
Numerical Methods for Differential Equations

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August 14, 2019

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- 1 Introduction
- 2 Euler formula
- 3 Runge-Kutta method
- 4 The stability and convergence of the one-step method
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In this course, we mainly consider about the numerical methods of the first order ODE

$$\begin{cases} y' = f(x, y), a \leq x \leq b \\ y(a) = n. \end{cases} \quad (1)$$

Which under the following assumption

(1). $f(x, y)$ and $\frac{\partial f(x, y)}{\partial y}$ are continues.

(2). The system 1 has a unique solution $y(x)$ and the solution is smooth on the region $\Omega = [a, b]$.

When we consider the numerical methods of this kind of systems. First we discrete the region Ω into n equal parts. We set space step $h = (b - a)/n$, $x_i = a + ih$, ($i = 0, 1, \dots, n$). The numerical solution is regarded as the approximation of the solution of the (1) on the discrete points x_i , ($i = 0, 1, \dots, n$). In order to design the numerical schemes for the ODE problem, we have two concepts.

- 1) Design the scheme based on the differential form.
- 2) Design the scheme based on the integral form.

Also, we have two main computation ways to get the solution. If we just use the information of y_i to get the y_{i+1} , we call these methods the one-step methods. On the other hand, if we need the information of the previous r steps, we call these kind of methods the r -steps methods.

Numerical integration formula

This part will shows some popular integration formulas

- Left rectangle formula

$$\int_a^b g(x)dx = (b-a)g(a) + \frac{(b-a)^2}{2}g'(\xi), \quad \xi \in (a, b)$$

- Right rectangle formula

$$\int_a^b g(x)dx = (b-a)g(b) + \frac{(b-a)^2}{2}g'(\xi), \quad \xi \in (a, b)$$

- Middle rectangle formula

$$\int_a^b g(x)dx = (b-a)g\left(\frac{a+b}{2}\right) + \frac{(b-a)^3}{24}g''(\xi), \quad \xi \in (a, b)$$

- Trapezoid formula

$$\int_a^b g(x) dt = \frac{b-a}{2} [g(a) + g(b)] - \frac{(b-a)^3}{12} g''(\xi) \quad \xi \in (a, b)$$

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Euler formula

We integrate the function (1) on the region $[x_i, x_{i+1}]$

$$\int_{x_i}^{x_{i+1}} y'(x) dx = \int_{x_i}^{x_{i+1}} f(x, y(x)) dx, \quad (2)$$

then, we can have

$$y(x_{i+1}) = y(x_i) + \int_{x_i}^{x_{i+1}} f(x, y(x)) dx. \quad (3)$$

After using the left rectangle formula to deal the integral operator, we can get

$$y(x_{i+1}) = y(x_i) + hf(x_i, y(x_i)) + R_{i+1}^{(1)}, \quad (4)$$

where

$$R_{i+1}^{(1)} = \frac{1}{2} \frac{df(x, y(x))}{dx} \Big|_{x=\xi_i} h^2 = \frac{1}{2} y''(\xi_i) h^2, \xi_i \in (x_i, x_{i+1}). \quad (5)$$

If we ignore the $R_{i+1}^{(1)}$, we have

$$y(x_{i+1}) \approx y(x_i) + hf(x_i, y(x_i)), 0 \leq i \leq n-1. \quad (6)$$

Under the initial condition, we have

$$y(x_0) = \eta \equiv y_0. \quad (7)$$

Putting this into (6) we can get

$$y(x_1) \approx y(x_0) + hf(x_0, y(x_0)) = y_0 + hf(x_0, y_0). \quad (8)$$

Normally, if we already know the approximation y_i of the solution $y(x_i)$, we can get from (6)

$$y(x_{i+1}) \approx y(x_i) + hf(x_i, y(x_i)) \approx y_i + hf(x_i, y_i) \equiv y_{i+1}. \quad (9)$$

Then we can have

$$y_{i+1} = y_i + hf(x_i, y_i), i = 0, 1, \dots, n-1. \quad (10)$$

We call the (10) the Euler formula and we can use this to get the approximation of $y(x_i)$

$$y_i, 0 \leq i \leq n.$$

Obviously, the Euler formula is a one-step explicit scheme.

For the ordinary one-step formula, we have the following structure

$$y_{i+1} = y_i + h\varphi(x_i, y_i, h), \quad (11)$$

$$y_0 = \eta. \quad (12)$$

We call the $\varphi(x_i, y_i, h)$ increment function.

