

SOFTWARE TESTING-I

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TESTING

- Aims to identify all defects in a program.
- Can reveal the **presence** of errors NOT their **absence**
- Completion of testing does not guarantee error free program
 - Due to large input domain.

BASIC CONCEPTS AND TERMINOLOGIES

○ Error

- A mistake committed by the development team during the development phases.
- Mistake may be in requirement, design or coding phase.
- Also referred as *fault*, *bug* or *defect*.

○ Failure

- Manifestation or symptom of an error.
- Not all errors leads to failure.



BASIC CONCEPTS AND TERMINOLOGIES

○ Test Case

- Is a triplet [I, S, O]
- I: is the data input to the system
- S: is the state of the system at which data is input
- O: is the expected output of the system

○ Test Suite

- Set of all test cases with which a given software product is tested.



BASIC CONCEPTS AND TERMINOLOGIES

- Verification:

- The software should conform to its specification.
- *"Are we building the product right ?"*

- Validation:

- The software should do what the user really requires.
- *"Are we building the right product ?"*

Verification and validation thus starts with **requirements reviews** and **continues through design and code reviews** to **product testing**. [1]

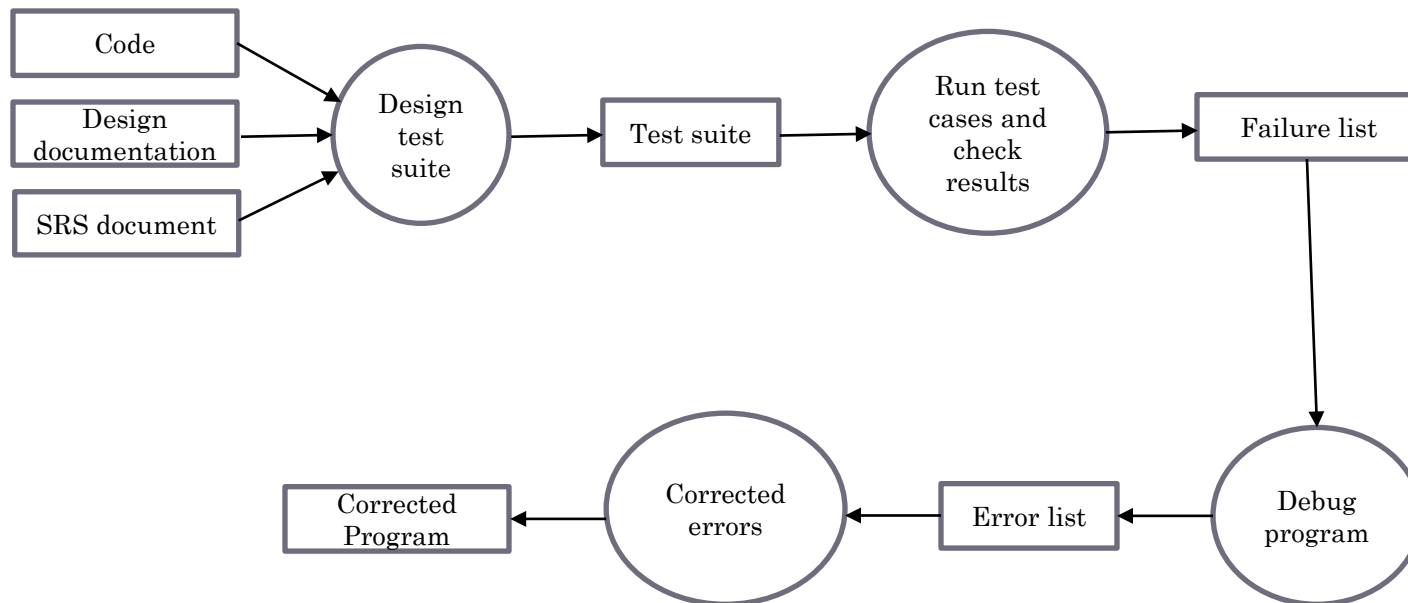
[1] https://www.sqa.org.uk/e-learning/SDPL03CD/page_16.htm

HOW DO WE TEST A SYSTEM?

