

# A\_1

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EE 679: Computing Assignment 1

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## 0.1 Question 1:

Given the following specification for a single-formant resonator, obtain the transfer function of the filter  $H(z)$  from the relation between resonance frequency / bandwidth, and the pole angle / radius. Plot filter magnitude response (dB magnitude versus frequency) and impulse response.

F1 (formant) = 900 Hz

B1(bandwidth) = 200 Hz

Fs (sampling freq) = 16 kHz

## 0.2 Solution:

We can calculate the transfer function using the following equation:

$$H(z) = \frac{1}{1 - 2r\cos\theta z^{-1} + r^2 z^{-2}}$$

Where  $r$  is the magnitude of the pole and  $\theta$  is the angle of the pole.

$$r = e^{-\pi BT} \theta = 2\pi FT$$

where,  $T$  is the sampling period and  $F$  is the frequency of the formant.

Further, to get the transfer function as a function of the frequency, we can substitute  $z$  as:

$$z = e^{j\omega T} = e^{\frac{j2\pi f}{F_s}}$$
$$\Rightarrow H(f) = \frac{1}{1 - 2r\cos\theta z^{-1} + r^2 z^{-2}} \Bigg|_{z=e^{\frac{j2\pi f}{F_s}}}$$

```
[8]: import numpy as np
import matplotlib.pyplot as plt
from scipy.io.wavfile import write

# Input Parameters
```

```

F1 = 900
B1 = 200
Fs = 16000

freq_range = np.arange(0,5000,1)

# Function to calculate the transfer function magnitude from poles parameters
def H_discrete_transfer_mag(F1, B1, Fs):
    """ Function to get the magnitude of the discrete transfer function from
    ↪ Formant freq and bandwidth

    Args:
        F1 (int): Formant frequency
        B1 (int): Formant bandwidth
        Fs (int): Sampling frequency

    Returns:
        [ndarray]: Magnitude of the discrete transfer function
    """
    T = 1/Fs # Sampling period
    H_discrete = [] # Empty list to store the discrete
    ↪ transfer function
    r1 = np.exp(-np.pi*B1*T) # Magnitude of the pole
    ↪ corresponding to the formant 1
    theta1 = 2*np.pi*F1*T # Angle of the pole corresponding
    ↪ to the formant 1
    freq_range = np.arange(0,5000,1) # define the range of frequency
    ↪ values

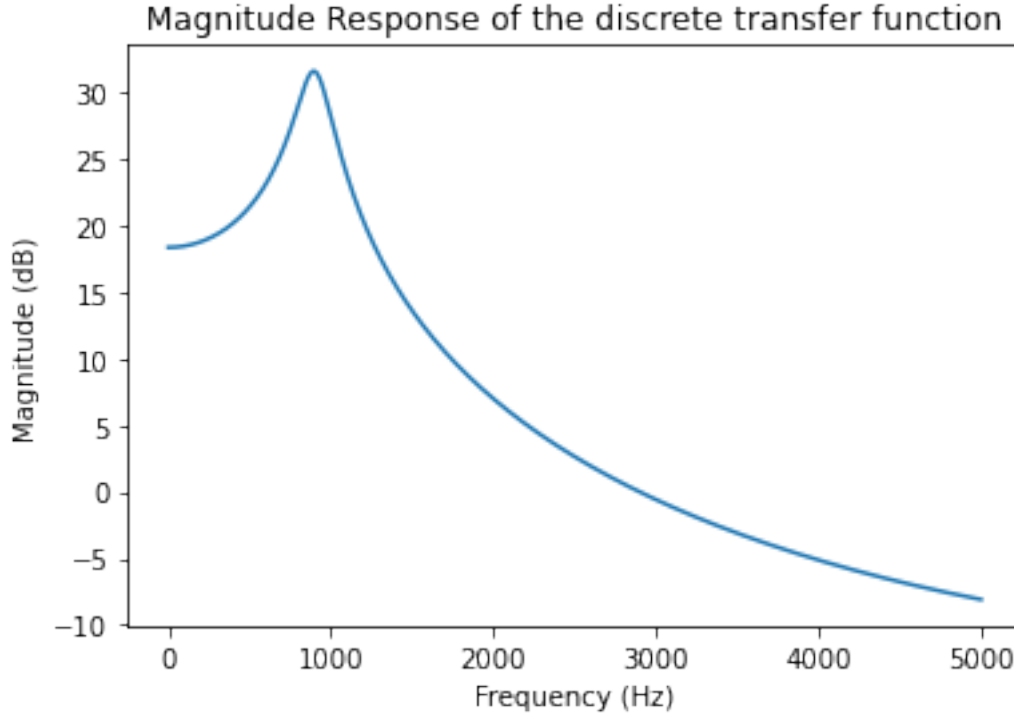
    for f in freq_range:
        z = np.exp(2j*np.pi*f/Fs) # complex exponential in discrete
    ↪ domain
        H = 1/(1-2*r1*np.cos(theta1)*z**-1 + r1**2*z**-2) # discrete transfer
    ↪ function calculation
        H_discrete.append(np.abs(H))

    return H_discrete

H = H_discrete_transfer_mag(F1, B1, Fs)

plt.plot(freq_range, 20* np.log10(H))
plt.xlabel('Frequency (Hz)')
plt.ylabel('Magnitude (dB)')
plt.title('Magnitude Response of the discrete transfer function')
plt.show()

