

# HILOS POSIX

LABORATORIO DE SISTEMAS DE OPERACIÓN I  
(ci-3825)

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# HILOS POSIX

- Librería

```
#include <pthread.h>
```

- Función que se comportará como hilo:

```
void * mihilo(void *arg) {  
    ... //instrucciones  
}
```

- Algunos tipos y macros:

```
pthread_t idh; //id del hilo
```

```
pthread_attr_t attr; //atributos del hilo
```

```
PTHREAD_SCOPE_SYSTEM: hilo a nivel de kernel
```

```
PTHREAD_SCOPE_PROCESS: hilo a nivel de usuario
```

- Inicializar y destruir atributos

```
pthread_attr_init(pthread_attr_t *attr);
```

```
pthread_attr_destroy(pthread_attr_t *attr);
```

# HILOS POSIX

- Ejemplo:

```
p_thread_attr_t misattr;  
...  
pthread_attr_init(&misattr);  
pthread_attr_setscope(&misattr, PTHREAD_SCOPE_PROCESS);  
.....  
pthread_attr_destroy(&misattr);
```

- Algunos atributos que pueden ser inicializados:

```
int pthread_attr_setdetachstate(pthread_attr_t *attr, int detachstate);  
int pthread_attr_setguardsize(pthread_attr_t *attr, size_t guardsize);  
int pthread_attr_setinheritsched(pthread_attr_t *attr, int inheritsched);  
int pthread_attr_setschedparam(pthread_attr_t *attr, const struct  
    sched_param *param);  
int pthread_attr_setschedpolicy(pthread_attr_t *attr, int policy);  
int pthread_attr_setscope(pthread_attr_t *attr, int contentionscope);  
int pthread_attr_setstackaddr(pthread_attr_t *attr, void *stackaddr);  
int pthread_attr_setstacksize(pthread_attr_t *attr, size_t stacksize);
```

# HILOS POSIX

- Ejemplo:

```
p_thread_attr_t misattr;  
...  
pthread_attr_init(&misattr);  
pthread_attr_setscope(&misattr, PTHREAD_SCOPE_PROCESS);  
.....  
pthread_attr_destroy(&misattr);
```

- Algunos atributos que pueden ser inicializados:

- \* Por defecto, los hilos se crean con ciertos atributos: hilos de kernel, todos con la misma cantidad de stack, la misma prioridad que el hilo padre, la misma política de scheduling, etc.
- \* Estos atributos se pueden cambiar.
- \* Si se quiere trabajar con los atributos por defecto, se usa NULL

```
int pthread_attr_setscope(pthread_attr_t *attr, int contentionscope);  
int pthread_attr_setstackaddr(pthread_attr_t *attr, void *stackaddr);  
int pthread_attr_setstacksize(pthread_attr_t *attr, size_t stacksize);
```

# HILOS POSIX

- Creación

```
int pthread_create(pthread_t * tid, const pthread_attr_t *attr,
```

```
void *(start_routine)(void *), void * arg) ==> arguments:
```

- tid: A unique identifier for the new thread returned by the subroutine.
  - attr: An attribute object that may be used to set thread attributes. You can specify a thread attributes object, or NULL for the default values.
  - start\_routine: the C routine that the thread will execute once it is created.
  - arg: A single argument that may be passed to start\_routine. It must be passed by reference as a pointer cast of type void. NULL may be used if no argument is to be passed
- pthread\_create devuelve 0 si la creación es exitosa o !=0 si hay error
  - Ejemplo:

```
pthread_t tid; pthread_attr_t mis_atr;
```

```
....
```

```
pthread_create(&tid,&mis_atr, mihilo,NULL)
```

# HILOS POSIX

- **Terminación**

There are several ways in which a Pthread may be terminated:

- The thread returns from its starting routine (the main routine for the initial thread).
- The thread makes a call to the **pthread\_exit** subroutine (covered below).
- The thread is canceled by another thread via the **pthread\_cancel(tid)**.
- The entire process is terminated due to a call to either the `exec` or `exit` subroutines

- `void pthread_exit(void *value)`

- Ejemplos:

**trozo de código de hilo 1:**

```
int *contador;  
contador = (int *)malloc(sizeof(int));  
....  
pthread_exit((void*)contador);
```

**trozo de código de hilo 2:**

```
int contador;  
....  
....  
pthread_exit((void*)&contador);
```

# HILOS POSIX

- **Terminación**

- El valor retornado pasado como argumento en **pthread\_exit** es recibido en **pthread\_join** llamado por otro hilo (al estilo de **exit** y **wait** de procesos)
- La llamada a **exit()** en cualquier parte del programa ocasiona que todos los hilos terminen
- La salida de un hilo deberá ser con **pthread\_exit** y no con **exit**. **Si lo hace con exit() todos los hilos finalizarán.**

# HILOS POSIX

- **Joining hilos:**

```
int pthread_join(pthread_t tid, void **value)
```

Devuelve 0 si es exitoso, !=0 en caso contrario.