- Input test data to the system.
- Observe the output:
 - Check if the system behaved as expected.
- If the program does not behave as expected:
 - Note the conditions under which it failed.
 - Later debug and correct.



HOW DO WE TEST A SYSTEM?



DESIGN OF TEST CASES

- Exhaustive testing of any non-trivial system is impractical:
 - input data domain is extremely large.
- Design an optimal test suite:
 - of reasonable size
 - to uncover as many errors as possible.
- If test cases are selected randomly:
 - many test cases do not contribute to the significance of the test suite.
 - many test cases detect errors already detected by other test cases in the suite.



DESIGN OF TEST CASES

- Testing a system using a large number of randomly selected test cases:
 - does not mean that many errors in the system will be uncovered.
- Consider an example:
 - finding the maximum of two integers x and y .



DESIGN OF TEST CASES

- If $(x > y)$ $\text{max} = x$;
 else $\text{max} = x$;
- The code has a simple error:
- test suite $\{(x=3, y=2); (x=2, y=3)\}$ can detect the error,
- a larger test suite $\{(x=3, y=2); (x=4, y=3); (x=5, y=1)\}$ does not detect the error.

“In contrast to **random test suite** we need carefully designed set of test cases such that, each test case helps detect different errors i.e. **minimal test suite**.”

DESIGN OF TEST CASES

Black-box approach	White (glass)-box approach
Test cases are designed using only the functional specification of the software - <i>knowledge of internal structure not required.</i>	Test cases requires thorough knowledge about the internal structure of software.
For this reason, black-box testing is known as functional testing .	white-box testing is known as called structural testing

These approaches are complementary. A program has to be tested using the test cases designed by both the approaches.

BLACK-BOX TESTING

- Test cases are designed from an examination of the input/output values only (knowledge of code or design not required)
- Two approaches for designing black-box test cases:
 - Equivalence class partitioning
 - Boundary value analysis



EQUIVALENCE CLASS PARTITIONING

- Domain of input values, to the program under test, is partitioned into a set of equivalence class.
- For every input data belonging to the same equivalence class, the program behave similarly.
 - Testing the program against any one input of given equivalence class suffice the test for that class.
- Eliminate the time required for exhaustive testing (testing for each input).
- Equivalence class test suite is a set of any one test cases from each equivalence classes.



EQUIVALENCE CLASS PARTITIONING

- Guidelines for designing the equivalence classes
 - If input data values is Range
 - Then one valid equivalence class & two invalid equivalence classes need to be defined. e.g. input data values [1, 10]
 - valid equivalence class: [1, 10]
 - invalid equivalence class: $[-\infty, 0]$ and $[11, \infty]$.
 - If input data values is specific set
 - Then one valid equivalence class & one invalid equivalence classes need to be defined. e.g. input data values {A, B, C}
 - valid equivalence class: {A, B, C}
 - invalid equivalence class: $U - \{A, B, C\}$.

EQUIVALENCE CLASS PARTITIONING

- Equivalence class partitioning test suite for a function that reads a character string of size less than five characters and displays whether it is a palindrome.
 - **Step 1:** Identify the input domain:
 - In this case string, set of discrete members
 - **Step 2:** Equivalence class based on input
 - valid equivalence class:
 - set of string of length five or less.
 - invalid equivalence class:
 - set of string of length six or more.
 - **Step 3:** Equivalence class based on Input and output
 - valid equivalence class:
 - set of string of length five or less and palindrome.
 - set of string of length five or less and non-palindrome.
 - invalid equivalence class:
 - set of string of length six or more.
- Hence required test suite: { aba, abc, abcdef }

PRACTICE PROBLEM: EQUIVALENCE CLASS

- Validity of Date of Journey
- Interface
 - Boolean isValidDOJ(date current_date, date input_date);
- Specification
 - The input_date should not be a past date.
 - The input_date should not exceed 90 days from current_date.
- Write all possible equivalence classes for the specification

