1.	Data type	a collection of data values and a set of predefined opera- tions on these values
2.	Modifiability	a programmer can change the type of a category of variables in a program by changing a type definition statemen only
3.	arrays and records	two most common structured data types in the imperative languages
4.	Descriptor	collection of the attributes of a variable
5.	object	represents an instance of a user-defined (abstract data) type
6.	Primitive Data Types	Data types that are not defined in terms of other types
7.	integer	the most common primitive numeric datatype Java: byte, short, int, long C++ & C# : unsigned int
8.	twos comple- ment	to store negative integers, which is convenient for addition and subtraction
9.	Floating point	data types model real numbers, but the representations are only approximations for many real values
10	float and double	two floating types
11.	Precision	accuracy of the fractional part of a value, measured as the number of bits
12	Range	combination of the range of fractions and more importanthe range of exponents

the range of exponents 13. Complex values represented as ordered pairs of floating point values data types that store a fixed number of decimal digits which are coded in Binary Coded Decimal (BCD) - essential to COBOL because of business 1/4

14. Decimal

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15. B c	oolean Types	often used to represent switches or flags in programs
16. C h	naracter Data	stored in computers as numeric codings
17. U n	nicode	includes the characters from most of the world's natural languages
18. AS	SCII	most commonly used coding
	naracter String pe	one in which the values consist of sequences of characters
	naracter String Instants	used to label output, and the input and output of all kinds of data are often done in terms of strings
	ost common ring operations	comparison, pattern matching, assignment, catenation, substring reference
22. su en	bstring refer- ce	a reference to a substring of a given string
	gular expres- ons	the pattern-matching expressions are somewhat loosely based on mathematical regular expressions
	atic length ring	the length can be static and set when the string is created
	nited dynamic ngth string	allow strings to have varying length up to a declared and fixed maximum set by the variable's definition
•	namic length ring	allow strings to have varying length with no maximum
	numeration pe	one in which all of the possible values, which are named constants, are provided, or enumerated, in the definition
_	numeration onstans	types provide a way of defining and grouping collections of named constants

29. **Array**

gate, relative to the first element 30. Subscripts or indices Specific elements of an array are referenced by means of a two-level syntactic mechanism, where the first part is the aggregate name, and the second part is a possibly dynamic selector consisting of one or more items known as 31. finite mappings arrays are sometimes called 32. static arrays one in which the subscript ranges are statically bound and storage allocation is static (done before run time) 33. fixed stack-dynamic arrays one in which the subscript ranges are statically bound, but the allocation is done at declaration elaboration time during execution 34. fixed heap-dynamic arrays similar to fixed stack-dynamic array, in that the subscript ranges and the storage binding are both fixed after storage is allocated 35. heap-dynamic array one in which the binding of subscript ranges and storage allocation is dynamic and can change any number of times during the array's lifetime 36. array operations one that operates on an array as a unit one in which the elements need not to be of the same type array 38. rectangular array a multidimensioned array in which all of the rows have the	PL Chapter 6 Study online at https:/	//quizlet.com/_cwk8mp
of a two-level syntactic mechanism, where the first part is the aggregate name, and the second part is a possibly dynamic selector consisting of one or more items known as		individual element is identified by its position in the aggre-
one in which the subscript ranges are statically bound and storage allocation is static (done before run time) 33. fixed stack-dynamic arrays one in which the subscript ranges are statically bound, but the allocation is done at declaration elaboration time during execution 34. fixed heap-dynamic arrays similar to fixed stack-dynamic array, in that the subscript ranges and the storage binding are both fixed after storage is allocated 35. heap-dynamic array one in which the binding of subscript ranges and storage allocation is dynamic and can change any number of times during the array's lifetime 36. array operations one that operates on an array as a unit 37. heterogeneous array array a multidimensioned array in which all of the rows have the same number of elements and all of the columns have the same number of elements 39. jagged array in which the lengths of the rows need not be the same. For example, a jagged matrix may consist of three rows, one with 5 elements, one with 7 elements, and one with	-	of a two-level syntactic mechanism, where the first part is the aggregate name, and the second part is a possibly dynamic selector consisting of one or more items known
storage allocation is static (done before run time) 33. fixed stack-dynamic arrays one in which the subscript ranges are statically bound, but the allocation is done at declaration elaboration time during execution 34. fixed heap-dynamic arrays osimilar to fixed stack-dynamic array, in that the subscript ranges and the storage binding are both fixed after storage is allocated 35. heap-dynamic array one in which the binding of subscript ranges and storage allocation is dynamic and can change any number of times during the array's lifetime 36. array operations one that operates on an array as a unit 37. heterogeneous array a multidimensioned array in which all of the rows have the same number of elements and all of the columns have the same number of elements 39. jagged array in which the lengths of the rows need not be the same. For example, a jagged matrix may consist of three rows, one with 5 elements, one with 7 elements, and one with	31. finite mappings	arrays are sometimes called
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37. heterogeneous array one in which the elements need not to be of the same type array 38. rectangular array a multidimensioned array in which all of the rows have the same number of elements and all of the columns have the same number of elements 39. jagged array in which the lengths of the rows need not be the same. For example, a jagged matrix may consist of three rows, one with 5 elements, one with 7 elements, and one with		allocation is dynamic and can change any number of times
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For example, a jagged matrix may consist of three rows, one with 7 elements, and one with	38. rectangular array	same number of elements and all of the columns have the
	39. jagged array	For example, a jagged matrix may consist of three rows, one with 5 elements, one with 7 elements, and one with

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40.	slice	an array is some substructure of that array
	row major order and column ma- jor order	
42.	associate arrays	an unordered collection of data elements that are indexed by an equal number of values called keys
43.	hashes	in perl associative arrays are called
44.	dictionaries	in python associative arrays are called
45.	record	aggregate of data elements in which the individual elements are identified by names and accessed through offsets from the beginning of the structure
	fully qualified ref- erence	record field is one in which all intermediate record names, from the largest enclosing record to the specific field, are named in the reference. In the COBOL example above the field reference is fully qualified

elements are not named

47. elliptical refer-

ence

48. **tuple**

the field is named, but any or all of the enclosing record names can be omitted, as long as the resulting reference

a data type that is similar to a record, except that the

is unambiguous in the referencing environment