

Real and Nonstandard Analyses: An Overview

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Introduction

A **set** is a collection of elements. These elements can be anything: numbers, shapes, colors, and so on. For instance, consider the set A of the primary colors:

$$A = \{\text{red, blue, yellow}\}$$

A **function** is a mapping between the elements of two sets where each element from one set is assigned to exactly one element from the other. In the realm of single variable calculus, functions predominantly deal with sets of real numbers. For example, the function

$$f(x) = x^2$$

takes a set of inputs (x) and produces a corresponding set of their squares f(x) in the form of **ordered pairs**:

x	f(x)
-3	9
-2	4
-1	1
0	0
1	1
2	4
3	9

Plotting the points generated by $f(x)$ on the XY coordinate plane produces the following graph:

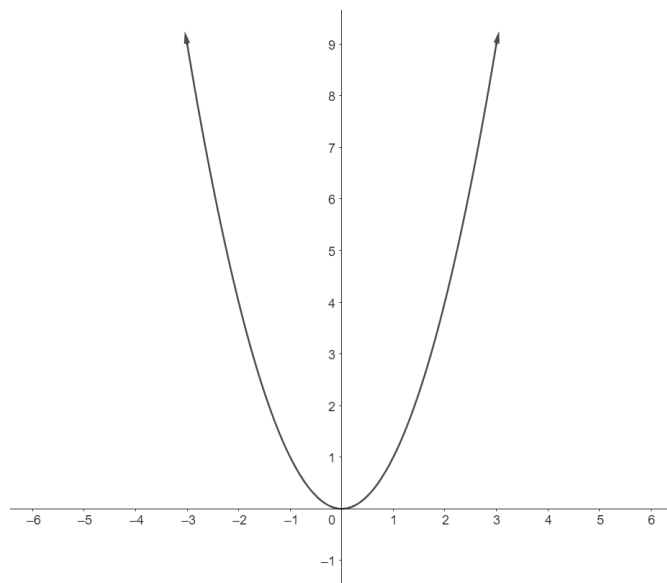


Figure 1: $f(x)$ produces a parabolic curve

Limits analyze how the outputs of such functions behave as their inputs (x) approach either a particular point or ∞ . For example, the parabolic function above approaches 4 as x approaches 2 and is denoted like so:

$$\lim_{x \rightarrow 2} x^2 = 4$$

As x approaches ∞ , x^2 also approaches ∞ :

$$\lim_{x \rightarrow \infty} x^2 = \infty$$

Limits are a result of **analysis**, an area of mathematics that deals with continuous change and continuous functions, broadly speaking. I intend to explore and compare two different branches of analysis that ultimately lead to the same results encountered in calculus. One relies on a rigorous employment of the limit, while the other abandons the idea of limits entirely in favor of a concept utilized in the upbringing of calculus over the past several centuries.

The Classical Approach

Introduction

Real analysis is the study of functions, sequences, and sets involving real numbers, and it is employed as the traditional means of formalizing the mechanisms presented in calculus courses. My overview of how real analysis builds toward certain calculus principles will follow section A.2 of Appendix A in

Simmons, G. (1996). *Calculus With Analytic Geometry* (2nd ed.), McGraw-Hill Education.

Being mindful of the fact that the absolute value of the difference between two values a and b ,

$$|a - b|,$$

represents the distance between them will greatly aid in understanding the notation that follows. The limit is defined in the following manner:

Let a function $f(x)$ be defined on some interval containing the number c such that there are x 's in the domain of $f(x)$ where

$$0 < |x - c| < \delta$$

for every positive number δ . The statement

$$\lim_{x \rightarrow c} f(x) = L$$

is then defined like so: For every positive number ε , there exists a positive number δ such that

$$|f(x) - L| < \varepsilon$$

for every x in the domain of $f(x)$ where

$$0 < |x - c| < \delta$$

This definition states that $f(x)$ approaches some value L as x approaches a certain value c if it can be shown that, for any set of outputs that lie within some distance ε from L , there exists a corresponding set of inputs (x 's) that lie within some distance δ from c which *guarantees* that $f(x)$ falls within said range (ε) of L . In this sense, we can bring the range of outputs as close as we want to L (letting epsilon go to 0) while being absolutely sure that $f(x)$ lies within it. This is known as the **epsilon-delta definition** of the limit.