PRACTICE PROBLEM: EQUIVALENCE CLASS

- Counting Characters in a String
- Interface
 - `void CharCount(int VoCount, int InCount);`
- Specification
 - the procedure keeps on reading Input from the keyboard; it stops when a non-alphabet (English) character or some upper value Max-Size has been reached
 - if the input is an alphabet character, then the counter InCount is incremented; if it is a vowel, then the counter VoCount is incremented
 - both counters are input and output parameters
 - the invariant $\text{VoCount} \leq \text{InCount}$ holds
- Write all possible equivalence classes for the specification

SOLUTION

- Equivalence classes for *InCount*
 1. $InCount < 0$ [invalid]
 2. $0 \leq InCount < MaxSize$ [valid]
 3. $InCount = MaxSize$ [valid]
 4. $InCount > MaxSize$ [invalid]
- Equivalence class for *VoCount*
 1. $VoCount < 0$ [invalid]
 2. $0 \leq VoCount \leq InCount$ [valid]
 3. $VoCount > InCount$ [Invalid]
- Equivalence classes for keyboard *Input*
 1. $Input < A$
 2. $Input < a$
 3. $Input > Z$
 4. $Input > z$
 5. $A \leq Input \leq Z$
 6. $a \leq Input \leq z$
 7. $Input = A$
 8. $Input = E$
 9. $Input = I$
 10. $Input = O$
 11. $Input = U$
 12. $Input = a$
 13. $Input = e$
 14. $Input = i$
 15. $Input = o$
 16. $Input = u$

[invalid] non-English alphabets

[valid]

BOUNDARY VALUE ANALYSIS

- programming error frequently occurs at the boundaries of different equivalence classes of inputs.
 - For example, programmers may improperly use $<$ instead of \leq , or conversely \leq .
 - The requirements are generally vague at the boundaries. e.g. different **Tax Rate** on different **Income Slab**.
 - Confusion in using loops and conditions checks (related to coding).
- Boundary value analysis leads to selection of test cases at the boundaries of the different equivalence classes.

BOUNDARY VALUE ANALYSIS

- For a function that computes the tax based on the income.

Income Slab	Tax Rate
Income up to Rs. 3,00,000	No Tax
Income from Rs. 3,00,000 – Rs. 5,00,000	5%
Income from Rs. 5,00,000 – 10,00,000	20%
Income more than Rs. 10,00,000	30%

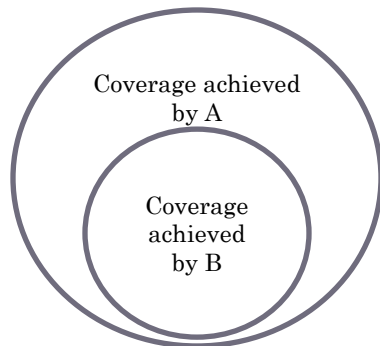
- The boundary value test suite is {299999, 300000, 499999, 500000, 999999, 1000000}

WHITE-BOX TESTING

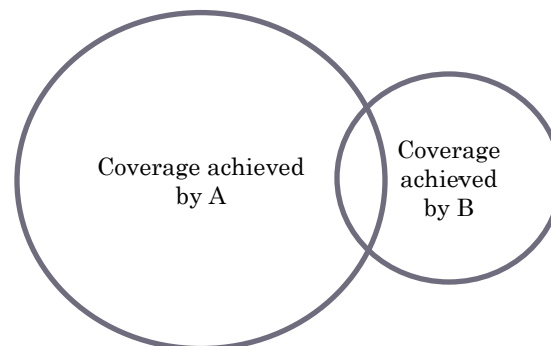
- Test cases are designed based on an analysis of the internal structure of the component or system.
- White-box testing strategy can be
 - **Coverage based testing:** Attempts to execute (i.e. cover) certain elements of the program.
 - Statement Coverage
 - Branch Coverage
 - Path-Coverage
 - condition coverage
 - **Fault-based testing:** Attempts to enhanced the existing test suite to detect certain types of faults.
 - Mutation Testing.

STRONGER, WEAKER AND COMPLEMENTARY TESTING

- Testing strategy A is said to be **stronger** than testing strategy B if A covers all type of program elements covers by B. (B is **weaker** than A)
- If neither A is stronger than B nor B is stronger than A. A and B said to be **complementary**.
- If a stranger testing has been performed, then a weaker testing **need not** be carried out.



