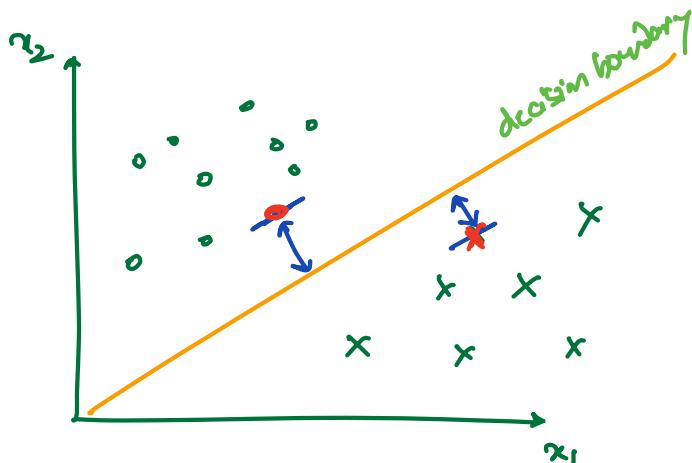
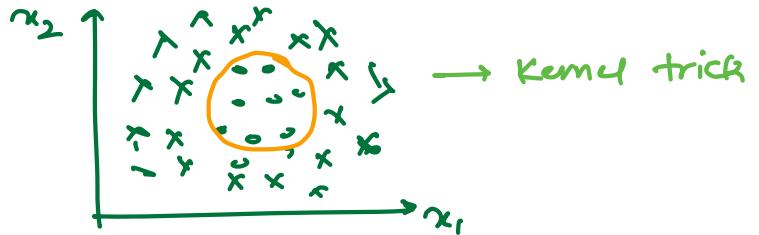
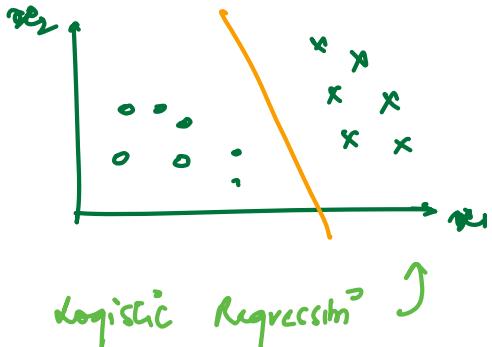


SVM (Support Vector Machine)

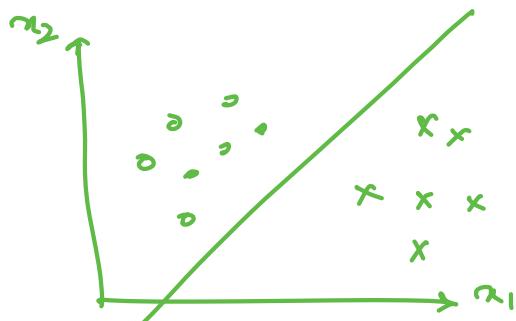
classifier → linearly separable data
 → non linearly separable data



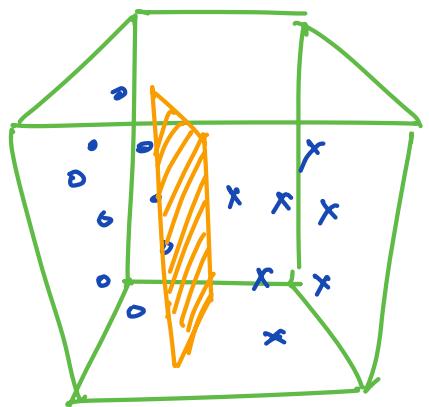
SVM:
 Points which are closest to your decision boundary should be very far away from each other.

Hyperplane:

n features hyperplane will be of n-1 dimensions & it should separate both the classes.



