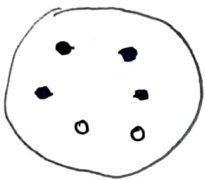


2.

Cluster Validation indices.

Purity: Purity of cluster is defined as follows.

$$\pi_j = \frac{1}{n_i} \max(n_{ij})$$



Purity of the given cluster

$$\pi_j = \frac{1}{6} \max(3, 2, 1)$$

$$= \frac{3}{6}$$

$$= \frac{1}{2}$$

$$= 0.5$$

3

Rand Index: Rand Index can be comprehended from the given analogy.

| | Ground Truth Value with class X | Ground Truth Value not having X |
|---------------------------------|---------------------------------|---------------------------------|
| Sample having class label X | A | C |
| Sample not having class label X | B | D |

$$\text{Rand Index (RI)} = \frac{A + D}{A + B + C + D}$$

b.

Intercluster Distance. Intercluster cluster distance gives the similarity between two different clusters.

Single Linkage intercluster distance. The minimum distance between two datapoints not present in the cluster gives single linkage distance.

a. Let us say S & T are two different clusters. So single linkage intercluster distance

$$\Delta_1(S, T) = \min_{\substack{\forall x \in S \\ \forall y \in T}} (d(x, y))$$

(4)

Complete Linkage Intercluster Distance: The maximum distance between two data points present in two different clusters.

Let us say S & T are two different clusters. So the distance is defined as.

$$\Delta_2(S, T) = \max_{\substack{\forall x \in S \\ \forall y \in T}} (d(x, y))$$

Intra Cluster Distance. Similarity between two ~~clusters~~ datapoints present in same cluster.

(diameter cluster distance)

Type 1. Intra cluster distance, for a cluster S

$$\Delta_1(S) = \max_{\substack{\forall x \in S \\ \forall y \in S \\ x \neq y}} (d(x, y))$$

Average Centroid Distance = ~~①~~ Average centroid distance is defined as follows for a cluster S .

$$\Delta_1(s) = \frac{1}{(|S| - 1)} \sum_{x \in S} \delta(x, \bar{u})$$

where $\bar{u} = \frac{1}{|S|} \sum_{y \in S} y$

Dunn's Cluster Validation Index. The Dunn's cluster validation index is defined as follows

③

$$D_{\text{index}} = \min_{1 \leq i \leq c} \left\{ \min_{\substack{1 \leq j \leq c \\ i \neq j}} \left\{ \frac{\delta(x_i, x_j)}{\max(\Delta(x_{ic}))} \right\} \right\}$$

To obtain a good cluster the Dunn's clustering index is ~~always maximized~~ minimized. It is always preferred that the inter cluster distance of any two clusters is high but the intra cluster distance is low.

~~the Dunn's index the numerator value is related the inter cluster between two clusters.~~ ~~Don't~~ Minimum ~~to~~ Minimization of the

two term $\frac{\delta(x_i, x_j)}{\max(\Delta(x_{ic}))}$ gives the same.

Q4.

$$P = 6, n = 4, I(P, n) = -\frac{6}{10} \log \frac{6}{10} - \frac{4}{10} \log \frac{4}{10}$$

$$= 0.29$$

| Outlook | P_i | n_i | $I(P, n_i)$ |
|----------|-------|-------|------------------|
| Sunny | 2 | 2 | 0.416 |
| Overcast | 2 | 0 | 0.000 |
| Rain | 2 | 2 | 0.416 |

$$I(2, 2) = \frac{2}{10} \times 0.29 = \frac{0.58}{10} = 0.058$$

$$= 0.058$$

$$I(2, 0) = \frac{2}{10} \times 0.29 = 0.058$$

$$E(A) = \sum \frac{P_i + n_i}{P + n} I(P, n_i)$$

$$= \frac{4}{10} \times 0.058 + \frac{2}{10} \times 0 + \frac{4}{10} \times 0.058$$

$$= 0.08$$

$$\text{GAIN(OUTLOOK)} = 0.29 - 0.08$$

$$= 0.21$$

32

| Humidity | P_i | n_i | $I(P, n_i)$ |
|----------|-------|-------|------------------|
| Normal | 4 | 1 | 0.416 |
| High | 2 | 3 | 0.416 |

