

Chapter 8: Timer Functions

Many applications require a dedicated **timer system** to perform

- **Time delay** creation and measurement.
- **Period and pulse width** measurement.
- **Frequency** measurement.
- Event **counting**.
- **Arrival time** comparison.
- Time-of-day tracking.
- **Periodic interrupt** generation.
- **Waveform** generation.

HCS12 Timer Module

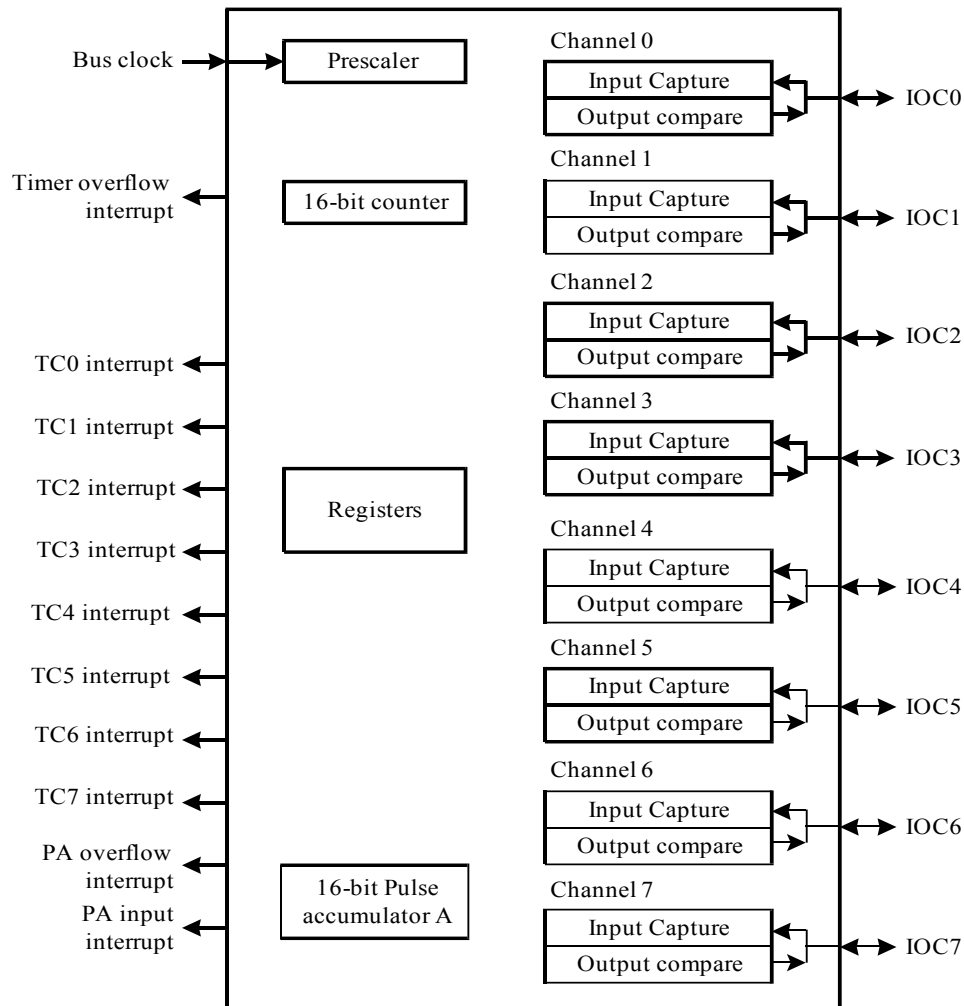


Figure 8.1 HCS12 Standard Timer (TIM) block diagram

HCS12 has a standard timer module, consisting of

- 8 channels of input-capture (IC) and output-compare (OC) modules. Each channel can be configured to perform IC or OC function, but not both at the same time.
- One 16-bit main timer counter (TCNT) serves as the base timer for these 8 channels. TCNT can be started and stopped at any time, and is driven by a clock signal derived from the E-clock divided with a prescaler.
- Port T pins PT7~PT0 correspond to the timer module inputs/outputs IOC7~IOC0.
- One 16-bit pulse accumulator, which can be used to count the number of events that has occurred. It shares the PT7 pins, which is referred as the PAI pin when the pin is used as the pulse-accumulator input. Usually used to count the events arriving in a certain interval or measure frequency or pulse width.

Timer Counter Register (TCNT) = counter

- TCNT is a 16-bit counter, required for IO and OC functions.
- Must be read in one 16-bit (high and low bytes) operation in one access in order to obtain the correct value. It is because the TCNT counter does not stop during the access operation. Thus the high byte and low byte won't be the same in two separate accesses.
- Three other registers are related to the operation of the TCNT counter: TSCR1, TMSK2, and TFLG2.

Timer System Control Register (TSCR1)

- Setting bit 7 = 1 (or 0) in TSCR1 starts (or stops) the TCNT timer.
- Setting bit 4 = 1 enables timer fast flag clear function to clear the timer overflow flag (TOF) in the TFLG2 register. Afterward, a read from or a write to TCNT will clear TOF.
- If bit 4 = 0, then the user must manually write a 1 to TOF to clear the flag.

```
movb  #$80, TSCR      ; enable TCNT to count, manual TOF clear
                        ; but need "bset TFLG2,$80" to clear TOF
```

```
movb  #$90, TSCR      ; enable TCNT to count; fast TOF clear
```

	7	6	5	4	3	2	1	0
value	TEN	TSWAI	TSFRZ	TFFCA	0	0	0	0
after reset	0	0	0	0	0	0	0	0

TEN -- timer enable bit

0 = disable timer; this can be used to save power consumption

1 = allows timer to function normally

TSWAI -- timer stops while in wait mode bit

0 = allows timer to continue running during wait mode

1 = disables timer when MCU is in wait mode

TSFRZ -- timer and modulus counter stop while in freeze mode

0 = allows timer and modulus counter to continue running while in freeze mode

1 = disables timer and modulus counter when MCU is in freeze mode

TFFCA -- timer fast flag clear all bit

0 = allows timer flag clearing to function normally

1 = For TFLG 1, a read from an input capture or a write to the output compare channel causes the corresponding channel flag, CnF, to be cleared. For TFLG2, any access to the TCNT register clears the TOF flag. Any access to the PACN3 and PACN2 registers clears the PAOVF and PAIF flags in the PAFLG register. Any access to the PACN1 and PACN0 registers clears the PBOVF flag in the PBFLG register.

Figure 8.2 Timer system control register 1 (TSCR1)

	7	6	5	4	3	2	1	0
value	TOI	0	0	0	TCRE	PR2	PR1	PR0
after reset	0	0	0	0	0	0	0	0

TOI -- timer overflow interrupt enable bit

0 = interrupt inhibited

1 = interrupt requested when TOF flag is set

TCRE -- timer counter reset enable bit

0 = counter reset inhibited and counter free runs

1 = counter reset by a successful output compare

If TC7 = \$0000 and TCRE = 1, TCNT stays at \$0000

continuously. If TC7 = \$FFFF and TCRE = 1, TOF will never be set when TCNT rolls over from \$FFFF to \$0000.