A is stronger than B



A and B are complementary

STATEMENT COVERAGE

- Aims to design test cases so as to execute every statement in a program at least once.
- The principal idea:
 - unless a statement is executed,
 - we have no way of knowing if an error exists in that statement.
- Observing that a statement behaves properly for one input value:
 - no guarantee that it will behave correctly for all input values.



EXAMPLE: EUCLID'S GCD ALGORITHM

```
int computeGCD(int x, int y)
{
    1.  while (x != y)
    2.  {
    3.      if (x>y) then
    4.          x=x-y;
    5.      else y=y-x;
    6.  }
    7.  return x;
}
```



EXAMPLE: EUCLID'S GCD ALGORITHM

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    6.  }
    7.  return x;
}
```

- By choosing the test set $\{(x=3,y=3),(x=4,y=3), (x=3,y=4)\}$
 - all statements are executed at least once.

BRANCH COVERAGE

- Test cases are designed such that:
 - different branch conditions given true and false values in turn.
- Each edge of program's control flow graph (CFG) is traversed at least once --- **edge testing**.



BRANCH COVERAGE

```
int f1(int x,int y)
{
    1.  while (x != y)
    2.  {
    3.      if (x>y) then
    4.          x=x-y;
    5.      else y=y-x;
    6.  }
    7.  return x;
}
```



BRANCH COVERAGE

