

Basic Electrical Engineering ONESHOTS

Unit 3

@ShameemSir
Sarcastic Teacher



AC Fundamentals

$$I_{\text{rms}} = \sqrt{\frac{i_m^2}{2}} = \frac{I_m}{\sqrt{2}} = 0.707 I_m$$

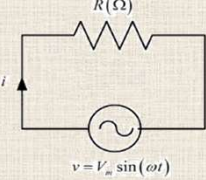
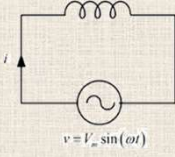
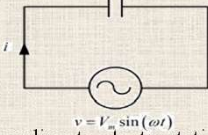
$$I_{\text{av}} = \frac{2I_m}{\pi} = 0.637 I_m$$

$$K_{\text{ff}} = \frac{I_{\text{rms}}}{I_{\text{avg}}} = \frac{\frac{I_m}{\sqrt{2}}}{\frac{2I_m}{\pi}} = \frac{\pi}{2\sqrt{2}} = 1.11$$

$$K_{\text{pf}} = \frac{I_m}{0.707 I_m} = \sqrt{2} = 1.414$$

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| Purely Resistive: | Purely Inductive: | Purely Capacitive: |
|---|--|--|
| Let us consider pure resistance across a 1- ϕ AC supply | Let us consider pure inductance across a 1- ϕ AC supply | Let us consider pure capacitance across a 1- ϕ AC supply |
|  |  |  |
| $v = V_m \sin \omega t$ $i = \frac{v}{R}$ $i = \frac{V_m \sin \omega t}{R} = \frac{V_m}{R} \sin \omega t$ $i_m = \frac{V_m}{R}$ $i = i_m \sin \omega t$ $v = V_m \sin \omega t$ | <p>According to Faraday's law of electromagnetic induction, induced emf in the inductor is:</p> $e = -L \frac{di}{dt}$ $i = -\frac{1}{L} \int e dt$ <p>According to Lenz's law $v = -e$, so</p> $i = \frac{1}{L} \int v dt \dots \dots (4)$ $i = \frac{1}{L} \int V_m \sin \omega t dt$ $i = \frac{V_m}{L} \left(\frac{-\cos \omega t}{\omega} \right) = \frac{V_m}{\omega L} \sin(\omega t - 90^\circ)$ $i = \frac{V_m}{X_L} \sin(\omega t - 90^\circ) = I_m \sin(\omega t - 90^\circ)$ $v = V_m \sin \omega t$ | <p>According to electrostatics, the charge in capacitor is:</p> $q = C \times v$ <p>We know that current is</p> $i = \frac{dq}{dt}$ $i = C \frac{dv}{dt}$ $i = C \frac{dV_m \sin \omega t}{dt} = C V_m \frac{d}{dt} \sin \omega t$ $i = \omega C V_m \cos \omega t = \frac{V_m}{\frac{1}{\omega C}} \cos \omega t$ $i = \frac{V_m}{X_C} \sin(\omega t + 90^\circ)$ $i = I_m \sin(\omega t + 90^\circ)$ $v = V_m \sin \omega t$ |
| Here ωL is inductive reactance. It is represented by $X_L = \omega L = 2\pi fL$ | | Here $\frac{1}{\omega C}$ is capacitive reactance. It is represented by $X_C = \frac{1}{\omega C} = \frac{1}{2\pi fC}$ |

Purely resistive

Instantaneous Power

$p = v \times i$

$$p = v_{\max} \sin \omega t \times i_{\max} \sin \omega t$$

$$= v_{\max} i_{\max} \sin^2 \omega t$$

$$= v_{\max} i_{\max} \left(\frac{1 - \cos 2\omega t}{2} \right)$$

$$p = \frac{v_{\max}}{\sqrt{2}} \frac{i_{\max}}{\sqrt{2}} - \frac{v_{\max}}{\sqrt{2}} \frac{i_{\max}}{\sqrt{2}} \cos 2\omega t$$

$$p = v_{\text{rms}} i_{\text{rms}} - v_{\text{rms}} i_{\text{rms}} \cos 2\omega t$$

Average Power

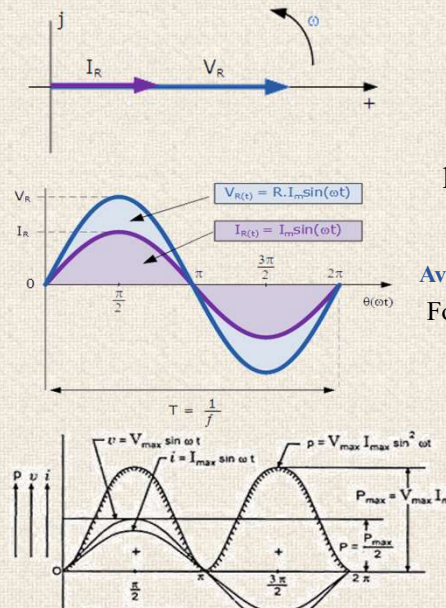
For a complete cycle i.e. 0 to 2π Part two is zero

$$P_{\text{av}} = v_{\text{rms}} i_{\text{rms}}$$

Power factor = $\cos \phi = 1$

$$S = V \times I$$

$$P = V \times I \times \cos \phi = V \times I$$

$$Q = V \times I \times \sin \phi = 0$$


Purely Inductive

- Voltage and current not in-phase quantity
- Current lags 90° by voltage
- Voltage leads 90° by current

