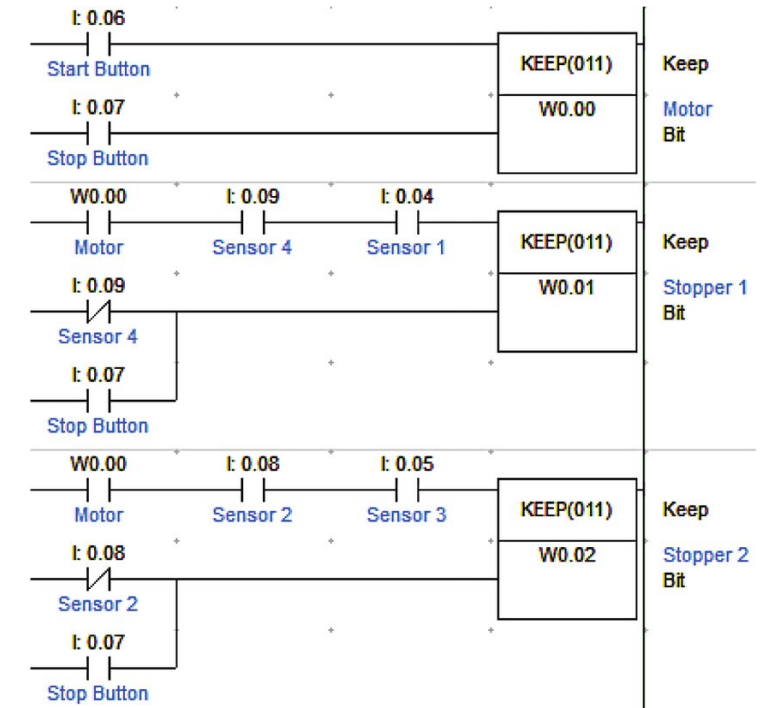


# Bio-inspired Autonomous Systems

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# (Very) classic robotics





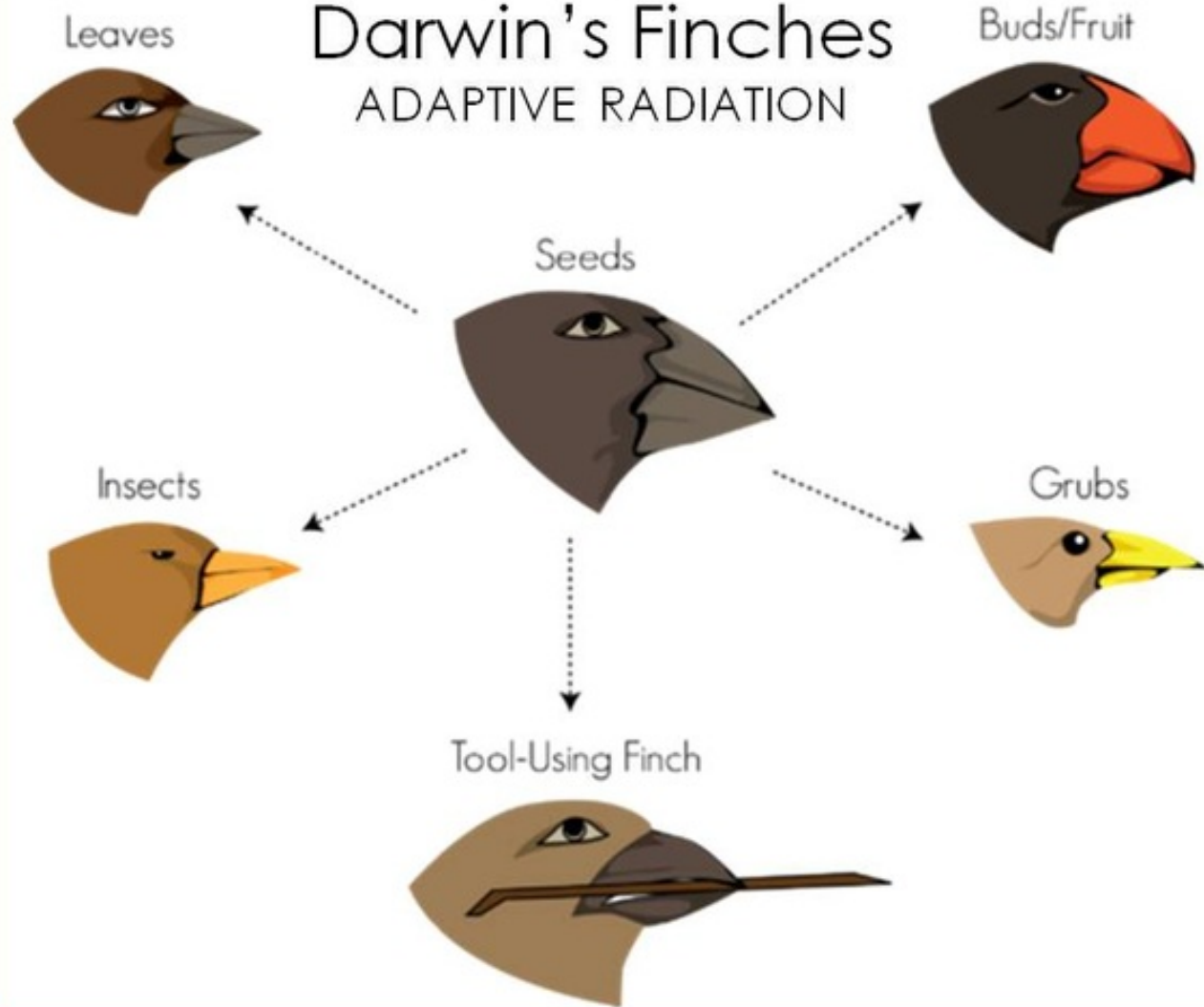




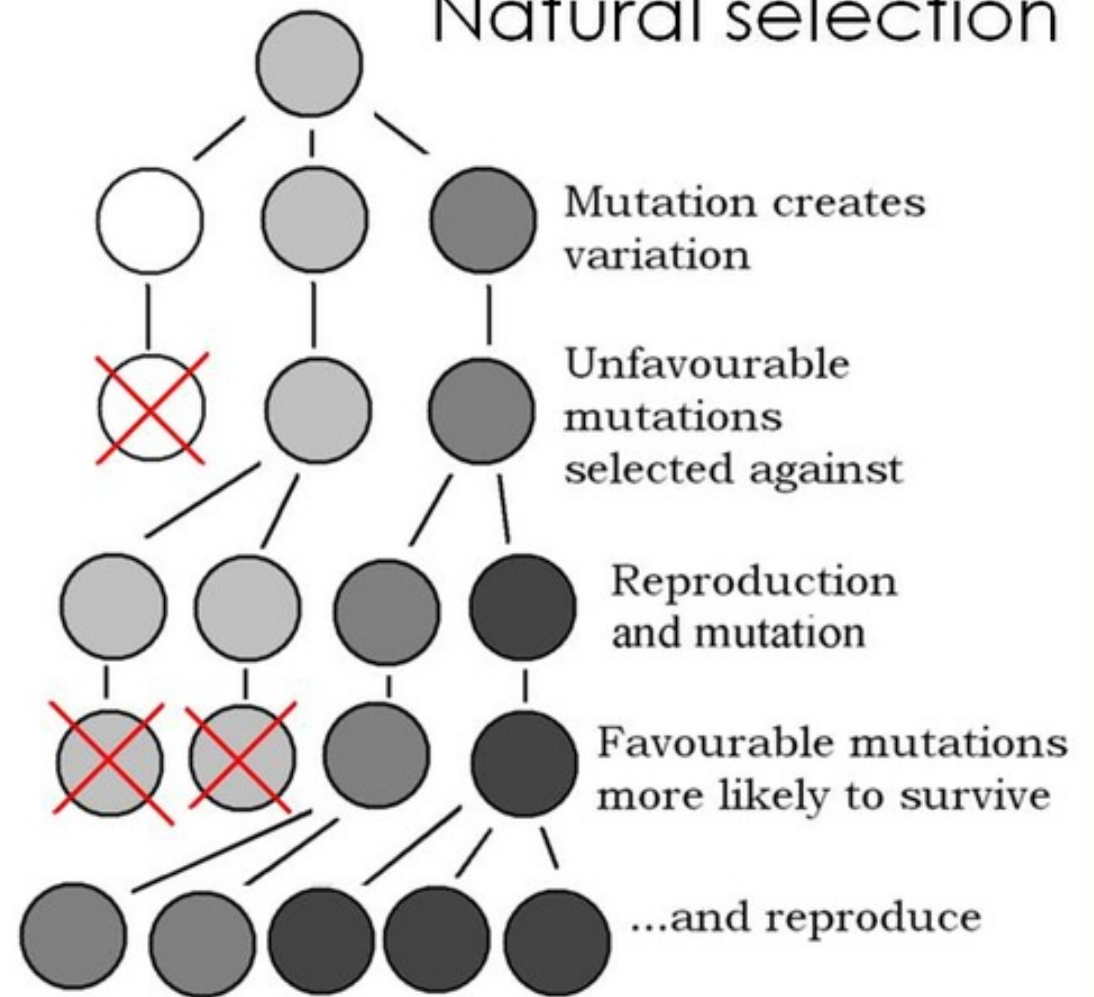




## Darwin's Finches ADAPTIVE RADIATION



## Natural selection



# World's first biologically-inspired robots (developed late 1940s)

Elmer and Elsie (ELeCtroMEchanical Robot, Light-Sensitive)



William Grey Walter

From:

<https://www.machinedesign.com/mechanical-motion-systems/article/21835853/7-bioinspired-robots-that-mimic-nature>  
and [https://www.sdu.dk/en/forskning/sdu\\_biorobotics/projects/morf](https://www.sdu.dk/en/forskning/sdu_biorobotics/projects/morf)