Next, we will show the definition of the local truncation error

Definition 1

We call

$$R_{i+1} = y(x_{i+1}) - [y(x_i) + h\varphi(x_i, y(x_i), h)] \quad (13)$$

the local truncation error of the one-step formula (11) on the point x_{i+1}

From the definition we can see the local truncation error of the Euler formula can be written as

$$R_{i+1} = y(x_{i+1}) - [y(x_i) + hf(x_i, y(x_i))] = \frac{h^2}{2} y''(\xi_i), \xi_i \in (x_i, x_{i+1}) \quad (14)$$

Backward Euler formula

If we use the right rectangle formula to deal with the integral operator of the (6), we can get

$$y(x_{i+1}) = y(x_i) + hf(x_{i+1}, y(x_{i+1})) + R_{i+1}^{(2)}, \quad (15)$$

where

$$R_{i+1} = -\frac{h^2}{2} \frac{df(x, y(x))}{dx} \Big|_{x=\xi_i} = -\frac{h^2}{2} y''(\xi_i), \xi_i \in (x_i, x_{i+1}). \quad (16)$$

We can get

$$y(x_{i+1}) \approx y(x_i) + hf(x_{i+1}, y(x_{i+1})) \approx y_i + hf(x_{i+1}, y_{i+1}), \quad (17)$$

and the backward Euler formula is

$$y_{i+1} = y_i + hf(x_{i+1}, y_{i+1}), \quad i = 0, 1, \dots, n-1. \quad (18)$$

Obviously, the backward Euler formula is a one-step implicit scheme.

For the ordinary one-step implicit formula, we have the following structure

$$y_{i+1} = y_i + h\varphi(x_i, y_i, y_{i+1}, h), \quad (19)$$

$$y_0 = \eta. \quad (20)$$

We call the $\varphi(x_i, y_i, y_{i+1}, h)$ increment function.

Next, we will show the definition of the local truncation error

Definition 2

We call

$$R_{i+1} = y(x_{i+1}) - [y(x_i) + h\varphi(x_i, y(x_i), y(x_{i+1}), h)] \quad (21)$$

the local truncation error of the one-step implicit formula (19) on the point x_{i+1}

From the definition we can see the local truncation error of the backward Euler formula can be written as

$$\begin{aligned} R_{i+1} &= y(x_{i+1}) - y(x_i) - hf(x_{i+1}, y(x_{i+1})) \\ &= -\frac{h^2}{2}y''(\xi_i), \xi_i \in (x_i, x_{i+1}) \end{aligned} \quad (22)$$

Trapezoid formula

If we use the trapezoid formula to deal with the integral operator of the (6), we can get

$$y(x_{i+1}) = y(x_i) + \frac{h}{2}[f(x_i, y(x_i)) + f(x_{i+1}, y(x_{i+1}))] + R_{i+1}^{(3)}, \quad (23)$$

where

$$\begin{aligned} R_{i+1} &= -\frac{h^3}{12} \frac{d^2 f(x, y(x))}{dx^2} \Big|_{x=\xi_i} \\ &= -\frac{1}{12} y'''(\xi_i) h^3, \quad \xi_i \in (x_i, x_{i+1}). \end{aligned} \quad (24)$$

If we ignore the $R_{i+1}^{(3)}$, we can have

$$\begin{aligned}y(x_{i+1}) &\approx y(x_i) + \frac{h}{2}[f(x_i, y(x_i)) + f(x_{i+1}, y(x_{i+1}))] \\&\approx y_i + \frac{h}{2}[f(x_i, y_i) + f(x_{i+1}, y_{i+1})],\end{aligned}\quad (25)$$

then we can get the trapezoid scheme of the (6)

$$y_{i+1} = y_i + \frac{h}{2}[f(x_i, y_i) + f(x_{i+1}, y_{i+1})], i = 0, 1, \dots, n-1. \quad (26)$$

It is a one-step implicit scheme, and the local truncation error is

$$\begin{aligned}R_{i+1} &= y(x_{i+1}) - \{y(x_i) + \frac{h}{2}[f(x_i, y(x_i)) + f(x_{i+1}, y(x_{i+1}))]\} \\&= -\frac{1}{12}y'''(\xi_i)h^3, \xi_i \in (x_i, x_{i+1}).\end{aligned}\quad (27)$$

Improved Euler formula

In this case, we use two steps to get the solution: the predicted step and the correction step.

$$\begin{cases} y_{i+1}^{(p)} = y_i + hf(x_i, y_i) (\text{predicted formula}) \\ y_{i+1} = y_i + \frac{h}{2}[f(x_i, y_i) + f(x_{i+1}, y_{i+1}^{(p)})] (\text{correction formula}) \end{cases} \quad (28)$$

