

# Mathematical Logic (V)

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## 1 The Semantics of First-order Logic

### 1.1 Substitution

**Definition 1.1.** Let  $t$  be an S-term,  $x_0, \dots, x_r$  variables, and  $t_0, \dots, t_r$  S-terms. Then the term

$$t \frac{t_0, \dots, t_r}{x_0, \dots, x_r}$$

is defined inductively as follows.

(a) Let  $t = x$  be a variable. Then

$$t \frac{t_0, \dots, t_r}{x_0, \dots, x_r} := \begin{cases} t_i & \text{if } x = x_i \text{ for some } 0 \leq i \leq r \\ x & \text{otherwise.} \end{cases}$$

(b) For a constant  $t = c$

$$c \frac{t_0, \dots, t_r}{x_0, \dots, x_r} := c.$$

(c) For a function term

$$ft'_1 \dots t'_n \frac{t_0, \dots, t_r}{x_0, \dots, x_r} := ft'_1 \frac{t_0, \dots, t_r}{x_0, \dots, x_r} \dots t'_n \frac{t_0, \dots, t_r}{x_0, \dots, x_r}. \quad \dashv$$

**Definition 1.2.** Let  $\varphi$  be an S-formula,  $x_0, \dots, x_r$  variables, and  $t_0, \dots, t_r$  S-terms. We define

$$\varphi \frac{t_0, \dots, t_r}{x_0, \dots, x_r}$$

inductively as follow.

(a) Assume  $\varphi = t'_1 \equiv t'_2$ . Then

$$\varphi \frac{t_0, \dots, t_r}{x_0, \dots, x_r} := t'_1 \frac{t_0, \dots, t_r}{x_0, \dots, x_r} \equiv t'_2 \frac{t_0, \dots, t_r}{x_0, \dots, x_r}.$$

(b) Let  $\varphi = Rt'_1 \dots t'_n$ . We set

$$\varphi \frac{t_0, \dots, t_r}{x_0, \dots, x_r} := Rt'_1 \frac{t_0, \dots, t_r}{x_0, \dots, x_r} \dots t'_n \frac{t_0, \dots, t_r}{x_0, \dots, x_r}.$$

(c) For  $\varphi = \neg\psi$

$$\varphi \frac{t_0, \dots, t_r}{x_0, \dots, x_r} := \neg\psi \frac{t_0, \dots, t_r}{x_0, \dots, x_r}.$$

(d) For  $\varphi = (\psi_1 \vee \psi_2)$

$$\varphi \frac{t_0, \dots, t_r}{x_0, \dots, x_r} := \left( \psi_1 \frac{t_0, \dots, t_r}{x_0, \dots, x_r} \vee \psi_2 \frac{t_0, \dots, t_r}{x_0, \dots, x_r} \right).$$

(e) Assume  $\varphi = \exists x \psi$ . Let  $x_{i_1}, \dots, x_{i_s}$  ( $i_1 < \dots < i_s$ ) be the variables  $x_i$  in  $x_0, \dots, x_r$  with  $x_i \in \text{free}(\exists x \varphi)$  and  $x_i \neq t_i$ . In particular,  $x \neq x_{i_1}, \dots, x \neq x_{i_s}$ . Then

$$\varphi \frac{t_0, \dots, t_r}{x_0, \dots, x_r} := \exists u \left[ \psi \frac{t_{i_1}, \dots, t_{i_s}, u}{x_{i_1}, \dots, x_{i_s}, x} \right],$$

where  $u = x$  if  $x$  does not occur in  $t_{i_1}, \dots, t_{i_s}$ ; otherwise  $u$  is the first variable in  $\{v_0, v_1, v_2, \dots\}$  which does not occur in  $\psi, t_{i_1}, \dots, t_{i_s}$ .  $\dashv$