Figure 8.3 Timer system control register 2 (TSCR2)

Timer Interrupt Mask Register 2 (TMSK2) = Timer System Control Register 2 (TSCR2)

- If (TOI) bit 7 = 1 in TMSK2, an **interrupt** will be requested when the **TCNT** timer **overflows** (i.e., rolls over from \$FFFF to \$0000).
- When the content of the **TCNT** register is equal to the **TC7 register**, the **TCNT** register can be **cleared to 0** by setting (TCRE) bit 3 = 1 of the TMSK2.
- The clock input to the TCNT counter can be derived from the **E-clock divided by a prescaler**, which is selected by **bits 2~0** of the TMSK2.

```
movb  #$07, TMSK2      ; prescaler=128; free-run mode (TCRE=0)
                        ; disable TCNT overflow interrupt (TOI=0)
```

Table 8.1 Timer counter prescale factor

PR2	PR1	PR0	Prescale Factor
0	0	0	1
0	0	1	2
0	1	0	4
0	1	1	8
1	0	0	16
1	0	1	32
1	1	0	64
1	1	1	128

Timer Interrupt Flag 2 Register (TFLG2)

- Only bit 7 (**TOF**) of this register is implemented.
- **Bit 7 = 1** whenever TCNT rolls over from \$FFFF to \$0000 (or **overflow**).
- TOF can be **cleared by writing a 1** to it.

```
bset  TFLG2,$80      ; writing a 1 to clear TOF
```

Input Capture (IC) Function

- Some applications need to know the **arrival time of events** (from a signal).
- Physical time is represented by the contents of the **main timer** (TCNT).
- The **occurrence of an event** is represented by a signal (**rising or falling**) **edge**.
- The time when an event occurs can be recorded by **latching the count of TCNT** when a signal edge arrives.
- HCS12 has **8 input-capture (IC) channels** for this operation.
- Each channel has a **16-bit IC register**, an **input pin**, **edge-detection** logic, and **interrupt generation** logic.
- Can be used to measure **frequency**, **period**, **pulse width**, **duty cycle**, and **timing reference** of the selected signal.

Input-Capture/Output-Compare Selection

- IC channels **share** most of the circuit (such as **signal pins** and **registers**) with OC functions. Thus, they **cannot be enabled simultaneously**.
- Selection of IC and OC is done by programming the **Timer Input-Capture/Output-Compare Select** (TIOS) register.

	7	6	5	4	3	2	1	0
value	IOS7	IOS6	IOS5	IOS4	IOS3	IOS2	IOS1	IOS0
after reset	0	0	0	0	0	0	0	0

IOS[7:0] -- Input capture or output compare channel configuration bits

0 = The corresponding channel acts as an input capture

1 = The corresponding channel acts as an output compare

Figure 8.5 Timer input capture/output compare select register (TIOS)

```
movb  #$F0,TIOS    ; IOC7~4 for OC operation; IOC3~0 for IC operation
```

Pins for Timer Port

- Port T has 8 signal pins (**PT7~PT0**) that can be used as **IC/OC channels**, or **general I/O** pins when timer function is not selected.
- Pin 7** can be program to act as input capture (**IC7**), output compare (**OC7**), or **pulse accumulator input (PAI)** functions.
- When a timer port pin is used as **general I/O**, its direction is configured by the **DDRT** register and its value is reflected in the associated bit in **PortT**.

Timer Control Register 3 and 4 (for Input Capture)

- The **signal** (rising or falling) **edge** to be captured is **selected** by the **timer control** registers, **TCTL3** and **TCTL4**.
- The edge to be captured is selected by **two bits**. The user can choose to **capture** the **rising edge**, **falling edge**, or **both edges**.
- When an IC7~0 channel is selected but **capture function is disabled** (i.e., **00** at the corresponding two bits in TCTL3 and TCTL4), the associated pin can be used as a **general-purpose I/O pin**.

	7	6	5	4	3	2	1	0
value	EDG7B	EDG7A	EDG6B	EDG6A	EDG5B	EDG5A	EDG4B	EDG4A
after reset	0	0	0	0	0	0	0	0

(a) Timer control register 3 (TCTL3)

	7	6	5	4	3	2	1	0
	EDG3B	EDG3A	EDG2B	EDG2A	EDG1B	EDG1A	EDG0B	EDG0A
	0	0	0	0	0	0	0	0

(b) Timer control register 4 (TCTL4)

EDGnB EDGnA -- Edge configuration

- | | | |
|---|---|---------------------------------|
| 0 | 0 | : Capture disabled |
| 0 | 1 | : Capture on rising edges only |
| 1 | 0 | : Capture on falling edges only |
| 1 | 1 | : Capture on both edges |

Figure 8.5 Timer control register 3 and 4

Timer Interrupt Mask Register 1 (TMSK1 or TIE) & Timer Interrupt Flag Register 1 (TFLG1)

- An IC7~0 channel can **optionally** generate an **interrupt request** to the CPU on the arrival of a selected edge by setting the associated **interrupt enable bit** (C7I~C0I) in **TMSK1** (also aka TIE).

	7	6	5	4	3	2	1	0
	C7I	C6I	C5I	C4I	C3I	C2I	C1I	C0I
reset:	0	0	0	0	0	0	0	0

C7I-C0I: input capture/output compare interrupt enable bits
 0 = interrupt disabled
 1 = interrupt enabled

Figure 8.7 Timer interrupt enable register (TIE)

	7	6	5	4	3	2	1	0
	C7F	C6F	C5F	C4F	C3F	C2F	C1F	C0F
reset:	0	0	0	0	0	0	0	0

CnF: input capture/output compare interrupt flag bits
 0 = interrupt condition has not occurred
 1 = interrupt condition has occurred

Figure 8.8 Timer interrupt flag register 1 (TFLG1)

- When a **selected edge** arrives at the **IC7~0 pin**, the corresponding **flag** (C7F~C0F) in **TFLG1** will be set to 1.
- To **clear a flag** in the TFLG1 register, write a 1 to it.

```
movb  #$01,TFLG1 ; clear the channel 0 flag (C0F)
```

- A better way to clear the flag that incurs **less overhead** is by **setting bit 4 = 1** (**timer fast clear all bits**) of **TSCR1**. This **clears a flag by reading the associated IC register or writing** a new value into the **OC register**. This operation is normally needed for the normal operation of the IC/OC function.
- Each **IC7~0** channel has a **16-bit register** (TC7~TC0) to **hold the count value** when the selected **signal edge** arrives at the pin. This register is **also used as the OC register** when the output-compare function is selected.

Applications of Input Capture Function

1. **Event arrival time recording.** Some applications, for example, a swimming competition, needs to **compare the arrival times of several swimmers**. The number of events that can be compared **is limited by the number of IC channels**.
2. **Period measurement.** The IC function should be configured to **capture the main timer values corresponding to two consecutive rising or falling edges**.

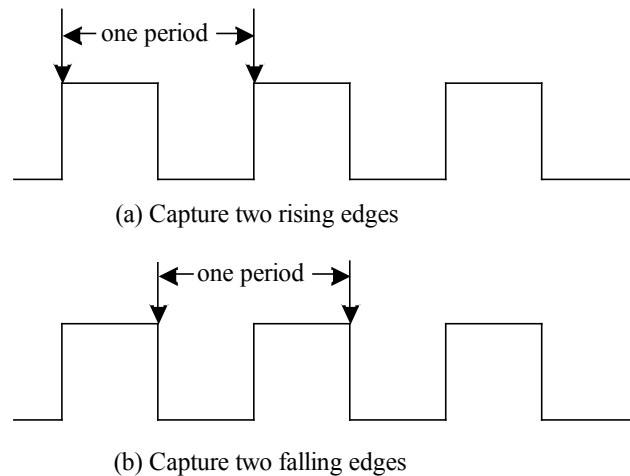


Figure 8.9 Period measurement by capturing two consecutive edges

3. **Pulse-width measurement.** **Capture two adjacent rising and falling edges.**

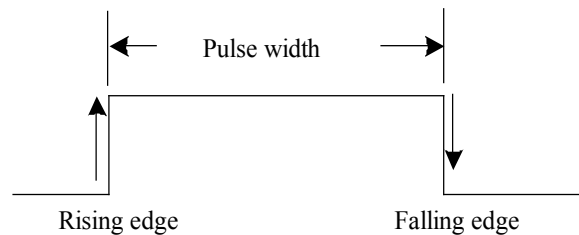


Figure 8.10 Pulse-width measurement using input capture

4. **Interrupt generation.** Each IC input can be used **as an edge-sensitive interrupt source**. Once enabled, interrupts will be generated on the selected edge(s).
5. **Event counting.** An event can be represented by a signal edge. An **IC channel** can be used in conjunction **with an OC function to count the number of events that occur during an interval**. An **event counter** can be set up and incremented by the **IC interrupt service routine** by counting the number of **signal edges** arrived during a period.