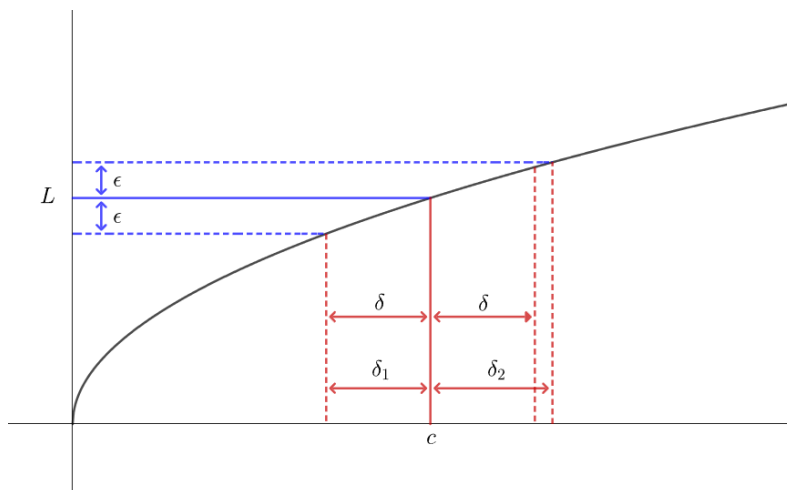


Figure 2: Epsilon-delta definition of the limit visualized

The interval $(L - \epsilon, L + \epsilon)$ describes the range of outputs that lie within a distance ϵ from L . One detail to note in the visualization above (Figure 2) is the presence of δ_1 and δ_2 . This is because the x corresponding to $L - \epsilon$ does not necessarily lie the same distance away from c as the x corresponding to $L + \epsilon$, since the rate at which $f(x)$ changes may vary as x sweeps from $c - \delta_1$ to $c + \delta_2$. To illustrate this, notice how the curvature in the graph is steeper on the left-hand side of c compared to that on the right-hand side. This means that sweeping through some range of outputs on the left requires a smaller increment of x as opposed to sweeping through that same range of outputs on the right, since the output of the function increases at a faster rate on the left. Therefore, $\delta_1 < \delta_2$ for this particular graph.

This complication can be readily resolved by letting δ equal the smaller of δ_1 and δ_2 :

$$\delta = \min(\delta_1, \delta_2)$$

$\min()$ is shorthand for taking the smallest value amongst the set of numbers present between the parentheses. For instance, if $x = \min(1, 2, 3)$, then $x = 1$. Allowing δ to be defined in this way works because of the following reasoning: Assume that $\delta_1 < \delta_2$ and that $|x - c| < \delta_2$ implies $|f(x) - L| < \epsilon$. If $|x - c| < \delta_1$, then $|x - c| < \delta_2$ since $\delta_1 < \delta_2$. It is therefore assured that $|f(x) - L| < \epsilon$.

Employing the Definition

The epsilon-delta definition of the limit can now be used to prove various properties of functions. As a basic example, consider the following theorem:

Theorem 1

If $f(x) = x$, then $\lim_{x \rightarrow a} f(x) = a$, or

$$\lim_{x \rightarrow a} x = a$$

To prove this, choose some $\epsilon > 0$, and let $\delta = \epsilon$. For any x satisfying the inequalities $0 < |x - a| < \delta$, we know that $|f(x) - a| < \epsilon$. This is because $f(x) = x$, and $\delta = \epsilon$. The theorem is therefore proven.

We can also prove some essential limit laws: their sums, differences, products, and quotients.

Theorem 2 - Limit Laws

If $\lim_{x \rightarrow a} f(x) = L$ and $\lim_{x \rightarrow a} g(x) = M$, then

$$(i) \quad \lim_{x \rightarrow a} [f(x) + g(x)] = L + M$$

$$(ii) \quad \lim_{x \rightarrow a} [f(x) - g(x)] = L - M$$

$$(iii) \quad \lim_{x \rightarrow a} f(x)g(x) = LM$$

$$(iv) \quad \lim_{x \rightarrow a} \frac{f(x)}{g(x)} = \frac{L}{M}$$

To prove (i), we let $\varepsilon > 0$ be given and allow $\delta_1, \delta_2 > 0$ where

$$0 < |x - a| < \delta_1 \Rightarrow |f(x) - L| < \frac{1}{2}\varepsilon$$

and

$$0 < |x - a| < \delta_2 \Rightarrow |f(x) - M| < \frac{1}{2}\varepsilon.$$

For those who are unfamiliar with the \Rightarrow symbol, it means that the statement following it is implied (or logically follows) from the statement preceding the symbol.