I_L lags V_L by 90°

Instantaneous Power $p = v \times i$

$$p = v_{max} \sin \omega t \times i_{max} \sin(\omega t - 90)$$

$$= -v_{max} \sin \omega t i_{max} \cos \omega t$$

$$= -\frac{v_{max} i_{max}}{2} 2 \sin \omega t \cos \omega t$$

$$p = -\frac{v_{max}}{\sqrt{2}} \frac{i_{max}}{\sqrt{2}} \sin 2\omega t$$

$$p = -v_{rms} i_{rms} \sin 2\omega t$$

Power for a complete cycle i.e. 0 to 2π

$$P_{av} = -\frac{1}{2\pi} \int_0^{2\pi} v_{rms} i_{rms} \sin 2\omega t d\omega t = -\frac{1}{2\pi} v_{rms} i_{rms} \int_0^{2\pi} \sin 2\omega t d\omega t = 0$$

Hence, the average power consumed in a purely inductive circuit is zero.

Phase angle $\phi = 90^\circ$ lagging

Power factor = $\cos \phi = 0$

$S = V \times I$

$P = V \times I \times \cos \phi = 0$

$Q = V \times I \times \sin \phi = V \times I$

Power Wave

Purely Capacitive

- Voltage and current not in-phase quantity
- Current lead 90° by voltage
- Voltage lag 90° by current

I_c leads V_c by 90°

Instantaneous Power $p = v \times i$

$$p = v_{max} \sin \omega t \times i_{max} \sin(\omega t + 90)$$

$$= v_{max} \sin \omega t i_{max} \cos \omega t$$

$$= \frac{v_{max} i_{max}}{2} 2 \sin \omega t \cos \omega t$$

$$p = \frac{v_{max}}{\sqrt{2}} \frac{i_{max}}{\sqrt{2}} \sin 2\omega t$$

$$p = v_{rms} i_{rms} \sin 2\omega t$$

Phase angle $\phi = 90^\circ$ leading

Power factor = $\cos \phi = 0$

$p = v_{rms} i_{rms} \sin 2\omega t$

$P_{av} = 0$

$S = V \times I$

$P_{av} = v_{rms} i_{rms}$

$P = V \times I \times \cos \phi = 0$

$Q = V \times I \times \sin \phi = V \times I$

Power Wave

Power factor:

It is the ratio of Power actually consumed in the circuit to the total power supplied.

It is the ratio of true power to apparent power.

It cannot be greater than 1.

Since the actual power is consumed

In the resistance and the total power

is supplied to the impedance it is also defined as the ratio of resistance to impedance.

$$\text{Power factor} = \frac{\text{True Power}}{\text{Apparent Power}} = \frac{VI \cos \phi}{VI} = \cos \phi$$

Apparent power

It is the total power supplied by the source to the circuit.

The product of root mean square (RMS) value of voltage and current is known as Apparent Power.

This power is measured in kVA or MVA.

$$S = V \times I$$

Active power

✓ The power which is actually consumed or utilized in an AC Circuit is called True power, Active Power, Real power or Actual power

✓ The product of apparent power and power factor is called active power

✓ It is measured in kilo watt (kW) or MW.

$$P = V \times I \times \cos \phi$$

Reactive power

The power which flows back and forth that mean it moves in both the direction in the circuit or react upon itself, is called Reactive Power

$$Q = V \times I \times \sin \phi$$

The product of apparent power and "sin" angle is called reactive power

The reactive power is measured in kilo volt ampere reactive (KVAR) or MVAR.