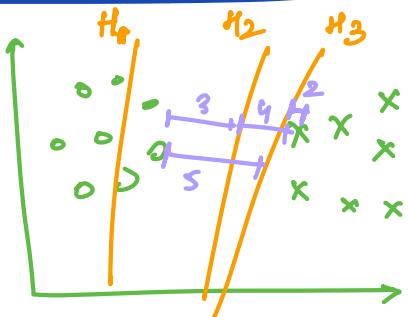
2 features:
 db: line (1D)



3D features

2D hyperplane : plane

Separating hyperplane:



$H_1 \rightarrow$ Separating hyperplane X

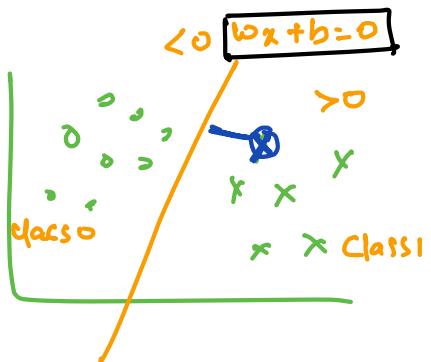
$H_2, H_3 \checkmark$

$$\begin{aligned} H_3: & (2, 5) - 2 \\ H_2: & (2, 4) - (2) \end{aligned} \quad] \text{ maximize it}$$



minimum distance

hyperplane is a separating hyperplane if:



$$y = mx + c$$

$$\frac{w_2 + b}{\|w\|_2} \rightarrow >0$$

$$w_2 + b > 0$$

If data points are from class 1

$$w_2 + b < 0$$

If data points are from class 0

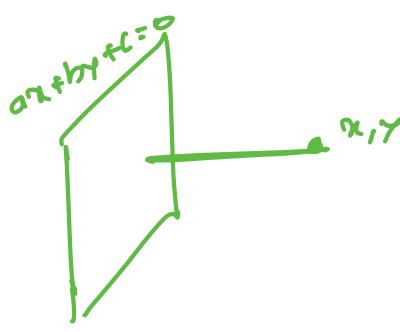
Linear Regressor:

$$\theta^T x = 0 \quad m\bar{x} + c = 0$$

$$x_1, x_2, x_3, \dots, x_n$$

$$\theta_1 x_1 + \theta_2 x_2 + \dots + \theta_n x_n + \dots$$

$$\theta_n x_n + \theta_0 x_0$$



$$\frac{ax + by + c}{\sqrt{a^2 + b^2}}$$

normalized distance

L_2 norm

$$\text{L}_2 \text{ norm: } (a^2 + b^2)^{1/2}$$

L_3 norm:

$$(a^3 + b^3)^{\frac{1}{3}}$$

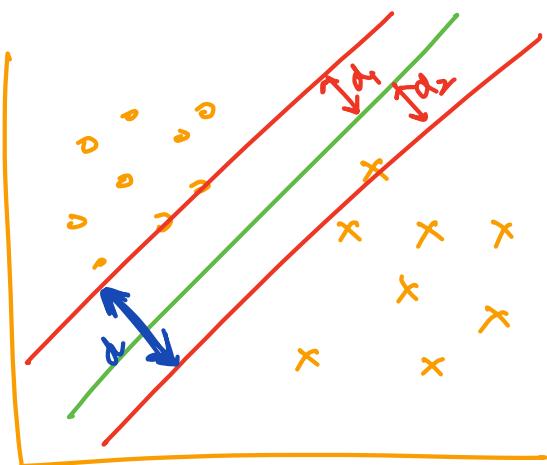
$$\frac{L_2 \text{ norm:}}{(a^2 + b^2)^{\frac{1}{2}}}$$

$$\omega x + b \rightarrow \omega_1 x_1 + \omega_2 x_2 + b = 0$$

\downarrow
bias

x_1, x_2 features
 ω_1, ω_2 weights

$$\frac{\omega_1 x_1^{(i)} + \omega_2 x_2^{(i)} + b}{\sqrt{\omega_1^2 + \omega_2^2}} \rightarrow \|\omega\|_2 \rightarrow L_2 \text{ norm}$$