**Definition 1.3.** Let  $\beta$  be an assignment in  $\mathfrak{A}$  and  $a_0, \dots, a_r \in A$ . Then

$$\beta \frac{a_0, \dots, a_r}{x_0, \dots, x_r}$$

is an assignment in  $\mathfrak{A}$  defined by

$$\beta \frac{a_0, \dots, a_r}{x_0, \dots, x_r}(y) := \begin{cases} a_i & \text{if } y = x_i \text{ for } 0 \leq i \leq r \\ \beta(y) & \text{otherwise.} \end{cases}$$

For an  $S$ -interpretation  $\mathcal{I} = (\mathfrak{A}, \beta)$  we let

$$\mathcal{I} \frac{a_0, \dots, a_r}{x_0, \dots, x_r} := \left( \mathfrak{A}, \beta \frac{a_0, \dots, a_r}{x_0, \dots, x_r} \right). \quad \dashv$$

**Lemma 1.4** (The Substitution Lemma). (a) For every  $S$ -term  $t$

$$\mathcal{I} \left( t \frac{t_0, \dots, t_r}{x_0, \dots, x_r} \right) = \mathcal{I} \frac{\mathcal{I}(t_0), \dots, \mathcal{I}(t_r)}{x_0, \dots, x_r}(t).$$

(b) For every  $S$ -formula  $\varphi$

$$\mathcal{I} \models \varphi \frac{t_0, \dots, t_r}{x_0, \dots, x_r} \iff \mathcal{I} \frac{\mathcal{I}(t_0), \dots, \mathcal{I}(t_r)}{x_0, \dots, x_r} \models \varphi. \quad \dashv$$

*Proof:* (a) Assume  $t = x$ . If  $x \neq x_i$  for all  $0 \leq i \leq r$ , then

$$t \frac{t_0, \dots, t_r}{x_0, \dots, x_r} = x.$$

Therefore,

$$\mathcal{I} \left( t \frac{t_0, \dots, t_r}{x_0, \dots, x_r} \right) = \mathcal{I}(x) = \mathcal{I} \frac{\mathcal{I}(t_0), \dots, \mathcal{I}(t_r)}{x_0, \dots, x_r}(x) = \mathcal{I} \frac{\mathcal{I}(t_0), \dots, \mathcal{I}(t_r)}{x_0, \dots, x_r}(t).$$

Otherwise,  $x = x_i$  for some  $0 \leq i \leq r$ . Then  $t \frac{t_0, \dots, t_r}{x_0, \dots, x_r} = t_i$ . It follows that

$$\mathcal{I} \left( t \frac{t_0, \dots, t_r}{x_0, \dots, x_r} \right) = \mathcal{I}(t_i) = \mathcal{I} \frac{\mathcal{I}(t_0), \dots, \mathcal{I}(t_r)}{x_0, \dots, x_r}(x_i) = \mathcal{I} \frac{\mathcal{I}(t_0), \dots, \mathcal{I}(t_r)}{x_0, \dots, x_r}(t).$$

The other cases of  $t$  can be shown similarly.

Sequent 就是这个证明的每一步。一个 sequent 说的就是“前者能够推导出后者”。

E.g.  $\Gamma\varphi$  就是一个 sequent,  $\Gamma$  是 antecedent,  $\varphi$  是 succedent。

(b) Assume that  $\varphi = Rt'_1 \dots t'_n$ . Then

$$\begin{aligned}
\mathcal{J} \models \varphi \frac{t_0, \dots, t_r}{x_0, \dots, x_r} &\iff \left( \mathcal{J} \left( t'_1 \frac{t_0, \dots, t_r}{x_0, \dots, x_r} \right), \dots, \mathcal{J} \left( t'_n \frac{t_0, \dots, t_r}{x_0, \dots, x_r} \right) \right) \in R^{\mathfrak{A}} \\
&\iff \left( \mathcal{J} \frac{\mathcal{J}(t_0), \dots, \mathcal{J}(t_r)}{x_0, \dots, x_r} (t'_1), \dots, \mathcal{J} \frac{\mathcal{J}(t_0), \dots, \mathcal{J}(t_r)}{x_0, \dots, x_r} (t'_n) \right) \in R^{\mathfrak{A}} \quad (\text{by (a)}) \\
&\iff \mathcal{J} \frac{\mathcal{J}(t_0), \dots, \mathcal{J}(t_r)}{x_0, \dots, x_r} \models Rt'_1 \dots t'_n \\
&\quad \text{i.e., } \mathcal{J} \frac{\mathcal{J}(t_0), \dots, \mathcal{J}(t_r)}{x_0, \dots, x_r} \models \varphi.
\end{aligned}$$

