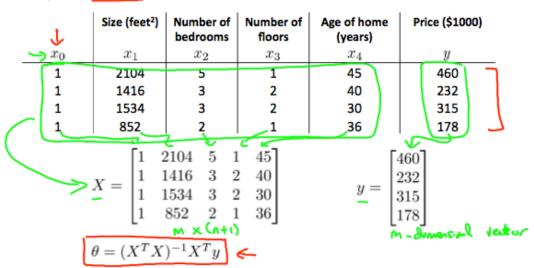# Normal Equation

Note: [8:00 to 8:44 - The design matrix X (in the bottom right side of the slide) given in the example should have elements x with subscript 1 and superscripts varying from 1 to m because for all m training sets there are only 2 features x_0 and x_1. 12:56 - The X matrix is m by (n+1) and NOT n by n.]

Gradient descent gives one way of minimizing J. Let's discuss a second way of doing so, this time performing the minimization explicitly and without resorting to an iterative algorithm. In the "Normal Equation" method, we will minimize J by explicitly taking its derivatives with respect to the θj 's, and setting them to zero. This allows us to find the optimum theta without iteration. The normal equation formula is given below:

$$\theta = (X^T X)^{-1} X^T y$$

Examples: $m = 4$.

Size (feet²)	Number of bedrooms	Number of floors	Age of home (years)	Price ($1000)
x_1	x_2	x_3	x_4	y
2104	5	1	45	460
1416	3	2	40	232
1534	3	2	30	315
852	2	1	36	178

x_0: 1, 1, 1, 1

$$X = \begin{bmatrix} 1 & 2104 & 5 & 1 & 45 \\ 1 & 1416 & 3 & 2 & 40 \\ 1 & 1534 & 3 & 2 & 30 \\ 1 & 852 & 2 & 1 & 36 \end{bmatrix} \qquad y = \begin{bmatrix} 460 \\ 232 \\ 315 \\ 178 \end{bmatrix}$$

$m \times (n+1)$ m-dimensional vector

$$\theta = (X^T X)^{-1} X^T y$$

There is **no need** to do feature scaling with the normal equation.

The following is a comparison of gradient descent and the normal equation:

Gradient Descent	Normal Equation
Need to choose alpha	No need to choose alpha
Needs many iterations	No need to iterate
O (kn^2)	O (n^3), need to calculate inverse of $X^T X$
Works well when n is large	Slow if n is very large

With the normal equation, computing the inversion has complexity $O(n^3)$. So if we have a very large number of features, the normal equation will be slow. In practice, when n exceeds 10,000 it might be a good time to go from a normal solution to an iterative process.