The $\frac{1}{2}$'s in front of the ε 's may cause some confusion, but recall that when $\lim_{x \rightarrow c} f(x) = L$, the epsilon-delta definition tells us that there exists a set of x 's lying within some distance δ from c such that the distance between $f(x)$ and L is always less than ε . Knowing this, it then follows that if there exists $\delta > 0$ such that $|f(x) - L| < \frac{1}{2}\varepsilon$ for some $\varepsilon > 0$, then $|f(x) - L| < \varepsilon$, because $\frac{1}{2}\varepsilon$ is smaller than ε .

Continuing the proof, we let $\delta = \min(\delta_1, \delta_2)$. If $0 < |x - a| < \delta$, then

$$|[f(x) + g(x)] - (L + M)| = |[f(x) - L] + [g(x) - M]| \quad (1)$$

$$\leq |f(x) - L| + |g(x) - M| \quad (2)$$

$$< \frac{1}{2}\varepsilon + \frac{1}{2}\varepsilon = \varepsilon, \quad (3)$$

proving (i). Analyzing the three-step sequence above in further detail: (1) simply takes advantage of the associative property of addition and moves terms around. (2) is a subtle application of the distances variation of the **triangle inequality** which states that, for real numbers x and y ,

$$|x + y| \leq |x| + |y|.$$

It essentially says that the distance between 0 and the sum of two numbers can be no more than the combined distances of x to 0 and y to 0. For example, if $x = 3$ and $y = -1$, then

$$|x + y| = |3 - 1| = 2 < 4 = |3| + |-1| = |x| + |y|.$$

While a formal proof is omitted, it may help to think of this inequality in terms of walking in two opposite directions. In particular, let positive numbers represent walking forward one way, while negative numbers represent walking backwards the other way. Therefore, if 0 is the position where one starts, $|x + y|$ represents the distance one stands from 0 after some combination of walking forwards and backwards, while $|x| + |y|$ represents the *total* distance walked. The distance from 0 can only ever be as large as the total distance walked (by walking only forwards or backwards), so $|x + y| \leq |x| + |y|$.

Returning to the limit proof, the two values involved in the triangle inequality are $f(x) - L$ and $g(x) - M$. (3) substitutes both $|f(x) - L|$ and $|g(x) - M|$ for $\frac{1}{2}\varepsilon$. Since $|f(x) - L| < \frac{1}{2}\varepsilon$ and $|g(x) - M| < \frac{1}{2}\varepsilon$, it follows that $|f(x) - L| + |g(x) - M| < \frac{1}{2}\varepsilon + \frac{1}{2}\varepsilon$. The theorem is ultimately proven, because the difference between the function, $f(x) + g(x)$, and the desired limit, $L + M$, was shown to be less than any $\varepsilon > 0$ given an appropriate δ .

The proof of (ii) is similar to that of (i). We once again allow $\delta_1, \delta_2 > 0$ where

$$0 < |x - a| < \delta_1 \Rightarrow |f(x) - L| < \frac{1}{2}\varepsilon$$

and

$$0 < |x - a| < \delta_2 \Rightarrow |f(x) - M| < \frac{1}{2}\varepsilon.$$

Let $\delta = \min(\delta_1, \delta_2)$. If $0 < |x - c| < \delta$, then

$$\begin{aligned}
|[f(x) - g(x)] - (L - M)| &= |[f(x) - L] + [M - g(x)]| \\
&\leq |f(x) - L| + |M - g(x)| \\
&= |f(x) - L| + |g(x) - M| \\
&< \frac{1}{2}\varepsilon + \frac{1}{2}\varepsilon = \varepsilon,
\end{aligned}$$

proving (ii).

To prove (iii), we add and subtract $f(x)M$ to help relate the quantity $f(x)g(x) - LM$ to the differences $f(x) - L$ and $g(x) - M$:

$$\begin{aligned}
|f(x)g(x) - LM| &= |[f(x)g(x) - f(x)M] + [f(x)M - LM]| \\
&\leq |f(x)g(x) - f(x)M| + |f(x)M - LM| \\
&= |f(x)||g(x) - M| + |M||f(x) - L| \\
&\leq |f(x)||g(x) - M| + (|M| + 1)|f(x) - L|. \quad (4)
\end{aligned}$$

Provided some $\varepsilon > 0$, it is certain that $\delta_1, \delta_2, \delta_3 > 0$ all exist where

$$0 < |x - a| < \delta_1 \Rightarrow |f(x) - L| < 1 \Rightarrow |f(x)| < |L| + 1; \quad (5)$$

$$0 < |x - a| < \delta_2 \Rightarrow |g(x) - M| < \frac{1}{2}\varepsilon \left(\frac{1}{|L| + 1} \right); \quad (6)$$

$$0 < |x - a| < \delta_3 \Rightarrow |f(x) - L| < \frac{1}{2}\varepsilon \left(\frac{1}{|M| + 1} \right). \quad (7)$$

