

$J(\omega)$: expected return of policy π .

$d^\pi(s)$: stationary distribution.

Note that policy gradient theorem says

$$\nabla_{\mathbf{z}} J(\pi) = \mathbb{E}_{s \sim d^\pi, a \sim \pi(\cdot|s)} [\nabla_{\mathbf{z}} \log \pi(a|s) \cdot A^\pi(s|a)] \quad (*)$$

$$\text{Since } \pi(a|s) = \frac{\exp(\mathbf{z}(s, a))}{\sum_{a \in A} \exp(\mathbf{z}(s, a))}$$

$$\Rightarrow \underbrace{\log(\pi(a|s))}_{\text{}} = \mathbf{z}(s, a) - \log\left(\sum_{a \in A} \exp(\mathbf{z}(s, a))\right)$$

$$\nabla \log(\pi(a|s)) = \frac{\nabla_{\mathbf{z}} \pi(a|s)}{\pi(a|s)} \quad (**)$$

substitute (**) into (*), get

$$\nabla_{\mathbf{z}} J(\pi) = \mathbb{E}_{s \sim d^\pi, a \sim \pi(\cdot|s)} \left[\frac{\nabla_{\mathbf{z}} \pi(a|s)}{\pi(a|s)} \cdot A^\pi(s|a) \right]$$

$$= \sum_{s \in S} d^\pi(s) \sum_{a \in A} \cancel{\pi(a|s)} \frac{\nabla_{\mathbf{z}} \pi(a|s)}{\cancel{\pi(a|s)}} A^\pi(s|a)$$

$$= \sum_{s \in S} d^\pi(s) \underbrace{\left(\sum_{a \in A} \nabla_{\mathbf{z}} \pi(a|s) \right)}_{\text{the integration of a gradient returns the original function: } \pi(a|s)} A^\pi(s|a)$$

the integration of a gradient returns the original function: $\pi(a|s)$.

$$= \sum_{s \in S} d^\pi(s) (\pi(a|s) A^\pi(s|a))$$

$$\text{since } d^\pi(s) := \sum_{s' \in S} d^\pi(s') P(s'|s, \pi(s))$$

$$= d^\pi(s) \pi(a|s) A^\pi(s|a) \text{ as desired } \square$$