1-φ AC on Series R-L Circuit

From the series RL circuit diagram

✓ Apply KVL then

$$V = V_R + V_L \dots (1)$$

Since $V_R = I_R \times R = I \times R$

$$V_L = I_L \times X_L = I \times jX_L$$

Put the value of V_R & V_L in eqⁿ (1), then

$$V = I (R + jX_L)$$

$$\frac{V}{I} = (R + jX_L) \dots (2)$$

From eqⁿ (2) define the impedance and phase angle of series RL circuit

$Z = R + jX_L$ (in rectangular form)

$Z = |Z| \angle \phi$ (in polar form) where

$$|Z| = \sqrt{R^2 + X_L^2} \text{ and } \phi = \tan^{-1} \frac{X_L}{R}$$

Instantaneous Power $p = v \times i$

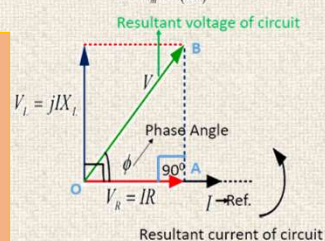
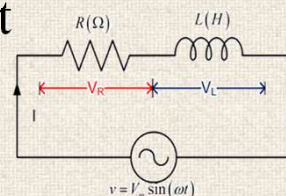
$$p = v_{\max} \sin \omega t \times i_{\max} \sin(\omega t - \phi)$$

$$= v_m i_m [\sin \omega t \sin(\omega t - \phi)] =$$

$$= \frac{v_m i_m}{2} [\cos \phi - \cos(2\omega t - \phi)]$$

$$p = \frac{v_m i_m}{2} \cos \phi - \frac{v_m i_m}{2} \cos(2\omega t - \phi)$$

Vector sum of resistance and inductive reactance is called **Impedance** of series RL circuit



Impedance is the opposition to alternating current presented by the combined effect of resistance and reactance in a circuit.

$$Z = \sqrt{R^2 + X_L^2}$$

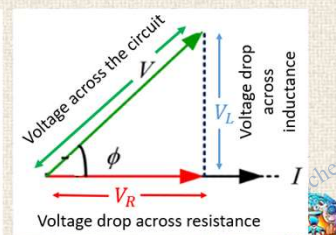
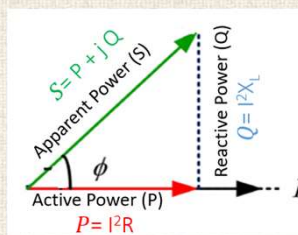
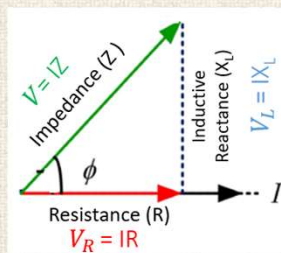
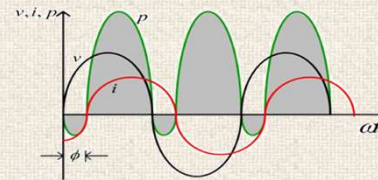
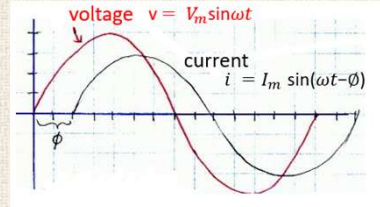
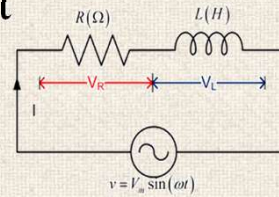
$$\tan \phi = \frac{\text{perpendicular}}{\text{base}} = \frac{V_L}{V_R} = \frac{I X_L}{I R} = \frac{X_L}{R}$$

$$\phi = \tan^{-1} \frac{X_L}{R}$$

1- ϕ AC on Series R-L Circuit

$$\text{PF} = \cos\phi = \frac{\text{Base}}{\text{Hypotenuse}} = \frac{V_R}{V} = \frac{IR}{IZ} = \frac{R}{Z}$$

$$\sin\phi = \frac{\text{Perpendicular}}{\text{Hypotenuse}} = \frac{V_L}{V} = \frac{IX_L}{IZ} = \frac{X_L}{Z}$$



1- ϕ AC on Series R-L Circuit

Average Power

$$P_{av} = \frac{1}{2\pi} \int_0^{2\pi} \left(\frac{v_m i_m}{2} \cos\phi - \frac{v_m i_m}{2} \cos(2\omega t - \phi) \right) d\omega t$$

Since the integration of cosine over a complete cycle is zero. Second term will be zero.

$$\therefore P_{av} = \frac{1}{2\pi} \int_0^{2\pi} \frac{v_m i_m}{2} \cos\phi d\omega t = \frac{v_m i_m}{2} \cos\phi$$

$$P_{av} = V_{rms} I_{rms} \cos\phi$$

$$\text{PF} = \cos\phi = \frac{\text{Base}}{\text{Hypotenuse}} = \frac{V_R}{V} = \frac{IR}{IZ} = \frac{R}{Z} = \frac{R}{\sqrt{R^2 + X_L^2}}$$

$$\sin\phi = \frac{\text{Perpendicular}}{\text{Hypotenuse}} = \frac{V_L}{V} = \frac{IX_L}{IZ} = \frac{X_L}{Z} = \frac{X_L}{\sqrt{R^2 + X_L^2}}$$

$$S = VI = I^2 Z = \frac{V^2}{Z} = P + jQ \quad \text{Apparent Power}$$

$$P = V \times I \times \cos\phi = I^2 R = \frac{V^2}{R} \quad \text{Active Power}$$

$$Q = V \times I \times \sin\phi = I^2 X_L = \frac{V^2}{X_L} \quad \text{Reactive Power}$$