(5) comes from the fact that $\lim_{x \rightarrow a} f(x) = L$, so a $\delta_1 > 0$ exists for every $\varepsilon > 0$. In the case of (5), $\varepsilon = 1$. While (6) and (7) may look confusing, they once again stem from the definition of the limit. For instance, since $\lim_{x \rightarrow a} g(x) = M$, a $\delta_2 > 0$ exists for every $\varepsilon > 0$. ε is fundamentally a positive value,

which makes $\frac{1}{2}\varepsilon \left(\frac{1}{|L| + 1} \right)$ also positive, justifying (6).

Resuming the proof, we let $\delta = \min(\delta_1, \delta_2, \delta_3)$. Then

$$0 < |x - a| < \delta \Rightarrow |f(x)g(x) - LM| < \frac{1}{2}\varepsilon + \frac{1}{2}\varepsilon = \varepsilon,$$

proving (iii). This final step is justified as so: (4) showed that

$$|f(x)g(x) - LM| \leq |f(x)||g(x) - M| + (|M| + 1)|f(x) - L|.$$

Since $|f(x)| < |L| + 1$ from (5), and $|g(x) - M| < \frac{1}{2}\varepsilon \left(\frac{1}{|L| + 1} \right)$ from (6),

$$|f(x)||g(x) - M| < (|L| + 1) \left[\frac{1}{2}\varepsilon \left(\frac{1}{|L| + 1} \right) \right] = \frac{1}{2}\varepsilon.$$

Since $|f(x) - L| < \frac{1}{2}\varepsilon \left(\frac{1}{|M| + 1} \right)$,

$$(|M| + 1)|f(x) - L| < (|M| + 1) \left[\frac{1}{2}\varepsilon \left(\frac{1}{|M| + 1} \right) \right] = \frac{1}{2}\varepsilon,$$

justifying the final step.

To prove (iv), we take advantage of the fact that

$$\lim_{x \rightarrow a} \left[\frac{f(x)}{g(x)} \right] = \lim_{x \rightarrow a} \left[f(x) \cdot \frac{1}{g(x)} \right]$$

due to (iii), so all that is required is to show that

$$\lim_{x \rightarrow a} \left[\frac{1}{g(x)} \right] = \left[\frac{1}{M} \right].$$

If $g(x) \neq 0$, then

$$\left| \frac{1}{g(x)} - \frac{1}{M} \right| = \frac{|g(x) - M|}{|Mg(x)|} \quad (1)$$

Let $\delta_1 > 0$ where

$$0 < |x - a| < \delta_1 \Rightarrow |g(x) - M| < \frac{1}{2} |M| \quad (2)$$

so that

$$\begin{aligned} |g(x)| &> \frac{1}{2}|M| \\ \frac{1}{|g(x)|} &< \frac{2}{|M|} \end{aligned}$$

which means

$$\left| \frac{1}{g(x)} - \frac{1}{M} \right| < \frac{2}{|M|^2} |g(x) - M|. \quad (3)$$

From (2), we know that the distance between $g(x)$ and M is smaller than $\frac{1}{2} |M|$. This means that $\frac{1}{2}|M| < |g(x)| < \frac{3}{2}|M|$, so $|g(x)| > \frac{1}{2}|M|$. (3) is achieved by substituting $\frac{1}{|g(x)|}$ on the right hand side of (1) with $\frac{2}{|M|}$.

Let $\varepsilon > 0$ be provided and $\delta_2 > 0$ such that

$$0 < |x - a| < \delta_2 \Rightarrow |g(x) - M| < \frac{|M|^2}{2} \varepsilon.$$

If $\delta = \min(\delta_1, \delta_2)$, then

$$0 < |x - a| < \delta \Rightarrow \left| \frac{1}{g(x)} - \frac{1}{M} \right| < \frac{2}{|M|^2} \cdot \frac{|M|^2}{2} \varepsilon = \varepsilon,$$

the final step coming from substituting $|g(x) - M|$ in (3) with $\frac{|M|^2}{2} \varepsilon$. This concludes the proof of (iv) and ultimately Theorem 2 in its entirety. It is interesting seeing how the limit laws are, in essence, results of brief sequences of subtle algebraic manipulations.

The final application of the epsilon-delta limit that will be analyzed is the classic **squeeze theorem**.