We call the above formula system the improved Euler formula. It is a one-step explicit formula and we can transform this into the following form

$$\begin{cases} y_{i+1}^{(p)} = y_i + hf(x_i, y_i) \\ y_{i+1}^{(c)} = y_i + hf(x_{i+1}, y_{i+1}^{(p)}) \\ y_{i+1} = \frac{1}{2}(y_{i+1}^{(p)} + y_{i+1}^{(c)}) \end{cases} \quad (29)$$

$$y_{i+1} = y_i + \frac{1}{2}[f(x_i, y_i) + f(x_{i+1}, y_i + hf(x_i, y_i))]. \quad (30)$$

The local truncation error can be written as

$$R_{i+1} = y(x_{i+1}) - y(x_i) - \frac{h}{2}[f(x_i, y(x_i)) + f(x_{i+1}, y(x_i) + f(x_i, y(x_i)))]. \quad (31)$$

We have two ways to get the local truncation error of the improved Euler formula.

METHOD 1:

$$\begin{aligned} R_{i+1} &= y(x_{i+1}) - y(x_i) - \frac{h}{2}[f(x_i, y(x_i)) + f(x_{i+1}, y(x_{i+1}))] \\ &\quad + \frac{h}{2}[f(x_{i+1}, y(x_{i+1})) - f(x_{i+1}, y(x_i) + hf(x_i, y(x_i)))] \\ &= -\frac{1}{2}y'''(\xi_i)h^3 + \frac{h}{2}\frac{\partial f(x_{i+1}, \eta_{i+1})}{\partial y}[y(x_{i+1}) - y(x_i) - hf(x_i, y(x_i))] \\ &= -\frac{1}{12}y'''(\xi_i)h^3 + \frac{h}{4}\frac{\partial f(x_{i+1}, \eta_{i+1})}{\partial y}y''(\tilde{\xi}_i)h^2 \\ &= [-\frac{1}{12}y'''(\xi_i) + \frac{1}{4}\frac{\partial f(x_{i+1}, \eta_{i+1})}{\partial y}y''(\tilde{\xi}_i)]h^3. \end{aligned}$$

METHOD 2:

We make the Taylor expansion of $y(x_i)$ on the point x_i and make the Taylor expansion of $f(x_{i+1}, y(x_i) + hf(x_i, y(x_i)))$ on the point $(x_i, y(x_i))$.

$$y(x_{i+1}) = y(x_i) + hy'(x_i) + \frac{1}{2!}h^2y''(x_i) + \frac{1}{3!}h^3y'''(x_i) + O(h^4),$$

$$\begin{aligned} f(x_{i+1}, y(x_i) + hf(x_i, y(x_i))) &= f(x_i + h, y(x_i) + hf(x_i, y(x_i))) \\ &= f(x_i, y(x_i)) + h\frac{\partial f}{\partial x}(x_i, y(x_i)) + hf(x_i, y(x_i))\frac{\partial f}{\partial y}(x_i, y(x_i)) \\ &\quad + \frac{1}{2!}[h^2\frac{\partial^2 f}{\partial x^2}(x_i, y(x_i)) + 2h^2f(x_i, y(x_i))\frac{\partial^2 f}{\partial x\partial y}(x_i, y(x_i)) \\ &\quad + h^2(f(x_i, y(x_i))^2\frac{\partial^2 f}{\partial y^2}(x_i, y(x_i)))] + O(h^3) \end{aligned}$$

$$= y'(x_i) + hy''(x_i) + \frac{1}{2}h^2(y'''(x_i) - y''(x_i)\frac{\partial f}{\partial y}(x_i, y(x_i))) + O(h^3)$$

Then we can have the local truncation error

$$\begin{aligned} R_{i+1} &= y(x_i) + hy'(x_i) + \frac{1}{2!}h^2y''(x_i) + \frac{1}{3!}y'''(x_i) + O(h^4) \\ &\quad - y(x_i) - \frac{1}{2}hy'(x_i) \\ &\quad - \frac{1}{2}h[y'(x_i) + hy''(x_i) + \frac{1}{2}h^2(y'''(x_i) - y''(x_i)\frac{\partial f}{\partial y}(x_i, y(x_i)))) + \\ &\quad O(h^3)] \\ &= [-\frac{1}{12}y'''(x_i) + \frac{1}{4}y''(x_i)\frac{\partial f}{\partial y}(x_i, y(x_i))]h^3 + O(h^4). \end{aligned}$$

Definition 3

If the local truncation error of the scheme is $R_{i+1} = O(h^{p+1})$, then we call this scheme the p -th order scheme.

According to this definition, we can see that the Euler formula and the backward Euler formula are first-order schemes, the trapezoid formula and the improved Euler formula are second-order schemes.