- Circuit
- $v = V_m \sin\omega t$
- $i = \frac{v}{Z}$
- $i = I_m \sin\omega t$
- Phasor Diagram
- Waveform Diagram
- Phase Angle
- Instantaneous Power
- Average Power
- Power Factor
- Power Waveform
- Apparent Power
- Active Power
- Reactive Power

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1- ϕ AC on Series R-C Circuit

From the series RC circuit diagram

✓ Apply KVL then

$$V = V_R + V_C \dots (1)$$

Since $V_R = I_R \times R = I \times R$

$$V_C = I_L \times -jX_C = -I \times jX_C$$

Put the value of V_R & V_C in eqn (1), then

$$V = I (R - jX_C)$$

$$\frac{V}{I} = (R - jX_C) \dots (2)$$

From eqn (2) define the impedance

and phase angle of series RL circuit

$$Z = R - jX_C \quad (\text{in rectangular form})$$

$$Z = |Z| \angle \phi \quad (\text{in polar form}) \text{ where}$$

$$|Z| = \sqrt{R^2 + X_C^2} \text{ and } \phi = \tan^{-1} \frac{-X_C}{R}$$

Instantaneous Power $p = v \times i$

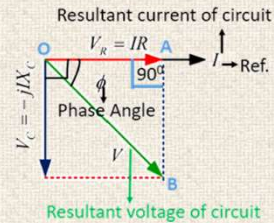
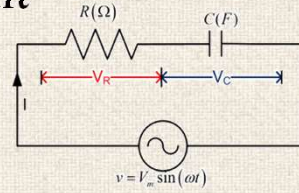
$$p = v_{max} \sin \omega t \times i_{max} \sin(\omega t + \phi)$$

$$= v_m i_m [\sin \omega t \sin(\omega t + \phi)]$$

$$= \frac{v_m i_m}{2} [\cos \phi - \cos(2\omega t + \phi)]$$

$$p = \frac{v_m i_m}{2} \cos \phi - \frac{v_m i_m}{2} \cos(2\omega t + \phi)$$

Vector sum of resistance and inductive reactance is called **Impedance** of series RL circuit



$$Z = \sqrt{R^2 + X_C^2}$$

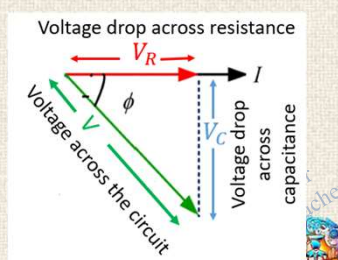
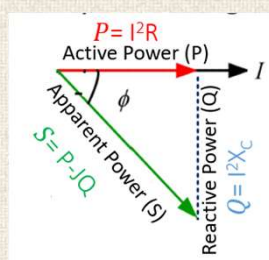
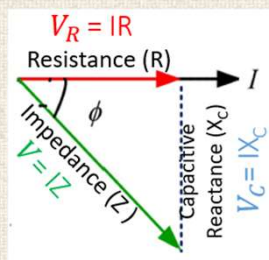
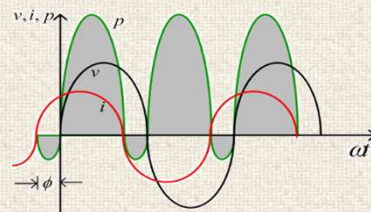
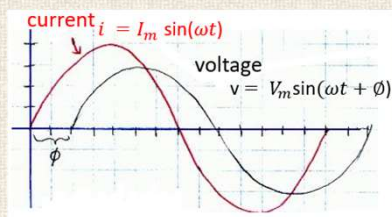
$$\tan \phi = \frac{\text{perpendicular}}{\text{base}} = \frac{V_C}{V_R} = \frac{-IX_C}{IR} = -\frac{X_C}{R}$$

$$\phi = \tan^{-1} \frac{-X_C}{R}$$

1- ϕ AC on Series R-C Circuit

$$\text{Power Factor} = \cos \phi = \frac{\text{Base}}{\text{Hypotenuse}} = \frac{V_R}{V} = \frac{IR}{IZ} = \frac{R}{Z}$$

$$\sin \phi = \frac{\text{perpendicular}}{\text{Hypotenuse}} = \frac{V_C}{V} = \frac{IX_C}{IZ} = \frac{X_C}{Z}$$



1- ϕ AC on Series R-C Circuit

Average Power

$$P_{av} = \frac{1}{2\pi} \int_0^{2\pi} \left(\frac{v_m i_m}{2} \cos\phi - \frac{v_m i_m}{2} \cos(2\omega t + \phi) \right) d\omega t$$