hyperplane with maximum margin

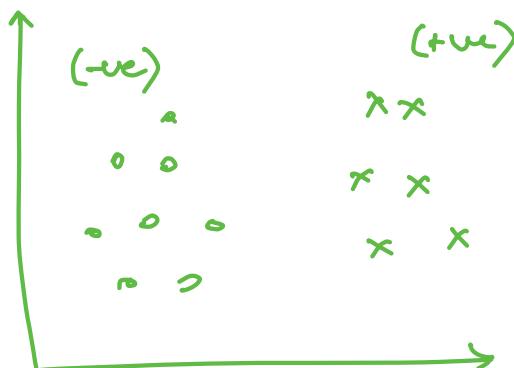
formulating Objective

$$x = \{x^1, x^2, \dots, x^m\}$$

$$Y = \{y^1, y^2, \dots, y^m\}$$

Binary Classification: $y^{(i)} \in \{-1, 1\}$

↳ class label will be 1 or -1



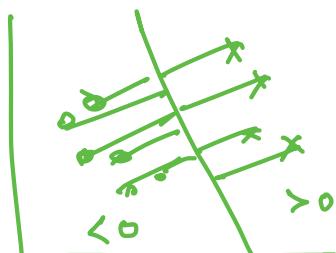
find a separating hyperplane with maximum margin.

$$\omega = \begin{bmatrix} \omega_1 \\ \omega_2 \\ \omega_3 \\ \vdots \\ \omega_n \end{bmatrix}$$

$$x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

$$\omega^T x + b = 0 \rightarrow \text{hyperplane equation}$$

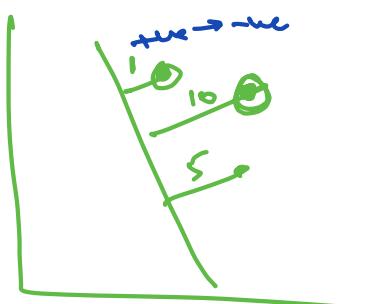
→ Separating hyperplane:



$$\omega^T x + b > 0 \quad \text{if } x \in \text{true class}$$

$$\omega^T x + b \leq 0 \quad \text{if } x \in \text{neg class}$$

→ Confident about the predictions



↳ if you slightly change the line the distance would become -ve from true.

$$z = \omega^T x + b$$

$$y_{pred} = g(z)$$

$\xrightarrow{\text{class +ve}}$

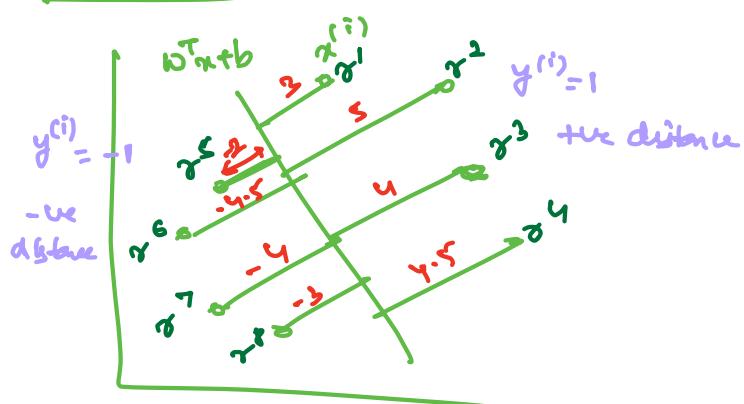
$$g(z) = +1 \quad \text{if } z > 0$$

$$g(z) = -1 \quad \text{if } z < 0$$

\downarrow

class +ve

Loss fxn:



distance of i -th point from d.b.

$$d^{(i)} = \frac{|w^T x^{(i)} + b|}{\|w\|_2}$$

$$\gamma = \boxed{\min_{i=1 \dots m} d^{(i)}}$$

→ among all the distances find the minimum

target: $\max \gamma$

SM objective

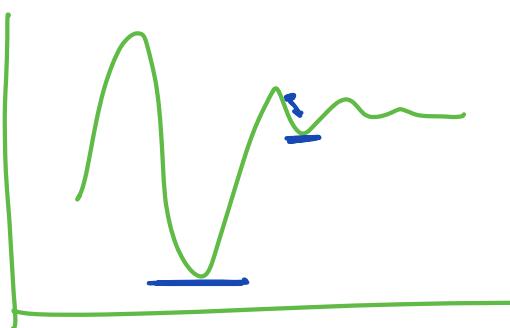
$\max \gamma$
 such that $\frac{y^{(i)} (w^T x^{(i)} + b)}{\|w\|_2} \geq \gamma \quad \text{for all } i=1 \dots m$