```



### 0.3 Calculation of the Impulse Response

To calculate the Impulse Response we construct the difference equation from the transfer function.

$$H(z) = \frac{1}{1 - 2r\cos\theta z^{-1} + r^2 z^{-2}}$$

Comparing  $H(z)$  with standard form of transfer function

$$H(z) = \frac{b_0}{a_0 + a_1 z^{-1} + a_2 z^{-2}}$$

we get:

$$a_0 = 1, a_1 = -2r\cos\theta, a_2 = r^2, b_0 = 1$$

Hence, we can form the difference equation from the transfer function as follows:

$$a_0 y[n] + a_1 y[n-1] + a_2 y[n-2] = b_0 x[n] \implies a_0 y[n] = b_0 x[n] - a_1 y[n-1] - a_2 y[n-2]$$

Substituting the values of  $a_0$ ,  $a_1$ ,  $a_2$  and  $b_0$  in the above equation we get:

$$y[n] = x[n] + 2r\cos\theta x[n-1] - r^2 x[n-2]$$

[9]: *# Implement the given filter as a difference equation*

```
def filter(x, F1, B1):
```

```

    """ Function to get the output signal when input signal x is passed through
    ↪ filter with Formant Freq F1 and
    Formant Bandwidth B1

    Args:
        x (ndarray): Input signal
        F1 (int): Formant Frequency
        B1 (int): Formant Bandwidth

    Returns:
        [ndarray]: Output signal
    """
    T = 1/Fs # Sampling period
    r1 = np.exp(-np.pi*B1*T) # Magnitude of the pole
    ↪ corresponding to the formant 1
    theta1 = 2*np.pi*F1*T # Angle of the pole corresponding
    ↪ to the formant 1
    y = np.zeros(x.size) # Initialize output array

    # Assuming initial reset we get the first two terms of the output as
    y[0] = x[0]
    y[1] = x[1] + 2*r1*np.cos(theta1)*y[0]

    # The rest of the output is calculated using the difference equation
    for i in range(2, x.size):
        y[i] = x[i] + 2*r1*np.cos(theta1)*y[i-1] - r1**2*y[i-2]

    return y

```

Now, to calculate the impulse response for the filter with given formant, we pass an impulse through the filter and observe the output.