Since the integration of cosine over a complete cycle is zero. Second term will be zero.

$$\therefore P_{av} = \frac{1}{2\pi} \int_0^{2\pi} \frac{v_m i_m}{2} \cos\phi d\omega t = \frac{v_m i_m}{2} \cos\phi$$

$$P_{av} = V_{rms} I_{rms} \cos\phi$$

$$PF = \cos\phi = \frac{\text{Base}}{\text{Hypotenuse}} = \frac{V_R}{V} = \frac{IR}{IZ} = \frac{R}{Z} = \frac{R}{\sqrt{R^2 + X_C^2}}$$

$$\sin\phi = \frac{\text{Perpendicular}}{\text{Hypotenuse}} = \frac{V_L}{V} = \frac{IX_L}{IZ} = \frac{X_C}{Z} = \frac{X_C}{\sqrt{R^2 + X_C^2}}$$

Apparent Power

$$S = VI = I^2 Z = \frac{V^2}{Z} = P + jQ$$

Active Power

$$P = V \times I \times \cos\phi = I^2 R = \frac{V^2}{R}$$

Reactive Power

$$Q = V \times I \times \sin\phi = I^2 X_L = \frac{V^2}{X_C}$$

- Circuit
- Impedance
- Phase angle
- $i = I_m \sin\omega t$
- Phasor Diagram
- Waveform Diagram
- Phase Angle
- Instantaneous Power
- Average Power
- Power Factor
- Power Waveform
- Apparent Power
- Active Power
- Reactive Power

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1- ϕ AC on Series R-L-C Circuit

For the better understanding of series R-L-C circuit Here consider three different case

- Case I $X_L > X_C$
- Case II $X_L < X_C$
- Case III $X_L = X_C$

Case I $X_L > X_C$

Series RLC phasor diagram under case I i.e. $X_L > X_C$

From the series RLC circuit diagram

✓ Apply KVL then

$$V = V_R + V_L + V_C \dots (1)$$

Since $V_R = I \times R$; $V_L = I \times jX_L$; $V_C = I \times (-jX_C)$

Put the value of V_R & V_L in eqⁿ (1), then

$$V = I (R + j(X_L - X_C))$$

$$\frac{V}{I} = R + j(X_L - X_C) \dots (2)$$

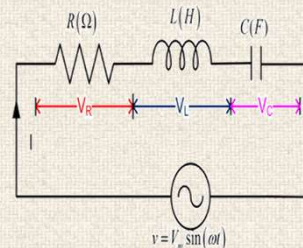
From eqⁿ (2) define the impedance

and phase angle of series RL circuit

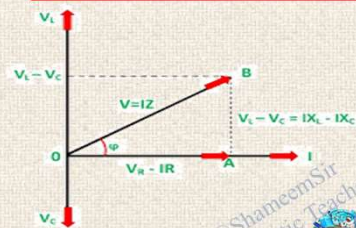
$Z = R + j(X_L - X_C)$ (in rectangular form)

$Z = |Z| \angle \phi$ (in polar form) where

$$|Z| = \sqrt{R^2 + (X_L - X_C)^2} \text{ and } \phi = \tan^{-1} \frac{(X_L - X_C)}{R}$$



- ✓ when $X_L > X_C$ the circuit is predominantly RL circuit
- ✓ $X_L \longrightarrow X_L - X_C$
- ✓ $V_L \longrightarrow V_L - V_C$



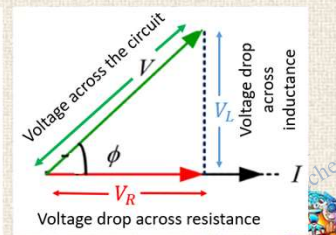
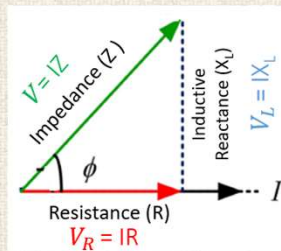
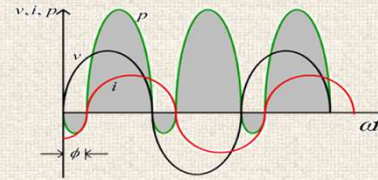
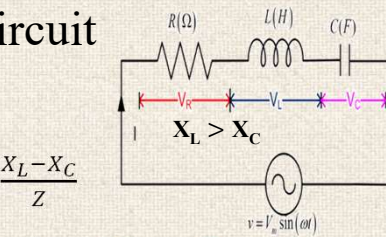
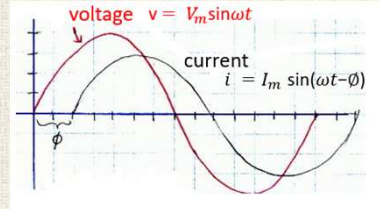
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1- ϕ AC on Series R-L-C Circuit

$$\text{PF} = \cos\phi = \frac{\text{Base}}{\text{Hypotenuse}} = \frac{V_R}{V} = \frac{IR}{IZ} = \frac{R}{Z}$$

$$\sin\phi = \frac{\text{Perpendicular}}{\text{Hypotenuse}} = \frac{V_L}{V} = \frac{I(X_L - X_C)}{IZ} = \frac{X_L - X_C}{Z}$$