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The construction idea of Runge-Kutta method

Using the

$$y(x_{i+1}) = y(x_i) + \int_{x_i}^{x_{i+1}} f(x, y(x)) dx,$$

we can have

$$y(x_{i+1}) = y(x_i) + hf(x_i + \theta h, y(x_i + \theta h)).$$

The term $f(x_i + \theta h, y(x_i + \theta h))$ is called the average gradient of $y(x)$ on $[x_i, x_{i+1}]$ and we use k^* as the notation.

We set

$$k_1 = f(x_i, y_i),$$

$$k_2 = f(x_{i+1}, y_i + hk_1),$$

if we use k_1 to approximate the k^* , we will have the first-order Euler formula. If we use $\frac{k_1+k_2}{2}$ to approximate the k^* , we will have the second-order improved second-order Euler formula.

Generally, the r -level Runge-Kutta method have the following form

$$\begin{cases} y_{i+1} = y_i + h \sum_{j=1}^r \alpha_j k_j \\ k_1 = f(x_i, y_i) \\ k_j = f(x_i + \lambda_j h, y_i + h \sum_{l=1}^{j-1} \mu_{jl} k_l), j = 2, 3, \dots, r \end{cases} \quad (32)$$

After choosing appropriate coefficients $\alpha_j, \lambda_j, \mu_{jl}$, we can get any order scheme.

Specifically, we consider the local truncation of the r -level Runge-Kutta method

$$R_{i+1} = y(x_{i+1}) - y(x_i) - h \sum_{j=1}^r \alpha_j K_j,$$

where

$$K_1 = f(x_i, y(x_i)),$$

$$K_j = f(x_i + \lambda_j h, y(x_i) + h \sum_{l=1}^{j-1} \mu_{jl} K_l), j = 2, 3, \dots, r,$$

We then expand it into a power series of h

$$R_{i+1} = c_0 + c_1 h + \dots + c_p h^p + c_{p+1} h^{p+1} + \dots$$

Then we let the $c_0 = c_1 = \dots = c_p$ and $c_{p+1} \neq 0$ by choosing appropriate coefficients $\alpha_j, \lambda_j, \mu_{jl}$. Then we get a p_{th} -order Runge-Kutta method.

Second-order Runge-Kutta method

The ordinary form of the second-order Runge-Kutta method can be written as

$$\begin{cases} y_{i+1} = y_i + h(\alpha_1 k_1 + \alpha_2 k_2) \\ k_1 = f(x_i, y_i) \\ k_2 = f(x_i + \lambda_2 h, y_i + h\mu_{21} k_1) \end{cases} \quad (33)$$

The local truncation error is

$$\begin{cases} R_{i+1} = y(x_{i+1}) - y(x_i) - h(\alpha_1 K_1 + \alpha_2 K_2) \\ K_1 = f(x_i, y(x_i)) \\ K_2 = f(x_i + \lambda_2 h, y(x_i) + h\mu_{21} K_1) \end{cases} \quad (34)$$

We also have

$$\begin{aligned}y(x_{i+1}) &= y(x_i) + hy'(x_i) + \frac{1}{2}h^2y''(x_i) + \frac{1}{3!}h^3y'''(x_i) + O(h^4) \\&= y(x_i) + hy'(x_i) + \frac{1}{2}h^2\left[\frac{\partial f}{\partial x}(x_i, y(x_i))\right. \\&\quad \left.+ y'(x_i)\frac{\partial f}{\partial y}(x_i, y(x_i))\right] + O(h^4),\end{aligned}$$

$$K_1 = y'(x_i),$$

$$\begin{aligned}K_2 &= f(x_i, y(x_i)) + \lambda_2 h \frac{\partial f}{\partial x}(x_i, y(x_i)) + h\mu_{21}y'(x_i)\frac{\partial f}{\partial x}(x_i, y(x_i)) \\&\quad + \frac{1}{2}\left[(\lambda_2 h)\frac{\partial^2 f}{\partial x^2}(x_i, y(x_i)) + 2\lambda_2\mu_{21}h^2y'(x_i)\frac{\partial^2 f}{\partial y^2}(x_i, y(x_i))\right. \\&\quad \left.+ (\mu_{21}hy'(x_i))^2\frac{\partial^2 f}{\partial y^2}(x_i, y(x_i))\right] + O(h^3).\end{aligned}$$

Put all the above equation into (34), we can have

$$\begin{aligned} R_{i+1} = & h(1 - \alpha_1 - \alpha_2)y'(x_i) + h^2\left[\left(\frac{1}{2} - \alpha_2\lambda_2\right)\frac{\partial f}{\partial x}(x_i, y(x_i))\right. \\ & + \left.\left(\frac{1}{2} - \alpha_2\mu_{21}\right)y'(x_i)\frac{\partial f}{\partial x}(x_i, y(x_i))\right] \\ & + h^3\left[\frac{1}{6}y'''(x_i) - \frac{1}{2}\alpha_2((\lambda + 2)^2\frac{\partial^2 f}{\partial x^2}(x_i, y(x_i))\right. \\ & + 2\lambda_2\mu_{21}y'(x_i)\frac{\partial^2 f}{\partial x\partial y}(x_i, y(x_i)) \\ & + \left.\left.\left(\mu_{21}y'(x_i)\right)^2\frac{\partial^2 f}{\partial y^2}(x_i, y(x_i))\right)\right] + O(h^4). \end{aligned}$$

