

Week 3 Jan 19

Exercise: Show that $GL_n(\mathbb{R}) = \{A_{n \times n} \text{ s.t. } \det A \neq 0\}$
is a group under matrix multiplication

Problems:

Euclidean division:

$$a, b \in \mathbb{Z}, \Rightarrow \exists q, r \in \mathbb{Z} \\ \text{s.t. } a = qb + r, \quad 0 \leq r < b$$

Bézout's Lemma:

$$a, b \in \mathbb{Z}, \exists x, y \in \mathbb{Z} \text{ s.t.} \\ ax + by = \gcd(a, b)$$

Equivalence relation definition (see notes)

Examples:

A, B $n \times n$ matrices over a field F (or just \mathbb{R})

$$A \sim B \Leftrightarrow \exists \text{ invertible } P \text{ s.t. } A = PDP^{-1}$$

f, g continuously differentiable functions

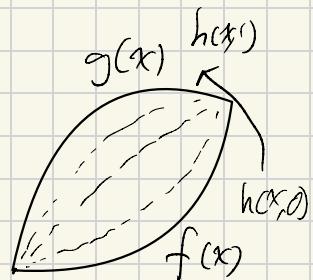
$$f \sim g \Leftrightarrow f = g + C \text{ for } C \in \mathbb{R} \\ \text{or equivalently, } f' = g'$$

Topological spaces X, Y , (homotopic relation)

f, g continuous functions $f, g: X \rightarrow Y$

$$f \sim g \Leftrightarrow \exists \text{ continuous } h: X \times [0, 1] \rightarrow Y \\ \text{s.t. } h(x, 0) = f(x) \text{ and } h(x, 1) = g(x) \quad \forall x \in X$$

Every cont. function $X \rightarrow \mathbb{R}^n$
 is in the same equiv class
 from \sim before



(Omit f in reading session)

Pf: \mathbb{R}^n is contractible, I claim
 the identity map $i: \mathbb{R}^n \rightarrow \mathbb{R}^n$
 is homotopic to $p: \mathbb{R}^n \rightarrow \mathbb{R}^n$ where $p(x) = \vec{0}$.

To this end, let $h: \mathbb{R}^n \times [0, 1] \rightarrow \mathbb{R}^n$

be defined as $h(x, y) = x - yx$, $y \in [0, 1]$, $x \in \mathbb{R}^n$.

For h is continuous, suffice to show

$\forall B_\epsilon(\vec{0}) \subseteq \mathbb{R}^n$, $h^{-1}(B_\epsilon(\vec{0}))$ is open. Observe if $\vec{0} \notin B_\epsilon(x)$,

$h^{-1}(B_\epsilon(x)) = \emptyset$ (which is open) and if $B_\epsilon(x)$'s

not centered at $\vec{0}$, we can choose a smaller $\epsilon' > 0$ s.t. $B_{\epsilon'}(\vec{0}) \subseteq B_\epsilon(x)$
 and suffices to show $h^{-1}(B_\epsilon(\vec{0}))$ is open since then $h^{-1}(B_\epsilon(x)) = \emptyset \cup h^{-1}(B_{\epsilon'}(\vec{0}))$
 $= h^{-1}(B_{\epsilon'}(\vec{0}))$

Furthermore, same holds if $\epsilon > 1$, so we check

$B_\epsilon(\vec{0})$ centered at $\vec{0}$ for some $1 > \epsilon > 0$. Now, $h^{-1}(B_\epsilon(\vec{0})) = B_\epsilon(\vec{0}) \times [0, 1-\epsilon]$,

$B_\epsilon(\vec{0})$ open in \mathbb{R}^n , $[0, 1-\epsilon] = [0, 1] \cap \underbrace{(0, 1-\epsilon)}_{\text{open in } \mathbb{R}}$ so $B_\epsilon(\vec{0}) \times [0, 1-\epsilon]$ is open in $\mathbb{R}^n \times [0, 1]$

Hence, h is continuous.