1- ϕ AC on Series R-L-C Circuit

$$\text{PF} = \cos\phi = \frac{\text{Base}}{\text{Hypotenuse}} = \frac{V_R}{V} = \frac{IR}{IZ} = \frac{R}{Z} = \frac{R}{\sqrt{R^2 + (X_L - X_C)^2}}$$

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$$S = VI = I^2 Z = \frac{V^2}{Z} = P + jQ \quad \text{Apparent Power}$$

$$P = V \times I \times \cos\phi = I^2 R = \frac{V^2}{R} \quad \text{Active Power}$$

$$Q = V \times I \times \sin\phi = I^2 X_L = \frac{V^2}{X_L - X_C} \quad \text{Reactive Power}$$

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1- ϕ AC on Series R-L-C Circuit

Case II $X_C > X_L$

Series RLC phasor diagram under case I i.e. $X_C > X_L$

From the series RLC circuit diagram

✓ Apply KVL then

$$V = V_R + V_L + V_C \dots (1)$$

Since $V_R = I \times R$; $V_L = I \times jX_L$; $V_C = I \times (-jX_C)$

Put the value of V_R & V_L in eqⁿ (1), then

$$V = I (R + j(X_L - X_C)) \text{ (since } X_C > X_L)$$

$$\frac{V}{I} = R - j(X_C - X_L) \dots (2)$$

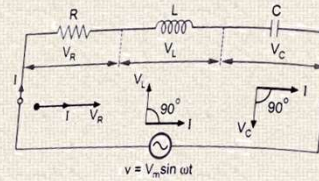
From eqⁿ (2) define the impedance

and phase angle of series RL circuit

$Z = R - j(X_C - X_L)$ (in rectangular form)

$Z = |Z| \angle \phi$ (in polar form) where

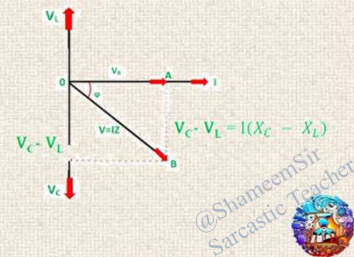
$$|Z| = \sqrt{R^2 + (X_C - X_L)^2} \text{ and } \phi = \tan^{-1} \frac{-(X_C - X_L)}{R}$$



✓ when $X_C > X_L$ the circuit is predominantly RC circuit

✓ $X_C \longrightarrow X_C - X_L$

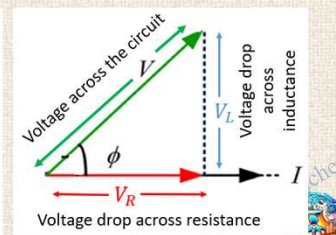
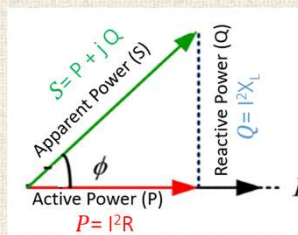
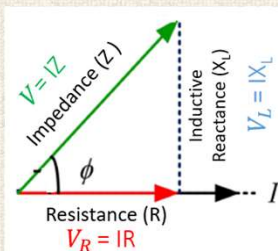
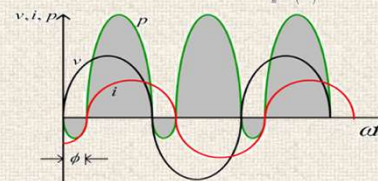
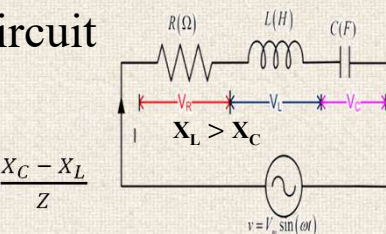
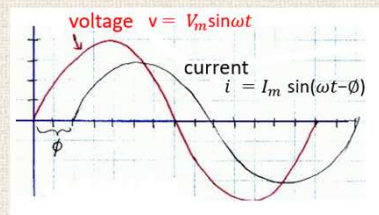
✓ $V_C \longrightarrow V_C - V_L$



1- ϕ AC on Series R-L-C Circuit

$$\text{PF} = \cos \phi = \frac{\text{Base}}{\text{Hypotenuse}} = \frac{V_R}{V} = \frac{IR}{IZ} = \frac{R}{Z}$$

$$\sin \phi = \frac{\text{Perpendicular}}{\text{Hypotenuse}} = \frac{V_L}{V} = \frac{I(X_L - X_C)}{IZ} = \frac{X_C - X_L}{Z}$$



