

# Real and Nonstandard Analyses: An Overview

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## Introduction

A **set** is a collection of elements. These elements can be anything: numbers, shapes, colors, and so on. For instance, consider the set A of the primary colors:

$$A = \{\text{red, blue, yellow}\}$$

A **function** is a mapping between the elements of two sets where each element from one set is assigned to exactly one element from the other. In the realm of single variable calculus, functions predominantly deal with sets of real numbers. For example, the function

$$f(x) = x^2$$

takes a set of inputs (x) and produces a corresponding set of their squares f(x) in the form of **ordered pairs**:

x	f(x)
-3	9
-2	4
-1	1
0	0
1	1
2	4
3	9

Plotting the points generated by  $f(x)$  on the XY coordinate plane produces the following graph:

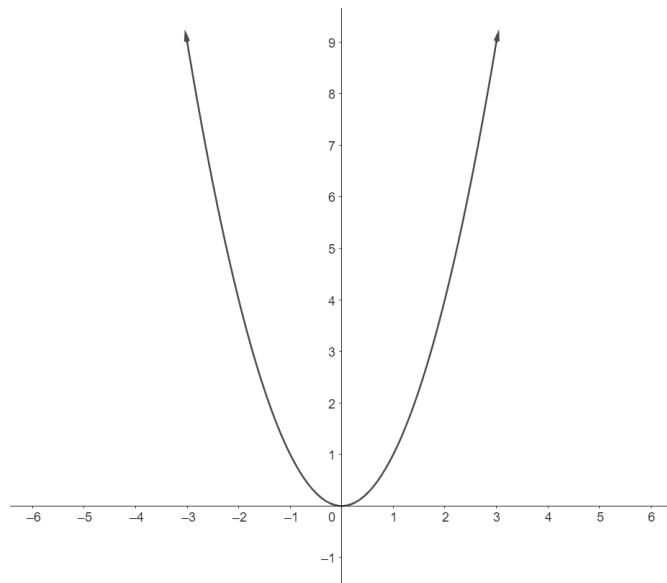


Figure 1:  $f(x)$  produces a parabolic curve

**Limits** analyze how the outputs of such functions behave as their inputs ( $x$ ) approach either a particular point or  $\infty$ . For example, the parabolic function above approaches 4 as  $x$  approaches 2 and is denoted like so:

$$\lim_{x \rightarrow 2} x^2 = 4$$

As  $x$  approaches  $\infty$ ,  $x^2$  also approaches  $\infty$ :

$$\lim_{x \rightarrow \infty} x^2 = \infty$$

Limits are a result of **analysis**, an area of mathematics that deals with continuous change and continuous functions, broadly speaking. I intend to not only explore and compare two different branches of analysis that ultimately lead to the same results encountered in calculus, but to do so in a meticulously pedagogical manner. One branch relies on a rigorous definition of the limit, while the other abandons the idea of limits entirely in favor of a concept utilized in the upbringing of calculus over the past several centuries.

## The Standard Approach

### Introduction

**Real analysis** is the study of functions, sequences, and sets involving real numbers, and it is used as the traditional means of formalizing the mechanisms presented in calculus courses. This overview of how real analysis builds toward certain calculus principles will follow section A.2 of Appendix A in

Simmons, G. (1996). *Calculus With Analytic Geometry* (2nd ed.), McGraw-Hill Education.

Being mindful of the fact that the absolute value of the difference between any two values,  $|a - b|$ , represents the distance between them will greatly aid in understanding the notation that follows. The limit is defined like so:

Let a function  $f(x)$  be defined on some interval containing the number  $c$  such that there are  $x$ 's in the domain of  $f(x)$  where

$$0 < |x - c| < \delta$$

for every positive number  $\delta$ . The statement

$$\lim_{x \rightarrow c} f(x) = L$$

is then defined like so: For every positive number  $\varepsilon$ , there exists a positive number  $\delta$  such that

$$|f(x) - L| < \varepsilon$$

for every  $x$  in the domain of  $f(x)$  where

$$0 < |x - c| < \delta$$

This definition states that  $f(x)$  approaches some value  $L$  as  $x$  approaches a some number  $c$  if it can be shown that, for any set of outputs that lie within some distance  $\varepsilon$  from  $L$ , there exists a corresponding set of inputs ( $x$ 's) that lie within some distance  $\delta$  from  $c$  which *guarantees* that  $f(x)$  falls within said range ( $\varepsilon$ ) of  $L$ . In this sense, we can bring the range of outputs as close as we want to  $L$  (letting epsilon go to 0) while being absolutely sure that  $f(x)$  lies within it. This is known as the **epsilon-delta definition** of the limit.

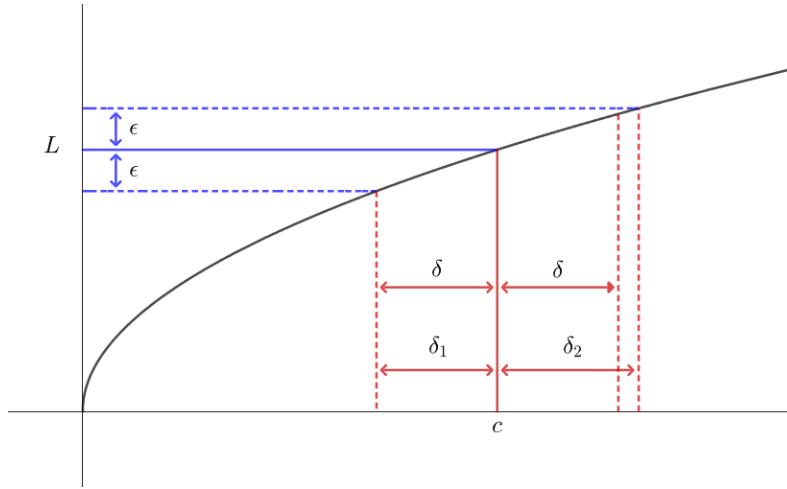


Figure 2: Epsilon-delta definition of the limit visualized

The interval  $(L - \varepsilon, L + \varepsilon)$  describes the range of outputs that lie within a distance  $\varepsilon$  from  $L$ . One detail to note in the visualization above (Figure 2) is the presence of  $\delta_1$  and  $\delta_2$ . This is because the  $x$  corresponding to  $L - \varepsilon$  does not necessarily lie the same distance away from  $c$  as the  $x$  corresponding to  $L + \varepsilon$ , since the rate at which  $f(x)$  changes may vary as  $x$  sweeps from  $c - \delta_1$  to  $c + \delta_2$ . To illustrate this, notice how the curvature in the graph is steeper on the left-hand side of  $c$  compared to that on the right-hand side. This means that sweeping through some range of outputs on the left requires a smaller increment of  $x$  as opposed to sweeping through that same range of outputs on the right, since the output of the function increases at a faster rate on the left. Therefore,  $\delta_1 < \delta_2$  for this particular graph.

This complication can be readily resolved by letting  $\delta$  equal the smaller of  $\delta_1$  and  $\delta_2$ :

$$\delta = \min(\delta_1, \delta_2).$$

$\min()$  is shorthand for taking the smallest value amongst the set of numbers present between the parentheses. For instance, if  $x = \min(1, 2, 3)$ , then  $x = 1$ . Allowing  $\delta$  to be defined in this way works because of the following reasoning: Assume that  $\delta_1 < \delta_2$  and that  $|x - c| < \delta_2$  implies  $|f(x) - L| < \varepsilon$  for some input  $x$ . If  $|x - c| < \delta_1$ , then  $|x - c| < \delta_2$  since  $\delta_1 < \delta_2$ . It is therefore assured that  $|f(x) - L| < \varepsilon$ .

