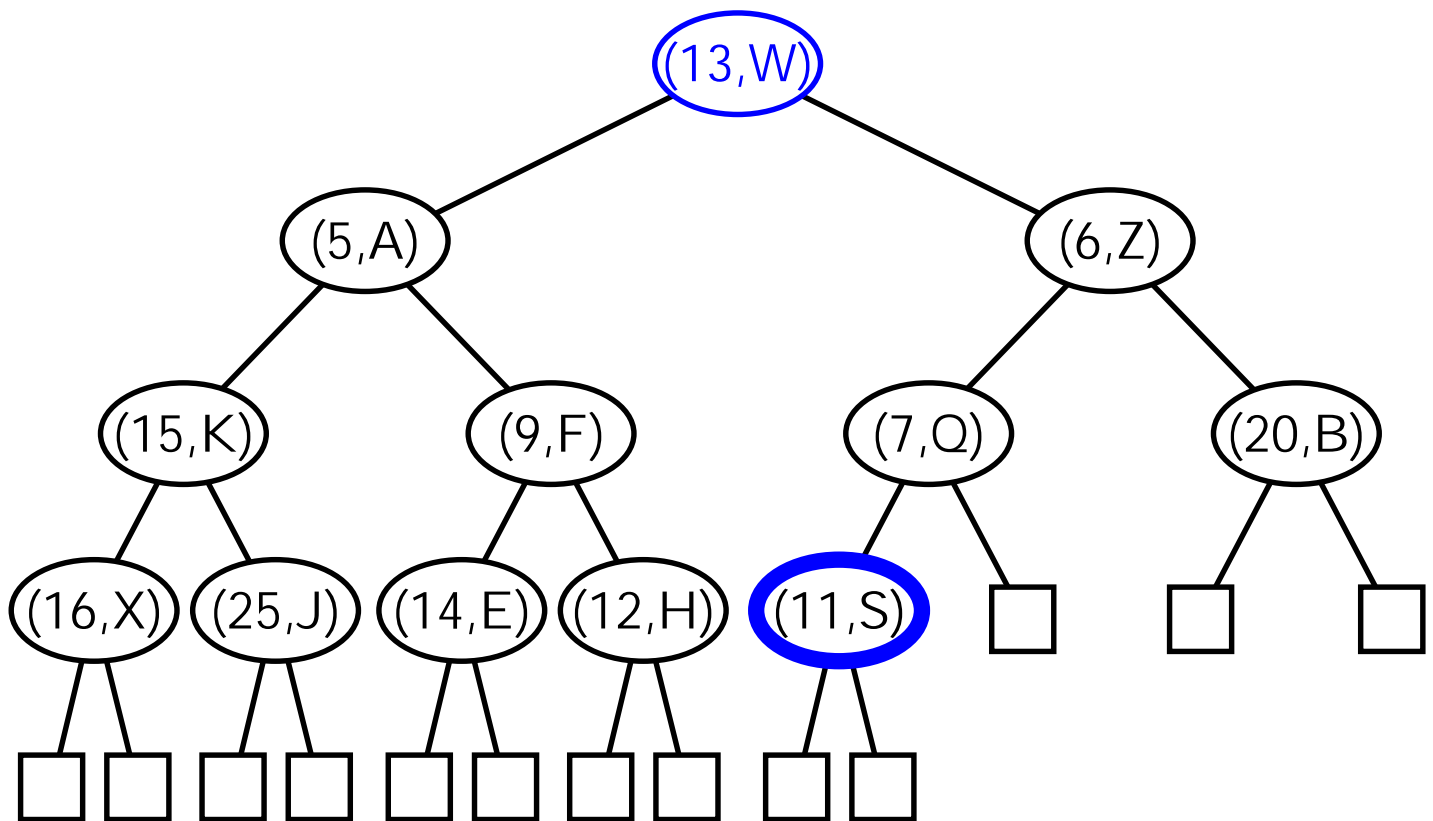
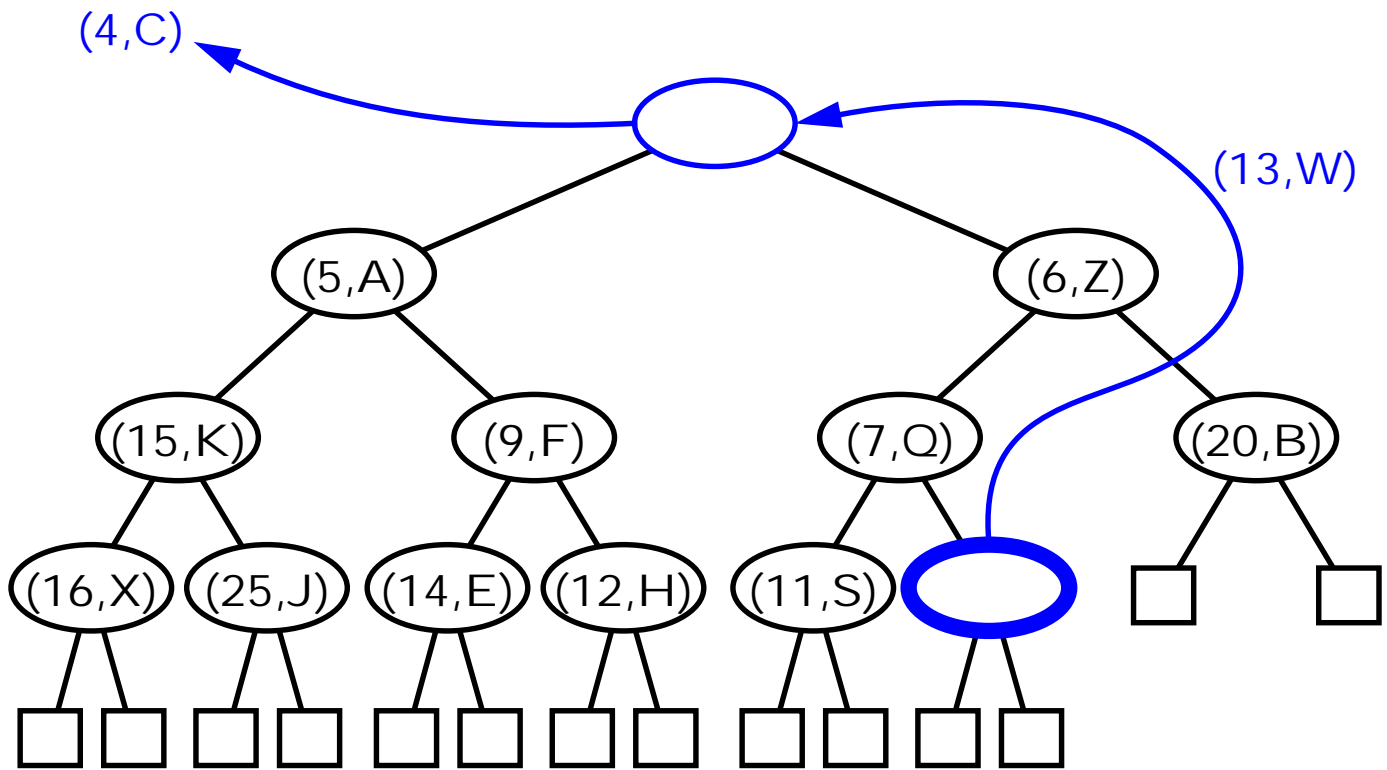