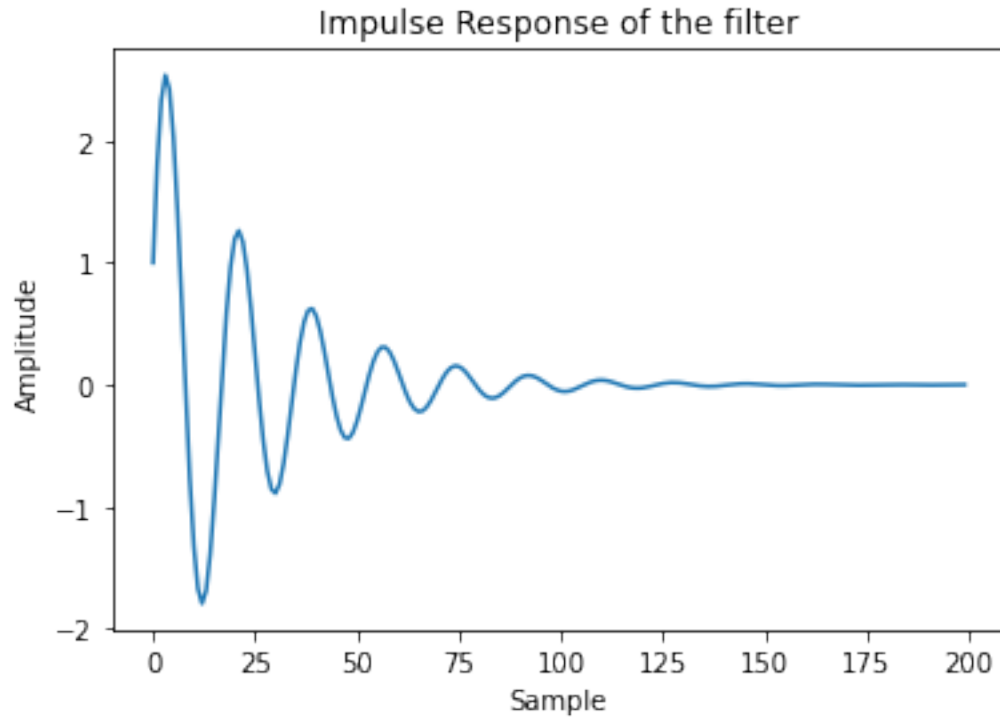
```

[10]: impulse = np.zeros(200)
      impulse[0] = 1 # Impulse signal

      impulse_response = filter(impulse,F1,B1) # Impulse response of the filter

      plt.plot(impulse_response)
      plt.xlabel('Sample')
      plt.ylabel('Amplitude')
      plt.title('Impulse Response of the filter')
      plt.show()

```



#### 0.4 Question 2:

Excite the above resonator (“filter”) with a periodic source excitation of  $F_0 = 140$  Hz. You can approximate the source signal by a narrow-triangular pulse train. Compute the output of the source-filter system over the duration of 0.5 second using the difference equation implementation of the LTI system. Plot the time domain waveform over a few pitch periods so that you can observe waveform characteristics. Play out the 0.5 sec duration sound and comment on the sound quality.

