## MECHATRONIC PROJECT 478: ECSA EXIT LEVEL OUTCOME EVALUATION

| ELO 1: Problem Solving  |                  |  |
|---|------------------|--|
| Demonstrate competence to identify, assess, formulate and solve | • Chapters 1,2,3 |  |
| convergent and divergent engineering problems creatively and    | and 4            |  |
| innovatively.   | Poster           |  |

- Identify the need for an inexpensive smart trainer that will be able to interface with Zwift.
- Indicate the criteria needed to connect with Zwift, as well as have a usable trainer done in Introduction and Literature Review. (Chapter 1 and 2).
- Best sollution for general problem presented, then split into seperate sections to solve further ito. Software and Hardware requirements (Chapter 3 and 4)

| ELO 2: Application of Scientific and Engineering Knowledge            |               |  |
|---|---------------|--|
| Demonstrate competence to apply knowledge of mathematics,             | • Section 4.1 |  |
| basic science and engineering sciences from first principles to solve |               |  |
| engineering problems.   |               |  |

- Model of Forces involved in trainer for use in basic hardware design and component selection.
- Mathematical model and analysis of Eddy Current Brake. (Section 4.1)

| ELO 3: Engineering Design                                   |                   |
|---|-------------------|
| Demonstrate competence to perform creative, procedural and  | • Chapter 2 and 3 |
| non-procedural design and synthesis of components, systems, |                   |
| engineering works, products or processes.                   |                   |

- Design the software approach, communicating with Zwift through BLE protocol.
- Design a hardware approach for both the resistance brake and the general trainer.
- Design the electro-mechanical control of the braking unit and the controlling software. (Chapter 2 and 3)