

Solutions to CNS 2013 PT4 - Kuramoto

4.a

-Expanding $r \exp(i\Theta) = \frac{1}{N} \sum_{j=1}^N \exp(i\theta_j)$, we have $r \cos(\Theta)$ equals $\frac{1}{N} \sum_{j=1}^N \cos(\theta_j)$ and $r \sin(\Theta)$ equals $\frac{1}{N} \sum_{j=1}^N \sin(\theta_j)$. Then,

$$\begin{aligned}\dot{\theta}_i &= \omega_i - \frac{K}{N} \sum_{j=1}^N \sin(\theta_i - \theta_j) \\ \dot{\theta}_i &= \omega_i - \frac{K}{N} \sin(\theta_i) \sum_{j=1}^N \cos(\theta_j) + \frac{K}{N} \cos(\theta_i) \sum_{j=1}^N \sin(\theta_j) \\ \dot{\theta}_i &= \omega_i - K \sin(\theta_i) r \cos(\Theta) + K \cos(\theta_i) r \sin(\Theta) \\ \dot{\theta}_i &= \omega_i - Kr \sin(\theta_i - \Theta).\end{aligned}$$

4.b

-When θ_j equals Θ , then r equals 1: therefore, r is a measure of a number of population that have the same phase.

- Θ represents an average phase of the population.

4.c

-The phase fixed point of each phase oscillator is $\sin^{-1}(\omega_i/(Kr)) + \Theta$. Jacobian matrix of each oscillator at the phase fixed point is $-Kr \cos(\sin^{-1}(\omega_i/(Kr)))$. Then, the phase fixed point is linearly stable if and only if $-Kr \cos(\sin^{-1}(\omega_i/(Kr))) < 0$, i.e. $\omega_i \in (-Kr, Kr)$: it is unstable if and only if $-Kr \cos(\sin^{-1}(\omega_i/(Kr))) > 0$, i.e. $\omega_i < -Kr$ or $\omega_i > Kr$.