$$\frac{w^T x^{(i)} + b}{\|w\|_2} \rightarrow \text{normalized distance}$$

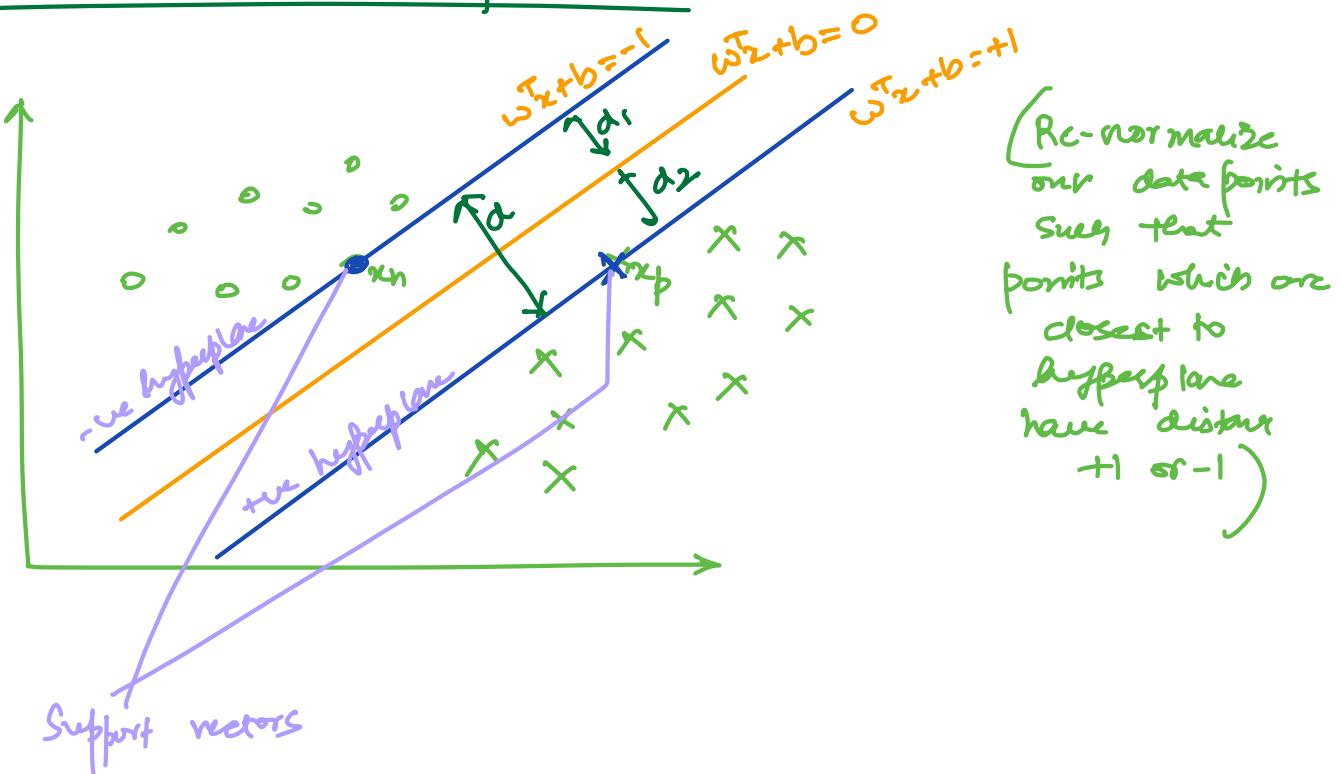
$\xrightarrow{\text{free}}$
 $\xrightarrow{\text{one}}$

$$y^{(i)} = \frac{(w^T x^{(i)} + b)}{\|w\|_2} \rightarrow \text{normalized absolute distance}$$

