

EE 771 : Recent Topics in Analytical Signal Processing

Assignment 2

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Q1

We are given a 1 dimensional periodic signal $x(t)$ with period $T = 1$ as:

$$x(t) = a_1 u(t - t_1) + a_2 u(t - t_2) - (a_1 + a_2) u(t - t_3)$$

with $0 < t_1 < t_2 < t_3$

1a

We want to find the number of samples of $x(t) * \text{sinc}(Bt)$ which are sufficient for the reconstruction of $x(t)$ and a suitable value for B . We note that $x(t)$ is an example of a non-uniform spline and therefore we can directly use Theorem 2 from the paper.

The minimum number of samples required are $N = 2M + 1$ where $M = \lfloor \frac{B\tau}{2} \rfloor$. We need $B \geq \rho$ where ρ is the rate of innovation. In this case $\rho = \frac{2K}{\tau}$ and $K = 3, \tau = 1$. Therefore $\rho = 6$. But we note that $c_1 + c_2 + c_3 = 0$ which reduces one degree of freedom and hence $\tau = 5$. Thus, we need $B \geq 5Hz$. Choosing $B = 5Hz$ gives us $M = 2$ and $N = 5$, i.e. we can reconstruct the signal given 5 samples and choosing $B = 5Hz$.

1b

We are now given a new 1d periodic signal $x_1(t)$ with the same period $T = 1$ as:

$$x_1(t) = x(t) + b_1 \delta(t - t_1) - b_1 \delta(t - t_3)$$

Clearly, this is an example of the stream of derivatives of dirac deltas and we can use Theorem 3 from the paper. First we find the rate of innovation. The degrees of freedom increases by only from the previous part. This gives us $\rho = \frac{6}{1} = 6Hz$. Choosing $B = 6Hz$ we get $M = 3$ and correspondingly $N = 7$.

Q2

We want to prove that the Yule Walker system in the algorithm mentioned in the paper is invertible.

Denote the Yule Walker system matrix as A . We consider a 3×3 matrix and note that the proof can be easily extended to any other $n \times n$ matrix.

$$A = \begin{bmatrix} X[0] & X[-1] & X[-2] \\ X[1] & X[0] & X[-1] \\ X[2] & X[1] & X[0] \end{bmatrix}$$

Here $X[m] = \frac{1}{\tau} \sum_{k=0}^{K-1} c_k \exp(-i2\pi m t_k / \tau)$. Denote $u_k = \exp(-i2\pi t_k / \tau)$. We can re-write $X[m] = \frac{1}{\tau} \sum_{k=0}^{K-1} c_k u_k^m$. In this case $K = 3$. Also it is clear that the value of τ wouldn't make a difference in the invertibility of the matrix A . Thus we can write the following:

$$X[0] = c_1 + c_2 + c_3$$

$$X[1] = c_1 u_1 + c_2 u_2 + c_3 u_3$$

$$\begin{aligned}
X[2] &= c_1 u_1^2 + c_2 u_2^2 + c_3 u_3^2 \\
X[-1] &= c_1 u_1^{-1} + c_2 u_2^{-1} + c_3 u_3^{-1} \\
X[-2] &= c_1 u_1^{-2} + c_2 u_2^{-2} + c_3 u_3^{-2}
\end{aligned}$$

We further note that we can write A as $A = [A_1 c | A_2 c | A_3 c]$. Here:

$$A_3 = \begin{bmatrix} u_1^{-2} & u_2^{-2} & u_3^{-2} \\ u_1^{-1} & u_2^{-1} & u_3^{-1} \\ 1 & 1 & 1 \end{bmatrix}$$

$$A_2 = U A_3$$

$$A_1 = U^2 A_3$$

$$U = \begin{bmatrix} u_1 & 0 & 0 \\ 0 & u_2 & 0 \\ 0 & 0 & u_3 \end{bmatrix}$$

Moreover, A_3 is a permutation of a vander monde matrix. Therefore A_3 is invertible and therefore is non-singular. Now denote the determinant of A by $\det(A)$. We have

$$\det(A) = \det(A_3 [U^2 c | U c | c]) = \det(A_3) \det([U^2 c | U c | c])$$

The first term on the rhs is non-zero since A_3 is non-singular. The second term on the rhs is

$$\det([U^2 c | U c | c]) = c_1 c_2 c_3 \det(B)$$

$$B = \begin{bmatrix} u_1^2 & u_1 & 1 \\ u_2^2 & u_2 & 1 \\ u_3^2 & u_3 & 1 \end{bmatrix}$$

Clearly B is also a vander monde matrix and therefore, B is also non-singular. Also, c_1, c_2, c_3 are also non-zero (else there will be no diracs at those places and the dimension of the matrix will reduce). Therefore we have:

$$\det(A) \neq 0$$

Consequently, we have proved that A is invertible.

Q3

We are given u_1, u_2 as the roots of unity. We want to construct the annihilation filter for the Fourier Series coefficients

$$X[m] = \sum_{r=0}^3 c_r m^r u_1^m + \sum_{r=0}^1 d_r m^r u_2^m$$

This can be re-written as:

$$X[m] = u_1^m (c_0 + c_1 m + c_2 m^2 + c_3 m^3) + u_2^m (d_0 + d_1 m)$$

$$X[m] = u_1^m * \text{poly}(m, 3) + u_2^m * \text{poly}(m, 1)$$

Here $\text{poly}(m, r)$ denotes a polynomial in m of degree r . The annihilation filter $A(z)$ can be constructed in the following way (as noted in the paper):

- For $u_1^m \text{poly}(m, 3)$ we need the annihilation filter $A_1(z) = (1 - u_1 z^{-4})$ (as stated in the paper). This is because, say $A_1(z) = \sum_{l=0}^4 A_1[l] z^{-l}$, then $A_1^{(n)}(u_1) = 0 = \sum_{l=0}^4 A_1[l] * l * (l-1) * \dots * (l-n+1) * z^{-l}$ and this would be true for all $n \leq 3$. Thus $\sum_{l=0}^4 A_1[l] P[l] u_1^{-l} = 0$. Here $P[l]$ is any polynomial of degree less than 3. Moreover, this is smallest possible annihilation filter as we need to annihilate polynomials of degree 3.
- Similarly, to annihilate $u_2^m \text{poly}(m, 1)$ we require $A_2(z) = (1 - u_2 z^{-1})^2$. This is the smallest filter to annihilate the components of u_2 .
- To annihilate the sum we simply take the product of the two filters. $A(z) = A_1(z) A_2(z)$.

$$A(z) = (1 - u_1 z^{-1})^4 (1 - u_2 z^{-1})^2$$

Q4

We are given

$$x(t) = \sum_{k=1}^K b_k \delta(t - t_k)$$

Here all t_k are in $(0, 1)$. Two RC filters with values (R_1, C_1) and (R_2, C_2) are used in parallel to filter out $x(t)$. We are also given the impulse response of the RC filters as:

$$h_i = \exp(-R_i C_i) u(t)$$

where $i = 1, 2$ and $u(t)$ is the unit time step signal. We need to find the conditions on sampling interval T so that the sampled signal $x(t) * h_i(t)|_{t=nT}$ are sufficient to reconstruct the parameters of $x(t)$.