Now, $h(x, 0) = x - 0x = x$, so $h(x, 0) = i(x)$. On the other hand, $h(x, 1) = x - x = \vec{0} = p(x)$,

so $i \sim p$. Let X be top. space and $f: X \rightarrow \mathbb{R}^n$ be
 continuous. ~~for since homotopic relation is reflexive,~~

$f = f \circ i \sim f \circ p(x) = p(x) = g \circ p(x) \sim g \circ i = g$ since $i \sim p(x)$, so
 By compatibility of homotopy & function composition $f \circ g$.

Quotient sets

X a set, \sim an equiv. relation, X/\sim the set of equiv. classes.

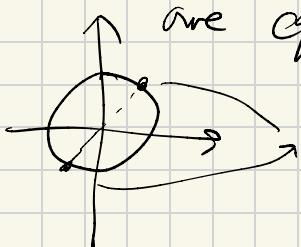
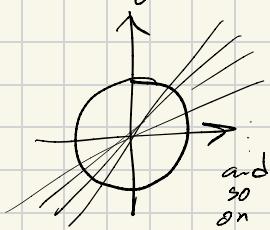
Natural map $\pi_C: X \rightarrow X/\sim$ where $\pi_C(x) = [x]$

Ex. points \mathbb{R}^2 , $p \sim q \Leftrightarrow$ a line λ passing p, q , and origin

Set of all 1-dimensional subspaces of \mathbb{R}^2 , can be

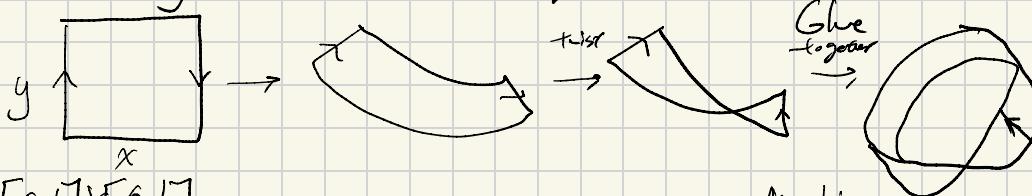
thought of as circle S^1 but anti-podal point

are equivalent, i.e.



$$\forall x, y \in S^1, \\ x \sim y \Leftrightarrow x = \pm y$$

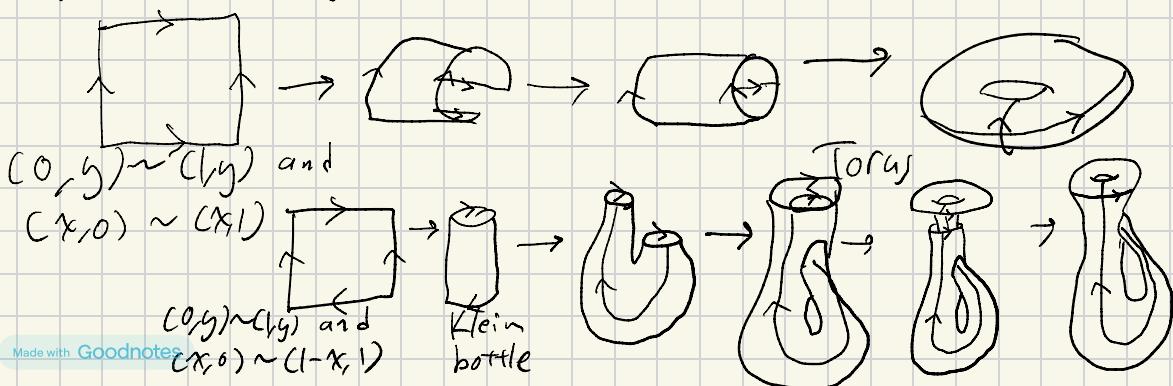
(Gluing) sides of a square



$$[0, 1] \times [0, 1]$$

Points of form (x, y) , $(0, y) \sim (1, 1-y)$

Möbius Strip



Dctn

A binary operation is a function $\circ : X \rightarrow X$ X set

Dctn

(X, \cdot) , \cdot is associative, called semigroup

E.g. set of even numbers under \times

$\{f: A \rightarrow A\}$ where A is set under \circ

Dctn

Semigroup + Identity 1 called a monoid.