If we want to get a second-order Runge-Kutta scheme, we need to solve the following system

$$\begin{cases} 1 - \alpha_1 - \alpha_2 = 0 \\ \frac{1}{2} - \alpha_2 \lambda_2 = 0 \\ \frac{1}{2} - \alpha_2 \mu_{21} = 0 \end{cases}$$

Obviously, α_2 cannot be zero.

When $\alpha_2 \neq 0$, we can get

$$\begin{cases} \alpha_1 = 1 - \alpha_2 \\ \lambda_2 = \frac{1}{2\alpha_2} \\ \mu_{21} = \frac{1}{2\alpha_2}. \end{cases}$$

So we can get a series of second-order Runge-Kutta formulas

$$\begin{cases} y_{i+1} = y_i + h[(1 - \alpha_2)k_1 + \alpha_2 k_2] \\ k_1 = f(x_i, y_i) \\ k_2 = f(x_i + \frac{1}{2\alpha_2}h, y_i + \frac{1}{2\alpha_2}hk_1). \end{cases}$$

When $\alpha_2 = \frac{1}{2}$, we can get the improved Euler formula. When $\alpha = 1$, we can get transformed Euler formula

$$\begin{cases} y_{i+1} = y_i + hk_2 \\ k_1 = f(x_i, y_i) \\ k_2 = f(x_i + \frac{1}{2}h, y_i + \frac{1}{2}hk_1). \end{cases}$$

If we choose $\alpha_2 = \frac{3}{4}$, we can have

$$\begin{cases} y_{i+1} = y_i + \frac{h}{4}(k_1 + 3k_2) \\ k_1 = f(x_i, y_i) \\ k_2 = f(x_i + \frac{2}{3}h, y_i + \frac{2}{3}hk_1). \end{cases}$$

We can also use the similar technic to build third-order, 4_{th}-order or even higher order Runge-Kutta schemes.

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Convergence

Definition 4

If $\{y(x_i)\}_{i=1}^n$ is the solution of the (1), $\{y_i^{[h]}\}_{i=1}^n$ is the approximate solution resulted from some numerical scheme. We call

$$E(h) = \max |y(x_i) - y_i^{[h]}|, \quad 1 \leq i \leq n$$

the global truncation error of the numerical scheme. If

$$\lim_{h \rightarrow 0} E(h) = 0,$$

we call the scheme is convergent.

Now we consider the one-step formula

$$\begin{cases} y_{i+1} = y_i + h\varphi(x_i, y_i, h), & i = 0, 1, \dots, n-1, \\ y_0 = \eta. \end{cases} \quad (35)$$

Theorem 5

Set $y(x)$ is the solution of the (1), $\{y_i\}_{i=0}^n$ is the solution of the (35). If

- There exists a constant $c_0 > 0$,

$$|R_{i+1}| \leq c_0 h^{p+1}, \quad i = 0, 1, \dots, n-1,$$

- There exists $h_0 > 0$, $L > 0$,

$$\max \left| \frac{\partial \varphi(x, y, h)}{\partial y} \right| \leq L.$$

Then, when $h \leq \min\{h_0 \sqrt[p]{\frac{\delta}{c}}\}$, we have

$$E(h) \leq ch^p.$$

where

$$D_\delta = \{(x, y) | a \leq x \leq b, y(x) - \delta \leq y \leq y(x) + \delta\},$$

$$c = \frac{c_0}{L} [e^{L(b-a)} - 1].$$

Stability

Definition 6

To the problem (1), we assume that $\{y_i\}_{i=0}^n$ is the approximate solution of the (35), $\{z_i\}_{i=0}^n$ is the solution with a tiny perturbation of the (35). Which have

$$\begin{cases} z_{i+1} = z_i + h[\varphi(x_i, y_i, h) + \delta_{i+1}], & i = 0, 1, \dots, n-1 \\ z_0 = \eta + \delta_0. \end{cases} \quad (36)$$

If we have positive constants C, ε_0, h_0 , for all $\varepsilon \in (0, \varepsilon_0]$, $h \in (0, h_0]$. When $\max|\delta_i| \leq \varepsilon$, we have

$$\max|y_i - z_i| \leq C_\varepsilon.$$

We call the one-step scheme (35) stable.