```
int f1(int x,int y)
{
    1.  while (x != y)
    2.  {
    3.      if (x>y) then
    4.          x=x-y;
    5.      else y=y-x;
    6.  }
    7.  return x;
}
```

○ Test cases for branch coverage can be:

- {(x=3,y=3),(x=3,y=2), (x=4,y=3), (x=3,y=4)}

BRANCH COVERAGE

- Branch Coverage-based testing is **stronger** than statement coverage-based testing.
 - Branch coverage ensures statement coverage, but not vice versa.

CONDITION COVERAGE

- Test cases are designed such that:
 - each component of a composite conditional expression
 - given both true and false values.
- Consider the conditional expression
 - $((c1.and.c2).or.c3)$:
- Each of $c1$, $c2$, and $c3$ are exercised at least once,
 - i.e. given true and false values.
- Consider a Boolean expression having n components:
 - for condition coverage we require 2^n test cases.
- practical only if n (the number of component conditions) is small.
 - Number of test cases increases exponentially.

CONDITION COVERAGE

- Condition testing
 - stronger testing than branch testing.



PATH COVERAGE

- Design test cases such that:
 - All **linearly independent paths** in the program are executed at least once.
- To understand the path coverage-based testing:
 - we need to learn how to draw control flow graph (CFG) of a program.



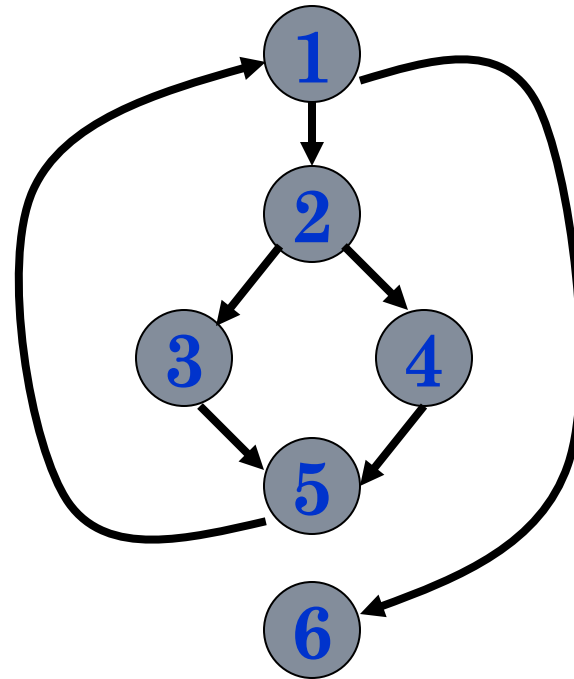
CONTROL FLOW GRAPH (CFG)

- A control flow graph (CFG) describes:
 - the sequence in which different instructions of a program get executed.
 - the way control flows through the program.
- Formally CFG is Directed Graph $G(N, E)$
 - Each node $n \in N$ corresponds to a unique program statement.
 - An edge $(n_i, n_j) \in E$ if control can transfer from statement n_i to statement n_j .



EXAMPLE

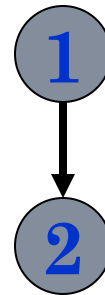
```
int f1(int x, int y)
{
  1.  while (x != y){
  2.    if (x>y) then
  3.      x=x-y;
  4.    else y=y-x;
  5.  }
  6.  return x;
}
```



HOW TO DRAW CONTROL FLOW GRAPH?

- Sequence:

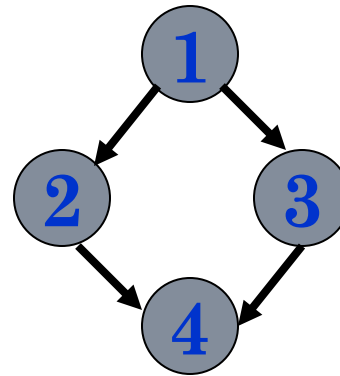
1. $a=5;$
2. $b=a*b-1;$



HOW TO DRAW CONTROL FLOW GRAPH?

○ Selection:

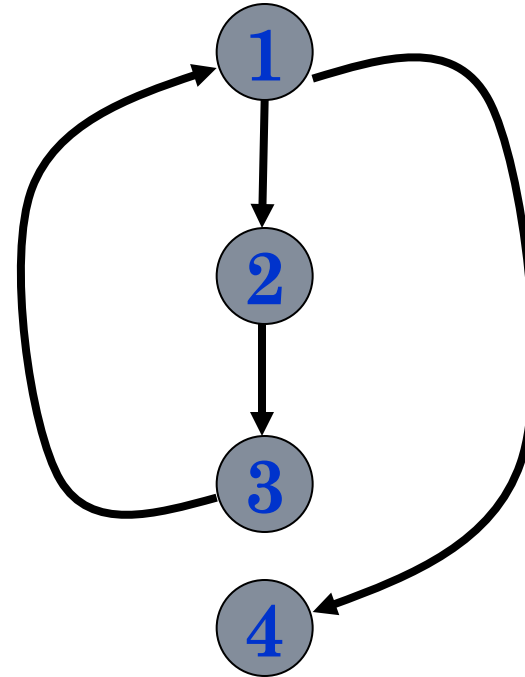
1. if(a>b) then
2. c=3;
3. else c=5;
4. c=c*c;



HOW TO DRAW CONTROL FLOW GRAPH?

○ Iteration:

1. while(a>b){
2. b=b*a;
3. b=b-1;}
4. c=b+d;



PATH

- A path through a program:
 - a node and edge sequence from the **starting node** to a **terminal node** of the control flow graph.
 - There may be several terminal nodes for program.
- There can be an *infinite number of paths* e.g. 12314, 12312314, 12312312314,
 - Coverage of all paths requires infinite many test cases.
 - Path coverage-based testing subset of paths – *Linearly independent paths* (basic paths).