SVM objective \rightarrow non convex



Re-formulate the SVM objective:



$$d_1 = \frac{\|w^T x_n + b\|}{\|w\|_2}$$

$$d_2 = \frac{\|w^T x_p + b\|}{\|w\|_2}$$

$w^T x + b = 1$ and run $w \leftarrow M w$

$$w^T x_n + b = -1$$

$$w^T x_p + b = 1$$

$$d_1 = \frac{1}{\|w\|_2}$$

$$d_2 = \frac{1}{\|w\|_2}$$

$$d = d_1 + d_2 = \frac{2}{\|w\|_2}$$

maximize distance d
minimize $\frac{\|w\|_2}{2}$

SVM
objective:

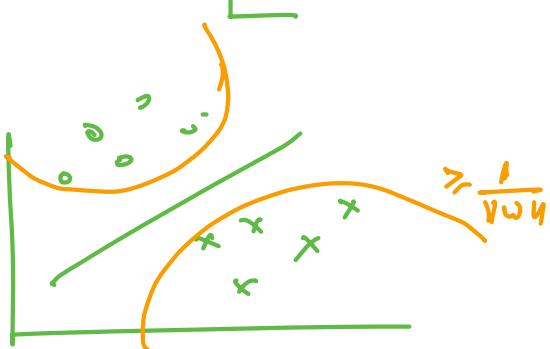
$$\min \frac{\|\omega\|}{2}$$

under the condition all points should have \min distance 1

$$\frac{y^{(i)}(\omega^T x^{(i)} + b)}{\|\omega\|_2} \geq \frac{1}{\|\omega\|_2}$$

SVM
objective

$$\begin{cases} \min \frac{\|\omega\|_2}{2} \\ \text{such that } y^{(i)}(\omega^T x^{(i)} + b) \geq 1 \\ \forall i \in \{1, \dots, m\} \end{cases}$$



all data points should have
at least distance of $\frac{1}{\|\omega\|}$

$$\omega = \sqrt{\omega_1^2 + \omega_2^2}$$

$$\text{or } (\sum w_i^2)^{1/2}$$

$$\omega \omega^T \leftarrow \omega^2 = \omega_1^2 + \omega_2^2 \rightarrow 2\omega_1 + 2\omega_2 = 2(\omega_1 + \omega_2)$$

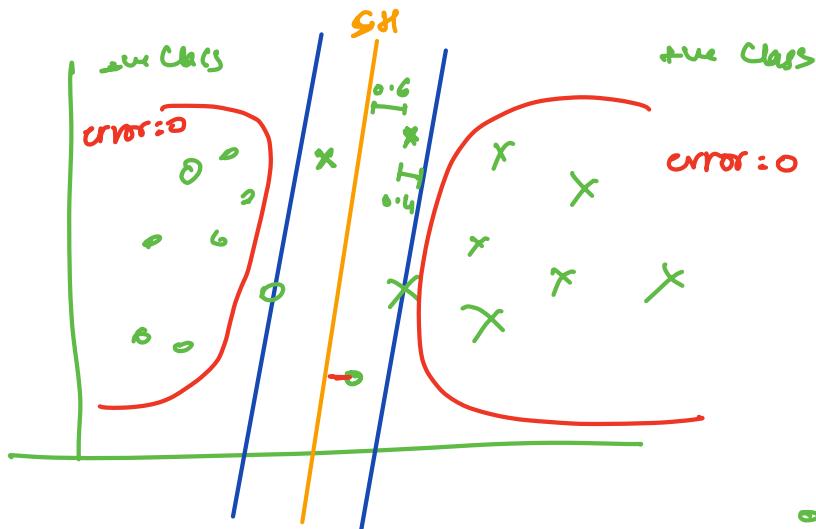
$$\begin{bmatrix} \omega \\ \vdots \\ \omega_n \end{bmatrix} \quad \begin{bmatrix} \omega^T \\ \vdots \\ \omega^T_n \end{bmatrix} = \begin{bmatrix} \omega_1 & \omega_2 & \dots & \omega_n \end{bmatrix}$$

Final
SVM
objective

$$\begin{cases} \min \frac{\|\omega\|_2^2}{2} \\ \text{such that } y^{(i)}(\omega^T x^{(i)} + b) \geq 1 \\ \forall i \in \{1, \dots, m\} \end{cases}$$

Convex function
with
SVC constraints.