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For the ordinary linear multi-step method we have the following general form

$$y_{i+1} = \sum_{j=0}^{k-1} a_j y_{i-j} + h \sum_{j=-1}^{k-1} b_j f(x_{i-j}, y_{i-j}), \quad (37)$$

where a_{k-1} and b_{k-1} can not be zero at the same time. When $b_{-1} = 0$, we have a explicit scheme; When $b_{-1} \neq 0$, we have a implicit scheme.

Definition 7

We call

$$R_{i+1} = y(x_{i+1}) - \left[\sum_{j=0}^{k-1} a_j y(x_{i-j}) + h \sum_{j=-1}^{k-1} b_j f(x_{i-j}, y(x_{i-j})) \right]$$

the local truncation error of (37) at the point x_{i+1} . When $R_{i+1} = O(h^{p+1})$, we call the (37) is a p_{th} order scheme.

Scheme based on the integration-Adams formula

We integrate the equation $y'(x) = f(x, y(x))$ on the interval $[x_i, x_{i+1}]$, we have

$$y(x_{i+1}) = y(x_i) + \int_{x_i}^{x_{i+1}} f(x, y(x)) dx. \quad (38)$$

1) Adams explicit scheme

Using the $x_i, x_{i-1}, \dots, x_{i-r}$ as the interpolation points, we get the Lagrange interpolation formula $L_r(x)$ from $f(x, y(x))$:

$$\begin{aligned} L_{i,r}(x) &= \sum_{j=0}^r f(x_{i-j}, y(x_{i-j})) l_{i-j}(x) \\ &= \sum_{j=0}^r f(x_{i-j}, y(x_{i-j})) \prod_{l=0, l \neq j}^r \frac{x - x_{i-l}}{x_{i-j} - x_{i-l}} \end{aligned}$$

We have

$$\begin{aligned}f(x, y(x)) &= L_{i,r}(x) + R_{i,r}(x) \\&= L_{i,r}(x) + \frac{1}{(r+1)!} \frac{d^{r+1}f(x, y(x))}{dx^{r+1}} \Big|_{x=\eta_i} \prod_{j=0}^r (x - x_{i-j}) \\&= L_{i,r}(x) + \frac{1}{(r+1)!} y^{(r+2)}(\eta_i) \prod_{j=0}^r (x - x_{i-j}).\end{aligned}\tag{39}$$

Put (39) into (38), we have

$$y(x_{i+1}) = y(x_i) + \int_{x_i}^{x_{i+1}} L_{i,r}(x) dx + \int_{x_i}^{x_{i+1}} R_{i,r}(x) dx$$

$$\begin{aligned}
&= y(x_i) + \sum_{j=0}^r f(x_{i-j}, y(x_{i-j})) \int_{x_i}^{x_{i+1}} \prod_{l=0, l \neq j}^r \frac{x - x_{i-l}}{x_{i-j} - x_{i-l}} dx \\
&+ \frac{1}{(r+1)!} \int_{x_i}^{x_{i+1}} y^{(r+2)}(\eta_i) \prod_{j=0}^r (x - x_{i-j}) dx \\
&= y(x_i) + h \sum_{j=0}^r f(x_{i-j}, y(x_{i-j})) \int_0^1 \prod_{l=0, l \neq j}^r \frac{l+t}{l-j} dt \quad (\text{set } x = x_i + th) \\
&+ h^{r+2} y^{(r+2)}(\xi_i) \frac{1}{(r+1)!} \int_0^1 \prod_{j=0}^r (j+t) dt,
\end{aligned}$$

where $\xi_i \in (x_{i-r}, x_{i+1})$

$$\beta_{rj} = \int_0^1 \prod_{l=0, l \neq j}^r \frac{l+t}{l-j} dt, \quad j = 0, 1, \dots, r,$$

$$\alpha_{r+1} = \frac{1}{(r+1)!} \int_0^1 \prod_{j=0}^r (j+t) dt,$$

then

$$y(x_{i+1}) = y(x_i) + h \sum_{j=0}^r \beta_{rj} f(x_{i-j}, y(x_{i-j})) \\ + \alpha_{r+1} h^{r+2} y^{(r+2)}(\xi_i).$$

If we ignore the $\alpha_{r+1} h^{r+2} y^{(r+2)}(\xi_i)$ and replace the $y(x_{i-j})$ with y_{i-j} . We can get the r-steps Adams explicit formula:

$$y_{i+1} = y_i + h \sum_{j=0}^r \beta_{rj} f(x_{i-j}, y_{i-j}). \quad (40)$$

The local truncation error of the (40) is

$$\begin{aligned} R_{i+1} &= y(x_{i+1}) - [y(x_i) + h \sum_{j=0}^r \beta_{rj} f(x_{i-j}, y(x_{i-j}))] \\ &= \alpha_{r+1} h^{r+2} y^{(r+2)}(\xi_i) \end{aligned}$$

So, (40) is a $(r+1)$ steps and $(r+1)$ order Adams formula.