# Bio-inspired robots



Octobot, Harvard



Snakebot, CMU



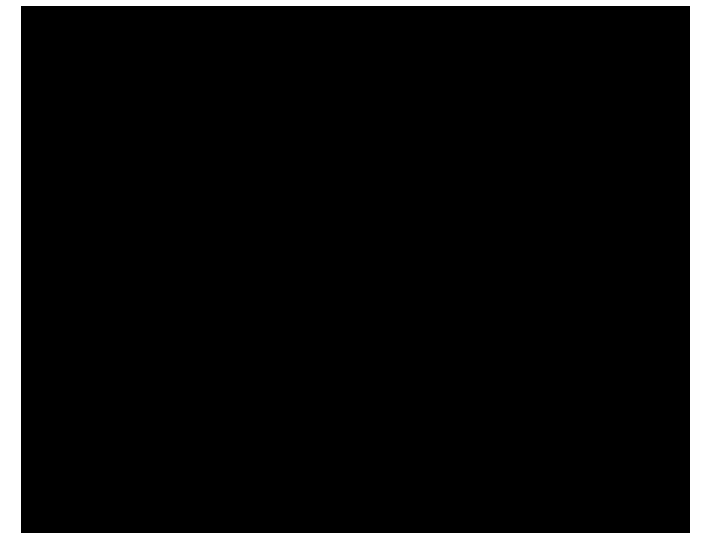
MORF, SDU



Festo's Bionic  
Cobot