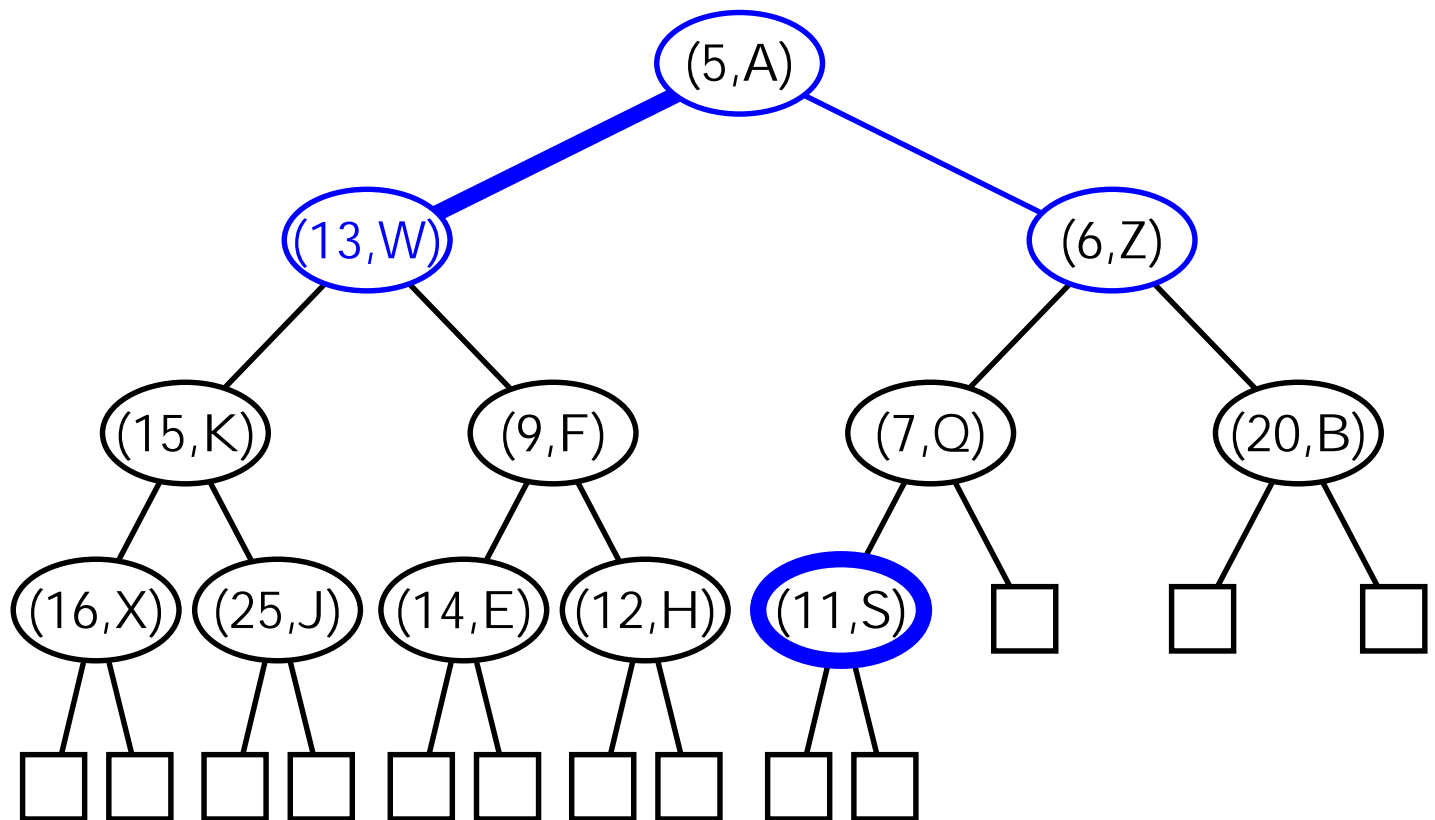
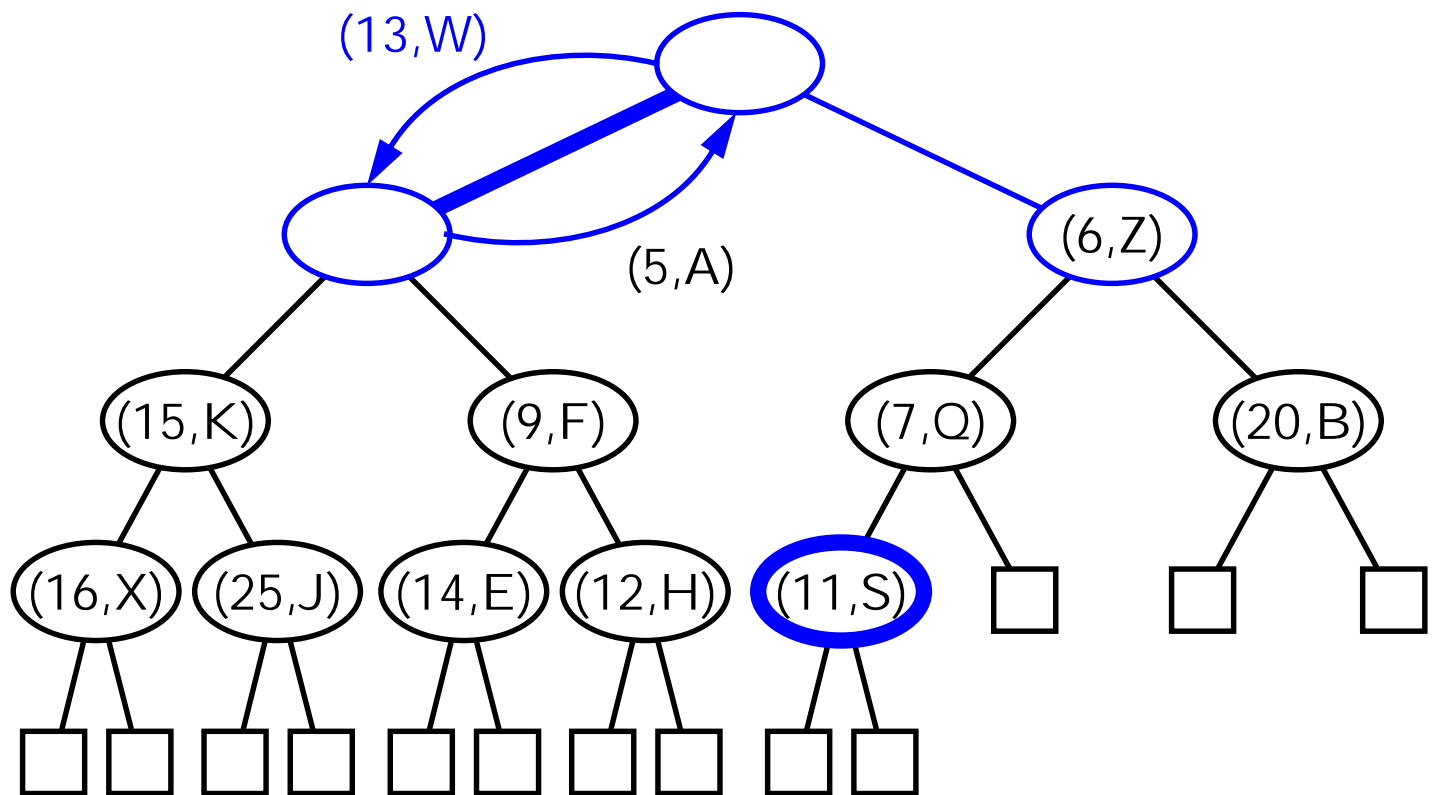
# Insertion into a Heap (cont.)