1- ϕ AC on Series R-L-C Circuit

$$\text{PF} = \cos\phi = \frac{\text{Base}}{\text{Hypotenuse}} = \frac{V_R}{V} = \frac{IR}{IZ} = \frac{R}{Z} = \frac{R}{\sqrt{R^2 + X_L^2}}$$

$$\sin\phi = \frac{\text{Perpendicular}}{\text{Hypotenuse}} = \frac{V_L}{V} = \frac{IX_L}{IZ} = \frac{X_L}{Z} = \frac{X_L}{\sqrt{R^2 + (X_C - X_L)^2}}$$

$$S = VI = I^2 Z = \frac{V^2}{Z} = P + jQ \quad \text{Apparent Power}$$

$$P = V \times I \times \cos\phi = I^2 R = \frac{V^2}{R} \quad \text{Active Power}$$

$$Q = V \times I \times \sin\phi = I^2 X_L = \frac{V^2}{X_C - X_L} \quad \text{Reactive Power}$$

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Case III $X_L = X_C$

Note –

- ✓ when $X_L = X_C$ the circuit is predominantly R circuit
- ✓ This case also called resonance state of series RLC circuit

From the series RLC circuit diagram

- ✓ Apply KVL then

$$V = V_R + (V_L + V_C) \dots (1)$$

$$\text{Since } V_R = I_R \times R = I \times R$$

$$V_L = I_L \times jX_L = I \times jX_L$$

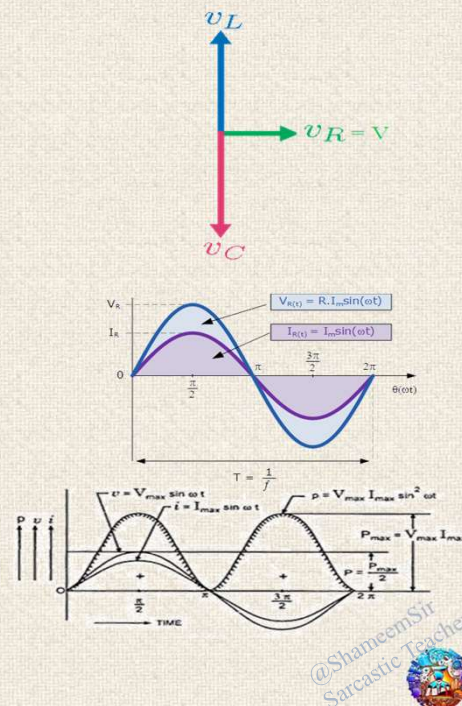
$$V_C = I_C \times -jX_C = -I \times jX_C$$

Net reactance voltage resultant is zero because $X_L = X_C$

$$V = V_R + j0 = IR$$

$$\frac{V}{I} = R \dots (2)$$

From eqⁿ (2) $Z = R$ & $\phi = \tan^{-1}\left(\frac{0}{R}\right) = 0$



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| Summary of RLC Circuits : | | | | | | |
|---------------------------|------------|------------------------------------|-------------------------------------|--|------------------|------------------------|
| Sr. No. | Circuit | Impedance (Z) | | ϕ | p.f. $\cos \phi$ | Remark |
| | | Polar | Rectangular | | | |
| 1. | Pure R | $R \angle 0^\circ \Omega$ | $R + j0 \Omega$ | 0° | 1 | Unity p.f. |
| 2. | Pure L | $X_L \angle 90^\circ \Omega$ | $0 + j X_L \Omega$ | 90° | 0 | Zero lagging |
| 3. | Pure C | $X_C \angle -90^\circ \Omega$ | $0 - j X_C \Omega$ | -90° | 0 | Zero leading |
| 4. | Series RL | $ Z \angle +\phi^\circ \Omega$ | $R + j X_L \Omega$ | $0^\circ \angle \phi \angle 90^\circ$ | $\cos \phi$ | Lagging |
| 5. | Series RC | $ Z \angle -\phi^\circ \Omega$ | $R - j X_C \Omega$ | $-90^\circ \angle \phi \angle 0^\circ$ | $\cos \phi$ | Leading |
| 6. | Series RLC | $ Z \angle \pm \phi^\circ \Omega$ | $R + j X \Omega$ $X = X_L - X_C$ | ϕ | $\cos \phi$ | $X_L > X_C$ Lagging |
| | | | | | | $X_L < X_C$ Leading |
| | | | | | | $X_L = X_C$ Unity |

