Neeloy Chakraborty

5557 Cottonport Dr, Brentwood, TN 37027 • (412) – 606 – 8494 • <u>neeloyc2@illinois.edu</u> • <u>https://theneeloy.github.io/</u> **Goal:** Pursuing graduate education & full-time opportunities in the field of human-centered autonomy.

Education:

• University of Illinois at Urbana Champaign

Exp. May 2021

o Bachelor of Science in Computer Engineering, Minor in Computational Science & Engineering

GPA 3.68/4.00

o Eta Kappa Nu Honors Society (HKN) & James Scholars Honors

Publications:

• S. Liu*, P. Chang*, **N. Chakraborty**, K. Driggs-Campbell, "Decentralized Vision-Based Robot Crowd Navigation" In preparation for IEEE International Conference on Robotics and Automation (ICRA), 2021.

ICRA 2021

Research Projects:

Multi-Agent Reinforcement Learning Approach to Heist-like Environments (Undergrad Thesis)
 Advisor: Professor Katie Driggs Campbell
 Developing MARL framework to train agents to collaborate in a simulated environment with sparse rewards.

Decentralized Vision-Based Robot Crowd Navigation

Fall 2019 -

Advisor: Professor Katie Driggs Campbell

University of Illinois

Training a robot to reach a goal state while avoiding colliding with other agents, in a partially observable setting.

Teaching Experience:

Undergraduate Course Assistant for Digital Systems Laboratory (ECE 385)
 Providing impactful assistance to students on TTL & System Verilog hardware labs

Aug 2019 – University of Illinois

Industry Experience:

Interim Engineering Intern in Global CAD at Qualcomm

Summer 2020

Building generalized data gathering solutions to support Design for Test pipeline

Qualcomm

- Leading design process of base framework for data gathering tool
- o Collaborating and adapting with international teams to consider multiple perspectives
- Global Management Trainee Intern in Solutions at Anheuser Busch

Summer 2019

Implementing short- and long-term process solutions leveraging technology with an annual ROI of \$1.5M

Anheuser Busch

- o Identifying root causes of multi-million-dollar annual problem via Six Sigma LEAN exercises
- o Pitching solutions to multidisciplinary teams in the People department including Managers & Directors
- Global Management Trainee Intern in Logistics at Anheuser Busch

Summer 2018

Increasing productivity of critical decision-making team by developing clear visualizations

Anheuser Busch

- Creating effective data visualizations through Qlik Sense and SQL databases
- Collaborating with multidisciplinary logistics teams and interns

Additional Projects:

• Efficient FPGA Smart Home Security Camera System (Project Watchdog)

Leading hardware design of accelerated IoT security system (Regional Finalist in InnovateFPGA 2019)

Apr 2019 – Oct 2019

Student Group Project

• Brain Computer Interface Platform for IoT Applications (Project HackMe)

Leading data analytics and storage team (HackIllinois 2019 Runner-up and Sponsor Award Winners)

Student Group Project

Human Interactive Balancing Security Robot (Project at Carnegie Mellon University)
 Advisor: Dr. George Kantor
 Engineering a human interactive segway security robot to roam halls of institution for safety

Aug 2016 – Jun 2017
Carnegie Mellon University

Robotics Project at ZeGoBeast LLC Pittsburgh
 Advisors: Mr. Daniel Goncharov and Mr. Alex Thomson
 Building & improving the ZeGoBeast Electric robot and presenting final work at New York Maker Faire

Coursework:

Artificial Intelligence

Intro to Artificial Intelligence
 Intro to Deep Learning
 Intro to Reinforcement Learning
 Search, classification, natural language understanding, computer vision, robotics
 Intro to Reinforcement Learning
 RL foundations, model-free, policy gradient methods, exploration/exploitation

Robotics

Intro to Robotics robot fundamentals, rigid motion, forward/inverse kinematics, motion planning, control, vision
 Human-Centered Robotics graduate course focusing on tools to design robots that interact with people safely

Hardware/Software Systems

Digital Systems Lab
 Computer Systems Engineering
 logic types, storage, I/O, design tradeoffs, FPGAs, microprocessor design operating system design, I/O, synchronization, interrupts, virtualization

Languages: Python, C/C++, x86 Assembly, System Verilog, Java

Tools: PyTorch, TensorFlow, Git, Raspberry Pi, ROS, OpenCV, Altera FPGAs & Quartus Prime, Autodesk Fusion 360

Soft Skills: Innovative, Leader, Responsible, Adaptable, Collaborative, Open-minded, Persistent

Honors: Dean's List, Anheuser Busch GMT Scholarship, James Scholar Honors, Eta Kappa Nu Honors Society