(a) $r=0$, we have the Euler formula

$$y_{i+1} = y_i + hf(x_i, y_i),$$

$$R_{i+1} = \frac{1}{2}h^2 y''(\xi_i), \quad \xi_i \in (x_i, x_{i+1}).$$

(b) $r=1$, we have

$$y_{i+1} = y_i + \frac{h}{2}[3f(x_i, y_i) - f(x_{i-1}, y_{i-1})],$$

$$R_{i+1} = \frac{5}{12}h^3 y^{(3)}(\xi_i), \quad \xi_i \in (x_{i-1}, x_{i+1}).$$

(c) $r=2$, we have

$$y_{i+1} = y_i + \frac{h}{12}[23f(x_i, y_i) - 16f(x_{i-1}, y_{i-1}) + 5f(x_{i-2}, y_{i-2})],$$

$$R_{i+1} = \frac{3}{8}h^4 y^{(4)}(\xi_i), \quad \xi_i \in (x_{i-2}, x_{i+1}).$$

(d) $r=3$, we have

$$y_{i+1} = y_i + \frac{h}{24}[55f(x_i, y_i) - 59f(x_{i-1}, y_{i-1}) \\ + 37f(x_{i-2}, y_{i-2}) - 9f(x_{i-3}, y_{i-3})],$$

$$R_{i+1} = \frac{251}{720}h^5 y^{(5)}(\xi_i), \quad \xi_i \in (x_{i-3}, x_{i+1}).$$

2) Adams implicit formula

Using the $x_{i+1}, x_i, x_{i-1}, \dots, x_{i-r+1}$ as the interpolation points, we get the Lagrange interpolation formula $L_r(x)$ from $f(x, y(x))$:

$$\begin{aligned} L_{i,r}(x) &= \sum_{j=-1}^{r-1} f(x_{i-j}, y(x_{i-j})) l_{i-j}(x) \\ &= \sum_{j=-1}^{r-1} f(x_{i-j}, y(x_{i-j})) \prod_{l=-1, l \neq j}^{r-1} \frac{x - x_{i-l}}{x_{i-j} - x_{i-l}} \end{aligned}$$

We have

$$\begin{aligned}
 f(x, y(x)) &= L_{i,r}(x) + R_{i,r}(x) \\
 &= L_{i,r}(x) + \frac{1}{(r+1)!} \frac{d^{r+1}f(x, y(x))}{dx^{r+1}} \Big|_{x=\eta_i} \prod_{j=-1}^{r-1} (x - x_{i-j}) \\
 &= L_{i,r}(x) + \frac{1}{(r+1)!} y^{(r+2)}(\bar{\eta}_i) \prod_{j=-1}^{r-1} (x - x_{i-j}).
 \end{aligned}$$

We put the function above into (38), we can get

$$\begin{aligned}
 y(x_{i+1}) &= y(x_i) + h \sum_{j=-1}^{r-1} f(x_{i-j}, y(x_{i-j})) \int_0^1 \prod_{l=-1, l \neq j}^{r-1} \frac{l+t}{l-j} dt \quad (x = x_i) \\
 &\quad + h^{r+2} y^{(r+2)}(\bar{\xi}_i) \frac{1}{(r+1)!} \int_0^1 \prod_{j=-1}^{r-1} (j+t) dt.
 \end{aligned}$$

Where $\bar{\xi}_i \in (x_{i-r+1}, x_{i+1})$, and

$$\bar{\beta}_{rj} = \int_0^1 \prod_{l=-1, l \neq j}^{r-1} \frac{l+t}{l-j}.$$

$$\bar{\alpha}_{r+1} = \frac{1}{(r+1)!} \int_0^1 \prod_{j=-1}^{r-1} (j+t).$$

We can have

$$\begin{aligned} y(x_{i+1}) &= y(x_i) + h \sum_{j=-1}^{r-1} \bar{\beta}_{rj} f(x_{i-j}, y(x_{i-j})) \\ &\quad + \bar{\alpha}_{r+1} h^{r+2} y^{(r+2)}(\bar{\xi}_i). \end{aligned}$$

If we ignore $\bar{\alpha}_{r+1}h^{r+2}y^{(r+2)}(\bar{\xi}_i)$ and replace $y(x_{i-j})$ with y_{i-j} , we can get r steps Adams implicit formula:

$$y_{i+1} = y_i + h \sum_{j=-1}^{r-1} \bar{\beta}_{rj} f(x_{i-j}, y_{i-j}). \quad (41)$$

Its local truncation error can be written as

$$\begin{aligned} R_{i+1} &= y(x_{i+1}) - [y(x_i) + h \sum_{j=-1}^{r-1} \bar{\beta}_{rj} f(x_{i-j}, y_{i-j})] \\ &= \bar{\alpha}_{r+1}h^{r+2}y^{(r+2)}(\bar{\xi}_i). \end{aligned}$$

So it is a r-steps, $(r+1)$ -order implicit Adams formula.