Handle Errors



$$y^{(i)}(\omega^T x^{(i)} + b) \geq 1$$

$$\frac{y^{(i)}(\omega^T x^{(i)} + b)}{\text{distance from } x^{(i)} \text{ from Sf.}} \geq 1 - \varepsilon^{(i)} \rightarrow 0.4$$

Allow some errors

$\varepsilon^{(i)}$ denotes the distance
of the i th point from
the hyperplane

$$\text{loss} = \frac{1}{2} \omega \cdot \omega^T + C \sum_{i=1}^m \varepsilon^{(i)}$$

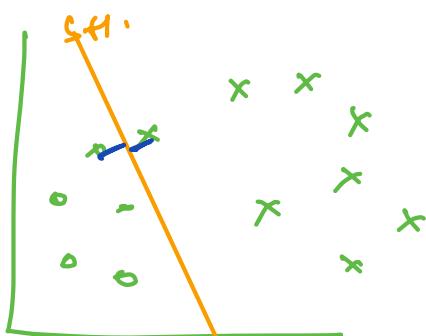
\downarrow

constant

st. $y^{(i)}(\omega^T x^{(i)} + b) \geq 1 - \varepsilon^{(i)}$

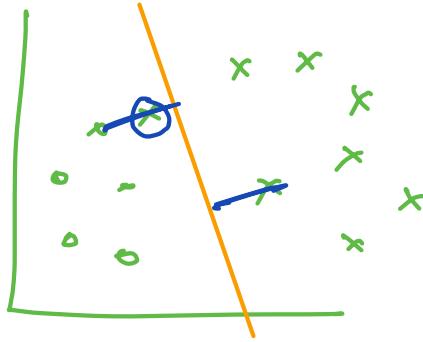
C = hyperparameter

$C = \infty$ 0 errors



You won't be able to achieve
maximum margin's hyperplane

$C=1$ afford some errors, maximum margin sep. hyperplane



Non Convex

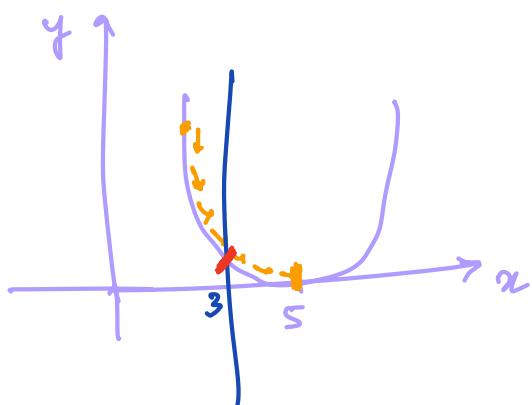
↓
Convex

↓
Misclassification
Errors.

distance 1

$$y = (x - 5)^2$$

value of x for which y is minimum. \rightarrow no constraint



$$y = (x - 5)^2 \text{ such that } x \leq 3$$

↓ constraints

$$\text{Loss} = \frac{1}{2} w \cdot w^T + C \sum_{i=1}^m \xi^{(i)}$$

constant

$$\text{s.t. } y^{(i)}(w^T x^{(i)} + b) \geq 1 - \xi^{(i)}$$

Convex fxn
with
constraints :
we want to get
rid of linear
constraints.