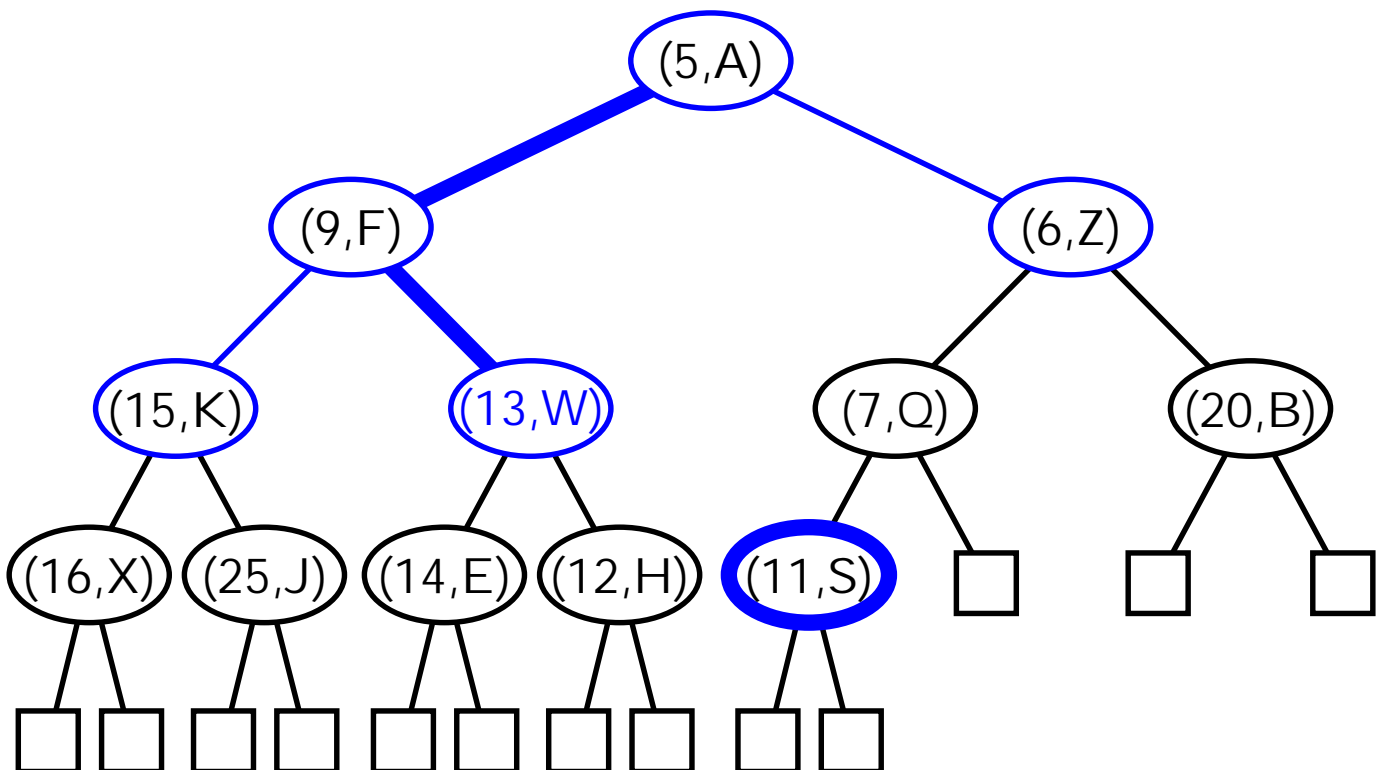
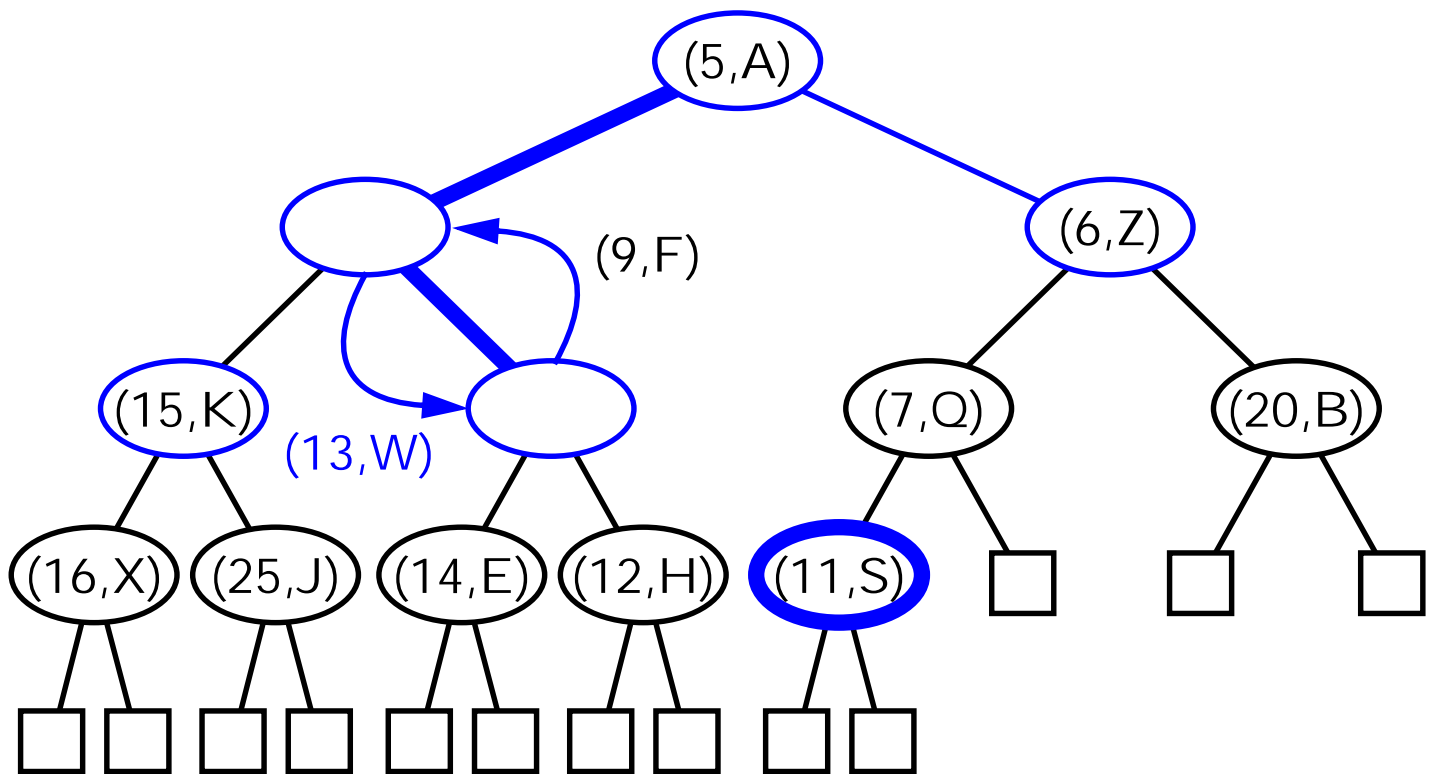
# Removal from a Heap



