

view\_frames Result

Recorded at time: 33.253

map

Broadcaster: /map\_to\_odom  
Average rate: 10.190 Hz  
Most recent transform: 33.329 ( -0.076 sec old)  
Buffer length: 4.907 sec

amazon\_warehouse\_robot/odom

Broadcaster: /gazebo  
Average rate: 10.208 Hz  
Most recent transform: 33.200 ( 0.053 sec old)  
Buffer length: 4.800 sec

amazon\_warehouse\_robot/base

Broadcaster: /base\_to\_laser  
Average rate: 49.980 Hz  
Most recent transform: 33.266 ( -0.013 sec old)  
Buffer length: 4.942 sec

amazon\_warehouse\_robot/hokuyo\_link

Broadcaster: /base\_to\_chassis  
Average rate: 10.187 Hz  
Most recent transform: 33.332 ( -0.079 sec old)  
Buffer length: 4.908 sec

amazon\_warehouse\_robot/amazon\_warehouse\_robot::chassis

Broadcaster: /gazebo  
Average rate: 10.208 Hz  
Most recent transform: 33.201 ( 0.052 sec old)  
Buffer length: 4.800 sec

amazon\_warehouse\_robot/amazon\_warehouse\_robot::left\_wheel

Broadcaster: /gazebo  
Average rate: 10.208 Hz  
Most recent transform: 33.201 ( 0.052 sec old)  
Buffer length: 4.800 sec

amazon\_warehouse\_robot/amazon\_warehouse\_robot::right\_wheel