

Date:

CS 302 HWS

Nov 21, 2019

Q1. a) $a^n b^m$ where $n > m$ and $n > 0$

b) $aab: \delta(q_0, a, z_0) \rightarrow \{(q_1, z_0)\}$

$\delta(q_1, a, z_0) \rightarrow \{(q_1, az_0)\}$

$\delta(q_1, b, a) \rightarrow \{(q_1, e)\}$

$abb: \delta(q_0, a, z_0) \rightarrow \{(q_1, z_0)\}$

No further steps, string is rejected.

$aba: \delta(q_0, a, z_0) \rightarrow \{(q_1, z_0)\}$

No further steps, string is rejected.

c) $aaabbb: \delta(q_0, a, z_0) \rightarrow \{(q_1, z_0)\}$

$\delta(q_1, a, z_0) \rightarrow \{(q_1, az_0)\}$

$\delta(q_1, a, a) \rightarrow \{(q_1, aa)\}$

$\delta(q_1, b, a) \rightarrow \{(q_1, e)\}$

$\delta(q_1, b, a) \rightarrow \{(q_1, e)\}$

Accepted by state (q_1)

$aaab: \delta(q_0, a, z_0) \rightarrow \{(q_1, z_0)\}$

$\delta(q_1, a, z_0) \rightarrow \{(q_1, az_0)\}$

$\delta(q_1, a, a) \rightarrow \{(q_1, aa)\}$

$\delta(q_1, b, a) \rightarrow \{(q_1, e)\}$

Accepted by state (q_1)

DALMATIAN

Q2 a) $Q = \{q_0, q_1, q_2, q_3\}$, $\Sigma = \{a, b\}$, $\Gamma = \{a\}$, $F := \{q_0, q_3\}$

$$\delta(q_0, a, z_0) \rightarrow \{(q_1, a)\}$$

$$\delta(q_0, b, z_0) \rightarrow \{(q_3, \epsilon)\}$$

$$\delta(q_1, a, a) \rightarrow \{(q_1, aa)\}$$

$$\delta(q_1, b, a) \rightarrow \{(q_2, \epsilon)\}$$

$$\delta(q_2, b, \epsilon) \rightarrow \{(q_3, \epsilon)\}$$

b) $Q = \{q_0, q_1, q_2, q_3, f\}$, $\Sigma = \{a, b, c\}$, $\Gamma = \{a, z_0\}$, $F := \{q_0, f\}$

$$\delta(q_0, a, z_0) \rightarrow \{(q_1, a)\}$$

$$\delta(q_0, c, z_0) \rightarrow \{(f, z_0)\}$$

$$\delta(q_1, a, a) \rightarrow \{(q_1, aa)\}$$

$$\delta(q_1, c, a) \rightarrow \{(q_2, a)\}$$

$$\delta(q_2, c, a) \rightarrow \{(q_2, a)\}$$

$$\delta(q_1, b, a) \rightarrow \{(q_3, \epsilon)\}$$

$$\delta(q_2, b, a) \rightarrow \{(q_3, \epsilon)\}$$

$$\delta(q_3, b, a) \rightarrow \{(q_3, \epsilon)\}$$

$$\delta(q_3, c, z_0) \rightarrow \{(f, z_0)\}$$

d) $Q = \{q_0, q_1, q_2, q_3, f\}$, $\Sigma = \{a, b, c\}$, $\Gamma = \{a, b, z_0\}$, $F := \{q_0, f\}$

$$\delta(q_0, a, z_0) \rightarrow \{(q_1, a)\}$$

$$\delta(q_1, a, a) \rightarrow \{(q_1, aa)\}$$

$$\delta(q_1, b, a) \rightarrow \{(q_2, \epsilon)\}$$

$$\delta(q_2, b, a) \rightarrow \{(q_2, \epsilon)\}$$

$$\delta(q_2, b, z_0) \rightarrow \{(q_2, bz_0)\}$$

$$\delta(q_2, c, b) \rightarrow \{(q_3, \epsilon)\}$$

$$\delta(q_3, c, b) \rightarrow \{(q_3, \epsilon)\}$$

$$\delta(q_3, c, z_0) \rightarrow \{(f, z_0)\}$$

Date:

$$e) Q = \{q_0, q_1, q_2, f\}, \Sigma = \{a, b\}, \Gamma = \{a, z_0\}, F := \{q_0, f\}$$

$$\delta(q_0, a, z_0) \rightarrow (q_1, az_0)$$

$$\delta(q_1, a, a) \rightarrow (q_1, aa)$$

$$\delta(q_1, b, a) \rightarrow (q_2, \epsilon)$$

$$\delta(q_2, b, a) \rightarrow (q_2, \epsilon)$$

$$\delta(q_2, b, z_0) \rightarrow (f, z_0)$$

$$\delta(f, b, z_0) \rightarrow (f, z_0)$$

$$f) Q = \{q_0, q_1, q_2, q_3, f\}, \Sigma = \{a, b, c\}, \Gamma = \{a, z_0\}, F := \{q_0, f\}$$

$$\delta(q_0, a, z_0) \rightarrow (q_1, az_0)$$

$$\delta(q_1, a, a) \rightarrow (q_1, aa)$$

$$\delta(q_1, b, a) \rightarrow (q_2, \epsilon)$$

$$\delta(q_2, b, a) \rightarrow (q_2, \epsilon)$$

$$\delta(q_2, c, a) \rightarrow (q_3, \epsilon)$$

$$\delta(q_1, c, a) \rightarrow (q_3, \epsilon)$$

$$\delta(q_3, \epsilon, z_0) \rightarrow (f, z_0)$$

$$\delta(q_2, \epsilon, z_0) \rightarrow (f, z_0)$$

$$\delta(q_3, c, a) \rightarrow (q_3, \epsilon)$$

$$\delta(q_1, c, a) \rightarrow (q_3, \epsilon)$$

Exercise 6.3.2

$$\delta(q_0, e, z_0) \rightarrow (q, Sz_0)$$

$$\delta(q, e, S) \rightarrow (q, aAA)$$

$$\delta(q, e, A) \rightarrow (q, aS)$$

$$\delta(q, e, A) \rightarrow (q, bS)$$

$$\delta(q, e, A) \rightarrow (q, a)$$

$$\delta(q, a, a) \rightarrow (q, \epsilon)$$

$$\delta(q, b, b) \rightarrow (q, \epsilon)$$

$$\delta(q, e, z_0) \rightarrow (q, \epsilon)$$