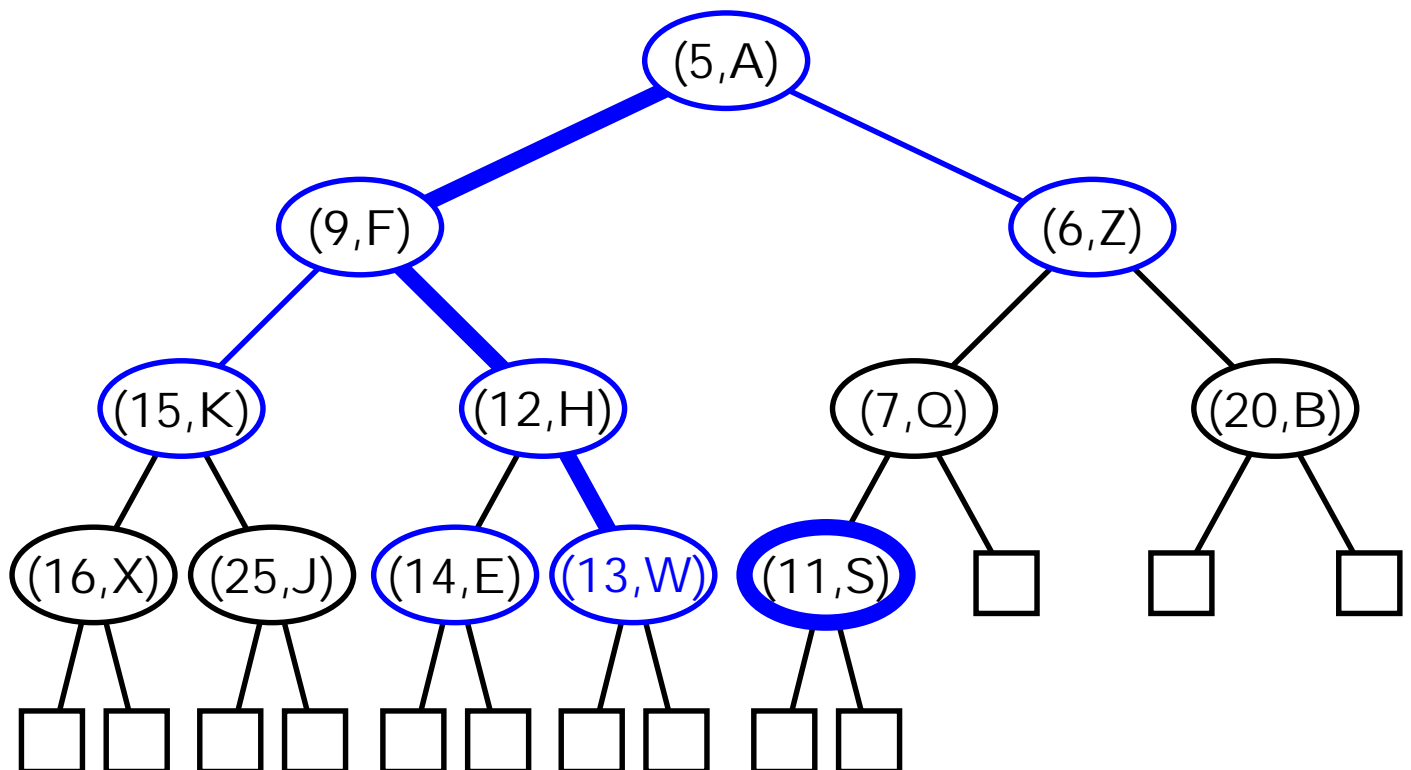
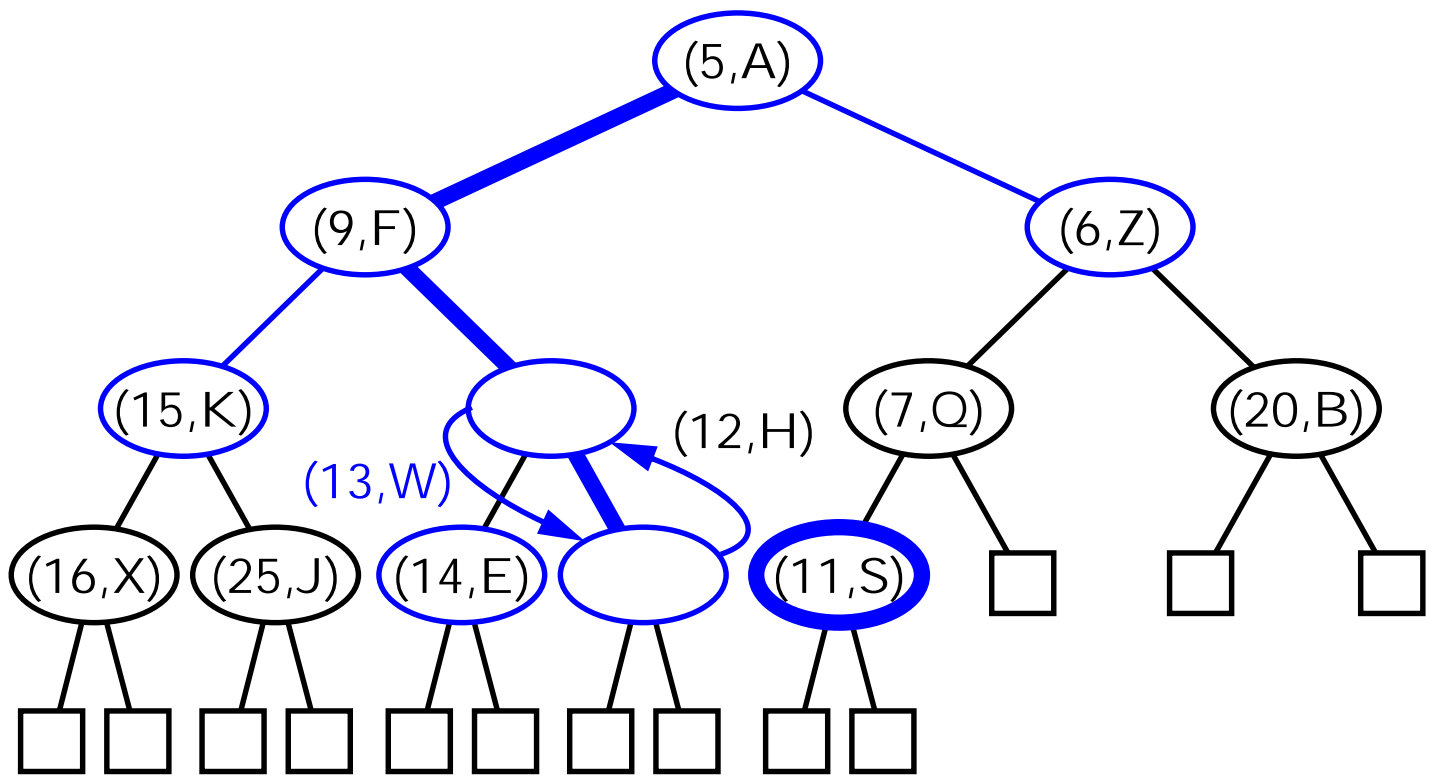
# Removal from a Heap (cont.)