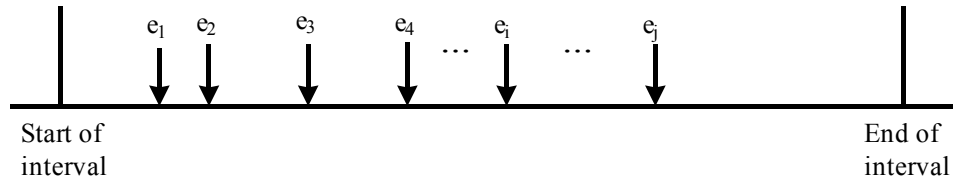


Figure 8.11 Using an inputcapture function for event counting

6. **Time referenced action.** An IC function is used in combination with an OC function. For example, to **activate an output** signal a certain number of clock cycles **after detecting an input event**. The **IC function** would be used to **record the time at which the edge is detected**. A number corresponding to the **desired delay** would be **added** to this captured value and **stored to an OC register**.

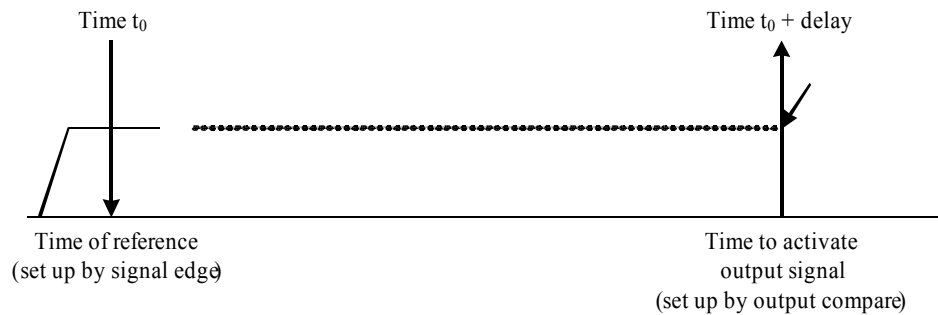


Figure 8.12 A time reference application

7. **Duty Cycle Measurement.** The duty cycle is the percent of time that the signal is high within a period in a periodic digital signal.

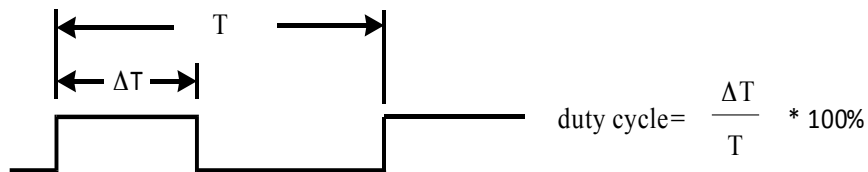


Figure 8.13 Definition of duty cycle

8. **Phase Difference Measurement.** Phase difference is defined as the **difference of arrival times** (in % of a period) of two signals that have the same frequency but do not coincide in their rising and falling edges.

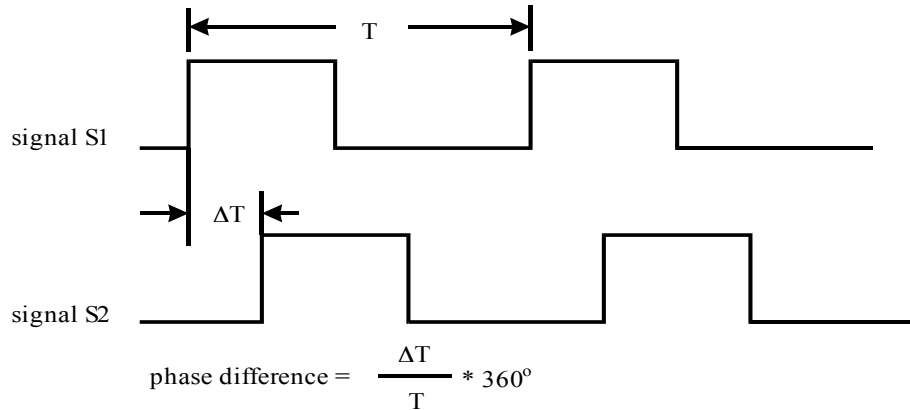


Figure 8.14 Phase difference definition for two signals

Example: Displaying the number of “overflows” in the TCNT timer on the LEDs.

The **clock input** to the 16-bit TCNT timer is equal to **E-clock/prescaler**. At E-clock = 24 MHz and **prescaler=128**, the TCNT timer overflows every $2^{16}/(24\text{MHz}/128) = 0.35 \text{ sec}$.

#include “reg9s12.h”

```

org    $2000
movb   #$FF,DDRB ; set PTB as output for LEDs
movb   #$FF,DDRJ ; set PTJ as output (required by Dragon12+)
movb   #$00,PTJ   ; set PTJ1=0 to enable LEDs
movb   #$FF,DDRP ; turn off 7-segment displays and RGB LEDs
movb   #$FF,PTP   ;

movb   #$80,TSCR  ; (=TSCR1) enable timer; manual TOF clear
movb   #$07,TMSK2 ; (=TSCR2) prescaler=128; free-run; no overflow interrupt

ldaa   #0          ; A stores the number of times the timer overflowing
over   bset    TFLG2,$80 ; clear the TOF by writing a 1 & start to count
       brclr   TFLG2,$80,* ; wait 0.35s for timer overflow; if TOF=1, exit loop
       inca    ; add 1 to the number of timer overflows
       staa    PortB ; display the content of A on LEDs
       bra     over

end

```

Possible project: Display the measured period, pulse width, duty cycle, etc of an unknown signal on the 7-segment or LCD displays.

Example: Use IC channel 0 (IC0) to **measure** the **period** of an unknown signal connected to **PT0**.

As each IC register is 16 bits, the **maximum measurable period and accuracy** depend on the value of **prescaler**. For example,

1. Set the **prescale factor** to TCNT to **1** and keep track of the number of times that TCNT overflows. [$2^{16}/24\text{MHz} = 2.73 \text{ ms}$ per TCNT overflow; accuracy = $1/24\text{MHz} = 0.04167 \mu\text{s}$]
2. Set the prescale factor to **64** and do not keep track of the number of times that TCNT overflows. [$2^{16}/(24\text{MHz}/64) = 174.76 \text{ ms}$ per TCNT overflow; accuracy = $1/(24\text{MHz}/64) = 2.667 \mu\text{s}$]

Here, use **prescaler = 64**. The period measurement will be in **number of clock cycles**. The **period** of each clock cycle is $1/(24\text{MHz}/64) = 2.667 \mu\text{s}$.