$$a \cdot 1 = 1 \cdot a = a \quad \forall a$$

Example: \mathbb{Z} under \times , set of integers mod n under \times ,
 $n \times n$ matrices under matrix multiplication

Group:

Monoid + 2 sided inverses, called abelian if
commutative

E.g. S_n "set of bijective functions $X \rightarrow X$ "

H — quaternions under \times

$\left\{ \begin{pmatrix} * & * & * \\ 0 & * & * \\ 0 & 0 & * \end{pmatrix} \right\}$ — unitriangular matrices

\mathbb{Z}^* (aka $\mathbb{Z} \setminus \{0\}$ under $\times\}$)

Defn

Subgroup — group inside a group
with same operation

Notation: G — group. H — subgroup.
 μ — monoid times operation, $H \trianglelefteq G$
 $g^n = g \cdot \dots \cdot g$ sometimes

E.g. Subgroups of \mathbb{Z} under $(+)$:

$n\mathbb{Z} = \{nx \mid x \in \mathbb{Z}\}$, and they are the only subgroups

Pf: Let $H \trianglelefteq \mathbb{Z}$. Choose minimal $k > 0 \in H$.

Claim: $H = \{kx \mid x \in \mathbb{Z}\}$. Let $m \in H$. By Euclidean div., $m = qk + r$ for some $q, r \in \mathbb{Z}$, $0 \leq r < k$

By closure, $m - qk = r \in H$, by minimality, $r = 0$, so $m = qk$.

m arbitrary $\Rightarrow H = \{kx \mid x \in \mathbb{Z}\}$. If $H = \{0\}$, $H = \{0\}$ ◻

Orthogonal group $O_n(\mathbb{R}) = \{AA^T = I\}$

$O_2(\mathbb{R})$ = rotational matrices, reflectional matrices

Thm: $\forall A \in O_n(\mathbb{R})$, $\det(A) = \pm 1$.

Pf: $1 = \det(AA^T) = \det(A)\det(A^T) = (\det(A))^2$ ◻

Thm:

$\forall A \in O_2(\mathbb{R})$, if A is a reflection, exactly one of
 λ_1, λ_2 as the eigenvalues
(Omit pf in reading session)

If: If λ_1, λ_2 are real, A preserves distance between vectors, so $\lambda_1, \lambda_2 = \pm 1$. Consider orientation of $A(e_1)$ and $A(e_2)$. Must have one negative eigenvalue, say λ_1 , since one of e_1, e_2 got flipped, and the other did not. A does not scale vectors so $\lambda_1 = -1, \lambda_2 = 1$.

Claim: No complex eigenvalues.

Contradiction. By fundamental theorem of algebra
 $\lambda_1 = z, \lambda_2 = \bar{z}$. $z \cdot \bar{z} = \det(A) \geq 0 > -1 \Rightarrow$

Weekly problem:

Lemma 1.1 says enough to find right identity + right inverse.
right identity first since inverses depend on identity.

We know:

— G finite

$$\begin{aligned} \text{— } ac = bc &\Rightarrow a = b \\ \text{— } ca = cb &\Rightarrow a = b \end{aligned}$$

G finite and want to somehow get a right identity from G . Try multiplying things. If we have $x \in G$, $xg = x$, we are happy since x can be a candidate as a right identity. Try fixing x , can we somehow get x from multiplying $g \in G$ to right of x by xg ?

$$G = \{g_1, g_2, g_3, \dots, g_n\}$$

$$xG = \{xg_1, xg_2, xg_3, \dots, xg_n\}$$

By closure, $xG \subseteq G$ but is $G \subseteq_x G$?

We know $x = g_i$, we want to show $xg_i \in G$
so if $G \subseteq_x G$, we are good to go.

Show $q(g) = xg$ is injective. ✓
holds by cancellation

$xg = x$ for some g . Claim: g is right identity

Every $a \in G = bx$ for some $b \in G$ since

$$G_x = \{g_1x, g_2x, \dots, g_nx\} = G \quad \text{by}$$

cancellation.

$$ag = bxg = bx = a, \quad g \text{ is right identity.}$$

For inverses, $\exists a \in G$ s.t. $a x = e$ since

$$xG = G \quad \checkmark$$