# Removal from a Heap (cont.)

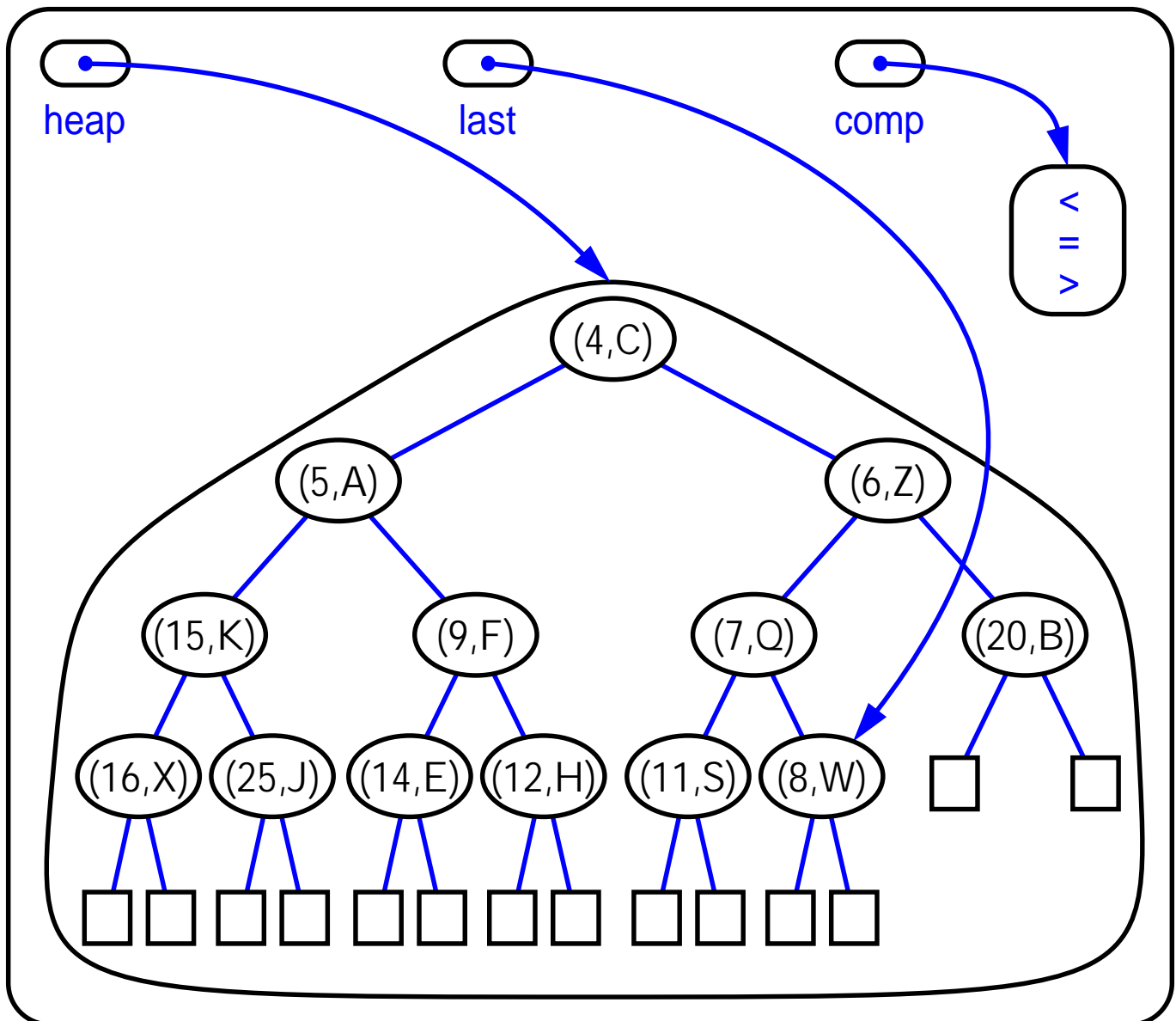


# Removal from a Heap(cont.)



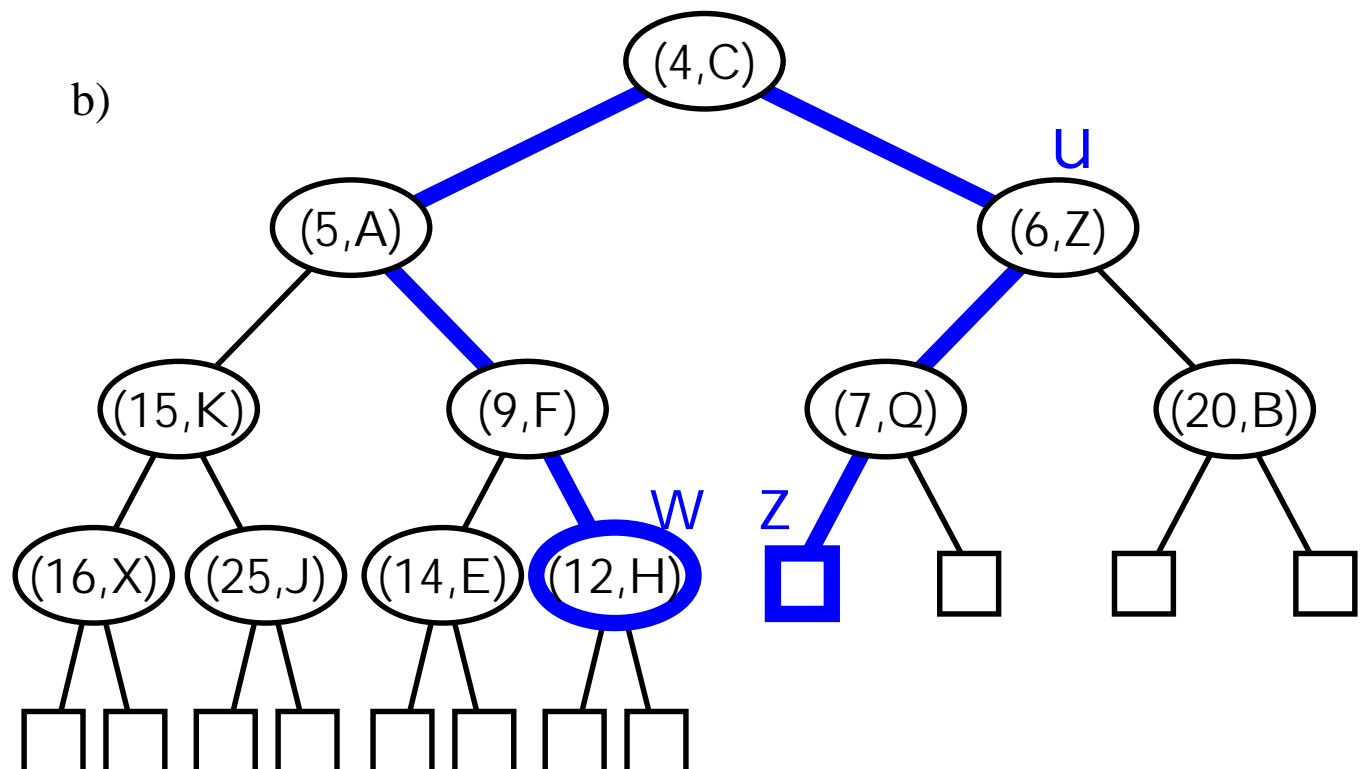
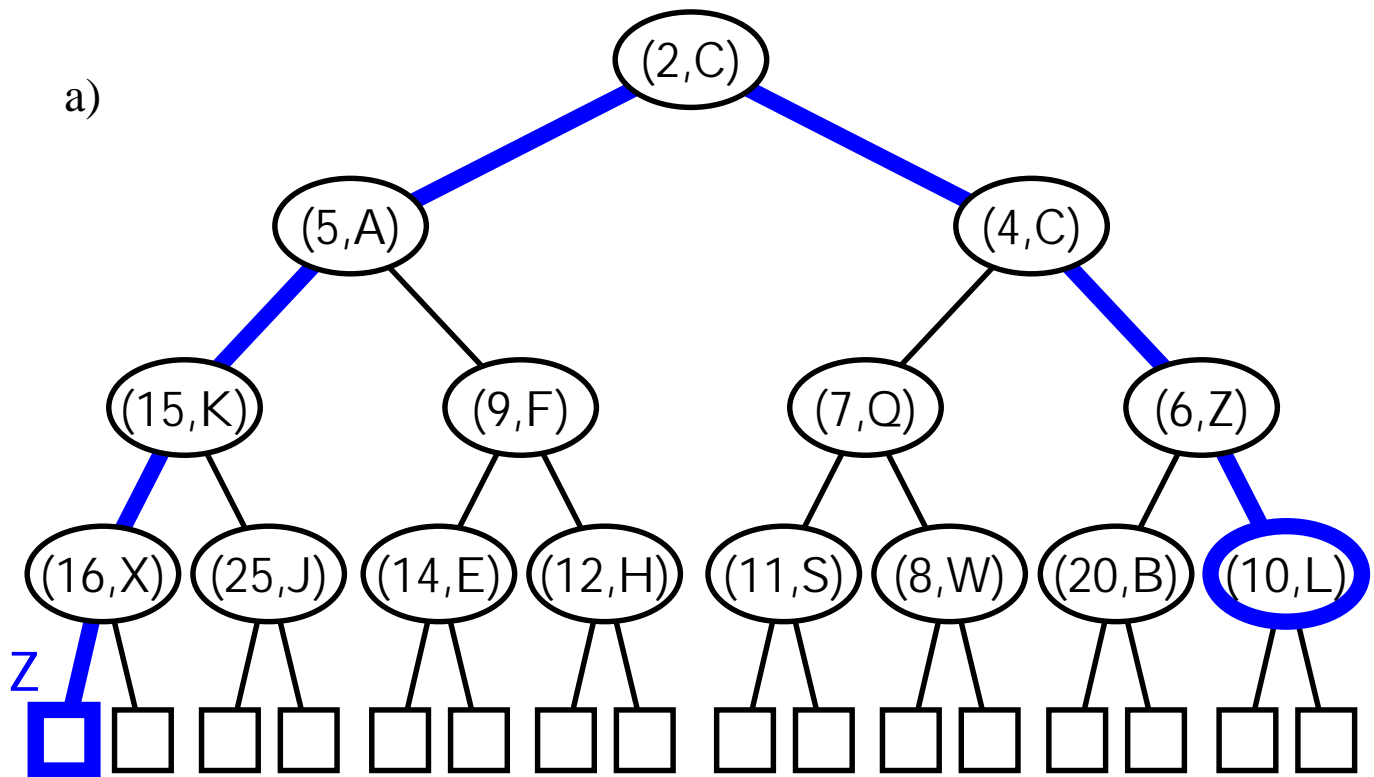
# Implementation of a Heap

```
public class HeapSimplePriorityQueue implements  
    SimplePriorityQueue {  
    BinaryTree T;  
    Position last;  
    Comparator comparator;  
    ...  
}
```



# Implementation of a Heap(cont.)

- Two ways to find the insertion position  $z$  in a heap:



# Heap Sort

- All heap methods run in logarithmic time or better
- If we implement PriorityQueueSort using a heap for our priority queue, **insertItem** and **removeMinElement** each take  $O(\log k)$ ,  $k$  being the number of elements in the heap at a given time.
- We always have  $n$  or less elements in the heap, so the worst case time complexity of these methods is  $O(\log n)$ .
- Thus each phase takes  $O(n \log n)$  time, so the algorithm runs in  $O(n \log n)$  time also.
- This sort is known as **heap-sort**.
- The  $O(n \log n)$  run time of heap-sort is much better than the  $O(n^2)$  run time of selection and insertion sort.