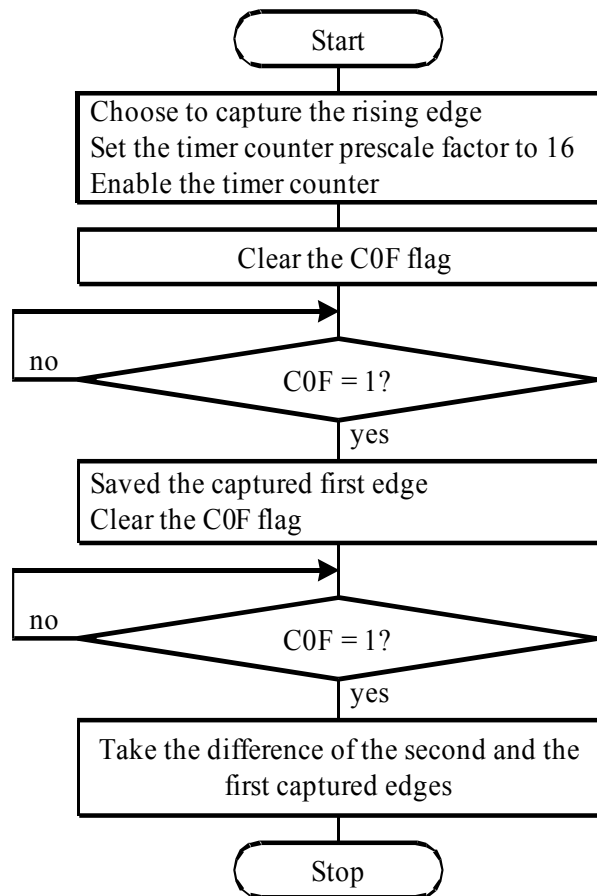


Figure 8.16 Logic flow of period measurement program

```
#include "reg9s12.h"
```

```
    org    $1000
edge   ds.b    2           ; hold the arrival time of the first edge
period ds.b    2           ; store the period

    org    $2000
    movb   #$90,TSCR      ; (=TSCR1) enable timer; enable fast TOF clear
    movb   #$06,TMSK2     ; prescaler=64; free runs; no timer overflow interrupt
    bclr   TIOS,$01       ; enable IOC at channel 0
    movb   #$01,TCTL4     ; capture rising edge of the PT0 signal
    movb   #$01,TFLG1     ; clear the C0F interrupt flag to wait for an event to occur

    brclr  TFLG1,$01,*    ; wait for the arrival of the first rising edge
    ldd    TC0            ; if C0F=1, the edge triggers an interrupt. The TC0 timer
    std    edge          ; content gives 1st edge time; C0F is cleared automatically
                        ; due to the use of #$90 in TSCR
    brclr  TFLG1,$01,*    ; clear C0F to wait for the arrival of the 2nd rising edge
    ldd    TC0            ; load the current TC0 timer content
    subd   edge          ; period = TC0 - edge1
    std    period
    swi
end
```

Measurement Steps

- 1) Set up the function generator with Hi-Z, 4.7Vpp (i.e., 0-4.7V), square wave, 1 kHz, and 50% duty cycle. (Important: Use the oscilloscope to confirm the setting!)
- 2) Connect the positive and ground terminals of the function generator to the PT0 and GND socket holes, respectively, using two pieces of wire. The two holes are found around the middle of the left-side (vertical) socket on Dragon12+.
- 3) Load the program to Dragon12+.
- 4) Type "g 2000" to make one measurement. The content of D gives the number of clock cycles in hex format.
- 5) Convert the hex value to decimal value. Then, multiple it with $2.667 \mu s$ as the measured period of the "unknown" signal.
- 6) Set the function generation with a different frequency setting, then repeat Steps 4-6.

For 1 kHz signal, the program gives $D = \$0177$, which is equal to 375 clock cycles. This gives the period of $375 \times 2.667 \mu s = 1 \text{ ms}$.

For 2 kHz, $D = \$00BB = 187$ clock cycles, giving the period of $187 \times 2.667 \mu s = 0.5 \text{ ms}$.

For 500 Hz, $D = \$02EE = 750$ clock cycles, giving the period of $750 \times 2.667 \mu s = 2 \text{ ms}$.

Example: Write a program to measure the pulse width of a signal connected to PT0 using IC function at channel 0 (IC0).

Setting the **prescale factor** to **32**, each count of the TCNT timer (or clock cycle) is $1/(24\text{MHz}/32) = 1.333 \mu\text{s}$, which is used as the unit of measurement.

Since the **pulse width may be longer than 2^8 clock cycles**, we need to **keep track of the number of times** that the **TCNT timer overflows**. Each TCNT overflow **adds 2^8 clock cycles** to the pulse width.

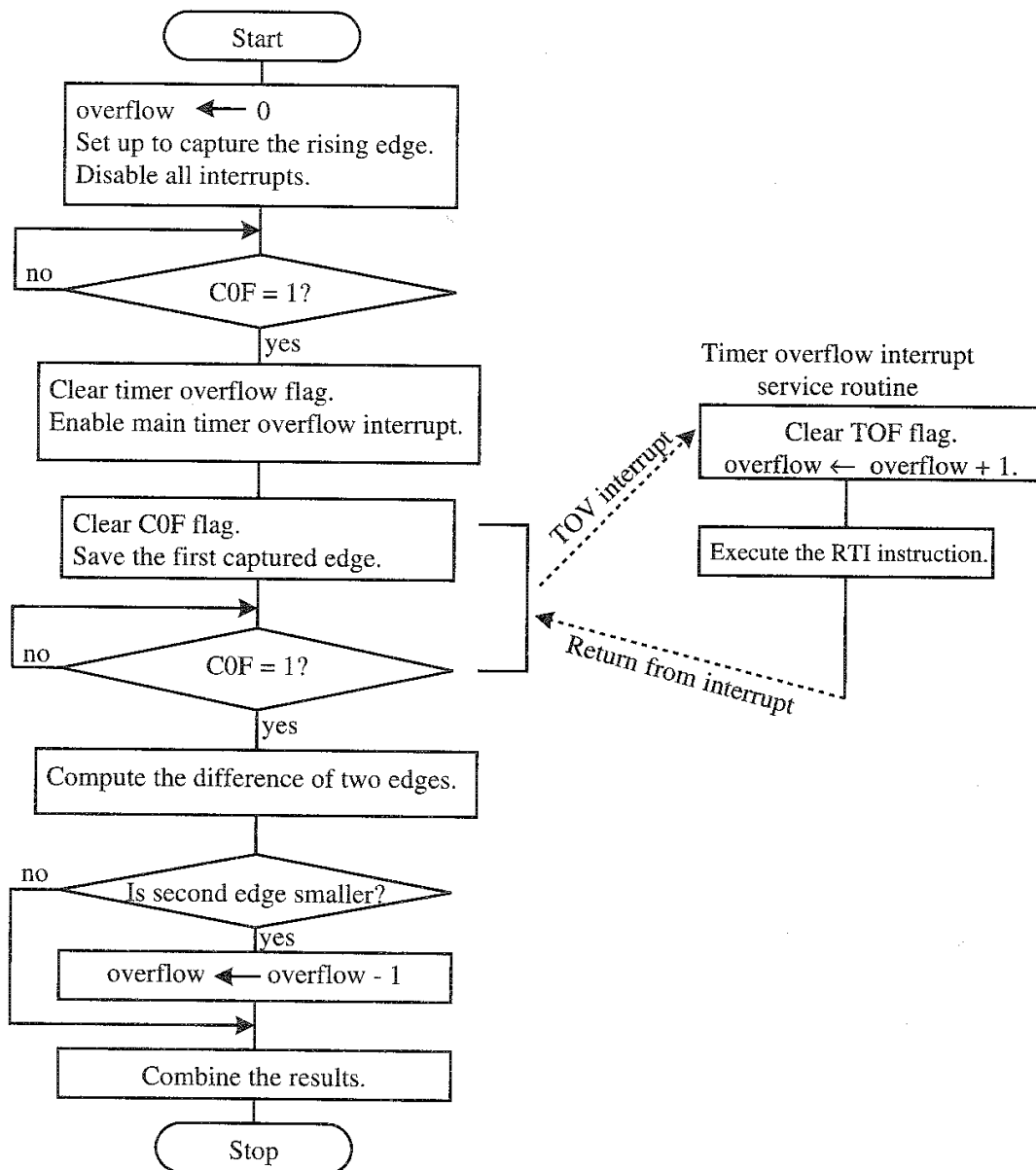


Figure 8.16 ■ Logic flow for measuring pulse width of slow signals

$ovcnt$ = TCNT timer overflow count
 $edge1$ = the captured time of the first edge
 $edge2$ = the captured time of the second edge

The pulse width can be calculated by

case 1 $edge2 \geq edge1$
 pulse width = $(2^{16} - edge1) + (ovcnt - 1) \times 2^{16} + edge2$
 = $ovcnt \times 2^{16} + |edge2 - edge1|$

case 2 $edge2 < edge1$
 pulse width = $(ovcnt - 1) \times 2^{16} + |edge2 - edge1|$

In case 2, the timer overflows at least once even if the pulse width is shorter than $2^{16} - 1$ clock cycles. Thus, we need to subtract 1 from the timer overflow count in order to get the correct result.