For another case, let  $\varphi = \exists x\psi$ . Again, let  $x_{i_1}, \dots, x_{i_s}$  be the variables  $x_i$  with  $x_i \in \text{free}(\exists x\psi)$  and  $x_i \neq t_i$ . Choose  $u$  according to Definition 1.2 (e). In particular,  $u$  does not occur in  $t_{i_1}, \dots, t_{i_s}$ . Then

$$\begin{aligned}
\mathcal{J} \models \varphi \frac{t_0, \dots, t_r}{x_0, \dots, x_r} &\iff \mathcal{J} \models \exists u \left[ \psi \frac{t_{i_1}, \dots, t_{i_s}, u}{x_{i_1}, \dots, x_{i_s}, x} \right] \\
&\iff \text{there exists an } a \in A \text{ such that } \mathcal{J} \frac{a}{u} \models \psi \frac{t_{i_1}, \dots, t_{i_s}, u}{x_{i_1}, \dots, x_{i_s}, x} \\
&\iff \text{there exists an } a \in A \text{ such that } \left[ \mathcal{J} \frac{a}{u} \right] \frac{\mathcal{J} \frac{a}{u} (t_{i_1}), \dots, \mathcal{J} \frac{a}{u} (t_{i_s}), \mathcal{J} \frac{a}{u} (u)}{x_{i_1}, \dots, x_{i_s}, x} \models \psi \\
&\quad (\text{by induction hypothesis}) \\
&\iff \text{there exists an } a \in A \text{ such that } \left[ \mathcal{J} \frac{a}{u} \right] \frac{\mathcal{J}(t_{i_1}), \dots, \mathcal{J}(t_{i_s}), a}{x_{i_1}, \dots, x_{i_s}, x} \models \psi \\
&\quad (\text{by the coincidence lemma and that } u \text{ does not occur in } t_{i_1}, \dots, t_{i_s}) \\
&\iff \text{there exists an } a \in A \text{ such that } \mathcal{J} \frac{\mathcal{J}(t_{i_1}), \dots, \mathcal{J}(t_{i_s}), a}{x_{i_1}, \dots, x_{i_s}, x} \models \psi \\
&\quad (\text{by (either } u = x \text{ or } u \text{ does not occur in } \psi) \text{ and the coincidence lemma}) \\
&\iff \text{there exists an } a \in A \text{ such that } \left[ \mathcal{J} \frac{\mathcal{J}(t_{i_1}), \dots, \mathcal{J}(t_{i_s})}{x_{i_1}, \dots, x_{i_s}} \right] \frac{a}{x} \models \psi \\
&\quad (\text{since } x \neq x_{i_1}, \dots, x \neq x_{i_s}) \\
&\iff \mathcal{J} \frac{\mathcal{J}(t_{i_1}), \dots, \mathcal{J}(t_{i_s})}{x_{i_1}, \dots, x_{i_s}} \models \exists x\psi \\
&\iff \mathcal{J} \frac{\mathcal{J}(t_0), \dots, \mathcal{J}(t_r)}{x_0, \dots, x_r} \models \exists x\psi \\
&\quad (\text{by } x_i \notin \text{free}(\exists x\psi) \text{ or } x_i = t_i \text{ for } i \neq i_1, \dots, i \neq i_s). \quad \square
\end{aligned}$$

## 2 Sequent Calculus

Antecedent - 前件 (条件或假设)

Succedent - 后件 (结论)

The goal of this section is to provide a formal definition of proofs, i.e., proofs are made into mathematical objects. To that end, we divide any proof into stages. In each stage, we establish a fact that under the **antecedent**  $\varphi_1, \dots, \varphi_n$ <sup>1</sup> the **succedent**  $\varphi$  holds. In a succinct form, this is written as a sequent

$$\varphi_1 \dots \varphi_n \varphi.$$

So our goal is to design a calculus  $\mathfrak{S}$  operating on sequents, i.e., **sequent calculus**.  $\mathfrak{S}$  contains a number of rules, which enable us to derive one sequent from another.

