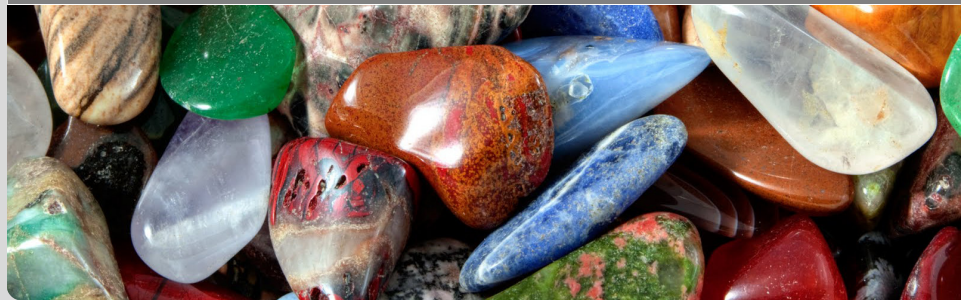


Dynamically Stable Walking For Humanoid Bipedal Robots Based On Walking Patterns

Bachelor Thesis

Patrick Niklaus | November 19, 2014

INSTITUTE FOR ANTHROPOMATICS AND ROBOTICS: HIGH PERFORMANCE HUMANOID TECHNOLOGIES LAB



Outline

References