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Vehicle Properties		
Total Length (in)	104	
Diameter (in)	5.46	
Gross Lift Off Weigh (lb)	22.6	
Airframe Material(s)	Carbon Fiber	
Fin Material and Thickness (in)	Fiberglass .25	
Coupler Length(s)/Shoulder Length(s) (in)	2.26	

Motor Properties		
Motor Brand/Designation	AeroTech L1000	
Max/Average Thrust (lb)	224.81	
Total Impulse (lbf-s)	2714 Ns	
Mass Before/After Burn (lb)	22.6/19.51	
Liftoff Thrust (lb)	22.6	
Motor Retention Method	Bolted plate	

Stability Anal	ysis
Center of Pressure (in. from nose)	80.305
Center of Gravity (in. from nose)	62.992
Static Stability Margin (on pad)	3.14
Static Stability Margin (at rail exit)	3.2
Thrust-to-Weight Ratio	12.8
Rail Size/Type and Length (in)	96
Rail Exit Velocity (ft/s)	80.1

Ascent Analysis		
Maximum Velocity (ft/s)	748	
Maximum Mach Number	0.673	
Maximum Acceleration (ft/s^2)	391	
Target Apogee (ft)	5280	
Predicted Apogee (From Sim.) (ft)	5727	

Recovery System Properties - Overall	
Total Descent Time (s)	71.7
Total Drift in 20 mph winds (ft)	800 max

Recovery System Properties - Energetics		
Ejection System Energetics (ex. Black Powder)		Black Powder
Energetics Mass - Drogue	Primary	2
Chute (grams)	Backup	2
Energetics Mass - Main	Primary	N/A
Chute (grams)	Backup	N/A
Energetics Mass - Other	Primary	2
(grams) - If Applicable	Backup	2

Mile	stone	CDR	
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Recovery System Properties - Recovery Electronics		
Primary Altimeter Make	e/Model	Strattologger CF/PerfectFlite
Secondary Altimeter Ma	ke/Model	Easy Mini/Altus Metrum
Other Altimeters (if app	olicable)	-
Rocket Locator (Make/	'Model)	Eggfinder TX
Additional Locators (if applicable)		-
Transmitting Frequencies (all - vehicle and payload)		***Required by CDR*** (Complete on pages 3 and 4)
Describe Redundancy Plan (batteries, switches, etc.)	powered seperately and connected to independent charges	
Pad Stay Time (Launch Configuration)	>1hr	

Recovery System Properties - Drogue Parachute				
Ma	nufacturer/Mo	del	Fruity Chutes	
Size o	or Diameter (in	or ft)	15 in	
Main Altim	neter Deployme	ent Setting	Apogee	
Backup Alti	meter Deploym	ent Setting	Apoge	e + 2 sec
Velocit	y at Deploymen	it (ft/s)		0
Terr	ninal Velocity (f	t/s)	113.189	
Recovery Harness Material, Size, and Type (examples - 1/2 in. tubular Nylon or 1 in. flat Kevlar strap)		1/2 in. tubular Nylon		
Recovery Harness Length (ft)		10		
Harness/Airfra	me Interfaces		1/4-20   Bolts	
Kinetic	Section 1 Section 2		Section 3	Section 4
Energy of Each Section (Ft-Ibs)	2262.3	1617.06		

Recovery System Properties - Main Parachute				
Ma	nufacturer/Mo	del	Fruity Chutes	
Size o	or Diameter (in	or ft)	60 in	
Main Altime	ter Deploymen	t Setting (ft)	500	
Backup Altim	eter Deploymei	nt Setting (ft)	5	500
Velocit	y at Deploymen	it (ft/s)	113	3.189
Terminal Velocity (ft/s)		t/s)	19.1601	
Recovery Harness Material, Size, and Type (examples - 1/2 in. tubular Nylon or 1 in. flat Kevlar strap)		1/2 in. tubular Nylon		
Recovery Harness Length (ft)		10		
Harness/Airframe Interfaces		1/4-20 I Bolts		
Kinetic	Section 1 Section 2 Section 3 Section		Section 4	
Energy of Each Section (Ft-Ibs)	64.82	46.34		

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	Payload
	Overview
Payload 1 (official payload)	Slim Sammy is the team's answer to the soil sample collection payload challenge. The rover has been designed to be safely and securely housed within the rocket's air frame during flight, deploy upon landing with the proper orientation correction, drive a minimum of 10ft from the landing sight taking into account the vast range of possible terrains, collect at least 10mL of soil, and seal the sample. The rover features a 3D printed unibody chassis driven by two independently driven silicone tracks. This enables the rover to traverse a majority of the expected terrains and perform obstacle avoidance maneuvers. Once the rover has reached a minimum of 10ft from the landed rocket airframe, the bull-dozer like soil sample collection scoop will deploy. The rover will then drive forward (further away from the rocket) and collect the soil sample. The scoop will then be returned to the closed position, pressed up against the sealing lid to complete the collection task.
	Overview
Payload 2 (non-scored payload)	

Test Plans, Status, and Results			
Ejection Charge Tests	Ejection charge tests will be completed before any flight of the the vehicle		
Sub-scale Test Flights	Sub-scale was flown on Decmber 8th at the LUNAR launch site at 4:01pm.		
Vehicle Demon- stration Flights	Full-Scale will be flown on Febuary 2nd or 9th		
Payload Demon- stration Flights	Payload will be demonstrated on Febuary 2nd or 9th		

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	Transn	nitter #1		
Location of transmitter:	Nosecone Location			
Purpose of transmitter:				
Brand	Eggfinder	RF Output Power (mW)	-	
Model	Eggfinder TX	Specific Frequency used by team (MHz)	-	
Handshake or frequency hopping? (explain)	None			
Distance to closest e-match or altimeter (in)				
Description of shielding plan:	Rover payload will shie	eld all incoming transmissions from other elect	tronic systems	

Transmitter #2				
Location of transmitter:	Recovery Section			
Purpose of transmitter: Reciver for payload activation				
Brand	Digi International	RF Output Power (mW)	250	
Model	XBee-PRO	Specific Frequency used by team (MHz)	900	
Handshake or frequency hopping? (explain)				
Distance to closest e-match or altimeter (in)	6 in for altimeter, 3in for black-powder charge.			
Description of shielding plan:	No shielding, module is a reciver.			

Transmitter #3			
N/A			
RF Output Power (mW)			
Specific Frequency used by team (MHz)			
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	Transmitter #4			
Location of transmitter:	N/A			
Purpose of transmitter:				
Brand	RF Output Power (mW)			
Model	Specific Frequency used by team (MHz)			
Handshake or frequency hopping? (explain)				
Distance to closest e-match or altimeter (in)				
Description of shielding plan:				

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	Transmitter #5
Location of transmitter:	N/A
Purpose of transmitter:	
Brand	RF Output Power (mW)
Model	Specific Frequency used by team (MHz)
Handshake or frequency hopping? (explain)	
Distance to closest e-match or altimeter (in)	
Description of shielding plan:	
1	
	Transmitter #6
Location of transmitter:	
	N/A
Purpose of transmitter:	
Brand	RF Output Power (mW)
Model	Specific Frequency used by team (MHz)
Handshake or frequency hopping? (explain)	
Distance to closest e-match or altimeter (in)	
Description of shielding plan:	
	Additional Comments
	payload section seperation once landed. These have their own arming circuit and
Terriote triggering. Osing a Digi in	ternational XBee-PRO reciver using a 900Mhz frequency and 250Mw of power.