Finally, the pulse width is obtained by computing $pulse\ width \times 1.333\ \mu s$.

```
#include "reg9s12.h"
```

```

                                org    $1000
edge      ds.w    1
ovcnt     ds.w    1
PW        ds.w    1

                                org    $2000
lds       #$2000      ; set up stack pointer
clr       ovcnt       ; clear the timer overflow counter
movb     #$90,TSCR    ; enable timer; fast timer flag clear
movb     #$05,TMSK2   ; disable TCNT interrupt, prescaler=32
bclr     TIOS,$01     ; select IC0

movb     #$01,TCTL4   ; set to capture rising edge on PT0 pin
movb     #01,TFLG1    ; clear C0F flag by writing a 1 to wait for event
brcclr   TFLG1,01,*   ; wait for the first rising edge
movw     TC0,edge     ; save the first edge; clear the C0F flag auto

movb     #$80,TFLG2   ; clear TOF flag of the TCNT timer for next event
bset     TMSK2,$80    ; enable TCNT overflow interrupt
cli      ; enable global interrupt

movb     #$02,TCTL4   ; set to capture the falling edge on PT0 pin

```

```

        brclr   TFLG1,01,*   ; wait for the arrival of the falling edge
        ldd     TC0
        subd    edge1        ; calculate pulse width
        std     PW
        bcc     next         ; is the second edge smaller?
        ldx     ovcnt         ; second edge is smaller, so decrement
        dex
        ; overflow count by 1
        stx     ovcnt        ;
next     swi

tov_isr   movb   #$80,TFLG2   ; clear TOF flag for next event to arrive
        ldx     ovcnt
        inx
        stx     ovcnt
        rti

        org     $3E5E
        fdb     tov_isr      ; set up TCNT overflow interrupt vector
        end

```

Measurement Steps

- 1) Set up the function generator with Hi-Z, 4.7Vpp (i.e., **0-4.7V**), square wave, 1 kHz, and 50% duty cycle. (**Important: Use the oscilloscope to confirm the setting!**)
- 2) Connect the positive and ground terminals of the function generator to the PT0 and GND socket holes, respectively, using two pieces of wire. The two holes are found around the middle of the left-side (vertical) socket on Dragon12+.
- 3) Load the program to Dragon12+.
- 4) Type “g 2000” to make one measurement. The content of D gives the number of clock cycles in hex format.
- 5) Convert the hex value to decimal value. Then, multiple it with $1.333 \mu s$ as the measured pulse width of the “unknown” signal.
- 6) Set the function generation with a different duty-cycle setting, then repeat Steps 4-6.

For **1 kHz** signal with **50% duty cycle**, the program gives **D = \$0177**, which is equal to **375 clock cycles**. This gives the pulse width of **$375 \times 1.333 \mu s = 0.5 \text{ ms}$** .

For 1 kHz signal with 30% duty cycle, $D = \$00E1 = 225$ clock cycles, giving the pulse width of $225 \times 1.333 \mu s = 0.3 \text{ ms}$.

For 2 kHz signal with 50% duty cycle, $D = \$00BB = 187$ clock cycles, giving the pulse width of $187 \times 1.333 \mu s = 0.25 \text{ ms}$.

Output Compare Functions

HCS12 has up to 8 OC channels. Each channel consists of

- a 16-bit **comparator**.
- a 16-bit **OC register TC7~0** (also used as IC register).
- an **output action pin (PT7~0)** that can be **pulled high**, pulled **low**, or **toggled**.
- control logic and an **interrupt** request circuit.

Operation of the Output-Compare Function

- One of the major applications of the OC function is to **trigger an action at a specific time in the future** (when the value of the 16-bit **TCNT timer** equals the **value stored** in the selected **TC register**).
- To use an OC function, the user
 1. makes a **copy** of the current contents of the **TCNT register**
 2. **adds** to this copy a value equals to the **desired delay**
 3. **stores** the sum into an **OC register (TC7~0)**

	7	6	5	4	3	2	1	0
value	OM7	OL7	OM6	OL6	OM5	OL5	OM4	OL4
after reset	0	0	0	0	0	0	0	0

(a) TCTL1 register

	7	6	5	4	3	2	1	0
value	OM3	OL3	OM2	OL2	OM1	OL1	OM0	OL0
after reset	0	0	0	0	0	0	0	0

(b) TCTL2 register

read: anytime

write: anytime

OMn OLn : output level

0	0	no action (timer disconnected from output pin)
0	1	toggle OCn pin
1	0	clear OCn pin to 0
1	1	set OCn pin to high

Figure 8.18 Timer control register 1 and 2 (TCTL1 & TCTL2)

- The **actions** that can be activated on an OC pin (**PT7~0**) by programming the **Timer Control registers** (TCTL1 and TCTL2) include
 1. pull up to **high**
 2. pull down to **low**
 3. **toggle**
- When either OMx or OLx is 1, the pin associated with OCx becomes an output tied to OCx regardless of the state of the associated DDRT bit.
- The **comparator compares** the value of the **TCNT timer** and that of the specified **OC register** (TC7~0) in every clock cycle. If they are **equal**, the specified action on the OC pin (**PT7~0**) **is activated** and the associated **status bit in TFLG1** will be **set to 1**. An **interrupt request** will be **generated** if it is enabled.
- An **interrupt** may be **optionally requested** if the associated **interrupt enable bit** in TMSK1 (or **TIE**) is set. The same bit will **enable** either **the IC or OC interrupt** depending on which one is being selected.

Applications of Output Compare Function

1. An OC function can be programmed to perform a variety of functions, such as **generation** of a single **pulse**, a **square wave**, and a specific **delay**.
2. To generate **square wave**, the user may use the OC function to **continuously toggle the selected Port T pin with appropriate delay** added in each OC operation.

Example: Sound the buzzer on PT5 using channel 5 timer with OC operation.

Prescaler = 128 gives **period** of each clock cycle (count) = $1/(24\text{MHz}/128) = 5.333 \mu\text{s}$.

Applying **5000 clock-cycle delay** gives **2.667ms of 1** and **2.667ms of 0**, this corresponds to the generation of a **square wave** with a period of **5.33ms** and frequency of **18.75Hz**.

```
#include "reg9s12.h"
```

```
org    $2000
lds    #$2000
movb   #$80,TSCR          ; (=TSCR1) enable timer; clear TOF manually
movb   #$07,TMSK2         ; (=TSCR2) prescaler=128; free runs
bset   TIOS,$20          ; set OC at chan 5 (PT5)
movb   #$04,TCTL1       ; OM5=0 & OL5=1 to enable PT5 toggle
```

```

again  ldd    TCNT           ; get current count of TCNT
        addd  #5000          ; change this number for different tone (pulse width)
        std   TC5            ; add 5000x5.33μs = 26.67ms delay
here    brclr  TFLG1,$20,here ; wait for TCNT=TC5. If yes, execute next line
        bset  TFLG1,$20      ; write 1 to clear the C5F flag for next round
                                   ; no need of this instruction if set TSCR=#$90
        bra   again          ; forever loop to toggle PT5
end

```

Example: Generate a delay of 5 seconds using OC6. A LED will be turned on at the beginning and then turned off after 5 seconds.

```
#include "reg9s12.h"
```

```

flag5      org    $1000
counter5    rmb    1

counter5    rmb    2

        org    $2000
        lds    # $2000
        movb   #$FF,DDRB      ; set PTB as output for LEDs
        movb   #$FF,DDRP      ; set PTP as output
        movb   #$FF,DDRJ      ; set PTJ as output
        movb   #$00,PTJ       ; PJ1=1 to enable LEDs (in Dragon12+)
        movb   #$FF,PTP       ; turn off 7-segment displays & RGB LEDs

        movb   # $80,TSCR      ; enable TCNT timer; manual TOF clear
        movb   # $40,TIOS      ; set chan 6 for OC operation
        movb   # $40,TIE      ; enable TC6 interrupt
        cli                      ; enable all interrupts

        bset   PortB,$01       ; turn on LED0 at PB0
        clr    counter5        ;
        clr    counter5+1
        clr    flag5
delay      ldaa  flag5          ; wait for flag5 to be set to 1
        beq    delay           ; generate 5s delay
        bclr   PortB,$01       ; turn off LED PB0
        swi

d5s_isr    ldx   counter5       ;
        inx