<sup>1</sup>In the sequel, we tacitly assume a fixed symbol set  $S$ .

A sequent rule has the following the form

$$\frac{\begin{array}{c} \Gamma_1 \quad \varphi_1 \\ \vdots \\ \Gamma_n \quad \varphi_n \end{array}}{\Gamma \quad \varphi} \quad (\text{side condition } \star)$$

**Intuition.** A new sequent  $\Gamma\varphi$  can be derived from the previously derived sequents  $\Gamma_1\varphi_1, \dots, \Gamma_n\varphi_n$ , 如果 these sequents satisfy the side condition  $(\star)$ .  
Sequent 就是这个证明的每一步。一个 sequent 说的就是“前者能够推导出后者”。

E.g.  $\Gamma\varphi$  就是一个 sequent,  $\Gamma$  是 antecequent

**Definition 2.1.** If in the calculus  $\mathcal{S}$  there is a derivation of the sequent  $\Gamma \varphi$ , then we write

$$\vdash \Gamma \varphi$$

and say that  $\Gamma \varphi$  is **derivable**. ⊢

**Definition 2.2.** A formula  $\varphi$  is **formally provable** or **derivable** from a set  $\Phi$  of formulas, written  $\Phi \vdash \varphi$ , if there are **finite many formulas**  $\varphi_1, \dots, \varphi_n$  in  $\Phi$  such that  
这个是在“证明系统”里, 然而  $\Phi \models \varphi$  是一个“语义世界”里的  
 $\vdash \varphi_1 \dots \varphi_n \varphi$ . ⊢

**Definition 2.3.** A sequent  $\Gamma \varphi$  is **correct** if

$$\{\psi \mid \psi \text{ is a member of } \Gamma\} \models \varphi.$$

in short,  $\Gamma \models \varphi$ .  $\Gamma$  typically 并不能表示集合, 但是如果这样写, 就表示 antecedent 公式的序列。 ⊢

**2.1 Basic Rules** 我们期待: 通过正确的规则, 正确的 sequent 能产出正确的 sequent

**Antecedent**

$$\frac{\Gamma \quad \varphi}{\Gamma' \quad \varphi} \quad \Gamma \subseteq \Gamma'$$

The correctness is straightforward. Assume that  $\Gamma \models \varphi$  and  $\mathcal{J} \models \Gamma'$ . Since  $\Gamma \subseteq \Gamma'$ , we conclude  $\mathcal{J} \models \Gamma$  and thus  $\mathcal{J} \models \varphi$ .

**Assumption**

$$\frac{}{\Gamma \quad \varphi} \quad \varphi \in \Gamma$$

**Case Analysis**

$$\frac{\begin{array}{c} \Gamma \quad \psi \quad \varphi \\ \Gamma \neg \psi \quad \varphi \end{array}}{\Gamma \quad \varphi}$$

**Contradiction**

$$\frac{\begin{array}{c} \Gamma \quad \neg \varphi \quad \psi \\ \Gamma \quad \neg \varphi \quad \neg \psi \end{array}}{\Gamma \quad \varphi}$$

**$\vee$ -introduction in antecedent**

$$\frac{\begin{array}{c} \Gamma \quad \varphi \quad \chi \\ \Gamma \quad \psi \quad \chi \end{array}}{\Gamma \quad (\varphi \vee \psi) \quad \chi}$$