#### 0.5 Solution:

First we make the required periodic source excitation. For this we assume triangular pulse train with a period of 0.5 sec with triangular pulse of frequency 140 Hz.

```
[11]: duration = 0.5                                # Duration of the
        ↪ signal

F0 = 140                                              # Impulse frequency
time = np.arange(0, duration, 1/Fs)                 # Time vector
# Function to generate the triangular pulse train with given impulse frequency
↪ F0
def triangular_pulse_train_gen(F0, duration, Fs):
    triangular_pulse_train = np.zeros(time.size)     # Empty vector to
    ↪ store the output
    # Generating the triangular pulse train
```

```

for i in range(time.size):
    if i%(Fs//F0) == 0 and i != 0:
        triangular_pulse_train[i] = 1
        triangular_pulse_train[i+1] = 0.75
        triangular_pulse_train[i-1] = 0.75
        triangular_pulse_train[i+2] = 0.5
        triangular_pulse_train[i-2] = 0.5
        triangular_pulse_train[i+3] = 0.25
        triangular_pulse_train[i-3] = 0.25

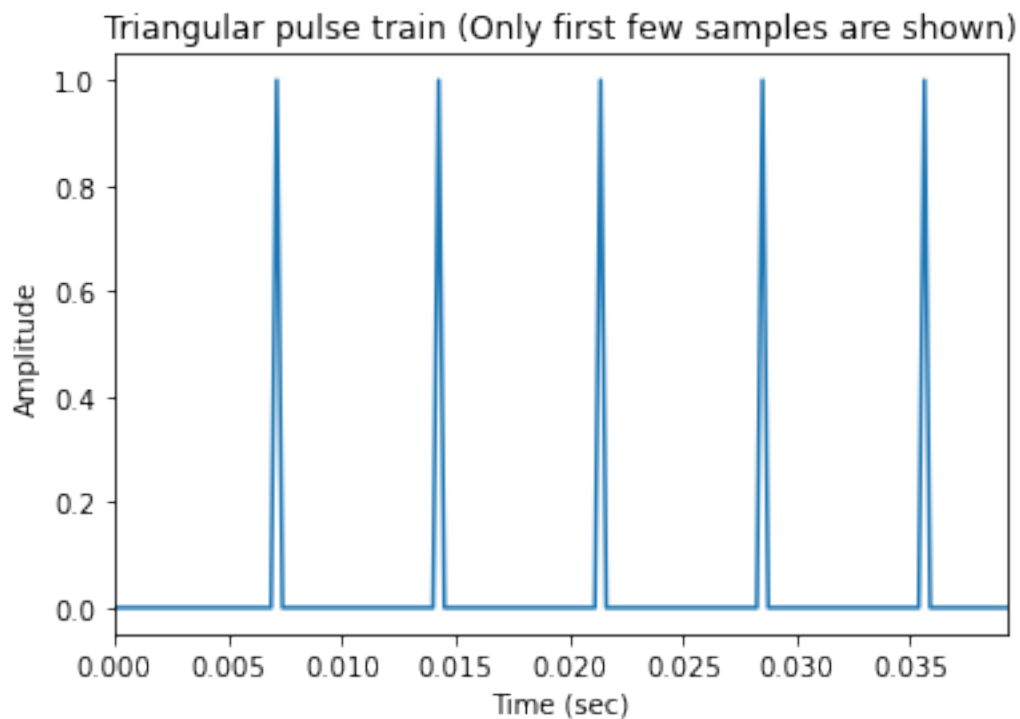
    return triangular_pulse_train

triangular_pulse_train = triangular_pulse_train_gen(F0, duration, Fs) #  

    ↪ Generating the triangular pulse train for given parameters

plt.plot(time, triangular_pulse_train) # Plot the triangular pulse train
plt.xlim(0, 5.5/F0) # Limit the x-axis to show 5 impulse periods
plt.xlabel('Time (sec)')
plt.ylabel('Amplitude')
plt.title('Triangular pulse train (Only first few samples are shown)')
plt.show()

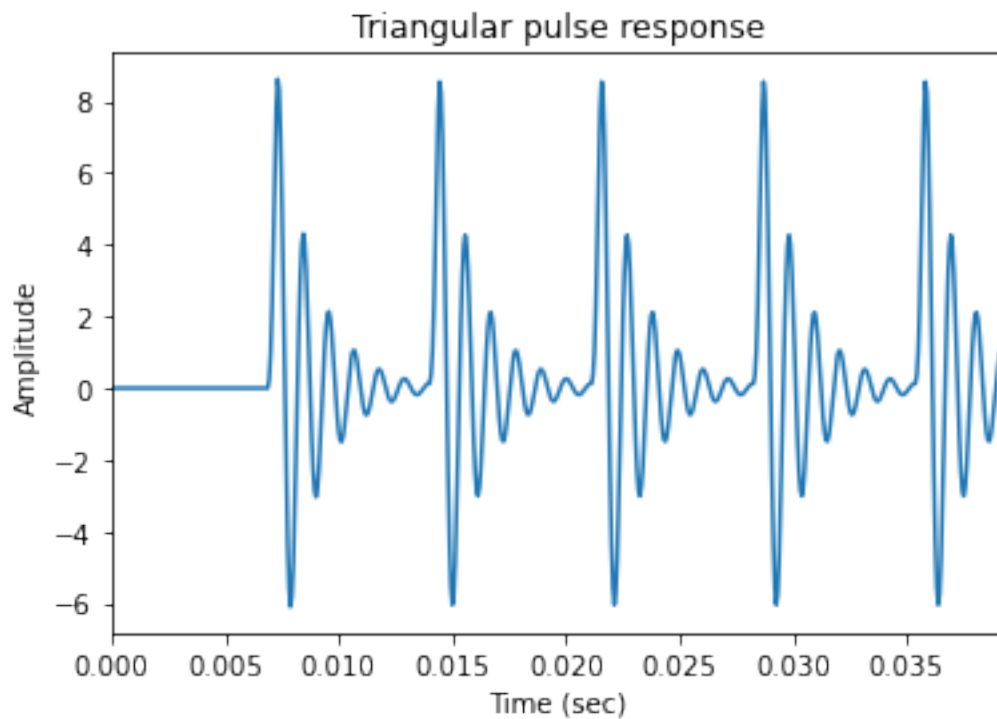
```