```

```

        stx    counter5
        cpx    #5000                ; generate 5000x1ms=5s delay
        bne    d1ms                ;
        clr    counter5
        clr    counter5+1
        ldaa   #1
        staa   flag5
        rti

d1ms    ldd    #24000                ; 24,000 x 1/24MHz = 1ms delay
        addd   TC6                  ; add to the current count in TC6 to for
        std    TC6                  ; round of 1ms delay interrupt
        bset   TFLG1,$40            ; clear C6 flag by writing a 1 to restart
        rti                          ; why use RTI?

        org    $3E62
        fdb    d5s_isr

end

```

Example: A square-wave generator using OC6. 500Hz square wave is seen on the PB0 LED and 2Hz square wave on the PB7 LED.

Connect PB0 and PB7 to Ch1 and Ch2 of an oscilloscope, the associated square waves can be displayed. Verify the frequencies using the Time Measure function in the scope.

```
#include "reg9s12.h"
```

```

counter    org    $1000
           rmb    1

           org    $2000
           lds    #$2000
           movb   #$FF,DDRB        ; set PTB as output for LEDs
           movb   #$FF,DDRP        ; set PTP as output
           movb   #$FF,DDRJ        ; set PTJ as output
           movb   #$00,PTJ         ; PJ1=1 to enable LEDs (in Dragon12+)
           movb   #$FF,PTP         ; turn off 7-segment displays & RGB LEDs

           movb   #$80,TSCR        ; enable TCNT timer; manual TOF clear
           movb   #$40,TIOS        ; set chan 6 for OC operation
           movb   #$40,TIE        ; enable TC6 interrupt

```

```

        cli                ; enable all interrupts
        clr    counter    ;
loop    ldaa    counter    ; this section toggles PB7 every 250ms;
        cmpa    #250      ; 250ms high and 250 ms low;
        bne     loop      ; gives a square wave with period=500ms
        clr     counter    ; and frequency = 2Hz
        ldaa    PortB     ; PT7 = LED7
        eora    #$80      ; toggle LED7 every 250ms => 2Hz square
        staa    PortB     ;
        jmp     loop
d1msISR inc    counter    ;
        ldd     #24000    ; 24,000 x 1/24MHz = 1ms
        addd    TC6       ; add to the current count in TC6 to for
        std     TC6       ; round of 1ms delay interrupt
        bset    TFLG1,$40 ; clear C6 flag by writing a 1 for next event
        ldaa    PortB     ;
        eora    #$01      ; toggle LED0 every 1ms => 500Hz square
        staa    PortB     ;
        rti
        org     $3E62
        fdb     d1msISR

end

```

Example: Generate a 1 kHz digital waveform with 30% duty cycle from the PT0 pin.

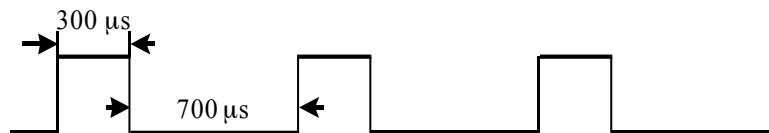


Figure 8.19 1 KHz 30 percent duty cycle waveform

Setting the **prescaler** to the TCNT to 8, then the period of the clock signal to the TCNT will be $1/(24\text{MHz}/8) = 1/3 \mu\text{s}$. The numbers of clock cycles that the signal is **high and low** are 900 and 2100, respectively.

Steps:

- 1) **Pull PT0 to low.** A new total count in the **TC0 timer** is calculated by the **current TC0 count + the number of clock cycles for low voltage.**
- 2) When TC0 reaches that new total count, **pull PT0 to high.**

- 3) A new total count in the TC0 timer is calculated by **the current TC0 count + the number of clock cycles for high voltage.**
- 4) When TC0 reaches that new total count, **repeat Step 1.**

```
#include "reg9s12.h"
```

```
hi_time    equ    900
lo_time    equ    2100
```

```

                org    $2000
                movb   #$90,TSCR        ; (=TSCR1) enable timer; auto TOF clear
                movb   #$03,TMSK2       ; (=TSCR2) prescaler=8; no TCNT interrupt
                bset   TIOS,$01         ; enable OC at chan 0 (PT0)

                movb   #$03,TCTL2      ; OM0=1 & OL0=1 to select pull high
                                           ; as pin action; this sets PT0=0V initially
loop           ldd     TCNT             ; load current count in TCNT timer
                addb   #lo_time        ; start an OC0 operation with 700us as delay
                std     TC0              ;
low            brclr   TFLG1,$01,low    ; wait until OC0 pin goes high

                movb   #$02,TCTL2      ; OM0=1 & OL0=0 to select pull low
                                           ; as pin action; this sets PT0 = 5V
                ldd     TC0              ; load current count in TCNT timer
                addb   #hi_time        ; start an OC operation with 300us as delay
                std     TC0              ;
high           brclr   TFLG1,$01,high   ; wait until OC0 pin goes low

                movb   #$03,TCTL2      ; repeat
                ldd     TC0
                bra     loop

                end
```

Possible project: Make a waveform generator that allows a user to select the period, duty cycle, pulse width, etc.

Making Sound Using the Output-Compare Function

A **sound** can be generated by creating a digital **waveform** with appropriate **frequency** and using it to drive a speaker or a buzzer. The simplest song is a two-tone siren.

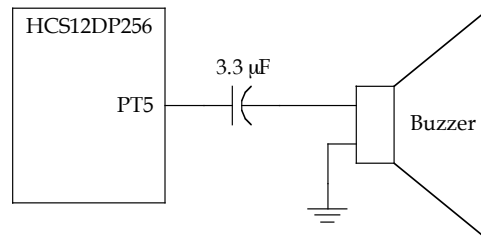


Figure 8.21 Circuit connection for a buzzer

Algorithm for Generating a Siren

- Step 1: Enable an OC **channel** (**OC5** in Drgaon12+) to drive the buzzer (or speaker).
- Step 2: Start an OC operation with a **delay count** equal to **half the period** of the siren.
- Step3: Enable the OC **interrupt**.
- Step 4: **Set up a 0.5-second loop**. During this time, **interrupts** will be requested many times by the **OC function to sound the siren**. The ISR simply restarts the OC operation for another round of interrupt.
- Step 5: At the end of the loop, choose a **different delay count** for the OC operation so that the siren sound for a **different frequency**.
- Step 6: Go to Step 4.

Example A two-tone siren that oscillates between **300 Hz** and **1200 Hz** for **0.5 seconds** each tone.