**$\vee$ -introduction in succedent**

$$(a) \frac{\Gamma \quad \varphi}{\Gamma \quad (\varphi \vee \psi)} \quad (b) \frac{\Gamma \quad \varphi}{\Gamma \quad (\psi \vee \varphi)}$$

注意: 我们现在讨论的是语法, 跟语义没有关系, 所以  $\varphi \vee \psi$  和  $\psi \vee \varphi$  是不同的语法对象。

$\exists$ -introduction in succedent

$$\frac{\Gamma \quad \varphi \frac{t}{x}}{\Gamma \quad \exists x \varphi}$$

$\exists$ -introduction in antecedent

$$\frac{\Gamma \quad \varphi \frac{y}{x} \quad \psi}{\Gamma \quad \exists x \varphi \quad \psi} \text{ if } y \notin \text{free}(\Gamma \cup \{\exists x \varphi, \psi\})$$

想: 如果  $y \in \text{free}$ , 那么这种情况矛盾:

$$y \equiv z_1, (x \equiv z_2) \frac{y}{x} \implies z_1 \equiv z_2$$

并不能推导出  $y \equiv z_1, \exists x x \equiv z_2 \implies z_1 \equiv z_2$

**Equality**

直观上来说, 为什么不成立? 因为  $y$  除了承担  $\varphi \frac{y}{x}$  中替代  $x$  之外, 还在  $\Gamma$  中出现了 (类似于被 capture)

$$\overline{t \equiv t}$$

**Substitution**

$$\frac{\Gamma \quad \varphi \frac{t}{x}}{\Gamma \quad t \equiv t' \quad \varphi \frac{t'}{x}}$$

## 2.2 Some Derived Rules

**Example 2.4** (The law of excluded middle).

1.  $\varphi$  (assumption)
2.  $\varphi \quad (\varphi \vee \neg \varphi)$  (V-introduction in succedent by 1)
3.  $\neg \varphi$  (assumption)
4.  $\neg \varphi \quad (\varphi \vee \neg \varphi)$  (V-introduction in succedent by 3)
5.  $(\varphi \vee \neg \varphi)$  (case analysis by 2 and 4).

Therefore  $\vdash (\varphi \vee \neg \varphi)$ .

$\dashv$

**Example 2.5** (The modified contradiction).

$$\frac{\Gamma \quad \psi}{\Gamma \quad \neg \psi} \quad \frac{\Gamma \quad \neg \psi}{\Gamma \quad \varphi}$$

We argue as follows.

1.  $\Gamma \quad \psi$  (premise)
2.  $\Gamma \quad \neg \psi$  (premise)
3.  $\Gamma \quad \neg \varphi \quad \psi$  (antecedent by 1)
4.  $\Gamma \quad \neg \varphi \quad \neg \psi$  (antecedent by 2)
5.  $\Gamma \quad \varphi$  (contradiction by 3 and 4).

$\dashv$

**Example 2.6** (The chain deduction).

$$\frac{\Gamma \quad \varphi \quad \psi}{\Gamma \quad \psi}$$

We have the following deduction.

1.  $\Gamma \quad \varphi$  (premise)
2.  $\Gamma \quad \varphi \quad \psi$  (premise)
3.  $\Gamma \quad \neg\varphi \quad \varphi$  (antecedent by 1)
4.  $\Gamma \quad \neg\varphi \quad \neg\varphi$  (assumption)
5.  $\Gamma \quad \neg\varphi \quad \psi$  (modified contradiction by 3 and 4)
6.  $\Gamma \quad \psi$  (case analysis by 2 and 5).

⊢

Let  $\Phi$  be a set of sentences and  $\varphi$  an formula.

**Lemma 2.7.**  $\Phi \vdash \varphi$  if and only if there exists a **finite**  $\Phi_0 \subseteq \Phi$  such that  $\Phi_0 \vdash \varphi$ .

⊢

**Theorem 2.8** (Soundness). *If  $\Phi \vdash \varphi$ , then  $\Phi \models \varphi$ .*

⊢

语法上的东西通过正确的证明能够得到正确的东西。  
这个结论能通过归纳来证。