Remove linear constraints

$$\varepsilon^{(i)} \geq 1 - y^{(i)} (\omega^\top x^{(i)} + b)$$

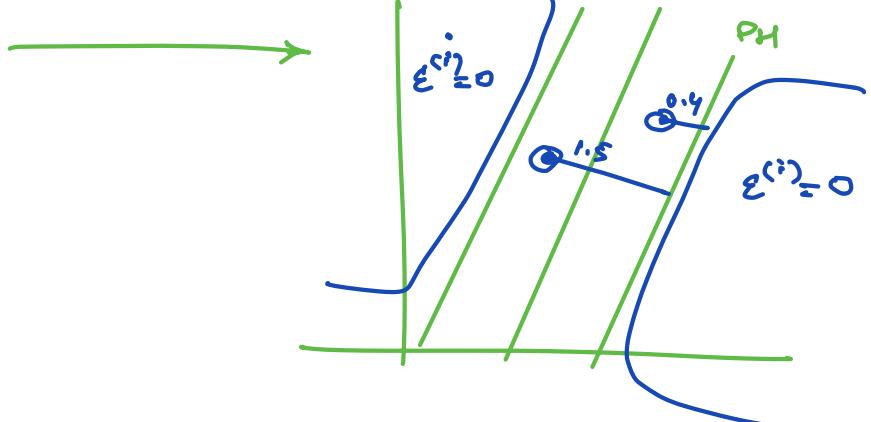
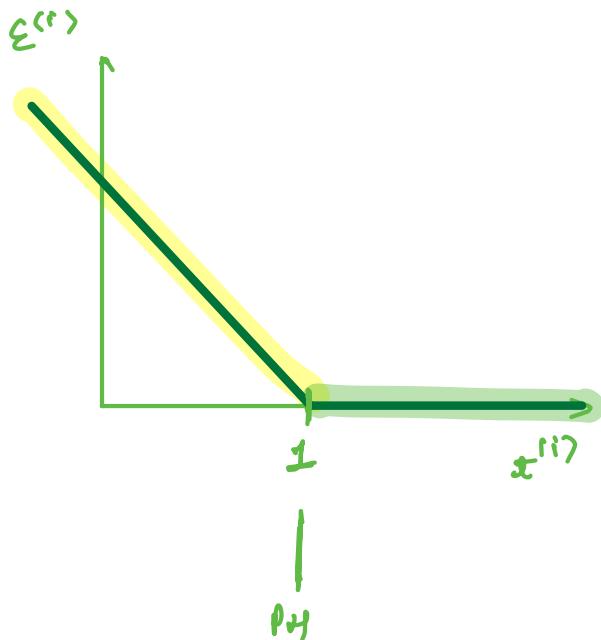
unnormalized absolute distance of $x^{(i)}$ from separating hyperplane.

$$\varepsilon^{(i)} \geq 1 - t^{(i)}$$

$$\varepsilon^{(i)} \geq 0$$

↓ Unbind

$$\varepsilon^{(i)} = \max(0, 1 - t^{(i)})$$



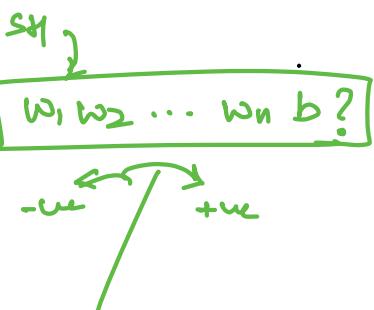
for differentiating $\varepsilon^{(i)}$, we will use the concept of **subgradient**

$$\begin{cases} 0 & \text{if } t_i \geq 1 \\ -1 & \text{if } t_i < 1 \end{cases}$$

$$L = \frac{1}{2} \omega^\top \omega + C \sum_{i=1}^m \max(0, 1 - t^{(i)})$$

$$\text{where } t^{(i)} = y^{(i)} (\omega^\top x^{(i)} + b)$$

SVM
Objective



GRADIENT DESCENT

$$\omega = \omega - \eta \frac{\partial L}{\partial \omega}$$

$$\frac{1}{2} \omega^T \omega = \frac{1}{2} (\omega_1^2 + \omega_2^2 + \dots + \omega_n^2)$$

$$\frac{\partial}{\partial \omega} \left(\frac{1}{2} \omega^T \omega \right) = \frac{1}{2} (2\omega_1 + 2\omega_2 + \dots + 2\omega_n) = \boxed{2\omega_1 + 2\omega_2 + \dots + 2\omega_n}$$