LINEARLY INDEPENDENT PATH

- Any path through the program:
 - introducing at least one new node:
 - that is not included in any other linear independent paths.
- Collection of such path is the set of linear independent paths.
 - For any given path in such set, its sub-path cannot be in that set.
- It is straight forward:
 - to identify linearly independent paths of simple programs.
- For complicated programs:
 - it is not so easy to determine the **number of linear independent paths**.



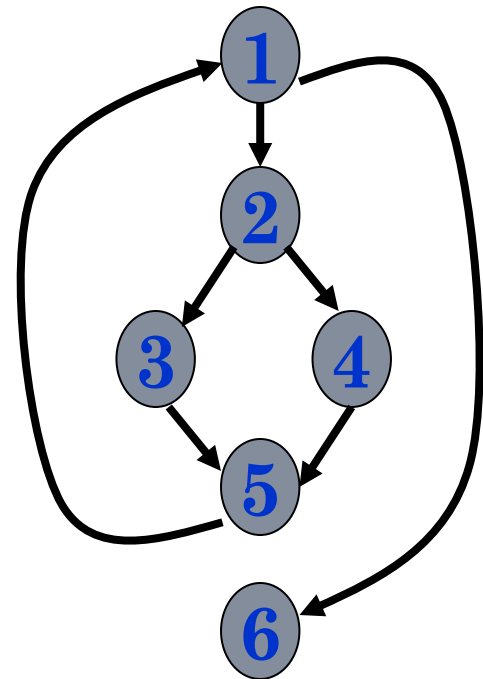
MCCABE'S CYCLOMATIC METRIC

- An upper bound:
 - for the number of linearly independent paths of a program
- Provides a practical way of determining:
 - the maximum number of *linearly independent paths* in a program.



MCCABE'S CYCLOMATIC METRIC [METHOD-1]

- Given a control flow graph G, cyclomatic complexity $V(G)$:
 - $V(G) = E - N + 2$
 - N is the number of nodes in G
 - E is the number of edges in G
- Cyclomatic complexity = $7 - 6 + 2 = 3$.



McCABE'S CYCLOMATIC METRIC

[METHOD-2]

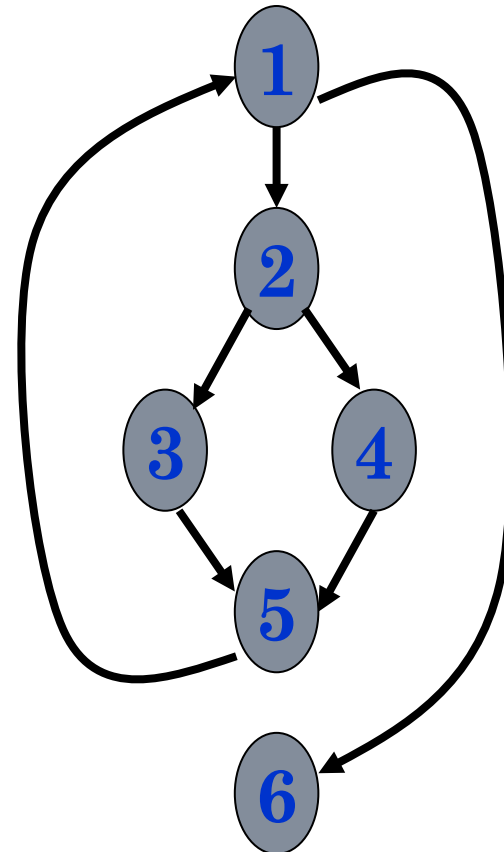
- Another way of computing cyclomatic complexity:
 - inspect control flow graph
 - determine number of bounded areas in the graph
- $V(G) = \text{Total number of bounded areas} + 1$
- Bounded area:
 - Any region enclosed by a nodes and edge sequence.



McCABE'S CYCLOMATIC METRIC

[METHOD-2]

- From a visual examination of the CFG:
 - the number of bounded areas is 2.
 - cyclomatic complexity = $2+1=3$.
- This method would not work for non planer graph.



CYCLOMATIC COMPLEXITY

- The first method of computing $V(G)$ is amenable to automation:
 - you can write a program which determines the number of nodes and edges of a graph
 - applies the formula to find $V(G)$.
- The cyclomatic complexity of a program provides:
 - a lower bound on the number of test cases to be designed
 - to guarantee coverage of all linearly independent paths.



CYCLOMATIC COMPLEXITY

- Knowing the number of test cases required:
 - does not make it any easier to derive the test cases,
 - only gives an indication of the minimum number of test cases required.



PATH TESTING

- The tester proposes:
 - an initial set of test data using his experience and judgment.
- A dynamic program analyzer is used:
 - to indicate which parts of the program have been tested
 - the output of the dynamic analysis
 - used to guide the tester in selecting additional test cases.



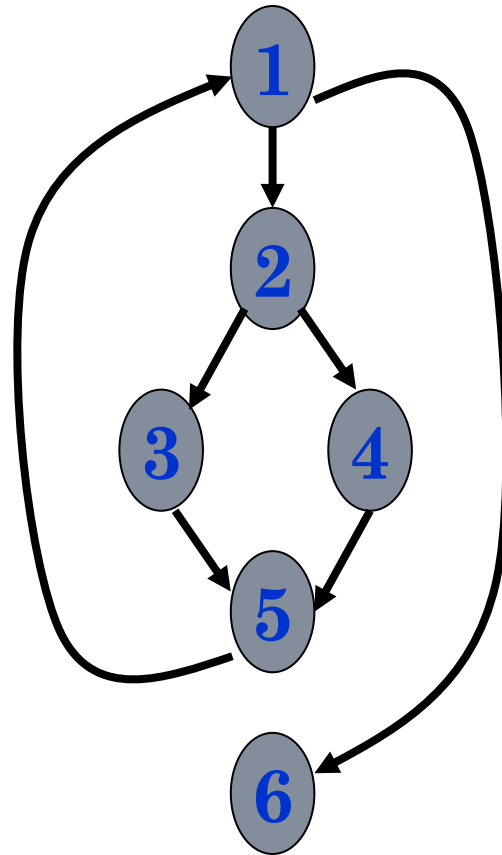
DERIVATION OF TEST CASES

- Draw control flow graph.
- Determine $V(G)$.
- Determine the set of linearly independent paths.
- Prepare test cases:
 - to force execution along each path.



EXAMPLE