- Set the **prescaler** to TCNT to **8**.
- Delay count for the **300Hz tone** = $(24000000 \div 8) \div 300 \div 2 = 5000$.
- Delay count for the **1200Hz tone** = $(24000000 \div 8) \div 1200 \div 2 = 1250$.

```
#include "reg9s12.h"
```

```
org    $1000
delay  ds.w  1           ; store the delay for OC operation

org    $2000
lds    #$2000
movb   #$90,TSCR        ; enable TCNT, fast timer flag clear
movb   #$03,TMSK2       ; set main timer prescaler to 8
```

```

        bset    TIOS,$20          ; enable OC5
        movb   #$04,TCTL1        ; select toggle for OC5 pin action

        ldd     #1250             ; 1200Hz
        std     delay            ; use high-frequency delay count first
        ldd     TCNT             ; start timer
        addd    delay            ;
        std     TC5              ;
        bset    TIE,$20          ; enable OC5 interrupt
        cli                     ;
forever  ldy     #25              ; tone last for 0.5 second
        jsr     d20ms            ;
                                     ;
        movw    #5000,delay      ; switch to low-frequency delay count
        ldy     #25              ; tone last for 0.5 second
        jsr     d20ms
        movw    #1250,delay      ; switch to high-frequency delay count
        bra     forever

OC5ISR   ldd     TC5              ; interrupt service routine to toggle OC5 pin
        addd    delay            ; according to the tone frequency in use
        std     TC5              ;
        rti

d20ms    bset    TIOS,$01        ; enable OC0
        ldd     TCNT             ;
again    addd    #60000          ; start an output compare operation
        std     TC0              ; for 60,000/(24MHz/8) = 20 ms delay
wait     brclr   TFLG1,$01,wait
        ldd     TC0
        dbne    y,again
        rts

        org     $3E64            ; from chapter 6
        fdb     OC5ISR

end

```

Playing Songs Using the Output Compare Function

- Place the **frequencies and durations** of **all notes** in a table.
- For every note, uses the OC function to **generate the digital waveform** with the specified frequency and duration.

Example: US National Anthem.

- Set the prescaler to TCNT to 8.
- **Timer count** for the **300Hz** tone = $(24000000 \div 8) \div 300 \div 2 = 5000$.

```
#include "reg9s12.h"
```

```
G3      equ    7653  ; delay count to generate G3 note (with prescaler=8)
B3      equ    6074  ; delay count to generate B3 note
C4      equ    5733  ; delay count to generate C4 note
C4S     equ    5412  ; delay count to generate C4S (sharp) note
D4      equ    5108  ; delay count to generate D4 note
E4      equ    4551  ; delay count to generate E4 note
F4      equ    4295  ; delay count to generate F4 note
F4S     equ    4054  ; delay count to generate F4S note
G4      equ    3827  ; delay count to generate G4 note
A4      equ    3409  ; delay count to generate A4 note
B4F     equ    3218  ; delay count to generate B4F note
B4      equ    3037  ; delay count to generate B4 note
C5      equ    2867  ; delay count to generate C5 note
D5      equ    2554  ; delay count to generate D5 note
E5      equ    2275  ; delay count to generate E5 note
F5      equ    2148  ; delay count to generate F5 note
ZZ      equ    20    ; delay count to generate an inaudible sound
```

```
notes    equ    101  ; number of notes in the song
```

```
org      $1000
delay    ds.w    1      ; store the delay for OC operation
rep_cntds.b 1      ; repeat the song this many times
ip       ds.b    1      ; remaining notes to be played
```

```
org      $2000
lds      #$2000
movw     #OC5ISR,$3E64  ; set the interrupt vector
movb     #$90,TSCR      ; enable TCNT, fast timer flag clear
movb     #$03,TMSK2     ; set main timer prescaler to 8
bset     TIOS,$20       ; enable OC5
movb     #$04,TCTL1     ; select toggle for OC5 pin action
```

```
ldx      #song          ; use as a pointer to score table
ldy      #duration       ; points to duration table
movb     #1,rep_cnt      ; play the song twice
movb     #notes,ip       ; set up the note counter
movw     2,x+,delay      ; start with zeroth note
```



```

        ldd    TCNT                ; play the first note
        addd   delay              ;      "
        std    TC5                ;      "
        bset   TIE,$20            ; enable OC5 interrupt
        cli                               ;      "

forever    pshy                  ; save duration table pointer in stack
          ldy    0,y              ; get the duration of the current note
          jsr    d10ms            ; play the note for "duration x 10ms"
          puly                  ; get the duration pointer from stack
          iny                               ; move the duration pointer
          iny                               ;      "
          ldd    2,x+              ; get the next note, move pointer
          std    delay            ;      "
          dec    ip                ; if not the last note, play again
          bne    forever          ;
          dec    rep_cnt           ; check how many times left to play song
          beq    done             ; if not finish playing, re-start from 1st note
          ldx    #song            ; pointers and loop count
          ldy    #duration        ;      "
          movb   #notes,ip        ;      "
          movw   0,x,delay        ; get the first note delay count
          ldd    TCNT            ; play the first note
          addd   #delay           ;      "
          std    TC5
          bra    forever

done       swi

OC5ISR     ldd    TC5                ; restart the OC function
          addd   delay
          std    TC5
          rti

; Create a time delay of 10ms Y times (prescaler = 8)
d10ms      bset   TIOS,#$01        ; enable OC0
          ldd    TCNT
again1     addd   #30000            ; start an output compare operation
          std    TC0              ; for 10ms delay
          brclr  TFLG1,C0F,*
          ldd    TC0
          dbne   y,again1
;          bclr   TIOS,OC0        ; disable OC0
          rts

; store the notes of the whole song
song       dc.w   D4,B3,G3,B3,D4,G4,B4,A4,G4,B3,C4$

```

```

dc.w D4,ZZ,D4,ZZ,D4,B4,A4,G4,F4S,E4,F4S,G4,ZZ,G4,D4,B3,G3
dc.w D4,B3,G3,B3,D4,G4,B4,A4,G4,B3,C4S,D4,ZZ,D4,ZZ,D4
dc.w B4,A4,G4,F4S,E4,F4S,G4,ZZ,G4,D4,B3,G3,B4,ZZ,B4
dc.w B4,C5,D5,ZZ,D5,C5,B4,A4,B4,C5,ZZ,C5,ZZ,C5,B4,A4,G4
dc.w F4S,E4,F4S,G4,B3,C4S,D4,ZZ,D4,G4,ZZ,G4,ZZ,G4,F4S
dc.w E4,ZZ,E4,ZZ,E4,A4,C5,B4,A4,G4,ZZ,G4,F4S,D4,ZZ,D4
dc.w G4,A4,B4,C5,D5,G4,A4,B4,C5,A4,G4

```

; each number is multiplied by 10 ms to give the duration of the corresponding note

```

duration dc.w 30,10,40,40,40,80,30,10,40,40,40
dc.w 80, 3,20,3,20,60,20,40,80,20,20,40,3,40,40,40,40
dc.w 30,10,40,40,40,80,30,10,40,40,40,80,3,20,3,20
dc.w 60,20,40,80,20,20,40,3,40,40,40,40,20,3,20
dc.w 40,40,40,3,80,20,20,40,40,40,3,80,3,40,60,20,40
dc.w 80,20,20,40,40,40,80,3,40,40,3,40,3,20,20
dc.w 40, 3,40,3,40,40,20,20,20,20,3,40,40,20,3,20
dc.w 60,20,20,20,80,20,20,60,20,40,80

```

end

Example: Fur Elise.

```
#include "reg9s12.h"
```

```

org $1000
spk_tone rmb 2
sound_dur rmb 1
xsound_save rmb 2
sound_repeat rmb 1
xsound_beg rmb 2
sound_start rmb 1
rest_note rmb 1
count_5ms rmb 1

```

; 2400000 / 2 / 261.63 Hz = note count for c3 (with **prescaler=1**)

```

c3 equ 45866 ; 261.63 Hz at 24 MHz
c3s equ 43293 ; 277.18 Hz at 24 MHz
d3 equ 40864 ; 293.66 Hz at 24 MHz
d3s equ 38569 ; 311.13 Hz at 24 MHz
e3 equ 36404 ; 329.63 Hz at 24 MHz
f3 equ 34361 ; 349.23 Hz at 24 MHz
f3s equ 32433 ; 369.99 Hz at 24 MHz