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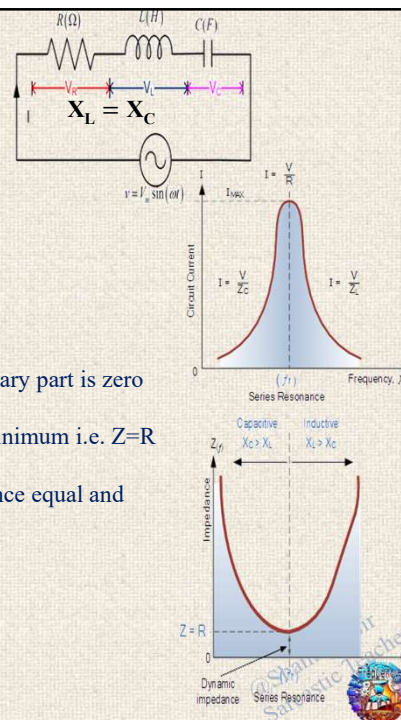
Resonance

- ✓ In a series RLC circuit when inductive reactance of the inductor becomes equal in value to the capacitive reactance of the capacitor is called resonance series RLC circuit
- ✓ In other words, $X_L = X_C$. The point at which this occurs is called the **Resonant Frequency** point, (f_r) of the circuit,

According to resonance circuit

- | | |
|----------------------------------|---|
| $X_L = X_C$ | • Reactive part is zero i.e. imaginary part is zero |
| $\omega L = \frac{1}{\omega C}$ | • Acceptor Circuit |
| $\omega^2 = \frac{1}{LC}$ | • impedance value is very less/minimum i.e. $Z=R$ |
| $\omega = \frac{1}{\sqrt{LC}}$ | • current value is very high |
| $2\pi f_r = \frac{1}{\sqrt{LC}}$ | • capacitive and inductive reactance equal and opposite |
| | • phase angle is zero |
| | • Power factor is unity |

$$\text{Resonant Frequency } f_r = \frac{1}{2\pi\sqrt{LC}}$$



Admittance

Useful in parallel circuits

- ✓ Conductance is the reciprocal of resistance: $G = 1/R$
- ✓ Susceptance is the reciprocal of reactance: $B = 1/X$
- ✓ Vector sum of conductance and Susceptance is called admittance
- ✓ Admittance is the reciprocal of impedance: $Y = 1/Z$

Admittance in RL circuit

$$Y = G - jB_L \quad \text{or} \quad Y = \sqrt{G^2 + B_L^2}$$

Admittance in RC circuit

$$Y = G + jB_C \quad \text{or} \quad Y = \sqrt{G^2 + B_C^2}$$

Admittance in RLC circuit

$$\text{or} \quad Y = \sqrt{G^2 + (B_C - B_L)^2}$$

$$Y = \frac{I}{V}$$

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Admittance for series circuit

Ans. : Admittance is defined as the reciprocal of the impedance. It is denoted by Y and is measured in unit siemens or mho.

- Consider an impedance given as, $Z = R + jX$
- Positive sign for inductive and negative for capacitive circuit.

$$\text{Admittance } Y = \frac{1}{Z} = \frac{1}{R + jX}$$

- Rationalising the above expression,

$$Y = \frac{R - jX}{(R + jX)(R - jX)} = \frac{R - jX}{R^2 + X^2} = \left(\frac{R}{R^2 + X^2} \right) - j \left(\frac{X}{R^2 + X^2} \right)$$

$$= \frac{R}{Z^2} - j \frac{X}{Z^2}$$

∴

$$Y = G - jB \quad \text{where } G = \text{Conductance} = \frac{R}{Z^2},$$

$$B = \text{Susceptance} = \frac{X}{Z^2}$$

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Analysis of 1- ϕ AC parallel R-L Circuit

From phasor diagram

$$v = V_m \sin \omega t$$

$$i = I_m \sin(\omega t - \phi)$$

From the parallel RL circuit diagram

✓ Apply KCL then $I = I_R + I_L \dots (1)$

$$\text{Since } I_R = V_R / R = V_R \times G$$

$$I_L = V_L / jX_L = -V_L \times jB_L$$

Put the value of I_R & I_L in eqⁿ (1), then

$$I = (V_R / R + V_L / jX_L) = (V_R G - jV_L B_L)$$

$$\frac{I}{V} = (G - jB_L) \dots (2) \quad \text{Since } V = V_R = V_L$$

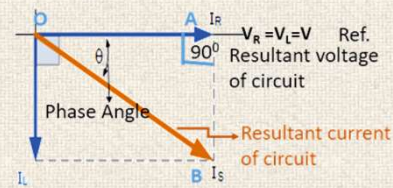
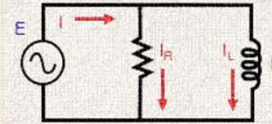
From eqⁿ (2) define the Admittance and phase angle of parallel RL circuit

$$Y = G - jB_L$$

And

$$\phi = \tan^{-1} \left(-\frac{B_L}{G} \right)$$

$$Y = 1/Z$$



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