- Ejemplos:

- pthread\_join(tid, NULL);

- void \*status; int rc;

.....

```
rc = pthread_join(tid, &status);
```

```
if (rc) {
```

```
    printf("ERROR; return code from pthread_join() is %d\n", rc);
```

```
    exit(-1);
```

```
}
```



# HILOS POSIX

- Pase de argumentos:

## Ejemplo 1

```
main () {  
  
    long *taskids[NUM_THREADS];  
    pthreads_t threads[NUM_THREADS];  
    int t;  
    for(t=0; t<NUM_THREADS; t++){  
        taskids[t] = (long *) malloc(sizeof(long));  
        *taskids[t] = t;  
        printf("Creating thread %ld\n", t);  
        rc = pthread_create(&threads[t], NULL, PrintHello, (void *) taskids[t]);  
        ...  
    }  
}
```

# HILOS POSIX

- **Pase de argumentos:**

## **Ejemplo 2:**

```
struct thread_data{  
    int thread_id;  
    int sum;  
    char *message;  
};  
struct thread_data thread_data_array[NUM_THREADS];  
  
void *PrintHello(void *threadarg) {  
    struct thread_data *my_data;  
    int taskid, sum;  
    char *hello_msg=(char *)malloc(sizeof(char)*MAX_CHAR);  
    ....  
    my_data = (struct thread_data *) threadarg;  
    taskid = my_data->thread_id;  
    sum = my_data->sum;  
    hello_msg = my_data->message;  
    ....  
    pthread_exit(NULL);  
}
```

# HILOS POSIX

- **Pase de argumentos: Ejemplo 2 (cont.):**

```
int main (int argc, char *argv[]){
    pthreads_t threads[NUM_THREADS];
    int t, rc;
    void *status;
    for(t=0; t<NUM_THREADS; t++){
        ...
        thread_data_array[t].thread_id = t;
        thread_data_array[t].sum = sum;
        thread_data_array[t].message = messages[t];

        rc = pthread_create(&threads[t], NULL, PrintHello, (void *) &thread_data_array[t]);

    }
    ....
    for(t=0; t<NUM_THREADS; t++) {
        rc = pthread_join(thread[t], &status);
        if (rc) {
            printf("ERROR; return code from pthread_join() is %d\n", rc);
            exit(-1);
        }
        printf("Main: completed join with thread %ld having a status of %ld\n",t,(long)status);
    }
}
```

# HILOS POSIX

- **Compilación**

- Es importante haber incluido la librería pthreads (`#include <pthread.h>`)

- Un solo programa:

```
gcc hilos.c -lpthread -o ejecutable
```

- En el makefile

```
ejecutable: depend1.o depend2.o ... dependN.o
```

```
gcc -o ejecutable depend1.o depend2.o ... dependN.o -lpthread
```

- **Enlaces de interés**

- <https://computing.llnl.gov/tutorials/pthreads/>

# SINCRONIZACIÓN EN HILOS

- INICIALIZACIÓN:

```
#include <pthread.h>
```

```
int pthread_mutex_init(pthread_mutex_t * restrict mutex, const pthread_mutexattr_t *  
    restrict attr);
```

```
pthread_mutex_t mutex = PTHREAD_MUTEX_INITIALIZER;
```

- LIBERACIÓN:

```
int pthread_mutex_destroy(pthread_mutex_t *mutex);
```

- ACCESO:

```
int pthread_mutex_lock(pthread_mutex_t *mutex);
```

```
int pthread_mutex_trylock(pthread_mutex_t *mutex);
```

```
int pthread_mutex_unlock (pthread_mutex_t *mutex);
```

# SINCRONIZACIÓN EN HILOS

- **pthread\_mutex\_lock()** - acquire a lock on the specified mutex variable. If the mutex is already locked by another thread, this call will block the calling thread until the mutex is unlocked.
- **pthread\_mutex\_unlock()** - unlock a mutex variable. An error is returned if mutex is already unlocked or owned by another thread.
- **pthread\_mutex\_trylock()** - attempt to lock a mutex or will return error code if busy. Useful for preventing deadlock conditions.