Theorem 3 - Squeeze Theorem

If there exists a $p > 0$ where

$$g(x) \leq f(x) \leq h(x)$$

for all x satisfying the inequalities $0 < |x - a| < p$, and if $\lim_{x \rightarrow a} g(x) = L$ and $\lim_{x \rightarrow a} h(x) = L$, then

$$\lim_{x \rightarrow a} f(x) = L$$

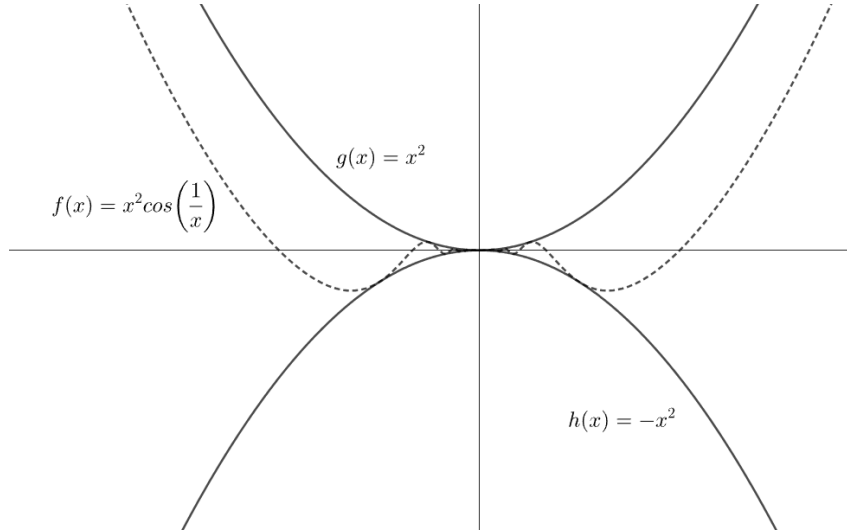


Figure 3: Squeeze theorem visualized

If a function $f(x)$ is bounded between two other functions $g(x)$ and $h(x)$, and $g(x)$ and $h(x)$ both approach the same limit L as x goes to a , then $f(x)$ is “squeezed” into the same limit L . For example, consider the functions displayed in Figure 3. We can show that $x^2 \cos(\frac{1}{x})$ lies in between x^2 and $-x^2$ like so:

$$\begin{aligned} -1 &\leq \cos(x) \leq 1 \\ -x^2 &\leq x^2 \cos(x) \leq x^2 \end{aligned}$$

Since $\lim_{x \rightarrow 0} -x^2 = \lim_{x \rightarrow 0} x^2 = 0$, the squeeze theorem tells us that $\lim_{x \rightarrow 0} x^2 \cos(\frac{1}{x}) = 0$.

To prove the theorem, let $\varepsilon > 0$ be provided, and choose $\delta_1, \delta_2 > 0$ where

$$0 < |x - a| < \delta_1 \Rightarrow L - \varepsilon < g(x) < L + \varepsilon$$

and

$$0 < |x - a| < \delta_2 \Rightarrow L - \varepsilon < h(x) < L + \varepsilon$$

Let $\delta = \min(\delta_1, \delta_2)$. Then

$$\begin{aligned} 0 < |x - a| < \delta &\Rightarrow L - \varepsilon < g(x) \leq f(x) \leq h(x) < L + \varepsilon \\ L - \varepsilon &< f(x) < L + \varepsilon \\ |f(x) - L| &< \varepsilon \end{aligned}$$

and thus the theorem is proven.

As a whole, we see how real analysis employs a delicate system of distances and algebraic manipulations involving them in order to concisely define what exactly a limit is and how its definition can be used to prove related theorems. This system is then used as a base to build up toward various other ideas in calculus including differentiation and integration. Such details will not be covered, as i) the goal here is to merely gain a baseline understanding of the nature of the argumentation present in real analysis and ii) they warrant a deeper level of study that lies far beyond the scope of my efforts. We will, however, get to see how the next field of analysis approaches various ideas of calculus without the concept of limits.

The Nonstandard Approach

One drawback with the real analysis approach involving the epsilon-delta definition of the limit is its cumbersome notation. Proofs can quickly become cluttered with absolute values and inequalities that at times can be challenging to keep track of and connect to one another. By formalizing the idea of the infinitesimal to where basic algebraic techniques can be applied to it, a new system of analysis can be developed to study the same material that real analysis does while taking advantage of simpler and more concise notation.

Introduction

This introduction follows section 1.4 of

Keisler, H. (1976). *Foundations of Infinitesimal Calculus*, Prindle Weber & Schmidt.

