

Final Project: Asteroid Planning

Robot Intelligence: Planning 4649/7649

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Abstract—

I. INTRODUCTION

II. RELATED WORK

III. METHODS

IV. EXPERIMENTS

V. ANALYSIS

VI. DISCUSSION

REFERENCES

- [1] Mike Stilman. Task constrained motion planning in robot joint space. In *Intelligent Robots and Systems, 2007. IROS 2007. IEEE/RSJ International Conference on*, pages 3074–3081. IEEE, 2007.
- [2] Tobias Kunz and Mike Stilman. Manipulation planning with soft task constraints. In *Intelligent Robots and Systems (IROS), 2012 IEEE/RSJ International Conference on*, pages 1937–1942. IEEE, 2012.