# SINCRONIZACIÓN EN HILOS

## ▪ Ejemplo 1:

```
#include <stdio.h>
```

```
#include <stdlib.h>
```

```
#include <pthread.h>
```

```
void *functionC();
```

```
pthread_mutex_t mutex1 = PTHREAD_MUTEX_INITIALIZER;
```

```
int counter = 0;
```

```
main() {
```

```
    int rc1, rc2;
```

```
    pthread_t thread1, thread2;
```

```
    if( (rc1=pthread_create( &thread1, NULL, &functionC, NULL)) ) {
```

```
        printf("Thread creation failed: %d\n", rc1);
```

```
    }
```

```
    if( (rc2=pthread_create( &thread2, NULL, &functionC, NULL)) ) {
```

```
        printf("Thread creation failed: %d\n", rc2);
```

```
    }
```

```
    pthread_join( thread1, NULL);
```

```
    pthread_join( thread2, NULL);
```

```
    exit(0);
```

```
}
```

```
void *functionC() {
```

```
    pthread_mutex_lock( &mutex1 );
```

```
    counter++;
```

```
    printf("Counter value: %d\n",counter);
```

```
    pthread_mutex_unlock( &mutex1 );
```

```
}
```

# SINCRONIZACIÓN EN HILOS

```
#include <stdio.h>
```

```
#include <stdlib.h>
```

```
#include <pthread.h>
```

```
void *functionC1();
```

```
void *functionC2();
```

```
pthread_mutex_t mutex1 = PTHREAD_MUTEX_INITIALIZER,  
                mutex2 = PTHREAD_MUTEX_INITIALIZER;
```

```
int counter1 = 0, counter2=0;
```

```
main() {
```

```
    int rc1, rc2;
```

```
    pthread_t threads1[MAXTHREADS], threads2[MAXTHREADS];
```

```
    for (i = 0; i < MAXTHREADS; i ++)
```

```
        if( (rc1=pthread_create( &threads1[i], NULL, &functionC, NULL)) ) {
```

```
            printf("Thread creation failed: %d\n", rc1);
```

```
        }
```

```
    for (i = 0; i < MAXTHREADS; i ++)
```

```
        if( (rc2=pthread_create( &threads2[i], NULL, &functionC, NULL)) ) {
```

```
            printf("Thread creation failed: %d\n", rc2);
```

```
        }
```

```
    for (i = 0; i < MAXTHREADS; i ++)
```

```
        pthread_join( threads1[i], NULL);
```

```
    for (i = 0; i < MAXTHREADS; i ++)
```

```
        pthread_join( threads2[i], NULL);
```

```
    exit(0);
```

```
}
```



# SINCRONIZACIÓN EN HILOS

```
#include <stdio.h>
```

```
#include <stdlib.h>
```

```
#include <pthread.h>
```

```
void *functionC1();
```

```
void *functionC2();
```

```
pthread_mutex_t mutex1 = PTHREAD_MUTEX_INITIALIZER;
```

```
pthread_mutex_t mutex2 = PTHREAD_MUTEX_INITIALIZER;
```

```
int counter1 = 0, counter2=0;
```

```
main() {
```

```
    int rc1, rc2;
```

```
    pthread_t threads1[MAXTHREADS], threads2[MAXTHREADS];
```

```
    for (i = 0; i < MAXTHREADS; i ++)
```

```
        if( (rc1=pthread_create( &threads1[i], NULL, &functionC, NULL)) != 0)
```

```
            printf("Thread creation failed: %d\n", rc1);
```

```
        }
```

```
    for (i = 0; i < MAXTHREADS; i ++)
```

```
        if( (rc2=pthread_create( &threads2[i], NULL, &functionC, NULL)) != 0)
```

```
            printf("Thread creation failed: %d\n", rc2);
```

```
        }
```

```
    for (i = 0; i < MAXTHREADS; i ++)
```

```
        pthread_join( threads1[i], NULL);
```

```
    for (i = 0; i < MAXTHREADS; i ++)
```

```
        pthread_join( threads2[i], NULL);
```

```
    exit(0);
```

```
}
```

```
void *functionC1() {
```

```
    pthread_mutex_lock( &mutex1 );
```

```
    counter1++;
```

```
    printf("Counter1 value: %d\n",counter1);
```

```
    pthread_mutex_unlock( &mutex1 );
```

```
}
```

```
void *functionC2() {
```

```
    pthread_mutex_lock( &mutex2 );
```

```
    counter2=counter2+2;
```

```
    printf("Counter2 value: %d\n",counter2);
```

```
    pthread_mutex_unlock( &mutex2 );
```

```
}
```