```

g3	equ	30613	; 391.99 Hz at 24 MHz
g3s	equ	28894	; 415.31 Hz at 24 MHz
a3	equ	27273	; 440.00 Hz at 24 MHz
a3s	equ	25742	; 466.16 Hz at 24 MHz
b3	equ	24297	; 493.88 Hz at 24 MHz
c4	equ	22934	; 523.25 Hz at 24 MHz
c4s	equ	21646	; 554.37 Hz at 24 MHz
d4	equ	20431	; 587.33 Hz at 24 MHz
d4s	equ	19285	; 622.25 Hz at 24 MHz
e4	equ	18202	; 659.26 Hz at 24 MHz
f4	equ	17181	; 698.46 Hz at 24 MHz
f4s	equ	16216	; 739.99 Hz at 24 MHz
g4	equ	15306	; 783.99 Hz at 24 MHz
g4s	equ	14447	; 830.61 Hz at 24 MHz
a4	equ	13636	; 880.00 Hz at 24 MHz
a4s	equ	12871	; 932.32 Hz at 24 MHz
b4	equ	12149	; 987.77 Hz at 24 MHz
c5	equ	11467	; 1046.50 Hz at 24 MHz
c5s	equ	10823	; 1108.73 Hz at 24 MHz
d5	equ	10216	; 1174.66 Hz at 24 MHz
d5s	equ	9642	; 1244.51 Hz at 24 MHz
e5	equ	9101	; 1318.51 Hz at 24 MHz
f5	equ	8590	; 1396.91 Hz at 24 MHz
f5s	equ	8108	; 1479.98 Hz at 24 MHz
g5	equ	7653	; 1567.98 Hz at 24 MHz
g5s	equ	7225	; 1661.22 Hz at 24 MHz
a5	equ	6818	; 1760.00 Hz at 24 MHz
a5s	equ	6435	; 1864.66 Hz at 24 MHz
b5	equ	6074	; 1975.53 Hz at 24 MHz
c6	equ	5733	; 2093.00 Hz at 24 MHz
c6s	equ	5412	; 2217.46 Hz at 24 MHz
d6	equ	5109	; 2349.32 Hz at 24 MHz
d6s	equ	4821	; 2489.02 Hz at 24 MHz
e6	equ	4551	; 2637.02 Hz at 24 MHz
f6	equ	4295	; 2793.83 Hz at 24 MHz
f6s	equ	4054	; 2959.96 Hz at 24 MHz
g6	equ	3827	; 3135.97 Hz at 24 MHz
g6s	equ	3612	; 3322.44 Hz at 24 MHz
a6	equ	3409	; 3520.00 Hz at 24 MHz
a6s	equ	3218	; 3729.31 Hz at 24 MHz
b6	equ	3037	; 3951.07 Hz at 24 MHz
c7	equ	2867	; 4186.01 Hz at 24 MHz

c7s	equ	2706	; 4434.92 Hz at 24 MHz
d7	equ	2554	; 4698.64 Hz at 24 MHz
d7s	equ	2411	; 4978.03 Hz at 24 MHz
e7	equ	2275	; 5274.04 Hz at 24 MHz
f7	equ	2148	; 5587.66 Hz at 24 MHz
f7s	equ	2027	; 5919.92 Hz at 24 MHz
g7	equ	1913	; 6271.93 Hz at 24 MHz
g7s	equ	1806	; 6644.88 Hz at 24 MHz
a7	equ	1705	; 7040.00 Hz at 24 MHz
a7s	equ	1609	; 7458.63 Hz at 24 MHz
b7	equ	1519	; 7902.13 Hz at 24 MHz
c8	equ	1	; for rest note

note_c	equ	0
note_cs	equ	1
note_d	equ	2
note_ds	equ	3
note_e	equ	4
note_f	equ	5
note_fs	equ	6
note_g	equ	7
note_gs	equ	8
note_a	equ	9
note_as	equ	10
note_b	equ	11

; dur18= 1/8 note, dur14= 1/4 note, \$FE= rest_note, \$FF = end of song

dur18	equ	50
dur14	equ	100

	org	\$2000	
	lds	#\$2000	
	movw	#timer6,\$3E62	
	movw	#timer5,\$3E64	
	movw	#3429,spk_tone	; 3500 Hz
	movb	#\$80,TSCR	; enable timer; manual TOF clear
	movb	#\$60,TIOS	; chan 5 & 6 (PT5&6) for OC operation
	movb	#\$60,TIE	; enable OC5&6 interrupts
	clr	count_5ms	
	cli		
	movb	#\$04,TCTL1	; set toggle OC5 action for speaker
	jsr	start_sound	
again	jmp	again	
timer6	inc	count_5ms	

```

        ldaa    count_5ms
        cmpa    #5
        bne     timer3
        clr     count_5ms
        ldaa    sound_start           ; processing every 5ms
        beq     timer3
        ldaa    sound_dur             ; duration
        deca
        staa    sound_dur
        bne     timer3
        ldx     xsound_save

repeat   ldab    0,X
        cmpb    #255
        beq     sound_end
        ldaa    1,X
        cmpa    #255
        beq     sound_end
        staa    sound_dur
        inx
        inx
        stx     xsound_save
        cmpb    #$FE
        bne     not_rest
        ldaa    #1
        staa    rest_note
        movw    #$08,TCTL1           ; turn off OC5 = turn off speaker
        jmp     timer3

not_rest   clr     rest_note
        movb    #$04,TCTL1           ; toggle speaker
        ldx     #note_table
        aslb
        abx
        ldx     0,X
        stx     spk_tone
        jmp     timer3

sound_end   ldaa    sound_repeat
        beq     no_rep
        ldx     xsound_beg
        jmp     repeat

no_rep:    movw    #3429,spk_tone      ; 3500 Hz
        movb    #$08,TCTL1           ; turn off OC5 = turn off speaker
        clr     sound_start

```

```

timer3      ldd    #24000          ; 1 ms time base
            addd   TC6
            std    TC6
            movb   #$40,TFLG1      ; clear C6F flag
            rti

timer5      ldd    spk_tone
            addd   TC5
            std    TC5
            movb   #$20,TFLG1      ; clear C5F flag
            rti

start_sound  ldx    #song
            stx     xsound_beg
            ldaa    #1
            staa    sound_repeat
            ldab    0,x
            ldaa    1,x
            staa    sound_dur
            inx
            inx
            stx     xsound_save
            ldx    #note_table
            aslb
            abx
            ldx     0,X
            stx     spk_tone
            ldaa    #1
            staa    sound_start
            rts

note_table:
            fdb     c3,c3s,d3,d3s,e3,f3,f3s,g3,g3s,a3,a3s,b3
            fdb     0,0,0,0          ; dummy byte
            fdb     c4,c4s,d4,d4s,e4,f4,f4s,g4,g4s,a4,a4s,b4
            fdb     0,0,0,0          ; dummy byte
            fdb     c5,c5s,d5,d5s,e5,f5,f5s,g5,g5s,a5,a5s,b5
            fdb     0,0,0,0          ; dummy byte
            fdb     c6,c6s,d6,d6s,e6,f6,f6s,g6,g6s,a6,a6s,b6
            fdb     0,0,0,0          ; dummy byte
            fdb     c7,c7s,d7,d7s,e7,f7,f7s,g7,g7s,a7,a7s,b7
            fdb     0,0,0,0          ; dummy byte
            fdb     c8

song        fcb     $20+note_e,dur18

```

```

fcb    $20+note_ds,dur18
fcb    $20+note_e,dur18
fcb    $20+note_ds,dur18
fcb    $20+note_e,dur18
fcb    $10+note_b,dur18
fcb    $20+note_d,dur18
fcb    $20+note_c,dur18
fcb    $10+note_a,dur14
fcb    $00+note_e,dur18
fcb    $00+note_a,dur18
fcb    $10+note_c,dur18
fcb    $10+note_e,dur18
fcb    $10+note_a,dur18
fcb    $10+note_b,dur14
fcb    $00+note_gs,dur18
fcb    $10+note_d,dur18
fcb    $10+note_e,dur18
fcb    $10+note_gs,dur18
fcb    $10+note_b,dur18
fcb    $20+note_c,dur14
fcb    $00+note_e,dur18
fcb    $00+note_a,dur18
fcb    $10+note_e,dur18
fcb    $FE,dur14
fcb    255,255

end

```

Possible project: Display the playing notes and durations on the 7-segment or LCD displays. Make a digital piano.

End of Chapter 8