$$\frac{\partial L}{\partial \omega} = \omega + c \sum_{i=1}^m \underbrace{\frac{\partial}{\partial \omega} (\max(0, 1 - \hat{x}^{(i)}))}_{f}$$

$$\frac{\partial L}{\partial \omega} = \omega + c \sum_{i=1}^m \frac{\partial f}{\partial x^{(i)}} \cdot \frac{\partial \hat{x}^{(i)}}{\partial \omega}$$

$$\frac{\partial f}{\partial \omega} = \frac{\partial F}{\partial x^{(i)}} \frac{\partial x^{(i)}}{\partial \omega}$$

$$\frac{\partial L}{\partial \omega} = \omega + c \sum_{i=1}^m \frac{\partial}{\partial \omega} (\max(0, 1 - \hat{x}^{(i)})) \cdot \frac{\partial \hat{x}^{(i)}}{\partial \omega}$$

$$\frac{\partial L}{\partial \omega} = \omega + c \sum_{i=1}^m \begin{bmatrix} 0 & \text{if } \hat{x}^{(i)} \geq 1 \\ -1 & \text{if } \hat{x}^{(i)} < 1 \end{bmatrix} \frac{\partial \hat{x}^{(i)}}{\partial \omega}$$

$$\hat{x}^{(i)} = y^{(i)} (\omega^T x^{(i)} + b)$$

$$\frac{\partial \hat{x}^{(i)}}{\partial \omega} = y^{(i)} x^{(i)}$$

$$\frac{\partial L}{\partial \omega} = \omega + c \sum_{i=1}^m \begin{bmatrix} 0 & \text{if } \hat{x}^{(i)} \geq 1 \\ -1 & \text{if } \hat{x}^{(i)} < 1 \end{bmatrix} y^{(i)} x^{(i)}$$

$$b = b - \gamma \boxed{\frac{\partial L}{\partial b}} ?$$

$$\frac{\partial L}{\partial b} = 0 + C \sum_{i=1}^m \frac{\partial}{\partial b} [\underbrace{\max(0, 1-x_i)}_f]$$

$$\frac{\partial L}{\partial b} = C \sum_{i=1}^m \frac{\partial f}{\partial x_i} \cdot \frac{\partial x^{(i)}}{\partial b}$$

$$\frac{\partial L}{\partial b} = C \sum_{i=1}^m \begin{bmatrix} 0 & \text{if } x^{(i)} > 1 \\ -1 & \text{if } x^{(i)} < 1 \end{bmatrix} \frac{\partial x^{(i)}}{\partial b}$$

$$\frac{\partial x^{(i)}}{\partial b} = \frac{\partial}{\partial b} (\gamma^{(i)} (\omega^T x^{(i)} + b))$$

$$= \gamma^{(i)}$$

$$\boxed{\frac{\partial L}{\partial b} = C \sum_{i=1}^m \begin{bmatrix} 0 & \text{if } \gamma^{(i)} > 1 \\ -1 & \text{if } \gamma^{(i)} < 1 \end{bmatrix} \gamma^{(i)}}$$

UPDATE RULES:

$$\omega = \omega - \eta \left[\omega + C \sum_{i=1}^m \begin{bmatrix} 0 & \text{if } x^{(i)} > 1 \\ -1 & \text{if } x^{(i)} < 1 \end{bmatrix} \gamma^{(i)} x^{(i)} \right]$$

$$\boxed{\omega = \omega - \eta \omega + \sum_{i=1}^m \begin{bmatrix} 0 & \text{if } x^{(i)} > 1 \\ \eta C \gamma^{(i)} x^{(i)} & \text{if } x^{(i)} < 1 \end{bmatrix}}$$

$$b = b - \left(\eta_c \sum_{i=1}^m \begin{bmatrix} 0 & \text{if } x^{(i)} \geq 1 \\ -1 & \text{if } x^{(i)} < 1 \end{bmatrix} y^{(i)} \right)$$

$$b = b + \sum_{i=1}^m \begin{bmatrix} 0 & \text{if } x^{(i)} \geq 1 \\ \eta_c y^{(i)} & \text{if } x^{(i)} < 1 \end{bmatrix}$$