# Bottom-Up Heap Construction

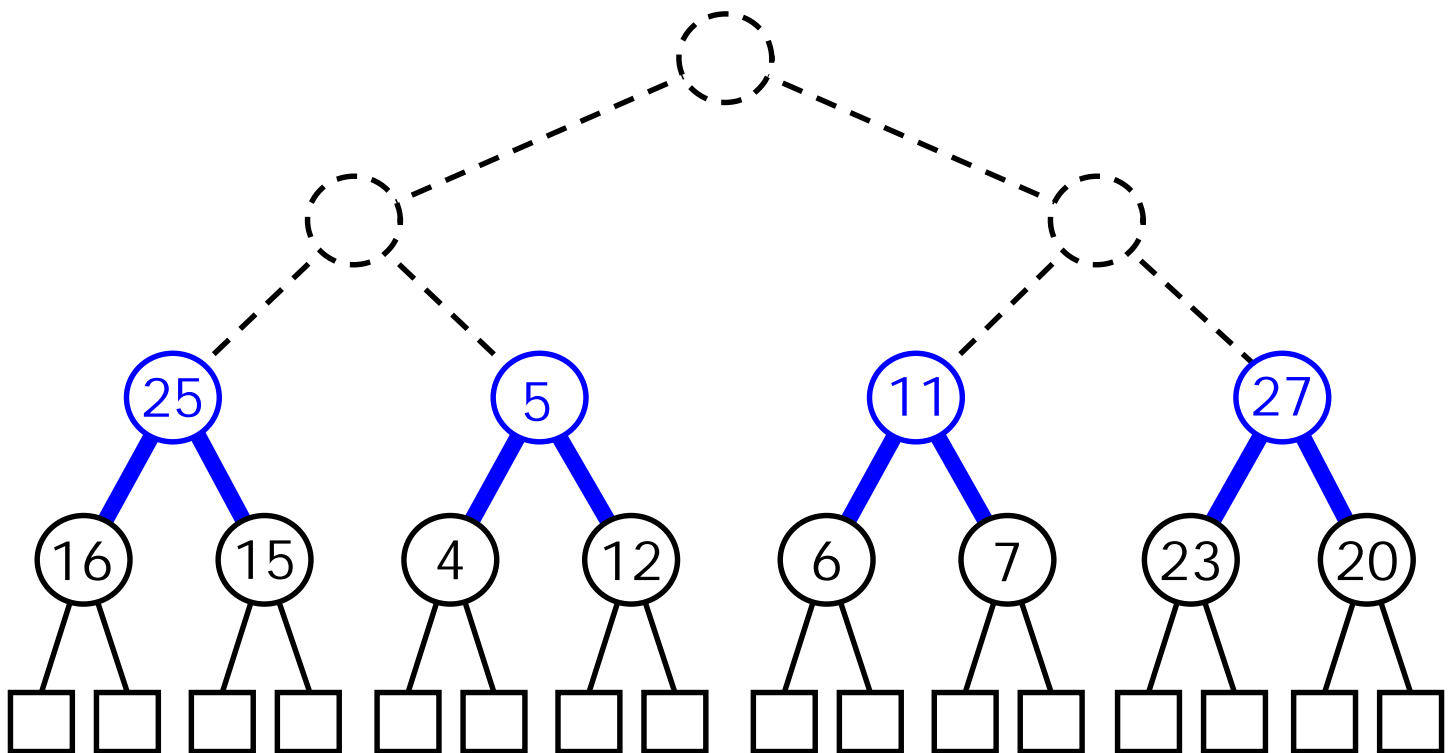
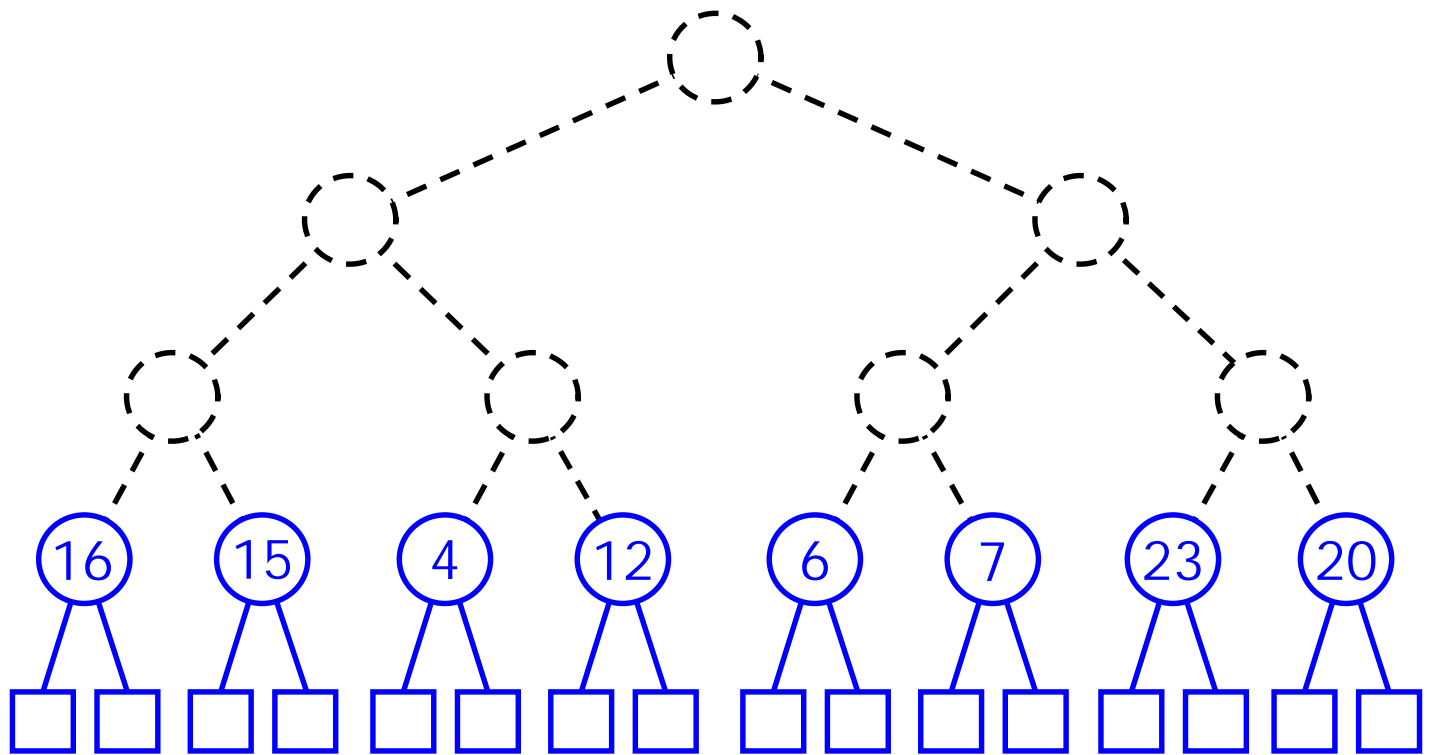
- If all the keys to be stored are given in advance we can build a heap **bottom-up** in  $O(n)$  time.
- Note: for simplicity, we describe bottom-up heap construction for the case for  $n$  keys where:

$$n = 2^h - 1$$

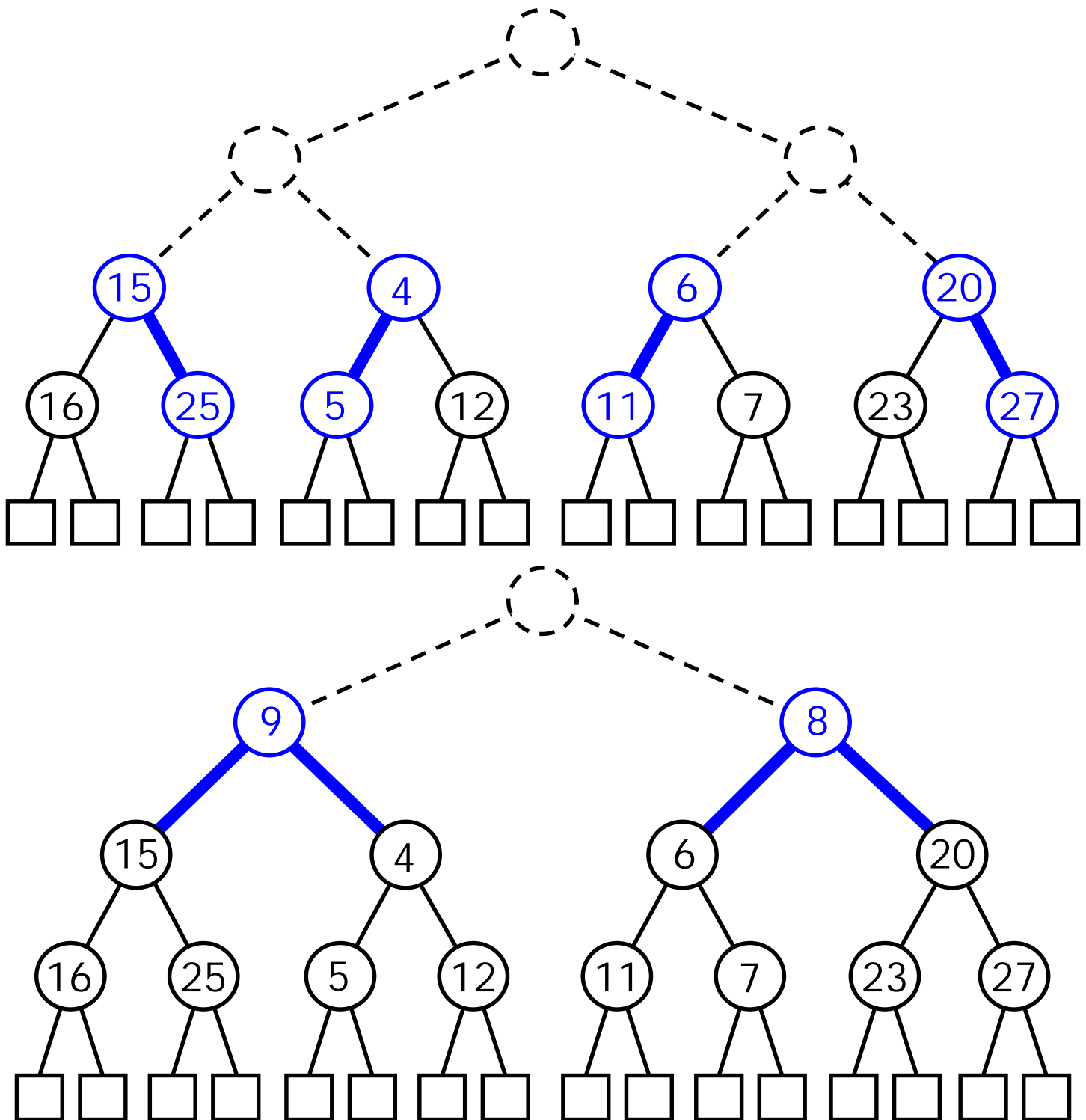
$h$  being the height.

