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CSE 4309 – Assignment 2

P (sensor = Maine) = 0.05, P (sensor = Sahara) = 0.95,

Task-1

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P \text{ (temp >= 80 | Maine)} = 0.2, P \text{ (temp < 80 | Maine)} = 0.8
P (temp >= 80 | Sahara) = 0.9, P (temp < 80 | Sahara) = 0.1
    a) P (Maine | temp < 80) = P (Maine) P (temp < 80 | Maine) / P (temp < 80)
       = P (Maine) P (temp < 80 | Maine) / [ P (Maine) P (temp < 80 | Maine) + P (Sahara) P
       (temp < 80 | Sahara)]
       = 0.05*0.8 / [0.05*0.8 + 0.95*0.1]
       = 0.04 / [0.04 + 0.095]
       = 0.04 / 0.135
       = 0.2963
    b) P (temp < 80) = P (Maine | temp < 80) * P (temp < 80 | Maine) + P (Sahara | temp < 80)
       * P (temp < 80 | Sahara)
       = 0.2963 * 0.8 + (1 - 0.2963) * 0.1
       = 0.23704 + 0.07037
       = 0.30741
   c) From part b, we get the probability of getting two emails indicating a daily high under 80
       degrees for 2 consecutive days. Let's call this event t<sub>1,2</sub>
       The probability of first three emails indicating daily highs under 80 could be represented
       with the product rule like- P(t1, t2, t3) = P(t1 \mid t2, t3) * P(t2 \mid t3) * P(t3).
        However, knowing the probability for the first 2 days, we could write it as:
        P(t_{1,2}, t_3) = P(t_{1,2} | t_3) * P(t_3) = P(t_3 | t_{1,2}) * P(t_{1,2}) from the bayes rule.
       And P (t3 | t_{1,2}) = P (t3 and t_{1,2}) / P (t_{1,2})
        P (temp < 80 at either location) = 0.2963 * 0.05 + 0.7031 * 0.95 = 0.014815 + 0.667945 =
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0.68276

Since each day is conditionally independent of the other day, P(t3) = 0.68276

Therefore, $P(t_{1,2}, t3) = P(t3 | t_{1,2}) * P(t_{1,2}) = P(t3 and t_{1,2}) = P(t3) * P(t_{1,2}) = 0.68276 * 0.30741 = 0.20988725$

Task-2

P is possibly a probability function. Probability cannot be great than 1. With P(A) = 0.3 and P(B) = 0.6, the P(A) + P(B) = 0.9. If P(C) + P(D) is equal to 0.1, then P is a probability function, otherwise it is not.

Tack-3

P is definitely not a probability function because integrating P(x) = 0.3 from the limits 0 to 10 would give us 3. This is not less than or equal to 1, so P cannot be a probability density function.

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Task-4

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• p(B = r) = 0.4
    • p(B = b) = 0.6
    • p(F = a | B = r) = 0.25
    • p(F = o \mid B = r) = 0.75
    • p(F = a \mid B = b) = 0.75
    • p(F = o \mid B = b) = 0.25
   P(F = a) = p(F = a, B = r) + p(F = a, B = b)
    = p (F = a | B = r) * p (B = r) + p (F = a | B = b) * p (B = b)
    = 0.25 * 0.4 + 0.75 * 0.6
    = 0.1 + 0.45
   = 0.55
   P(F = 0) = 1 - P(F = a) = 0.45
P(B = r \mid F = a) = p(F = a \mid B = r) * p(B = r) / p(F = a) = 0.25 * 0.4 / 0.55 = 0.1818
P(B = b \mid F = a) = p(F = a \mid B = b) * p(B = b) / p(F = a) = 0.75 * 0.6 / 0.55 = 0.8181
P(B = r \mid F = o) = p(F = o \mid B = r) * p(B = r) / p(F = o) = 0.75 * 0.4 / 0.45 = 0.6667
P(B = b \mid F = o) = p(F = o \mid B = b) * p(B = b) / p(F = o) = 0.25 * 0.6 / 0.45 = 0.3333
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If F = a, if the prediction is B = r, then the classifier will be 18.18% correct. If F = a, if the prediction is B = b, then the classifier will be 81.81% correct. If F = a, if the prediction is B = r, then the classifier will be 66.67% correct. If F = a, if the prediction is B = b, then the classifier will be 33.33% correct.

Task-5

Run command for your terminal:

python3 naive_bayes.py [path of training file] [path of test file]

classification accuracy is 0.4483