## Question 3

- Compressive sensing reconstructions involve estimating a sparse signal  $\mathbf{x} \in \mathbb{R}^n, n \gg 2$  from a vector  $\mathbf{y} \in \mathbb{R}^m (m \ll n)$  of compressed measurements of the form  $\mathbf{y} = \mathbf{\Phi} \mathbf{x}$  where  $\mathbf{\Phi} \in \mathbb{R}^{m \times n}$  is the measurement matrix (assume there is no noise). Now answer the following questions, from first principles. **Do not merely quote theorems or algorithms.** 
  - 1. If it is known that  $\mathbf{x}$  has only 1 non-zero element and that the other elements are zero, can you uniquely estimate  $\mathbf{x}$  if m = 1? If yes, how? If not, why not? Now further suppose, you knew beforehand the index (but not the value) of the non-zero element of  $\mathbf{x}$ ? Does this help you any further? If yes, how? If not, why not?
  - 2. If it is known that  $\mathbf{x}$  has only 1 non-zero element and that the other elements are zero, can you uniquely estimate  $\mathbf{x}$  if m = 2? If yes, how? If not, why not?
  - 3. If it is known that  $\mathbf{x}$  has only 2 non-zero elements and that the other elements are zero, can you uniquely estimate  $\mathbf{x}$  if m=3? If yes, describe an algorithm that is guaranteed to estimate it accurately. If not, explain why not, and explain whether there are any special instances of  $\Phi$  for which unique estimation is possible?
  - 4. Repeat part (c) with m = 4. [1+2+3+4=10 points]

Answer:

**a**)

$$\mathbf{y} = \Phi \mathbf{x}, \, y \in R^m, \, x \in R^n, \, \Phi \in R^{mxn}$$

If m=1, we can calculate  $\frac{y}{\Phi_j}$  for each  $1 \leq j \leq n$ . But since we do not know at which index the non zero element of x is, we cannot find the unique solution of x but we will have a set of finite possible solutions.

If the index (i) of the non zero element is also known, we can uniquely find x if  $\Phi_i \neq 0$ . If  $\Phi_i = 0$ , we cannot.

**b**)

Let the index of the non zero element of x be j.

$$y_1 = \phi_{1j} x_j$$

$$y_2 = \phi_{2j} x_j$$

$$\frac{y_1}{y_2} = \frac{\phi_{1j}}{\phi_{2j}}$$

$$(1)$$

We can find the column j in  $\Phi$  for which the above equation 1 is satisfied. Then we can easily calculate

$$x_j = \frac{y_1}{\phi_{1j}}$$

However, there can be multiple columns in  $\Phi$  which can satisfy equation-1. So for unique solution, no two columns of  $\Phi$  should have elements in same ratio.

 $\mathbf{c})$ 

Let i and j be the indices of the 2 non-zero elements of x.

$$y_{1} = \phi_{1i}x_{i} + \phi_{1j}x_{j}$$
$$y_{2} = \phi_{2i}x_{i} + \phi_{2j}x_{j}$$
$$y_{3} = \phi_{3i}x_{i} + \phi_{3i}x_{i}$$

To uniquely find x, it is necessary that any 4 columns of  $\Phi$  are linearly independent. But since we only have 3 rows, any 4 columns will be linearly dependent. This is because any 4 vectors in 3D space are always linearly dependent (which can be proved by the argument that- if they were linearly independent then we can take any 3 which will also be linearly independent, and use as basis to express the remaining vector as a linear combination of those 3 and hence the contradiction) Thus it is not possible to uniquely find x for any such  $\Phi$ 

## **d**)

If m=4 and x has 2 non zero elements, we can uniquely find x if any 4 columns of  $\Phi$  are linearly independent.

$$y_1 = \phi_{1i} x_i + \phi_{1i} x_i \tag{2}$$

$$y_2 = \phi_{2i} x_i + \phi_{2j} x_j \tag{3}$$

$$y_3 = \phi_{3i}x_i + \phi_{3j}x_j \tag{4}$$

$$y_4 = \phi_{4i}x_i + \phi_{4i}x_i \tag{5}$$

To find x, we can do the following,-

- Consider the set of all pairs of columns (i,j) of  $\Phi$ . loop over the set.
- For the measurements say  $y_1$  and  $y_2$ , find the solution  $(x_i, x_j)^T$  by taking the inverse of the subset 2x2 matrix.(here solving equations 2 and 3)
- Check if the solution satisfies the equations of the remaining two measurements (say equations 4 and 5 here). If it does, we have found the unique solution and so end loop.