- Steps:
  - 1) Construct  $(n+1)/2$  elementary heaps with one key each.
  - 2) Construct  $(n+1)/4$  heaps, each with 3 keys, by joining pairs of elementary heaps and adding a new key as the root. The new key may be swapped with a child in order to preserve heap-order property.
  - 3) Construct  $(n+1)/8$  heaps, each with 7 keys, by joining pairs of 3-key heaps and adding a new key. Again swaps may occur.
  - ...
  - 4) In the  $i$ th step,  $2 \leq i \leq h$ , we form  $(n+1)/2^i$  heaps, each storing  $2^i - 1$  keys, by joining pairs of heaps storing  $(2^{i-1} - 1)$  keys. Swaps may occur.

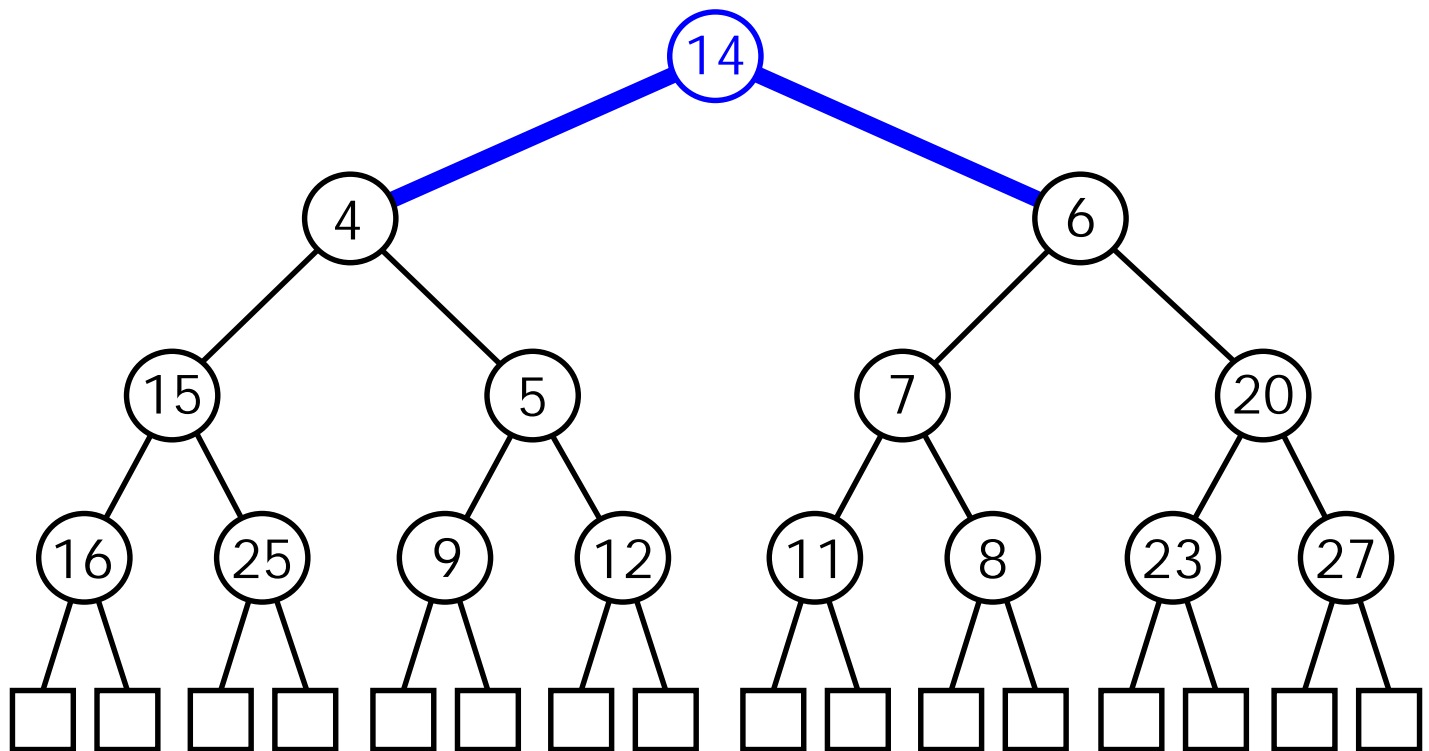
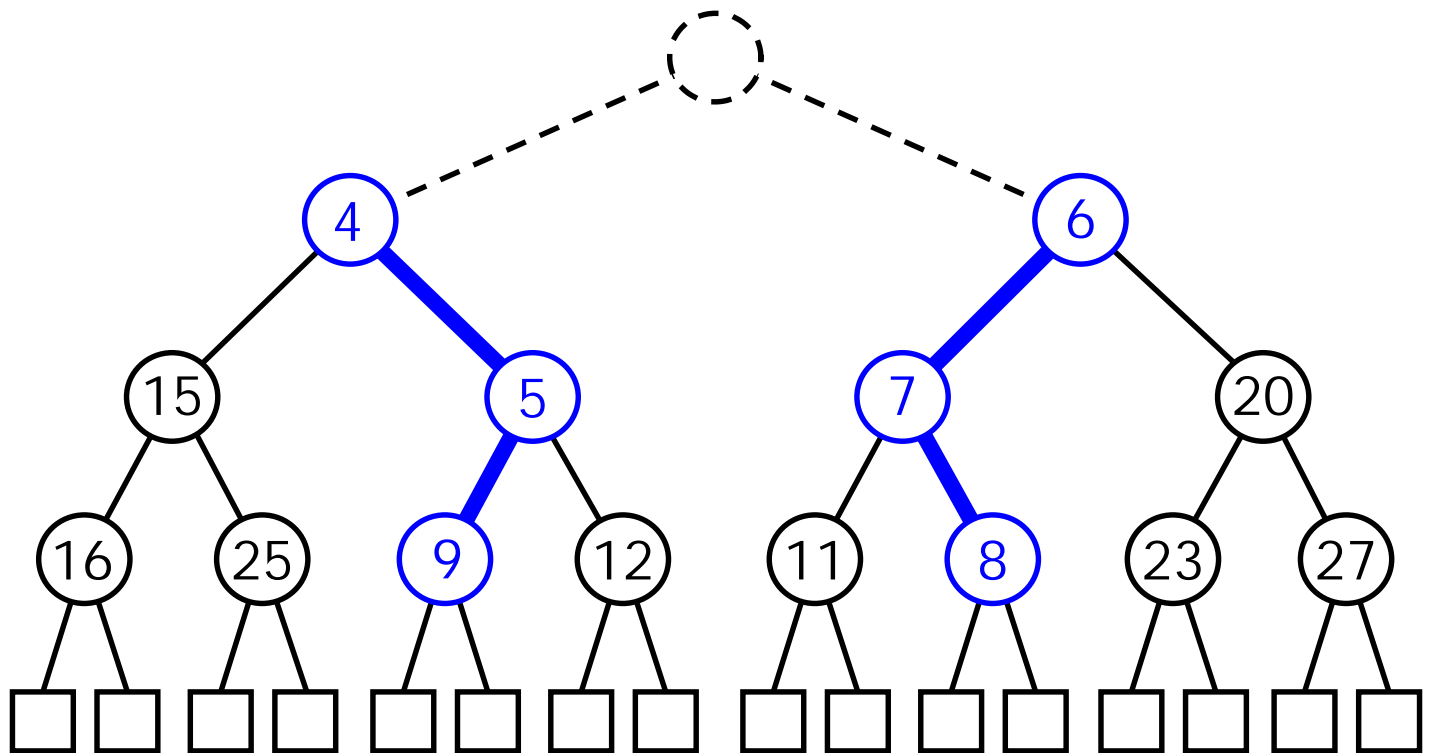
# Bottom-Up Heap Construction (cont.)