Now, we pass this `triangular_pulse_train` through the filter and observe the output.

```
[12]: triangular_pulse_response = filter(triangular_pulse_train,F1,B1) # Pass the
      ↪triangular pulse train through the filter

plt.plot(time, triangular_pulse_response) # Plot the output
      ↪of the filter
plt.xlim(0,5.5/F0) # Limit the x-axis to show 5
      ↪impulse periods
plt.xlabel('Time (sec)')
plt.ylabel('Amplitude')
plt.title('Triangular pulse response')
plt.show()
```



Now, we play this triangular\_pulse\_response to observe the sound.

```
[13]: # Write the input sound to input.wav
input_sound = np.int16(triangular_pulse_train/np.max(np.
      ↪abs(triangular_pulse_train))*32767)
write('input.wav', Fs, input_sound)

# Write the output sound to output.wav
output_sound = np.int16(triangular_pulse_response/np.max(np.
      ↪abs(triangular_pulse_response))*32767)
write("output.wav",Fs,output_sound)
```

### 0.6 Question 3:

Vary the parameters as indicated below; plot and comment on the differences in waveform and in sound quality for the different parameter combinations. -  $F_0 = 120$  Hz,  $F_1 = 300$  Hz,  $B_1 = 100$  Hz  
-  $F_0 = 120$  Hz,  $F_1 = 1200$  Hz,  $B_1 = 200$  Hz  
-  $F_0 = 180$  Hz,  $F_1 = 300$  Hz,  $B_1 = 100$  Hz

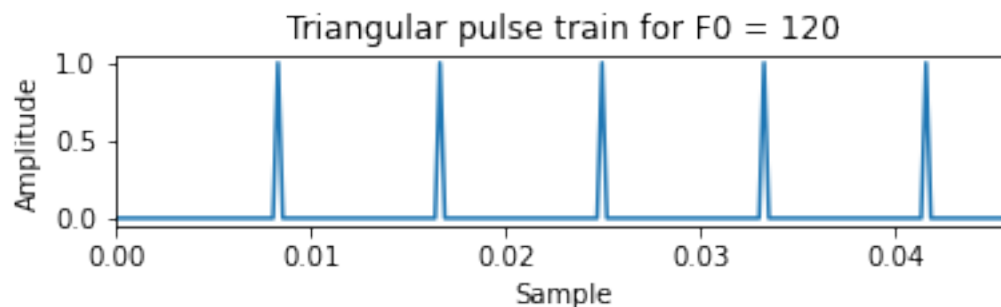
### 0.7 Solution:

