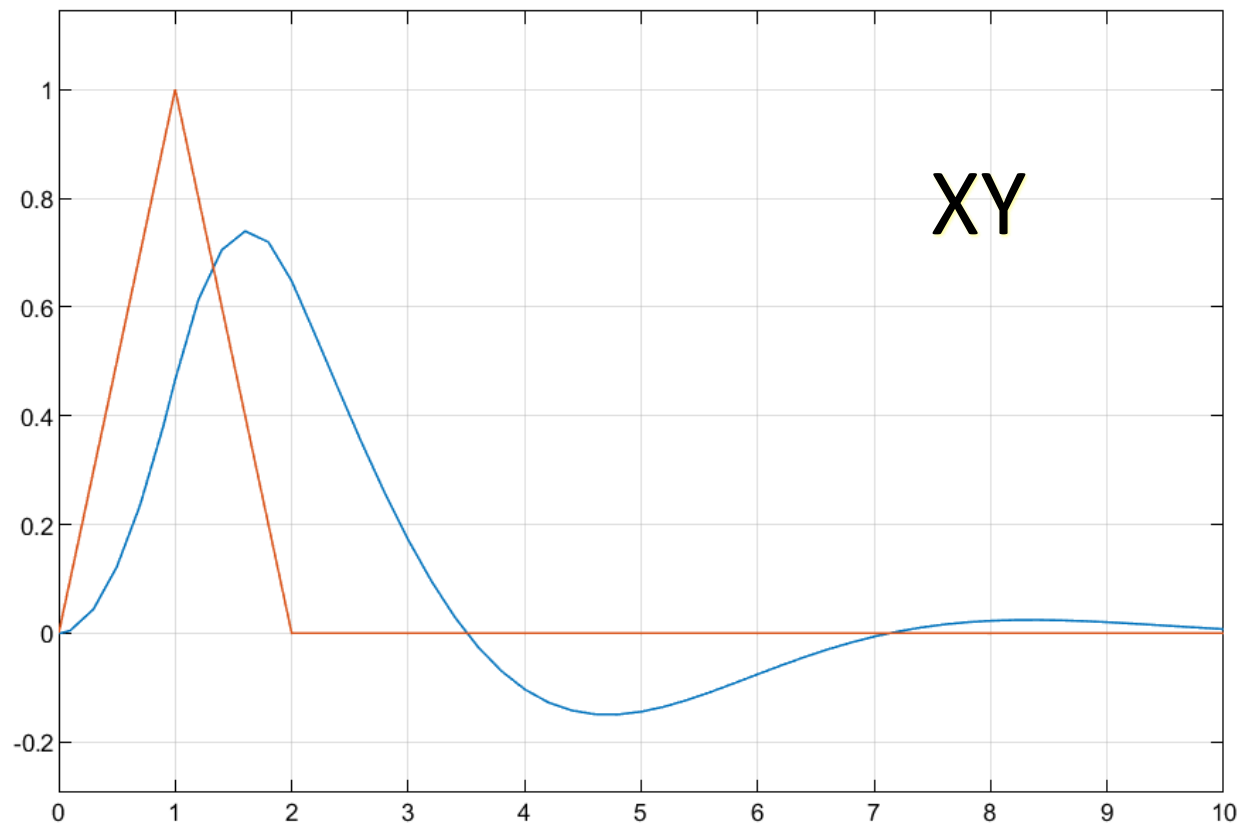
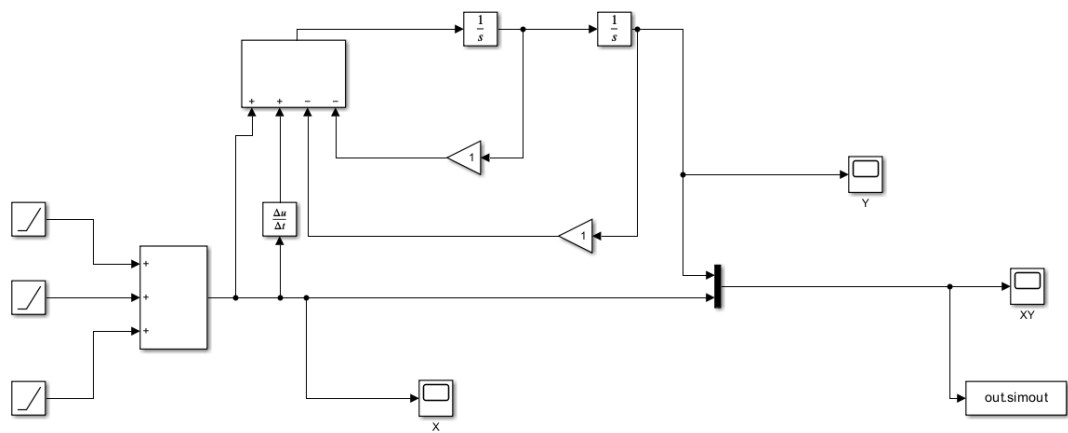