Let us first consider two points on the parabola $f(x) = x^2$. One will be a fixed point at (x_0, y_0) , while the other will lie some distance away at $(x_0 + \Delta x, y_0 + \Delta y)$ where Δx and Δy represent the horizontal and vertical distances between the two points.

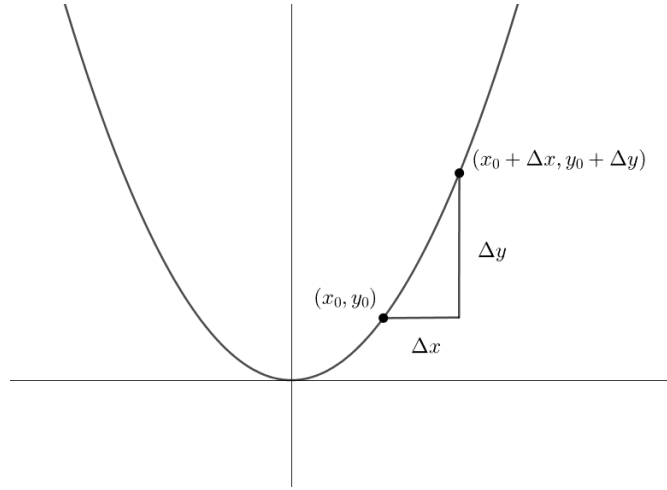


Figure 4: (x_0, y_0) and $(x_0 + \Delta x, y_0 + \Delta y)$ on $f(x) = x^2$

The average slope between any two points (x_1, y_1) and (x_2, y_2) is the ratio of the change in y to the change in x :

$$\frac{\Delta y}{\Delta x} = \frac{y_2 - y_1}{x_2 - x_1}.$$

Therefore, the average slope between the two points on the parabola above is

$$\frac{(y_0 + \Delta y) - y_0}{(x_0 + \Delta x) - x_0}. \quad (1)$$

The function is $f(x) = x^2$, so any y value is determined by plugging in its corresponding input x into it. The points then become (x_0, x_0^2) and $(x_0 + \Delta x, (x_0 + \Delta x)^2)$. Substituting in these new y coordinates into (1) gives

$$\begin{aligned} \frac{\Delta y}{\Delta x} &= \frac{(x_0 + \Delta x)^2 - x_0^2}{(x_0 + \Delta x) - x_0} \\ &= \frac{[x_0^2 + 2x_0\Delta x + (\Delta x)^2] - x_0^2}{(x_0 + \Delta x) - x_0} \\ &= \frac{2x_0\Delta x + (\Delta x)^2}{\Delta x} \\ &= 2x_0 + \Delta x. \end{aligned} \quad (2)$$

(2) gives us the slope in terms of a fixed point's x -coordinate and its horizontal distance Δx from some variable point. If we want to find the slope of a line that lies **tangent** to the curve – meaning that it intersects the curve at exactly one point – at (x_0, x_0^2) , then we can treat Δx as a very small number so that the tangent line's slope is very close to (2). We *cannot* set Δx equal to zero, because (2) follows from a quotient where Δx is present in the denominator of a quotient. Anyhow, treating it as a minisule value leads to the intuitive result that the slope of some line tangent to the point (x_0, x_0^2) on the parabola is essentially

$$2x_0.$$

This loose usage of an infinitesimal – treating a value as infinitely small to where it can be ignored – has in fact produced decently accurate results throughout the development of calculus over the past several centuries, being used by those such as Newton, Leibniz, Euler, and others in varying forms. However, it is by no means rigorous and does not establish results with absolute certainty. Why? This is because we are left with a problem: How do we know exactly when numbers are small enough to be treated as negligible in a calculation?

This now brings us to our first formal definition:

An **infinitesimal** is a number ε where

$$-a < \varepsilon < a$$

for any positive real number a .

Amongst the real numbers, 0 would be the only value that qualifies as infinitesimal. What we now do is expand the real number system by introducing **hyperreal numbers**. These include the real numbers along with nonzero infinitesimals, which can be thought of as numbers that lie infinitely close to 0. The set of all real numbers is represented by \mathbb{R} , while the set of all hyperreal numbers is represented by \mathbb{R}^* . Various symbols including $\Delta x, \Delta y, \varepsilon$, and δ are used to symbolize infinitesimals. For instance, $x + \Delta x$ is interpreted as some quantity that lies *infinitely* close to x , and $\frac{1}{\varepsilon}$ represents an **infinite positive number**. Hyperreal numbers that are not infinitely positive or negative are **finite numbers**.

