## S&DS 365 / 665 Intermediate Machine Learning

#### **Mercer Kernels**

September 10



#### Please note

- Materials posted to http://interml.ydata123.org
- Readings from "Probabilistic Machine Learning: An Introduction"
- https://probml.github.io/pml-book/book1.html

#### Some reminders

- Assn 1 posted today
- Due at midnight, September 25 (two weeks, Thursday)
- Topics: Lasso, smoothing, Mercer kernels, leave-one-out

## **Topics for today**

- Calculation from last class
- Mercer kernels

### Bias-variance for density estimation

We'll derive an expression for the squared bias of kernel density estimation using a Taylor expansion

The calculation is very similar for the variance

#### **Bias**

The calculation:

$$\mathbb{E}\widehat{f}(x) = \frac{1}{nh^p} \sum_{i=1}^n \mathbb{E}K\left(\frac{X_i - x}{h}\right)$$

$$= \frac{1}{h^p} \int K\left(\frac{u - x}{h}\right) f(u) du$$

$$= \int K(v) f(x + hv) dv$$

$$= \int K(v) \left(f(x) + hv^T \nabla f(x) + \frac{1}{2}h^2 v^T \nabla^2 f(x)v + o(h^2)\right) dv$$

$$= f(x) + C(x)h^2 + o(h^2)$$
using  $\int K(u) du = 1$  and  $\int uK(u) du = 0$ 

6

#### **Variance**

By a similar argument, using  $Var(X) \leq \mathbb{E}X^2$ 

$$\begin{split} \mathbb{E}\widehat{f}(x)^2 &\leq C_2 \frac{1}{n^2 h^{2p}} \sum_{i=1}^n \mathbb{E}K\left(\frac{X_i - x}{h}\right)^2 \\ &= C_2 \frac{1}{n h^{2p}} \int K\left(\frac{u - x}{h}\right)^2 f(u) du \\ &= C_2 \frac{f(x)}{n h^p} \int K(v)^2 dv + o\left(\frac{1}{n h^p}\right) \\ &= C_2 \frac{f(x)}{n h^p} + o\left(\frac{1}{n h^p}\right) \end{split}$$

assuming  $nh^p \to \infty$ .

7

#### **Risk**

This gives

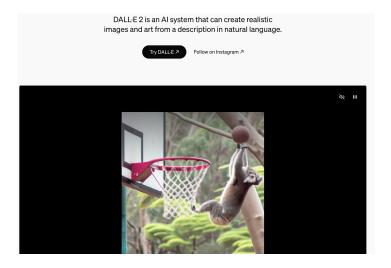
bias<sup>2</sup> 
$$\approx h^4$$
 var  $\approx \frac{1}{nh^p}$ 

On the assignment, you'll work with these expressions to reason about the smallest possible risk and the curse of dimensionality

8

- The KDE is a generative model
- We can sample from the density to "generate" a new data point
- What is an algorithm for sampling from the estimated distribution?

- Sample an index i uniformly from 1 to n
- ② Sample a point x from a Gaussian with mean  $X_i$  and variance  $h^2$



As we'll see later in the course, Transformers can be naturally seen as a form of kernel smoothing and kernel density estimation.

## Mercer Kernels: The big picture



Instead of using local smoothing, we can optimize the fit to the data subject to regularization (penalization). Choose  $\widehat{m}$  to minimize

$$\sum_{i} (Y_i - \widehat{m}(X_i))^2 + \lambda \text{ penalty}(\widehat{m})$$

where penalty( $\widehat{m}$ ) is a *roughness penalty*.

 $\lambda$  is a parameter that controls the amount of smoothing.

How do we construct a penalty that measures roughness? One approach is: *Mercer Kernels* and *RKHS = Reproducing Kernel Hilbert Spaces*.



One of the more technical topics in the class.

Don't need to completely grok it!

A kernel is a bivariate function K(x, x'). We think of this as a measure of "similarity" between points x and x'.

A kernel is a bivariate function K(x, x'). We think of this as a measure of "similarity" between points x and x'.

A Mercer kernel has a special property: For any set of points  $x_1, \ldots, x_n$  the  $n \times n$  matrix

$$\mathbb{K} = \left[ K(x_i, x_j) \right]$$

is positive semidefinite (no negative eigenvalues)

A kernel is a bivariate function K(x, x'). We think of this as a measure of "similarity" between points x and x'.

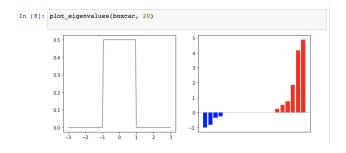
A Mercer kernel has a special property: For any set of points  $x_1, \ldots, x_n$  the  $n \times n$  matrix

$$\mathbb{K} = \big[K(x_i, x_j)\big]$$

is positive semidefinite (no negative eigenvalues)

This property has many important (and beautiful!) mathematical consequences. It is a characterization of Mercer kernels.