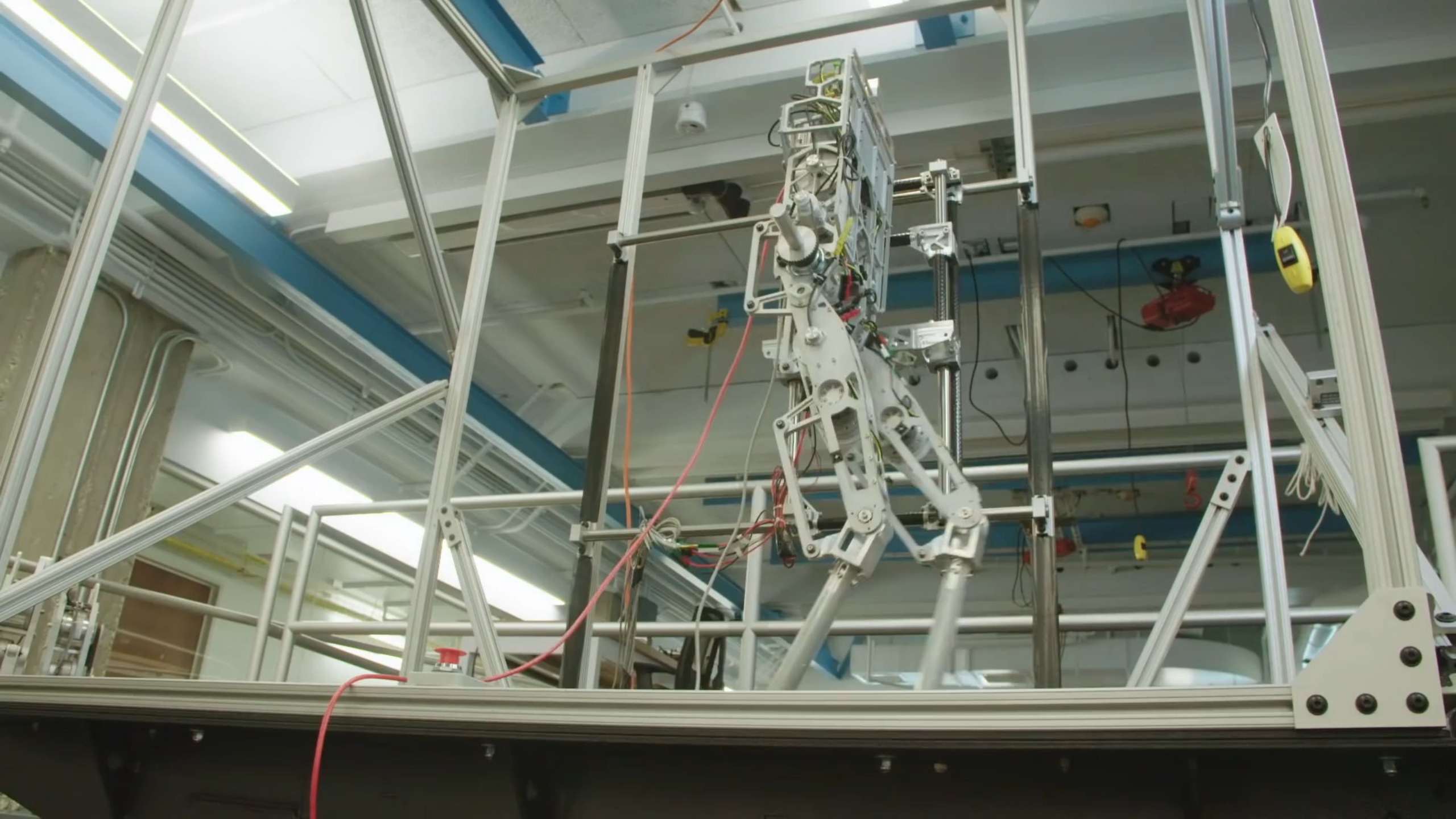


Spot mini, Boston Dynamics



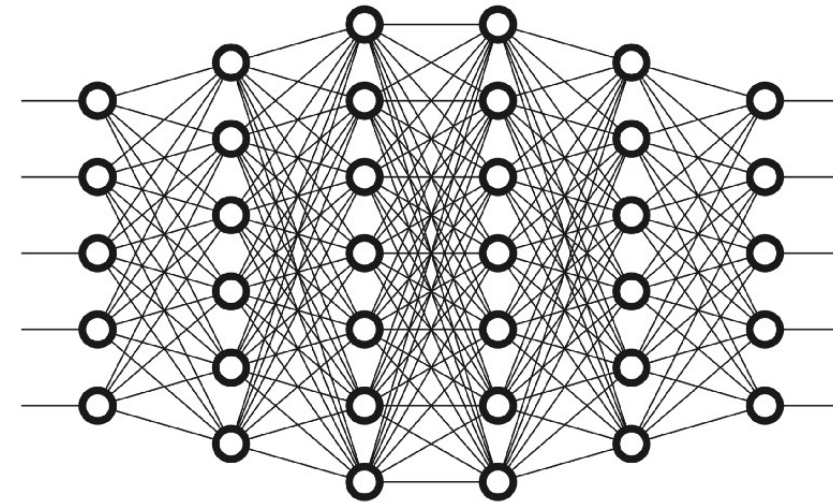
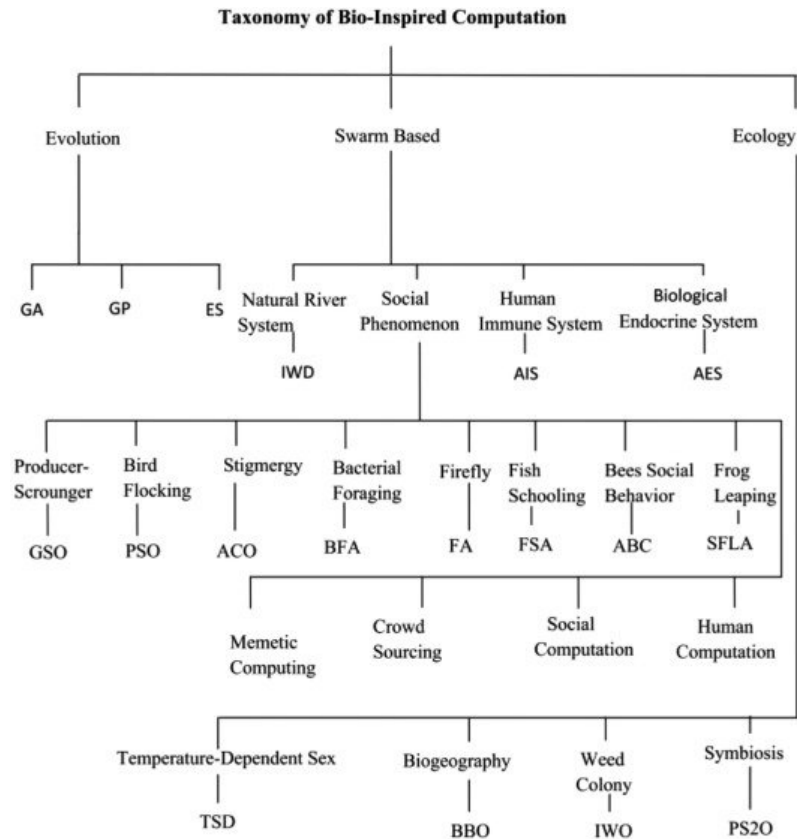
Agility Robotics