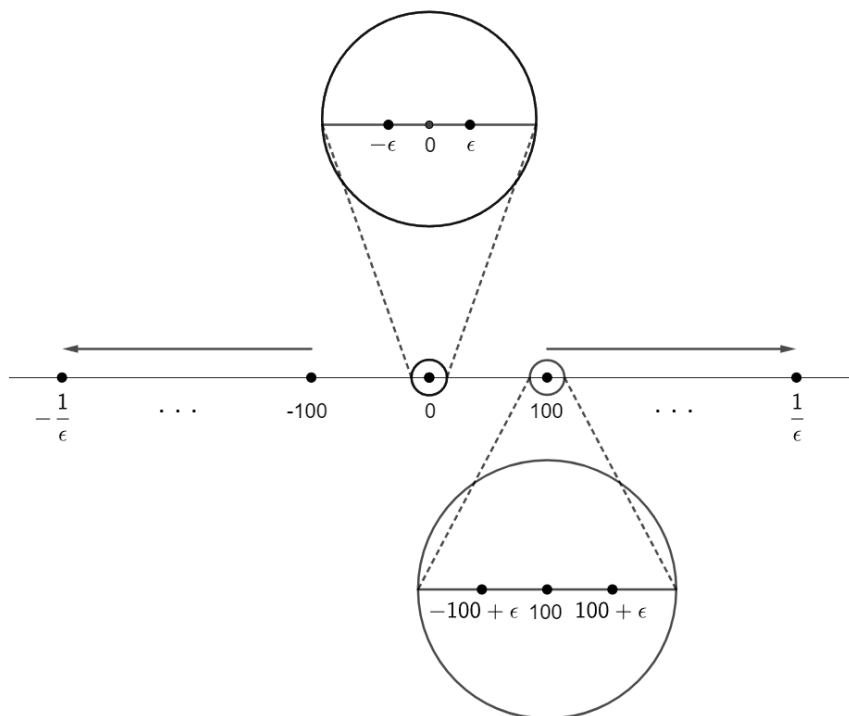


Figure 5: Hyperreal number line visualized

We can conceptualize the scale of hyperreal numbers by imagining ourselves “zooming in” infinitely close onto on a real number such as 0 or 100 on the hyperreal number line (Figure 5). This helps to clarify the nature of hyperreal numbers as merely an extension of the real numbers, so much so to where its properties and the arithmetic involved with them match closely with that of the reals.

Going back to the calculation of the instantaneous slope of $f(x) = x^2$, we now treat the value of Δx as a nonzero infinitesimal under this new lense of analysis. This means that the expression

$$2x_0 + \Delta x$$

lies infinitely close to $2x_0$, so the slope of any line tangent to (x_0, x_0^2) is concluded to be $2x_0$.

Let’s use infinitesimals to try computing the instantaneous slope of the function

$$f(x) = \sqrt{x}.$$

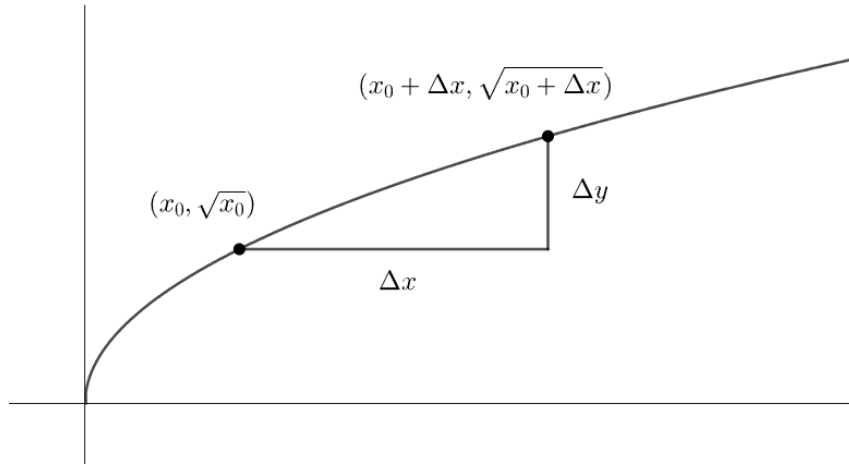


Figure 6: $f(x) = \sqrt{x}$

The average slope between a fixed point and a variable point on the square root function is

$$\begin{aligned} \frac{\Delta y}{\Delta x} &= \frac{f(x_0 + \Delta x) - f(x_0)}{\Delta x} \\ &= \frac{\sqrt{x_0 + \Delta x} - \sqrt{x_0}}{\Delta x} \end{aligned}$$