```
int f1(int x, int y)
{
  1.  while (x != y){
  2.    if (x>y) then
  3.      x=x-y;
  4.    else y=y-x;
  5.  }
  6.  return x;
}
```



DERIVATION OF TEST CASES

- Number of independent paths: 3
 - 1,6 test case (x=1, y=1)
 - 1,2,3,5,1,6 test case(x=1, y=2)
 - 1,2,4,5,1,6 test case(x=2, y=1)

OTHER APPLICATIONS OF MCCABE'S CYCLOMATIC METRIC

- Estimation of structural complexity of code.
 - McCabe's metric is based on code structure
 - Intuitively, it correlates the psychological complexity or difficulty level of understanding the program.
 - Good software development organizations:
 - restrict cyclomatic complexity of functions to a maximum of **ten** or so.
- Estimation of testing efforts.
 - McCabe's metric is a measures of maximum number of basic paths.
 - Implies, minimum number of **test case required** for path coverage.
 - Hence in turn estimate the test efforts.
 - restrict cyclomatic complexity of functions to **seven** to reduce testing effort.

OTHER APPLICATIONS OF MCCABE'S CYCLOMATIC METRIC

- Estimation of program reliability
 - Study indicates
 - the number of errors latent in the code after testing has direct relation with McCabe's metric.
 - The relationship possibly due to McCabe's metric is based on structural complexity of the code.
 - Usually, larger the structural complexity, the more difficult to test and debug.

SUMMARY

- Exhaustive testing of non-trivial systems is impractical:
 - we need to design an optimal set of test cases
 - should expose as many errors as possible.



SUMMARY

- If we select test cases randomly:
 - many of the selected test cases do not add to the significance of the test set.



SUMMARY

- There are two approaches to testing:
 - black-box testing and
 - white-box testing.

SUMMARY

- Designing test cases for black box testing:
 - does not require any knowledge of how the functions have been designed and implemented.
 - Test cases can be designed by examining only SRS document.



SUMMARY

- White box testing:
 - requires knowledge about internals of the software.
 - Design and code is required.

SUMMARY

- We have discussed a few white-box test strategies.
 - Statement coverage
 - branch coverage
 - condition coverage
 - path coverage



SUMMARY

- A stronger testing strategy:
 - provides more number of significant test cases than a weaker one.
 - Condition coverage is strongest among strategies we discussed.



SUMMARY

- We discussed McCabe's Cyclomatic complexity metric:
 - provides an upper bound for linearly independent paths
 - correlates with understanding, testing, and debugging difficulty of a program.



THANK YOU