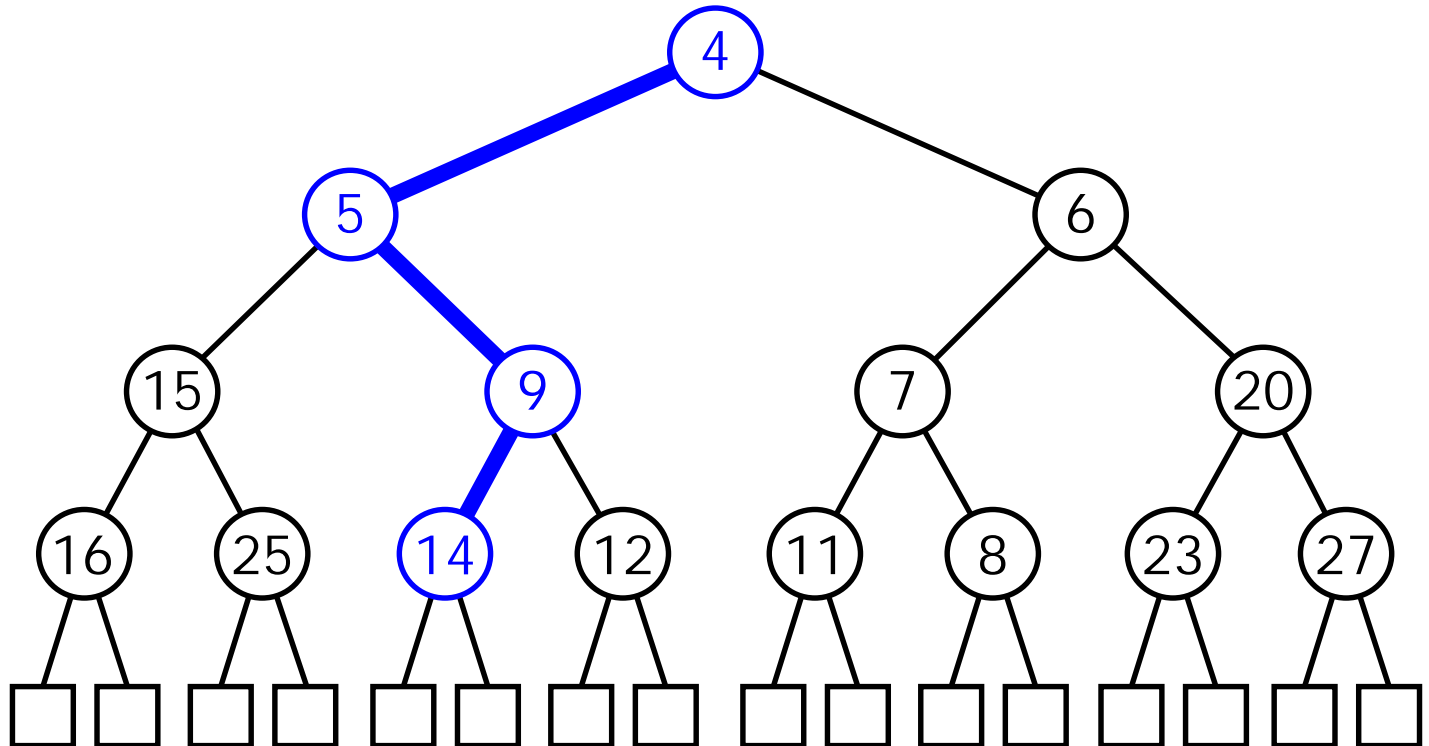
# Bottom-Up Heap Construction (cont.)



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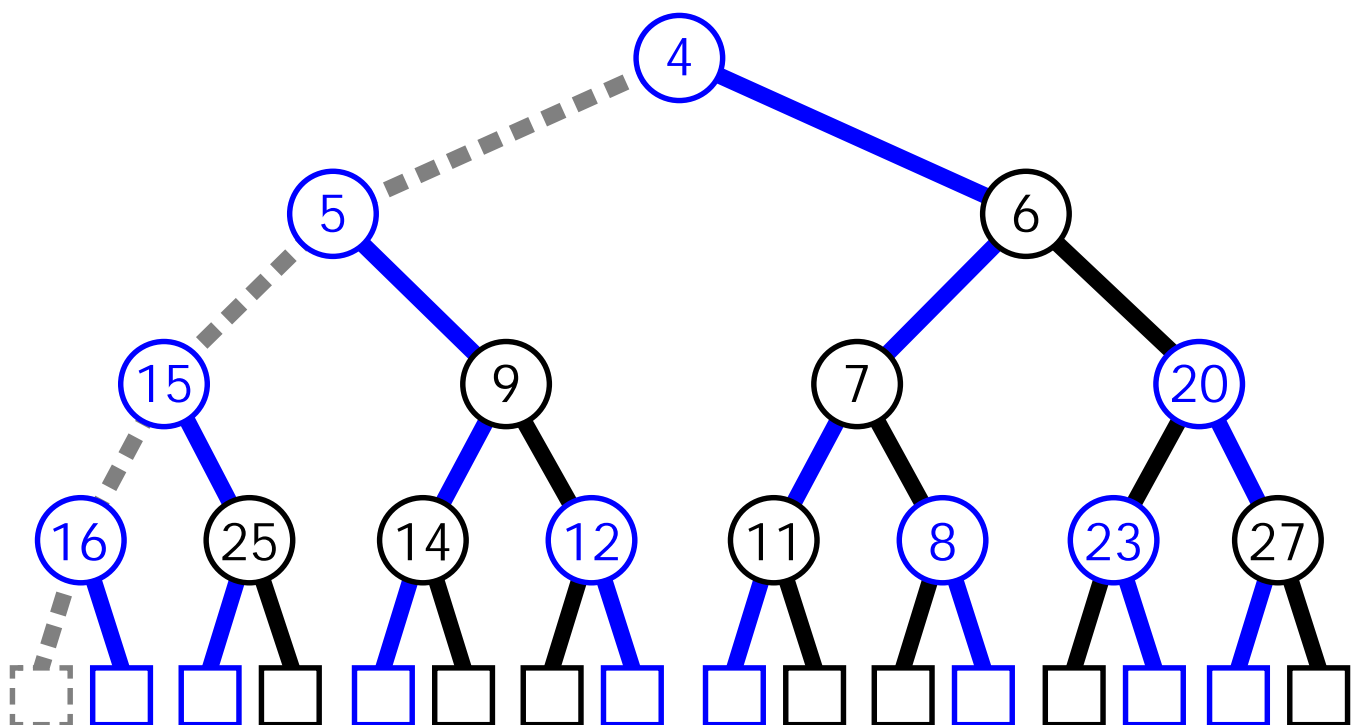
# Bottom-Up Heap Construction (cont.)



**The End**

# Analysis of Bottom-Up Heap Construction

- **Proposition:** Bottom-up heap construction with  $n$  keys takes  $O(n)$  time.
  - Insert  $(n + 1)/2$  nodes
  - Insert  $(n + 1)/4$  nodes
  - Upheap at most  $(n + 1)/4$  nodes 1 level.
  - Insert  $(n + 1)/8$  nodes
  - ...
  - Insert 1 node.
  - Upheap at most 1 node 1 level.



- $n$  inserts,  $n/2$  upheaps of 1 level =  $O(n)$