# Bio-inspired algorithms and models



Neural networks, deep NNs, spiking NNs, ...

See: Binitha, S., and S. Siva Sathya. "A survey of bio-inspired optimization algorithms." *International Journal of Soft Computing and Engineering* 2.2 (2012): 137-151.



# Structure of the course

Introductory week (this one)

Three weeks:

- Robot swarms and self-organization
- Soft robotics and intelligent materials
- Locomotion and control

Then an assignment in one of the above topics in groups.



# Evaluation

- Assignments due: May 17, 2026, 23h59
- Oral exam in June, project and course material:
  - Presentation (prepared slides)
  - Questions to presentation, Bio-inspired Autonomous Systems in general

Grading is on 7-point scale.



we will.



# Bioinspiration

See course page for paper

## 2. Biological systems and bioinspiration

### 2.1. Bioinspiration, molecules, materials, structures and functions

Because biology offers remarkable examples of new structures and processes at every scale, where should one focus? In biology, at all scales, *function* is the key idea: organisms cannot afford—in the great Darwinian competition—to decorate themselves with functionless features. By trying to mimic the behaviours and properties of living systems, we are therefore automatically engaged in mimicking functional processes and structures. ‘Bioinspiration’ thus leads—directly or indirectly—to function, some of which is useful to the organism, and some of which *might* be useful to us. Surrounding *function*, however, are other, more conceptual ideas that guide the selection of problems—and the design of appropriate research strategies—in bioinspired investigations.

### 2.2. Some characteristics of biology and bioinspiration

# ”Bio-inspired” copying, adaptation or derivation from biology

## Related terms

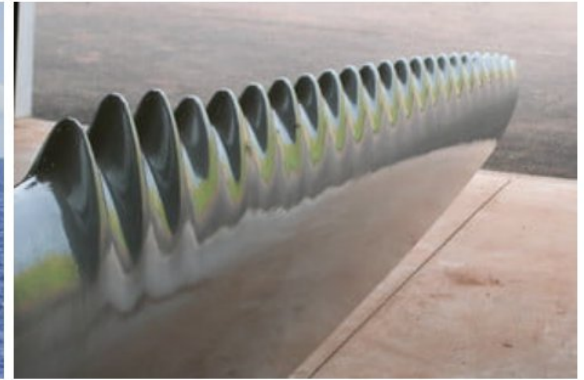
- **Biomimetics/biomimicry:** emulation of the models, systems, and elements of nature for the purpose of solving complex human problems.
- **Bionics:** Biology and electronics
- **Cybernetics:** circular causal feedback mechanisms. Norbert Wiener’s definition: “control and communication in the animal and the machine”



# Examples of bio-inspired designs



Nose of the Japanese bullet train modelled after the King Fisher's beak to avoid "tunnel boom".



Wind turbines modeled after Humpback whales



Ventilation systems inspired by termites

From: <https://www.digitaltrends.com/cool-tech/biomimicry-examples/>

# Topics covered in the course

- Collective behavior / swarm intelligence
- Materials
- Locomotion



# Today

- In groups of three students, find a paper on bio-inspired autonomous systems from 2025. You can use Google Scholar.
- Preferably a conference paper (6-8 pages) on a concrete study (e.g., not a survey paper).
- Read and discuss the paper.
- Prepare a four slides and a 3-minute presentation (see itslearning for template).

# Note

- No class next week
- Presentations should be ready for the class Feb. 17
- Class on Feb. 17 starts at 13.00.