$$I(4, 1) = \frac{1}{5} \times 0.29 = 0.058$$

$$= 0.058$$

$$I(2, 3) = \frac{3}{5} \times 0.29 = 0.174$$

$$= 0.174$$

$$E(A) = \sum \frac{P_i + n_i}{P + n} I(P, n_i)$$

$$= \frac{5}{10} \times 0.058 + \frac{5}{10} \times 0.174$$

$$= 0.116$$

$$\text{Gain(Humidity)} = 0.29 - 0.116$$

$$= 0.174$$

| Wind | P_i | n_i | $I(P_i, n_i)$ |
|--------|-------|-------|---------------|
| Strong | 2 | 3 | 0.97 |
| Weak | 4 | 1 | 0.72 |

$$I(2, 3) = 0.97$$

$$I(4, 1) = 0.72$$

$$\begin{aligned}
 E(A) &= \sum \frac{P_i + n_i}{P + n} I(P_i, n_i) \\
 &= \frac{5}{10} \times 0.97 + \frac{5}{10} \times 0.72 \\
 &= 0.845
 \end{aligned}$$

$$\text{Gain}(\text{wind}) = -0.555$$

So both ^{outlook} wind and humidity can be the root.

b. Possible terminating criteria for decision tree:

i. The generation of decision during the training stops if the obtained gini index impurity at some node is higher than its parent.

ii. In ID3 approach, depending on the gain value ~~the~~ generated during the training process.

iii. During testing when the process reaches the leaf node it returns the possible output and terminates.

c. A model generally overfits when there is ^{high} ~~low~~ variance in the data points but low bias.

The possible causes

- i. There is a high variance present in the dataset.
- ii. There is low bias present in the dataset.
- iii. The model is not trained in such a way, i.e. the weights are initialized in such a way, that the model cannot predict unseen data.

Decision tree classifier is prone to overfit. as solution to overfitting

1. Use of Random forest: In random forest classifier multiple decision trees are used during training. And after the classification is done the majority output is returned as predicted class.
2. Meta Modelling: Overfitting is also dealt with a technique known as meta modelling. Here multiple decision tree classifier trained over different instances are taken. And their outputs are in turn fed into a different classifier to predict the values.

5. a

We need to calculate $P(\text{outlook} = \text{"yes"} / \text{outlook})$
 $\neq P(\text{outlook} / \text{playTennis} = \text{"no"})$

$$\frac{P(\text{outlook} = \text{"Overcast"} / \text{playTennis} = \text{"yes"})}{P(\text{playTennis} = \text{"yes"})}$$

Let us say $X = \langle \text{outlook} = \text{"overcast"}, \text{humidity} = \text{"high"}, \text{wind} = \text{"weak"} \rangle$

4

we are to calculate $P(\text{playTennis} = \text{"yes"} / X)$ and $P(\text{playTennis} = \text{"no"} / X)$

$$P(\text{playTennis} = \text{"yes"} / X) = \frac{P(X / \text{playTennis} = \text{"yes"}) \times P(\text{playTennis} = \text{"yes"})}{P(X / \text{PT} = \text{"y"}) P(\text{PT} = \text{"y"}) + P(X / \text{PT} = \text{"n"}) P(\text{PT} = \text{"n"})}$$

$$P(\text{playTennis} = \text{"no"}) = \frac{4}{10} \quad P(\text{playTennis} = \text{"yes"}) = \frac{6}{10}$$

$$P(\text{Outlook} = \text{"Overcast"} / \text{playTennis} = \text{"yes"}) = \frac{2}{2} = 1$$

$$P(\text{Outlook} = \text{"Overcast"} / \text{playTennis} = \text{"no"}) = \frac{0}{2} = 0$$

$$P(\text{humidity} = \text{"high"} / \text{playTennis} = \text{"yes"}) = \frac{1}{4}$$

$$P(\text{humidity} = \text{"high"} / \text{playTennis} = \text{"no"}) = \frac{3}{4}$$

$$P(\text{wind} = \text{"weak"} / \text{playTennis} = \text{"yes"}) = \frac{4}{5}$$

$$P(\text{wind} = \text{"weak"} / \text{playTennis} = \text{"no"}) = \frac{1}{5}$$

$$P(X / \text{playTennis} = \text{"yes"}) = \frac{4}{5} \times \frac{1}{4} \times 1 = \frac{1}{5}$$

$$P(X / \text{playTennis} = \text{"no"}) = 0 \times \frac{1}{5} \times \frac{3}{4} = 0$$

$$P(\text{playTennis} = \text{"yes"} / X) = \frac{\frac{6}{10} \times \frac{1}{5}}{\frac{6}{10} \times \frac{1}{5} + \frac{4}{10} \times 0}$$

$$= \frac{6/50}{6/50}$$

$$= 1$$

$$P(\text{playTennis} = \text{"no"} / X) = \frac{0 \times \frac{4}{10}}{\frac{6}{10} \times \frac{1}{5} + \frac{4}{10} \times 0}$$

$$= 0$$

∴ The class label of the give sample would be playTennis = "yes".