0.7.1 Generate triangular pulse train with period of 0.5 sec and frequencies mentioned above.

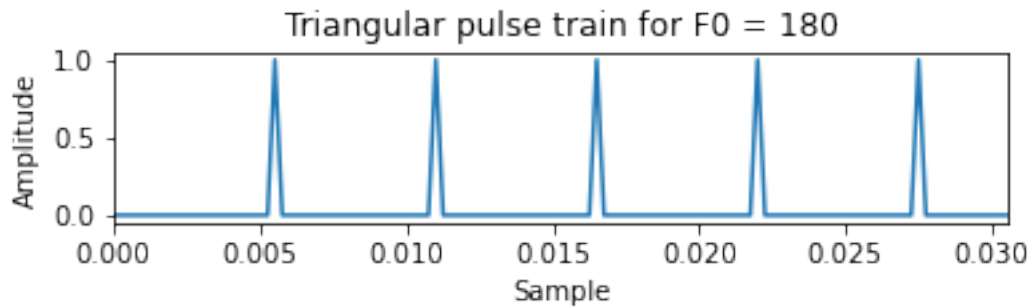
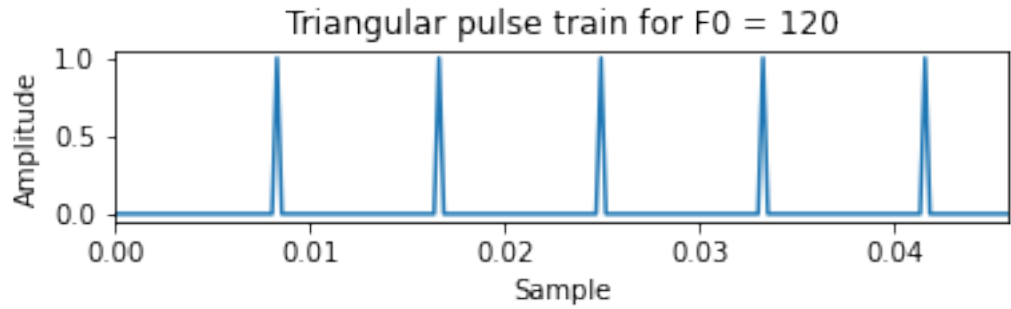
```
[14]: F0s = np.array([120,120,180])           # Array of F0 values

# Generate triangular pulse train with given impulse frequencies F0s
triangular_pulse_trains = [triangular_pulse_train_gen(F0s[i], duration, Fs) for i in range(len(F0s))]

# Plot the triangular pulse trains for the three cases
for i in range(len(F0s)):
    plt.subplot(len(F0s),1,i+1)
    plt.plot(time, triangular_pulse_trains[i])
    plt.xlim(0,5.5/F0s[i])
    plt.xlabel('Sample')
    plt.ylabel('Amplitude')
    plt.title('Triangular pulse train for F0 = ' + str(F0s[i]))
    plt.show()
```





