

Part I

We can model this system with the tuple $S = (Q, \Sigma_1, \Sigma_2, q_0, \vee, \wedge)$, where:

$$Q = \{ \text{dormant, exit, init, idle, monitoring, error_diagnosis, safe_shutdown} \}$$
$$\Sigma_1 = \{ \text{kill, start, init_ok, begin_monitoring, init_crash, retry_init, shutdown, sleep, idle_crash, idle_rescue, moni_rescue} \}$$
$$\Sigma_2 = \{ \text{retry++}, \text{broadcast init_err_msg}, \text{broadcast idle_err_msg}, \text{broadcast moni_err_msg} \}$$
$$q_0 = \text{dormant}$$
$$\vee = \text{retry} : \mathbb{N}_0 ; \text{init_err_msg} : \text{string} ; \text{idle_err_msg} : \text{string} ; \text{moni_err_msg} : \text{string}$$
$$\wedge : \text{transition specification} :$$

1. $\longrightarrow \text{dormant}$
2. $\text{dormant} \xrightarrow{\text{kill}} \text{exit}$
3. $\text{dormant} \xrightarrow{\text{start}} \text{init}$
4. $\text{init} \xrightarrow{\text{kill}} \text{exit}$
5. $\text{init} \xrightarrow{\text{init_ok}} \text{idle}$
6. $\text{idle} \xrightarrow{\text{kill}} \text{exit}$
7. $\text{idle} \xrightarrow{\text{begin_monitoring}} \text{monitoring}$
8. $\text{init} \xrightarrow{\text{init_crash/broadcast init_err_msg}} \text{error_diagnosis}$
9. $\text{error_diagnosis} \xrightarrow{\text{retry_init[retry<3]/ retry++}} \text{init}$
10. $\text{error_diagnosis} \xrightarrow{\text{kill}} \text{exit}$
11. $\text{error_diagnosis} \xrightarrow{\text{shutdown[retry>2]}} \text{safe_shutdown}$
12. $\text{safe_shutdown} \xrightarrow{\text{kill}} \text{exit}$
13. $\text{safe_shutdown} \xrightarrow{\text{sleep}} \text{dormant}$
14. $\text{idle} \xrightarrow{\text{idle_crash/broadcast idle_err_msg}} \text{error_diagnosis}$
15. $\text{error_diagnosis} \xrightarrow{\text{idle_rescue}} \text{idle}$
16. $\text{monitoring} \xrightarrow{\text{monitor_crash/broadcast moni_err_msg}} \text{error_diagnosis}$
17. $\text{error_diagnosis} \xrightarrow{\text{moni_rescue}} \text{monitoring}$
18. $\text{monitoring} \xrightarrow{\text{kill}} \text{exit}$

Part II

As **init** is a composed state, we define it as the tuple $S = (Q, \Sigma_1, q_0, \wedge)$, where:

$$Q = \{ boot_hw, senchk, tchk, psichk, ready \}$$

$$\Sigma_1 = \{ hw_ok, senok, psi_ok \}$$

$$q_0 = boot_hw$$

\wedge : transition specification :

$$1. \longrightarrow boot_hw$$

$$2. boot_hw \xrightarrow{hw_ok} senchk$$

$$3. senchk \xrightarrow{senok} tchk$$

$$4. tchk \xrightarrow{t_ok} psichk$$

$$5. psichk \xrightarrow{psi_ok} ready$$

Part III

As **monitoring** is a composed state, we define it as the tuple $S = (Q, \Sigma_1, \Sigma_2, q_0, \vee, \wedge)$, where:

$$Q = \{ \text{monidle}, \text{regulate_enironment}, \text{lockdown} \}$$

$$\Sigma_1 = \{ \text{no_contagion}, \text{after_100ms}, \text{contagion_alert}, \text{purge_succ} \}$$

$$\Sigma_2 = \{ \text{broadcast FACILITY_CRIT_MESG} \}$$

$$q_0 = \text{monidle}$$

$$\vee = \text{FACILITY_CRIT_MESG} : \text{string} ; \text{inlockdown} : \text{Boolean}$$

$$\wedge : \text{transition specification} :$$

$$1. \longrightarrow \text{monidle}$$

$$2. \text{monidle} \xrightarrow{\text{no_contagion}} \text{regulate_environment}$$

$$3. \text{regulate_environment} \xrightarrow{\text{after_100ms}} \text{monidle}$$

$$4. \text{regulate_environment} \xrightarrow{\text{contagion_alert} / \text{broadcast FACILITY_CRIT_MESG}, \text{inlockdown}:=\text{true}} \text{psichk}$$

$$5. \text{lockdown} \xrightarrow{\text{purge_succ} / \text{inlockdown}:=\text{false}} \text{monidle}$$

super :

$$6. \text{monitoring} \xrightarrow{\text{monitor_crash} [\text{inlockdown}] / \text{broadcast moni_err_msg}} \text{error_diagnosis}$$

$$7. \text{monitoring} \xrightarrow{\text{kill} [\text{inlockdown}]} \text{exit}$$

Part IV

As **lockdown** is a composed state, we define it as the tuple $S = (Q, \Sigma_1, \Sigma_2, q_0, \vee, \wedge)$, where

$$Q = \{ \text{prep_vpurge}, \text{alt_temp}, \text{alt_psi}, \text{risk_assess}, \text{safe_status}, \text{exit} \}$$

$$\Sigma_1 = \{ \text{initiate_purge}, \text{tcyc_comp}, \text{psicyc_comp} \}$$

$$\Sigma_2 = \{ \text{lock_doors}, \text{unlock_doors} \}$$

$$q_0 = \text{prep_vpurge}$$

$$\vee = \text{risk} : \{ \text{risk} \in \mathbb{Q} \mid 0 \leq \text{risk} \leq 1 \}$$

\wedge : transition specification :

$$1. \longrightarrow \text{prep_vpurge}$$

$$2. \text{prep_vpurge} \xrightarrow{\text{initiate_purge/lock_doors}} \text{alt_temp}$$

$$3. \text{prep_vpurge} \xrightarrow{\text{initiate_purge/lock_doors}} \text{alt_psi}$$

$$4. \text{alt_temp} \xrightarrow{\text{tcyc_comp}} \text{risk_assess}$$

$$5. \text{alt_psi} \xrightarrow{\text{psicyc_comp}} \text{risk_assess}$$

$$6. \text{risk_assess} \xrightarrow{[\text{risk} > 0.01]} \text{prep_vpurge}$$

$$7. \text{risk_assess} \xrightarrow{[\text{risk} < 0.01]/\text{unlock_doors}} \text{safe_status}$$

$$8. \text{safe_status} \longrightarrow \text{exit}$$