Qb. Yes, there is an error in such prediction.

Here from the dataset we can see that if outlook = "overcast" then there is no such sample where playTennis = "no". So in that

situation $P(\text{playTennis} = \text{"no"} / \text{outlook} = \text{"overcast"})$

is 0. So no matter what ~~the~~ value the other featureset has ~~it will~~ outlook = "overcast" will

return class label no.

4 To deal with this problem there are several methodologies available. One of them is Laplace correction.

In Laplace correct we add a very small value to both numerator and denominator making the probability of the biased class a very small non zero value.

So let us say we have 1000 sample. And in class prediction comes up where the probability distribution become

$$P_1 = \frac{549}{1000}$$

$$P_2 = \frac{300}{1000}$$

$$P_3 = \frac{151}{1000}$$

$$P_4 = \frac{0}{1000}$$

After Laplace correction the probability distribution becomes.

$$P_1 = \frac{550}{1004}$$

$$P_3 = \frac{152}{1004}$$

$$P_2 = \frac{301}{1004}$$

$$P_4 = \frac{1}{1004}$$

So P_4 will not result to zero after Bayes probability prediction, rather it will return a value close to zero.

c. If any feature in naive bayes classification has a continuous value. ~~to~~ ~~the~~ Rather using the product we use the gaussian normal distribution

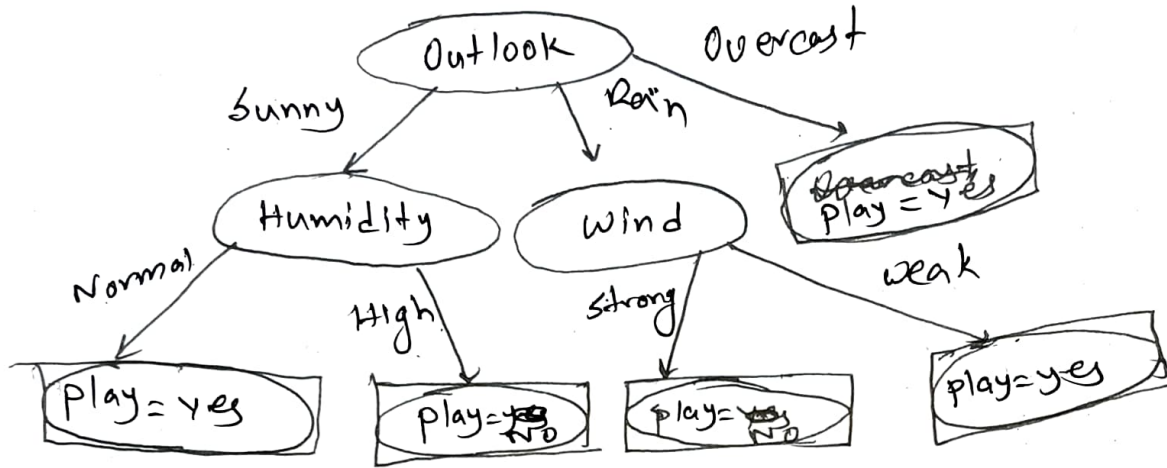
$$Q(x, \mu, \sigma) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

so for a sample x_k , $Q(x_k, \mu_k, \sigma_k) = \frac{1}{\sigma_k\sqrt{2\pi}} e^{-\frac{(x_k - \mu_k)^2}{2\sigma_k^2}}$

3 so $P(X/Y) = \frac{P(Y(x)) \times P(x)}{\sum P(x)}$

so in this case first let us consider the x_k has a continuous ~~probab~~ distribution then we ~~use~~ instead of ~~the~~ probability normal ~~of~~ value we ~~to~~ use the gaussian value.