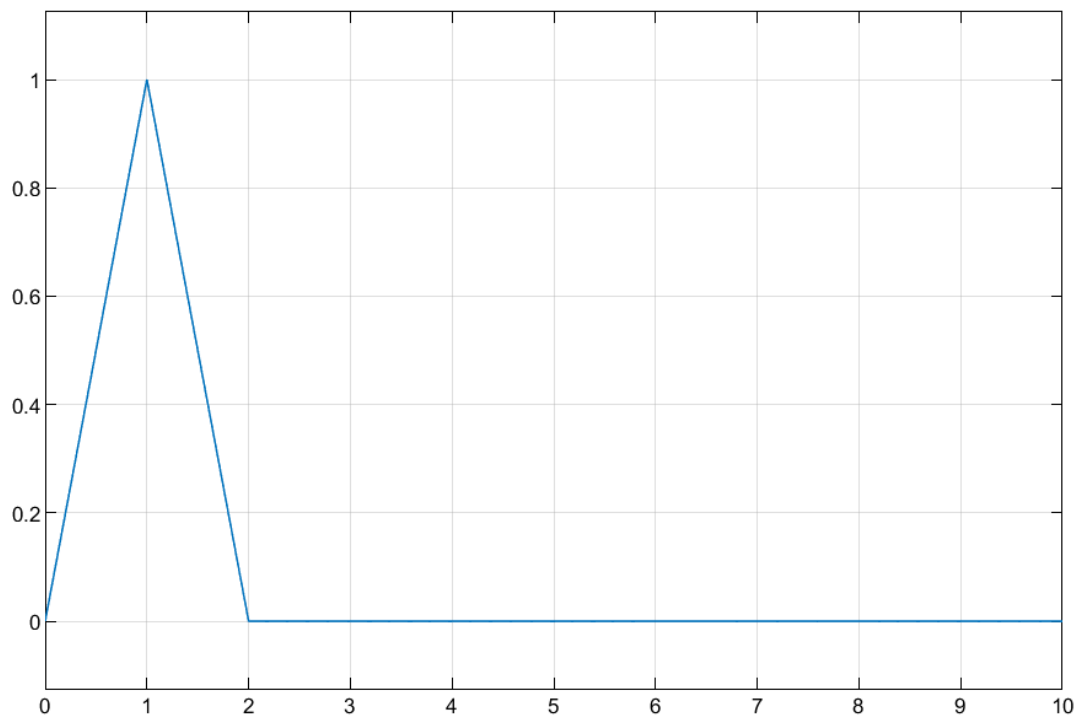