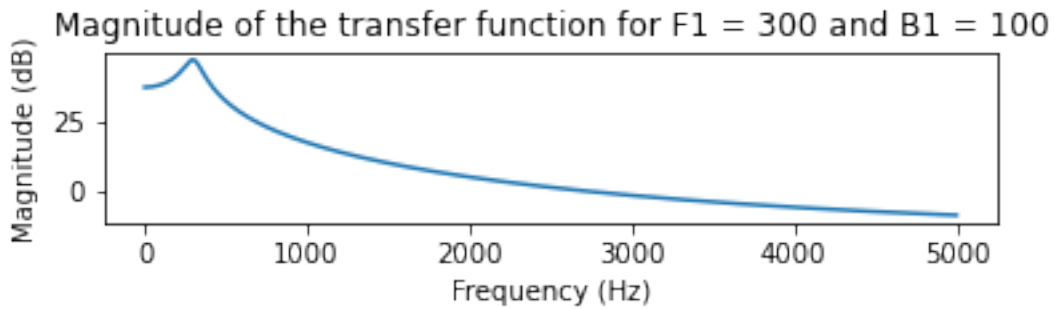
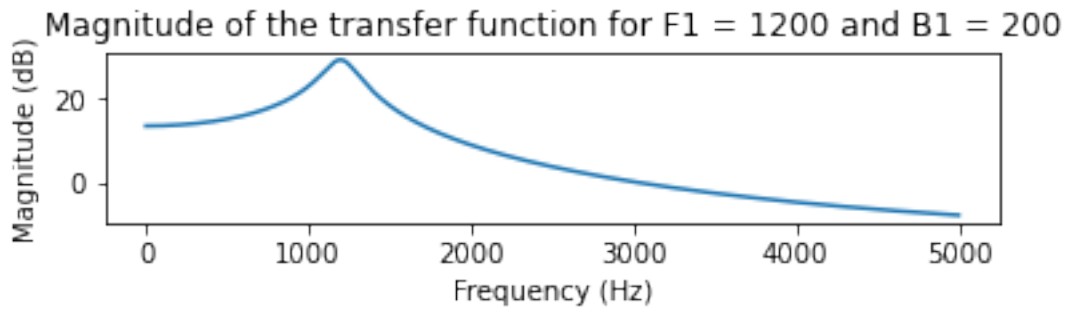
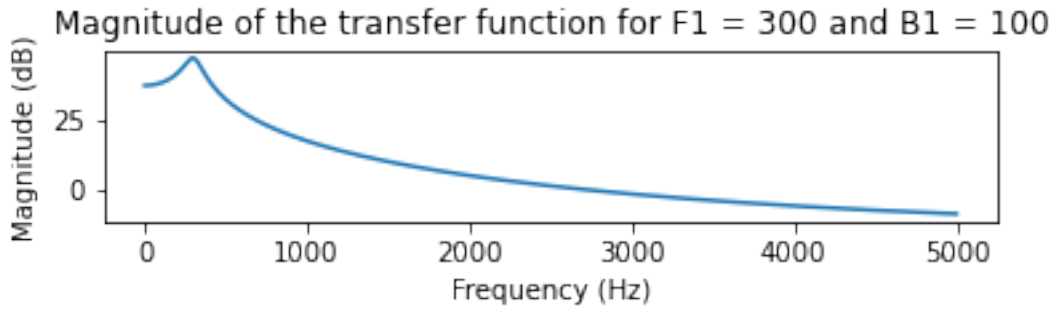


**0.7.2** Now, let's have a look at the Magnitude of the transfer function for the given three cases

```
[15]: F1s = np.array([300,1200,300])           # Array of F1 values
      B1s = np.array([100,200,100])           # Array of B1 values

      H_mags = [H_discrete_transfer_mag(F1s[i], B1s[i], Fs) for i in range(len(F1s))]
      ↪ # Array of H magnitudes

      # Plot the Magnitude of the transfer function for the three cases
      for i in range(len(F1s)):
          plt.subplot(len(F1s),1,i+1)
          plt.plot(freq_range, 20*np.log10(H_mags[i]))
          plt.xlabel('Frequency (Hz)')
          plt.ylabel('Magnitude (dB)')
          plt.title('Magnitude of the transfer function for F1 = ' + str(F1s[i]) + '
          ↪ and B1 = ' + str(B1s[i]))
          plt.show()
```