6.a)



| Outlook | Humidity | Wind | Play Tennis CV = yes | play Tennis predicted class |
|-----------------------------|----------|--------|------------------------------------|-----------------------------------|
| Sunny | Normal | strong | Yes | Yes |
| Rain overcast | Normal | strong | No | Yes |
| Rain | High | strong | Yes | NO |
| Sunny | High | Weak | NO | NO |
| Rain | High | Strong | NO | NO |

Confusion Matrix.

| | | Predicted Class | |
|------------|-----|---------------------|--------------------------|
| | | Yes | No |
| True Class | Yes | True Positive 1 | False Negative 1 |
| | No | False Positive 1 | False Negative True 2 |

$$\text{Precision} = \frac{TP}{TP + FP}$$

4

$$= \frac{1}{1+1} = 0.5$$

$$\text{Recall} = \frac{TP}{TP + FN} = \frac{1}{2} = 0.5$$

$$F_1 \text{ score} = \frac{2 \times \text{precision} \times \text{recall}}{\text{precision} + \text{recall}}$$

$$F_1 \text{ score} = \frac{1+\beta^2}{\beta^2} \times \frac{\text{precision} \times \text{recall}}{\text{precision} + \text{recall}}$$

$$F_1 \text{ score} = \frac{2 \times 0.5 \times 0.5}{0.5 + 0.5}$$

$$= 0.5$$

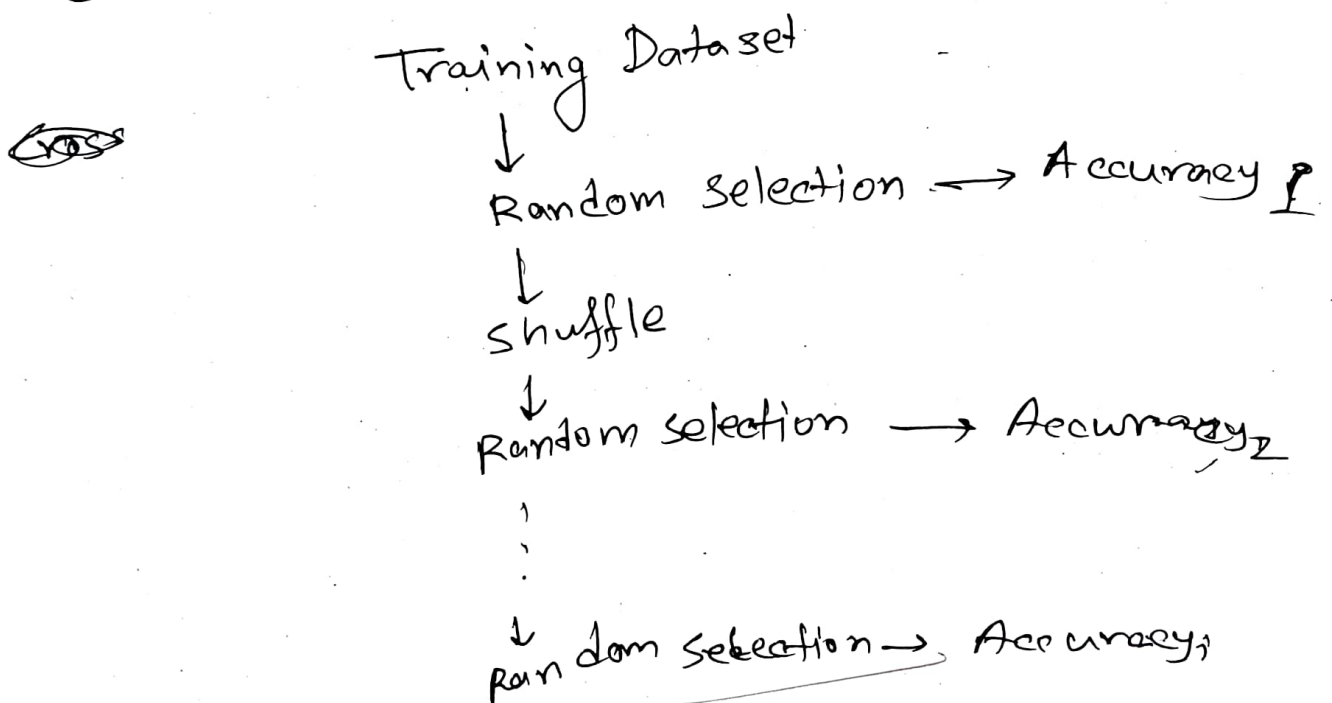
b)

i.

Holdout Method: In holdout method a ~~from~~ ^{part} of the dataset ~~a for~~ a percentage of the dataset is taken for training & the rest of the dataset is used for validation.

This selection is ~~20~~ completely random and repeated ~~for~~ a number of times.