Problem 4 :

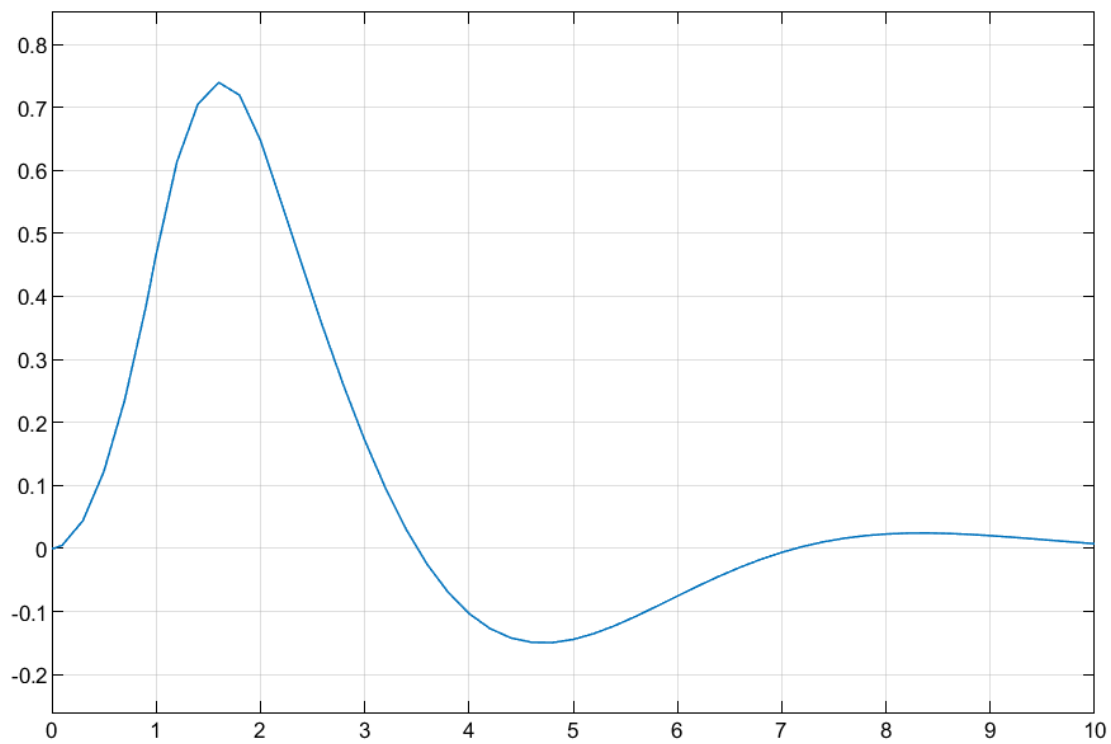
- Simulink:



X



Y



Problem 5:

- Code:

- `t = out.tout;`
-
-
- `a = .5;`
-
- `w = sqrt(3) / 2;`
- `ws = .75;`
- `q = 1/ w;`
-
-
- `c0 = t;`
- `ch1 = (t - 1) .* heaviside(t - 1);`
- `ch2 = (t - 2) .* heaviside(t - 2);`
-
- `s0 = - q * (exp((-a) * t) .* sin(w * t));`
- `sh1 = - q * (exp((-a) * (t-1)) .* sin(w * (t-1))) .* heaviside(t - 1);`
- `sh2 = - q * (exp(-a * (t-2)) .* sin(w * (t-2))) .* heaviside(t - 2);`
-
-
- `y = (c0 - 2 * (ch1) + ch2 + s0 - 2 * sh1 + sh2);`
-
-
-
-
-
- `figure(1);`
- `hold on`
- `ps0 = plot(out.tout, y, "-.", 'LineWidth', 2);`
- `% ps1 = plot(out.tout, y1, "-.", 'LineWidth', 3);`
- `% ps2 = plot(out.tout, y2, "-.", 'LineWidth', 3);`
-
-
- `ps_sim = plot(out.simout, "--", 'LineWidth', 3);`
-
- `legend('Theoretical', 'Simulation Out', 'Simulation In');`
-
- `hold off`
-
-
-