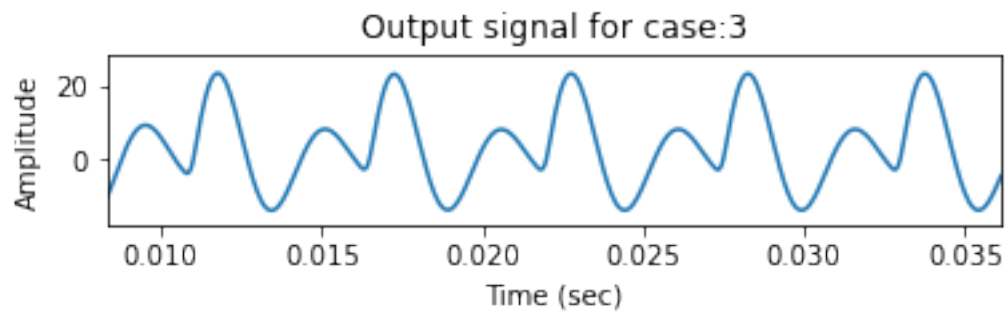
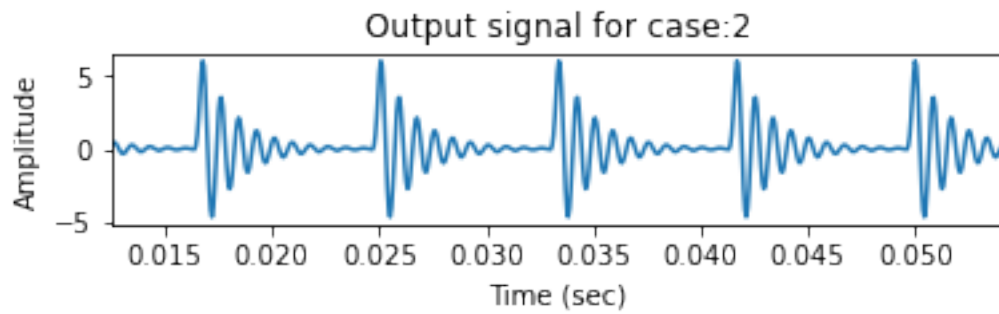
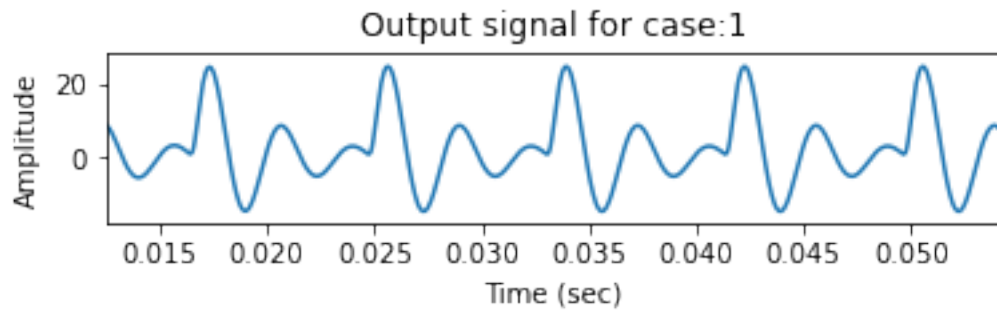


**0.7.3** Now let us see the output of the filter for the given three cases.

```
[18]: outputs = [filter(triangular_pulse_trains[i],F1s[i],B1s[i]) for i in
    ↪range(len(F1s))] # Array of output signals

# Plot the output signals for the three cases
for i in range(len(F1s)):
    plt.subplot(len(F1s),1,i+1)
    plt.plot(time, outputs[i])
    plt.xlim(1.5/F0s[i],6.5/F0s[i])
```

```
plt.xlabel('Time (sec)')
plt.ylabel('Amplitude')
plt.title('Output signal for case:' + str(i+1))
plt.show()
```



0.7.4 Now we save the input and output of the filter for the given three cases.

```
[17]: # Write the input sound to input.wav
input_sounds = [np.int16(triangular_pulse_trains[i])*32767 for i in
    range(len(F1s))] # No need to divide by max since it is 1
for i in range(len(F1s)):
    write('input_'+str(i+1)+'.wav', Fs, input_sounds[i])

# Write the output sound to output.wav
output_sounds = [np.int16(outputs[i]/np.max(np.abs([outputs[i]])))*32767 for i
    in range(len(F1s))]
for i in range(len(F1s)):
    write("output_"+str(i+1)+".wav",Fs,output_sounds[i])
```

```
[ ]:
```