(a) $r=1$, we get the trapezoid formula

$$y_{i+1} = y_i + \frac{h}{2}[f(x_{i+1}, y_{i+1}) + f(x_i, y_i)]$$

$$R_{i+1} = -\frac{1}{12}h^3 y'''(\xi_i), \quad \xi_i \in (x_i, x_{i+1}).$$

(b) $r=2$, we get

$$y_{i+1} = y_i + \frac{h}{12}[5f(x_{i+1}, y_{i+1}) + 8f(x_i, y_i) - f(x_{i-1}, y_{i-1})]$$

$$R_{i+1} = -\frac{1}{24}h^4 y^{(4)}(\xi_i), \quad \xi_i \in (x_{i-1}, x_{i+1})$$

Adams predictor-corrector method

Combining the explicit Adams formula and the implicit Adams formula, we can get the Adams predictor-corrector method. For example, if we combine the second-order explicit Adams formula and the second-order implicit Adams formula, we can get the following predictor-corrector method

$$\text{step 1 } y_{i+1}^{(p)} = y_i + \frac{h}{2}[3f(x_i, y_i) - f(x_{i-1}, y_{i-1})]$$

$$\text{step 2 } y_{i+1} = y_i + \frac{h}{2}[f(x_{i+1}, y_{i+1}^{(p)}) + f(x_i, y_i)]$$

Here, we first use the explicit formula to get the predict term $y_{i+1}^{(p)}$. Then we use the predict term to get the y_{i+1} .

Also, we can give a fourth order Adams predictor-corrector method:

$$\text{step 1 } y_{i+1}^{(p)} = y_i + \frac{h}{24} [55f(x_i, y_i) - 59f(x_{i-1}, y_{i-1}) + 37f(x_{i-2}, y_{i-2}) - 9f(x_{i-3}, y_{i-3})]$$

$$\text{step 2 } y_{i+1} = y_i + \frac{h}{24} [9f(x_{i+1}, y_{i+1}^{(p)}) + 19f(x_i, y_i) - 5f(x_{i-1}, y_{i-1}) + f(x_{i-2}, y_{i-2})]$$

The method of undetermined coefficients based on the Taylor expansion

If we want to create the linear k-steps scheme as follows

$$y_{i+1} = \sum_{j=0}^{k-1} a_j y_{i-j} + h \sum_{j=-1}^{k-1} b_j f(x_{i-j}, y_{i-j}), \quad (42)$$

it has the local truncation error

$$R_{i+1} = y(x_{i+1}) - \left[\sum_{j=0}^{k-1} a_j y(x_{i-j}) - h \sum_{j=-1}^{k-1} b_j f(x_{i-j}, y(x_{i-j})) \right]$$

Using the equation (1) and the Taylor expansion we can get

$$\begin{aligned}
 R_{i+1} &= y(x_{i+1}) - \sum_{j=0}^{k-1} a_j y(x_{i-j}) - h \sum_{j=-1}^{k-1} b_j y'(x_{i-j}) \\
 &= \left(1 - \sum_{j=0}^{k-1} a_j\right) y(x_i) + \sum_{l=1}^{p+1} \frac{1}{l!} \left[1 - \sum_{j=0}^{k-1} (-j)^l a_j - l \sum_{j=-1}^{k-1} (-j)^{l-1} b_j\right] \\
 &\quad h^l y^{(l)}(x_i) + O(h^{p+2}).
 \end{aligned}$$

If we want (42) to be a p_{th} order scheme, the coefficients a_j and b_j need to obey

$$1 - \sum_{j=0}^{k-1} a_j = 0$$

$$1 - \sum_{j=0}^{k-1} (-j)^l a_j - l \sum_{j=-1}^{k-1} (-j)^{l-1} b_j = 0. \quad l = 1, 2, \dots, p$$

Now, the local truncation error is shown as follows

$$R_{i+1} = \frac{1}{(p+1)!} \left[1 - \sum_{j=0}^{k-1} (-j)^{p+1} a_j \right. \\ \left. - (p+1) \sum_{j=-1}^{k-1} (-j)^p b_j \right] h^{p+1} y^{(p+1)}(x_i) + O(h^{p+2})$$