In order to calculate the instaneous slope, we need a way to cancel out Δx from the denominator. This can be readily accomplished by multiplying the quotient by the conjugate of the numerator in the form of 1 to induce a difference of squares:

$$\begin{aligned} \frac{\sqrt{x_0 + \Delta x} - \sqrt{x_0}}{\Delta x} &\cdot \left(\frac{\sqrt{x_0 + \Delta x} + \sqrt{x_0}}{\sqrt{x_0 + \Delta x} + \sqrt{x_0}} \right) = \frac{(\sqrt{x_0 + \Delta x})^2 - (\sqrt{x_0})^2}{\Delta x(\sqrt{x_0 + \Delta x} + \sqrt{x_0})} \\ &= \frac{(x_0 + \Delta x) - x_0}{\Delta x(\sqrt{x_0 + \Delta x} + \sqrt{x_0})} \\ &= \frac{\Delta x}{\Delta x(\sqrt{x_0 + \Delta x} + \sqrt{x_0})} \\ &= \frac{1}{\sqrt{x_0 + \Delta x} + \sqrt{x_0}} \end{aligned}$$

Since the Δx in the denominator is infinitesimal, this means that the quantity $\sqrt{x_0 + \Delta x}$ is infinitely close to $\sqrt{x_0}$, so

$$\begin{aligned}\frac{1}{\sqrt{x_0 + \Delta x} + \sqrt{x_0}} &= \frac{1}{\sqrt{x_0} + \sqrt{x_0}} \\ &= \frac{1}{2\sqrt{x_0}}.\end{aligned}$$

The skeptical reader may question how exactly this system has solved the concern regarding rigor. In particular, how do the ideas presented so far formalize the concept of deeming a quantity in a given calculation as negligible? What has happened is that we have *defined* what it means for a number to be considered negligibly small, so if a given quantity does not meet the criteria specified, then we know that it cannot be ignored. Beyond that, however, a more intimate understanding of the formalization of infinitesimals requires a working knowledge of abstract algebra. The details are obviously left out, as they lie far beyond my expertise. While the curious reader may feel discouraged or unfulfilled by this, keep in mind that the formalization of many concepts require complicated, abstract machinery, so it is commonplace for students of mathematics to take a result at face value at first and uncover its logical validity far later. As a direct analogue to the current situation, consider the analysis behind limits covered in the first half of this paper. It is likely that most calculus students who have studied limits will never encounter this rigorous treatment of them – let alone give it any consideration. Ambitious students, however, will inevitably run across it in a real analysis course further down the road, and the formalities are unveiled then. We now lie in the very same boat with infinitesimals!

Basic Applications of Infinitesimals

This section follows

Stroyan, Keith. (2012). *A Brief Introduction to Infinitesimal Calculus*, can be found at <https://homepage.math.uiowa.edu/~stroyan/InfsmlCalculus/Lecture1/Lect1.pdf>

It is due time for us to see how infinitesimal arithmetic can be used to provide basic intuitive proofs of various ideas seen in calculus. Note that these are by no means formal proofs.

Theorem 4 - The Extreme Value Theorem

Consider a function $f(x)$ that is continuous on a closed interval $[a, b]$. There then exists two numbers x_{\min} and x_{\max} where $f(x)$ achieves its minimum and maximum respectively where

$$f(x_{\min}) \leq f(x) \leq f(x_{\max})$$

for all other x 's.

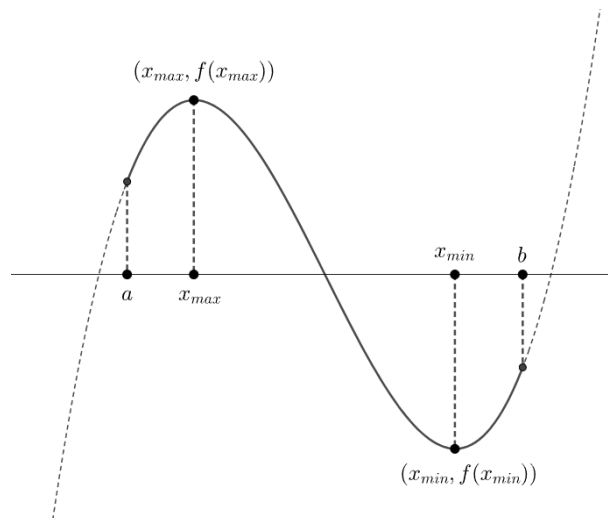


Figure 7: Extreme value theorem visualized

The extreme value theorem asserts that if a function smoothly travels over an interval of inputs, then it must take on a maximum and a minimum value at least two x 's.