## Which of the kernels we used for smoothing are Mercer? (demo)



## Mercer Kernels: Key example

A Gaussian gives us a Mercer kernel:

$$K(x,x')=e^{-\frac{\|x-x'\|^2}{2h^2}}$$

Note: Here we fix the bandwidth *h*.

A *Mercer kernel* K(x, x') is symmetric and positive semidefinite bivariate function:

$$\int \int f(x)f(x')K(x,x')\,dx\,dx'\geq 0$$

for all (univariate) functions f.

#### **Basis functions**

We can create a set of *basis functions* based on *K*.

Fix z and think of K(z, x) as a function of x. That is,

$$K(z,x)=K_z(x)$$

is a function of the second argument, with the first argument fixed.

## Defining a norm from the kernel

Because of the positive semidefinite property, we can create an *inner product* and *norm* over the span of these functions

If 
$$f(x) = \sum_{r} \alpha_{r} K_{z_{r}}(x)$$
,  $g(x) = \sum_{s} \beta_{s} K_{y_{s}}(x)$ , the inner product is  $\langle f, g \rangle_{K} = \sum_{r} \sum_{s} \alpha_{r} \beta_{s} K(z_{r}, y_{s})$ 
$$= \alpha^{T} \mathbb{K} \beta$$

where  $\mathbb{K} = [K(z_r, y_s)]$ 

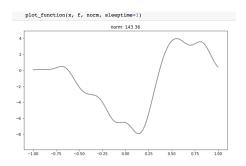
### Defining a norm from the kernel

Because of the positive semidefinite property, we can create an *inner product* and *norm* over the span of these functions

The norm is

$$\begin{split} \|f\|_{K}^{2} &= \langle f, f \rangle_{K} = \sum_{r} \sum_{s} \alpha_{r} \alpha_{s} K(z_{r}, z_{s}) \\ &= \alpha^{T} \mathbb{K} \alpha \geq 0 \end{split}$$

# What do the functions look like? (demo)



## Defining a Hilbert space from the kernel

This gives us an infinite dimensional space of functions with a geometry — a notion of angle from the inner product  $\langle \cdot, \cdot \rangle_K$ 

Technically speaking, we define the Hilbert space by "completing" the functions to include the limits of all Cauchy sequences with respect to the norm.

## Defining a Hilbert space from the kernel

This gives us an infinite dimensional space of functions with a geometry — a notion of angle from the inner product  $\langle \cdot, \cdot \rangle_{\mathcal{K}}$ 

It is called a Reproducing Kernel Hilbert Space (RKHS) because

$$\langle f, K_{x}(\cdot) \rangle_{K} = f(x)$$

That is, the kernel "reproduces" the values of the functions through the inner products

Technically speaking, we define the Hilbert space by "completing" the functions to include the limits of all Cauchy sequences with respect to the norm.

## Defining a Hilbert space from the kernel

This gives us an infinite dimensional space of functions with a geometry — a notion of angle from the inner product  $\langle \cdot, \cdot \rangle_{\mathcal{K}}$ 

It is called a Reproducing Kernel Hilbert Space (RKHS) because

$$\langle f, K_{x}(\cdot) \rangle_{K} = f(x)$$

That is, the kernel "reproduces" the values of the functions through the inner products

Exercise: Verify this identity!

Technically speaking, we define the Hilbert space by "completing" the functions to include the limits of all Cauchy sequences with respect to the norm.

## Nonparametric regression using Mercer kernels

The norm gives us a way to penalize functions for being too complex.

We carry out least squares regression subject to this penalty:

Minimize

$$\sum_{i=1}^{n} (Y_i - m(X_i))^2 + \lambda ||m||_K^2.$$

over the RKHS of functions

#### Dilemma?

How do we carry out this penalized regression? It looks complicated!

Or maybe intractable...

## Linear algebra to the rescue!

#### **Representer Theorem**

Let  $\widehat{m}$  minimize

$$J(m) = \sum_{i=1}^{n} (Y_i - m(X_i))^2 + \lambda ||m||_{K}^{2}.$$

Then

$$\widehat{m}(x) = \sum_{i=1}^{n} \alpha_i K(X_i, x)$$

for some  $\alpha_1, \ldots, \alpha_n$ .

So, we only need to find the coefficients

$$\alpha = (\alpha_1, \ldots, \alpha_n).$$

## Mercer kernel regression

Plug 
$$\widehat{m}(x) = \sum_{i=1}^{n} \alpha_i K(X_i, x)$$
 into  $J$ :

$$J(\alpha) = \|Y - \mathbb{K}\alpha\|^2 + \lambda \alpha^T \mathbb{K}\alpha$$

where 
$$\mathbb{K}_{jk} = K(X_j, X_k)$$

Now we find  $\alpha$  to minimize J. We get (Assn 1):

$$\widehat{\alpha} = (\mathbb{K} + \lambda I)^{-1} Y$$

$$\widehat{m}(x) = \sum_{i} \widehat{\alpha}_{i} K(X_{i}, x)$$

### Mercer kernel regression

The estimator depends on the amount of regularization  $\lambda$ .

