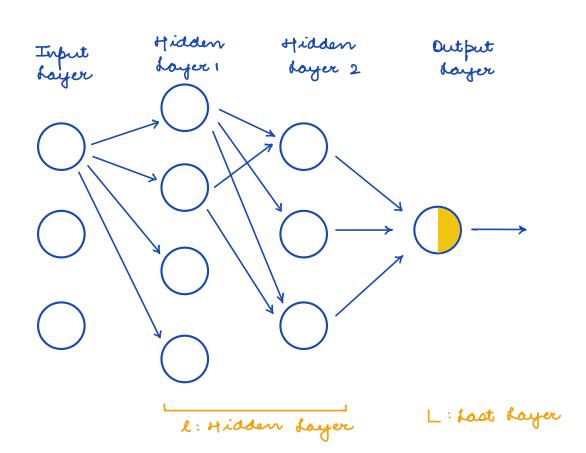
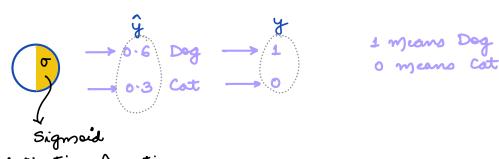
Backpropagation is considered as a challenging froblem in Machine Kearning, reason being it involves knowledge of hiseax Algebra and Calculus. Given the formula it is not very difficult to implement but the important thing is how you reached at the formula.

If you have a neural network then you can do a forward hase, get the frediction but frediction are going to be random because you are doing random initialization of weights. We want that our network should be able to learn and should give good results for regression and classification. Libraries like Tensor flow and Py Torch will automatically do Backpropagation for you.

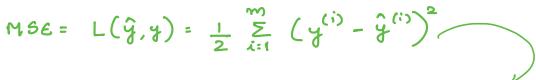


Backpropagation algo is needed because: let's say your algo said that I am 60% sure that it is a dag but actual output you wanted is 1. Your algo said probability of cat is 0.3, you will take sigmoid and it will become 0.

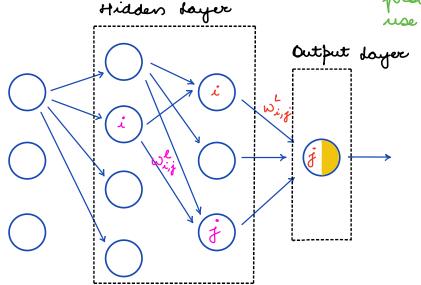


Activation function: converts no to probability

we want to figure out the loss. Loss is $\hat{y}-y$. Loss function we generally use in classification is Gross Entropy. For simplification, we are using mean squared evice loss.



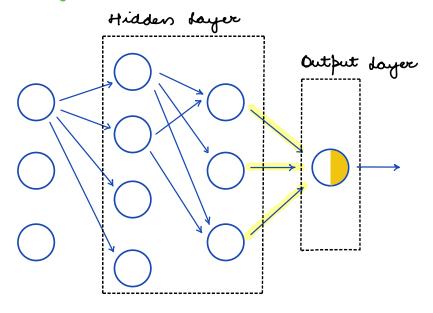
In general, this type of loss is non convex for a given classification froblem, so we generally use cross entropy.



I want to analyse how loss function changes on changing the weights, if I make a change in $W_{i,j}^L$ then how does my verox, loss and frediction change.

There are 2 type of neurons: one which are in output layer and other neurons are in hidden layer.

Output neurons are directly connected with loss, if you want to change your loss by SL then you can find out what change I Should make to these weights:



You need to compute 2 things:

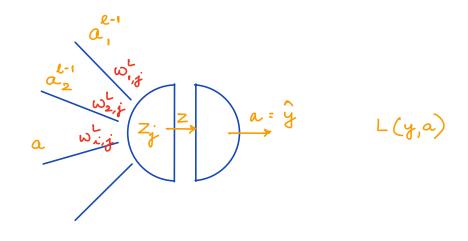
Case 1: output Layer

Cape 2: Hidden Layer

we need to find out how loss changes when weight and bias changes.

Cape 1:

output dayer



We want to find out how ŷ changes with wi,j

$$\frac{\partial L}{\partial \omega_{i,j}} = \frac{\partial L}{\partial a_{j}} \cdot \frac{\partial a_{j}}{\partial z_{j}} \cdot \frac{\partial z_{j}}{\partial \omega_{i,j}} \quad \text{(Chain Rule)}$$

$$\begin{cases} \delta_{j} = \frac{\partial L}{\partial z_{j}} \end{cases}$$

$$\frac{\partial L}{\partial a_{j}} = \frac{1}{2} \cdot 2 \cdot (y_{j} - a_{j})$$

 $) \rightarrow a_i^L \quad 0.5 \quad | \quad 1$

$$\frac{\partial L}{\partial a_{j}} = -(y_{j} - a_{j})$$

$$a_{j} = \sigma(z_{j})$$

$$\frac{\partial a_{j}}{\partial z_{j}} = \sigma'(z_{j})$$

$$= (1 - \sigma(z_{j})) \sigma(z_{j})$$

$$Z_{\dot{f}}^{\ell} = \sum_{i}^{\ell} \omega_{i,\dot{f}} \cdot \underline{a_{i}}^{\ell-1} + b_{\dot{f}}^{\ell}$$

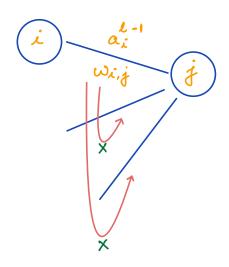
If you take derivative wrt wi, j then you will get activation. For all other terms it will be o and only a; will be left.

$$\frac{\partial z_{j}}{\partial w_{i,j}} = \alpha_{i}^{l-1}$$

It is the activation associated with previous layer.

l-1 layer

L layer



Wi, j will depend on ai activation.

Wi,j won't be influenced by other activation values.

Combining (1), (2) and (3)

$$\frac{\partial L}{\partial \omega_{i,j}} = -(y_j - \alpha_j) \sigma'(z_j) \alpha_i^{l-1}$$

$$\delta_j^{L}$$

Bias

$$\frac{\partial L}{\partial b_{j}} = \frac{\partial L}{\partial a_{j}} \cdot \frac{\partial a_{j}}{\partial z_{j}} \cdot \frac{\partial z_{j}}{\partial b_{j}}$$

$$z_{j}^{l} = \sum_{i}^{l} \omega_{i,j} a_{i}^{l-1} + b_{j}^{l} \text{ will become } l$$
will become l

$$\frac{\partial z_{j}}{\partial b_{j}} = 1$$

$$\frac{\partial L}{\partial b_{j}} = S_{j}^{L} \cdot I$$

for output layer,

$$\frac{\partial L}{\partial \omega_{i,j}} = S_j^L \cdot \alpha_i^{l-1}$$

$$\frac{\partial L}{\partial b_{j}} = S_{j}^{L} \cdot 1$$

$$S_j^L = -(y_j - a_j) \sigma'(z_j)$$

$$S_{j}^{\prime} = (\alpha_{j} - \gamma_{j}) \sigma'(z_{j})$$