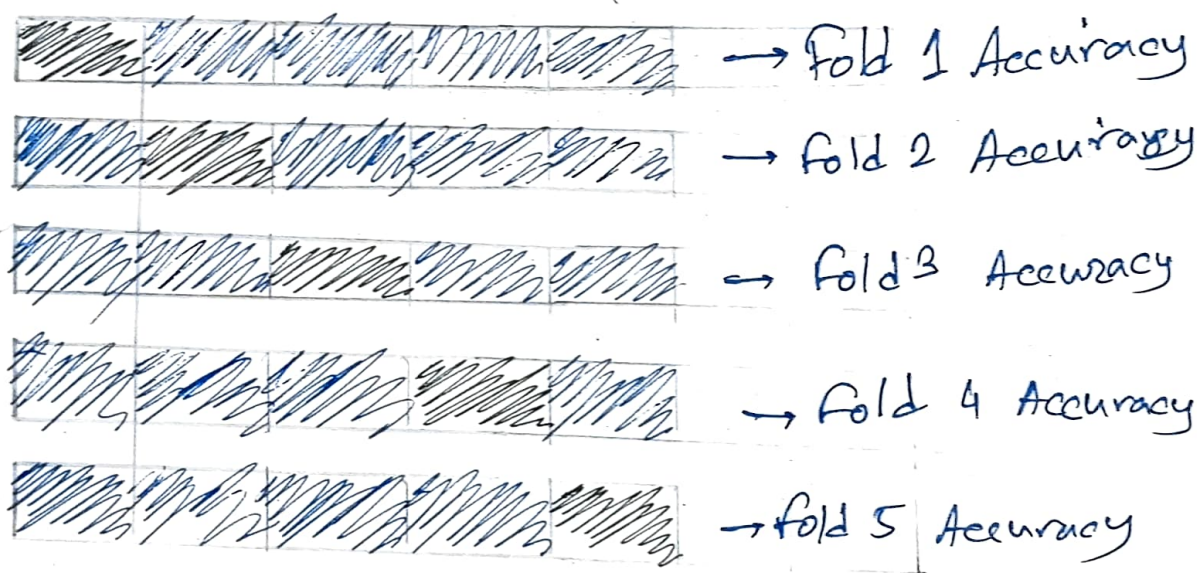
And ~~mean~~ normally the mean of the all accuracies are reported with an error approximation, i.e. the standard deviation.



$$\text{Accuracy} = \text{mean}(\text{Accuracy}_1, \text{Accuracy}_2, \dots, \text{Accuracy}_i) \\ + \text{std_deviation}(\text{Accuracy}_1, \text{Accuracy}_2, \dots, \text{Accuracy}_i)$$

Cross validation: There are mainly two types of cross validation present. i. K Fold cross validation and stratified cross validation.

In cross validation the dataset is divided into K folds. And the metrics is calculated K times. First each of the fold is used as a validator for once, and the rest of the folds are used for training



$$\text{Accuracy} = \text{mean}(\text{Folds Accuracy}) + \text{std-deviation}(\text{Accuracy})$$

Bootstrap Method: ^{The} bootstrap method works by the principle "resampling by replacement". Suppose there are d instances present in a bootstrap. One percentage of the bootstrap is used for training and the rest of the portion which could not make it to the bootstrap is used for testing. The normal bootstrap is 0.368 , as $1 - \frac{1}{d} \approx e^{-1} \approx 0.368$

The accuracy is calculated as follows.

$$Acc = (0.368 \text{ Acc}_{\text{train-set}} + 0.632 \times \text{Acc}_{\text{test-set}})$$

c. Main Purpose of ensemble classifier.

i. Ensemble classifier use of ensemble classifier is fruitful in various ways. For example a hypothesis is trained over a training set and the accuracy is calculated. But there is a possibility that the training set has some unseen instances. So using an ensemble

classifier outputs to a set of accuracy and predicted class labels. Depending on that weighted class majority the correct class label is chosen from a set of class labels.

2.2 Adaboost: Ada boost is boosting algorithm used in ensemble classifiers. In boosting Ada boost several instances of classifiers are taken. ~~And then depending on that instance~~ And if a new instance is introduced that instance is give priority over all. And during training there exist some particular threshold. If the new value instance works worse compared to that threshold the instance is discarded. the threshold is determined using null hypothesis or t testing

$$t = \frac{err(M_1) - err(M_2)}{\sqrt{var(M_1) - var(M_2)}}$$