Again, there is a bias-variance tradeoff.

We choose  $\lambda$  by cross-validation. This is like the bandwidth in smoothing kernel regression.

#### **Takeaways**

- Mercer kernels have a special property: When restricted to a finite sample they give positive semidefinite matrices
- This allows us to define an inner product and a norm
- We use the norm to penalize functions for being too rough

The underlying math is rich—see the notes if you want to learn more!

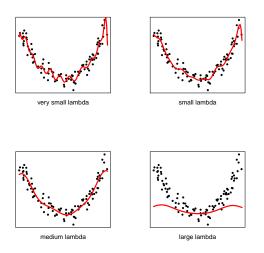
### **Smoothing Kernels** *Versus* **Mercer Kernels**

*Smoothing kernels*: bandwidth *h* controls the amount of smoothing.

*Mercer kernels*: norm  $||f||_K$  controls the amount of smoothing.

In practice these two methods give answers that are very similar.

## **Mercer Kernels: Examples**



#### Kernels from features—and vice-versa

If  $x \to \varphi(x) \in \mathbb{R}^d$  is a feature mapping, we can define a Mercer kernel by

$$K(\mathbf{x}, \mathbf{x}') = \varphi(\mathbf{x})^T \varphi(\mathbf{x}')$$

Conversely, for any Mercer kernel we can derive the corresponding feature map (from the spectral theorem)

## The importance of being Kernelist

- Mercer kernels play a central role in machine learning
  - Can define similarity functions that are kernels for all kinds of data — graphs, molecules, text documents
  - Gaussian processes
  - Modern understanding of deep neural networks

## **Summary for today**

- Smoothing methods compute local averages, weighting points by a kernel. The details of the kernel don't matter much
- Mercer kernels using penalization rather than smoothing
- Defining property: Matrix K is always positive semidefinite
- Equivalent to a type of ridge regression in function space
- The curse of dimensionality limits use of both approaches

## Some technical details (optional)

## **Defining the inner product**

Check that it is well defined:

If 
$$f = \sum_{r} \alpha_{r} K(z_{r}, \cdot)$$
,  $g = \sum_{s} \beta_{s} K(y_{s}, \cdot)$ , the inner product is  $\langle f, g \rangle_{K} = \sum_{r} \sum_{s} \alpha_{r} \beta_{s} K(z_{r}, y_{s})$ 

$$= \sum_{r} \alpha_{r} g(z_{r})$$

$$= \sum_{s} \beta_{s} f(y_{s})$$

using the reproducing property  $\langle f, K(x, \cdot) \rangle = f(x)$ 

### Representer theorem: Proof sketch

We can write any  $f \in \mathcal{H}_K$  as

$$f(x) = \sum_{i} \alpha_{i} K(X_{i}, x) + v(x)$$

where  $\nu$  is orthogonal to the span of the functions  $K(X_i,\cdot)$ 

By the reproducing property,  $f(X_i)$  does not depend on v, and

$$||f||_K^2 = \alpha^T \mathbb{K} \alpha + ||\mathbf{v}||_K^2.$$

So, it must be that the minimizing function has v = 0

### Feature maps

If M is symmetric, positive semidefinite matrix, can write

$$M = U^T \wedge U$$

where *U* is an orthogonal matrix. Can rewrite this as

$$M = \Phi^T \Phi$$

where

$$\Phi = \sqrt{\Lambda} U$$

This transformation allows us to define *features* or *feature maps* for Mercer kernels

#### **Features for Mercer kernels**

Eigen-decomposition:  $\{\psi_j\}$ ,  $\{\lambda_j\}$  where

$$\int K(x,y)\psi_j(y)dy = \lambda_j\psi_j(x) \quad (K\psi_j = \lambda_j\psi_j)$$

The spectral theorem (see previous slide for finite dimensional case) tells us that

$$K(x,y) = \sum_{j=1}^{\infty} \lambda_j \psi_j(x) \psi_j(y)$$

We can think of the kernel in terms of the feature map

$$x \longrightarrow \Phi(x) = (\sqrt{\lambda_1}\psi_1(x), \sqrt{\lambda_2}\psi_2(x), \ldots)$$

## Features for Mercer kernels (continued)

Since  $\psi_i$  forms an orthonormal basis, can write any function f as

$$f(x) = \sum_{r=1}^{\infty} a_r \psi_r(x)$$

By construction of the RKHS, can also write it as

$$f(x) = \sum_{j} \alpha_{j} K(x_{j}, x)$$

It follows that

$$||f||_K^2 = \sum_{r=1}^\infty \frac{a_r^2}{\lambda_r}$$

The functions that are smooth in the RKHS assign small weight to eigenfunctions with small eigenvalues