## Employing the Definition

The epsilon-delta definition of the limit can now be used to prove various properties of functions. As a basic example, consider the following theorem:

### Theorem 1

If  $f(x) = x$ , then  $\lim_{x \rightarrow a} f(x) = a$ , or

$$\lim_{x \rightarrow a} x = a$$

In order to prove this limit, we need to demonstrate that for any set of outputs that lie within  $\varepsilon$  of the limit ( $a$ ), there exists a corresponding set of inputs that lie within  $\delta$  of  $x = a$  that assures that the output of  $f(x) = x$  lies within the distance  $\varepsilon$  from  $a$ .

To start, choose some  $\varepsilon > 0$ , and let  $\delta = \varepsilon$ . For any  $x$  satisfying the inequalities  $0 < |x - a| < \delta$ , we know that  $|f(x) - a| < \varepsilon$ . This is because  $f(x) = x$ , and  $\delta = \varepsilon$ . The theorem is therefore proven.

We can also prove some essential limit laws: their sums, differences, products, and quotients.

**Theorem 2 - Limit Laws**

If  $\lim_{x \rightarrow a} f(x) = L$  and  $\lim_{x \rightarrow a} g(x) = M$ , then

- (i)  $\lim_{x \rightarrow a} [f(x) + g(x)] = L + M$
- (ii)  $\lim_{x \rightarrow a} [f(x) - g(x)] = L - M$
- (iii)  $\lim_{x \rightarrow a} f(x)g(x) = LM$
- (iv)  $\lim_{x \rightarrow a} \frac{f(x)}{g(x)} = \frac{L}{M}$

To prove (i), we let  $\varepsilon > 0$  be given and allow  $\delta_1, \delta_2 > 0$  where

$$0 < |x - a| < \delta_1 \Rightarrow |f(x) - L| < \frac{1}{2}\varepsilon$$

and

$$0 < |x - a| < \delta_2 \Rightarrow |g(x) - M| < \frac{1}{2}\varepsilon.$$

For those unfamiliar with the  $\Rightarrow$  symbol, it means that the statement following it is implied (or logically follows) from the statement preceding the symbol.

The  $\frac{1}{2}$ 's in front of the  $\varepsilon$ 's may cause some confusion, but recall that when  $\lim_{x \rightarrow c} f(x) = L$ , the epsilon-delta definition tells us that there exists a set of  $x$ 's lying within some distance  $\delta$  from  $c$  such that the distance between  $f(x)$  and  $L$  is always less than  $\varepsilon$ . Knowing this, it then follows that if there exists  $\delta > 0$  such that  $|f(x) - L| < \frac{1}{2}\varepsilon$  for some  $\varepsilon > 0$ , then  $|f(x) - L| < \varepsilon$ , because  $\frac{1}{2}\varepsilon$  is smaller than  $\varepsilon$ .

Continuing the proof, we let  $\delta = \min(\delta_1, \delta_2)$ . If  $0 < |x - a| < \delta$ , then

$$|[f(x) + g(x)] - (L + M)| = |[f(x) - L] + [g(x) - M]| \quad (1)$$

$$\leq |f(x) - L| + |g(x) - M| \quad (2)$$

$$< \frac{1}{2}\varepsilon + \frac{1}{2}\varepsilon = \varepsilon, \quad (3)$$

proving (i). Analyzing the three-step sequence above in further detail: (1) takes advantage of the associative property of addition and moves terms around. (2) is a subtle application of the distances variation of the **triangle inequality** which states that, for real numbers  $x$  and  $y$ ,

$$|x + y| \leq |x| + |y|.$$

It essentially says that the distance between 0 and the sum of two numbers can be no more than the combined distances of  $x$  to 0 and  $y$  to 0. For example, if  $x = 3$  and  $y = -1$ , then

$$|x + y| = |3 - 1| = 2 < 4 = |3| + |-1| = |x| + |y|.$$

While a formal proof is omitted, it may help to think of this inequality in terms of walking in two opposite directions. In particular, let positive numbers represent walking forward one way, while negative numbers represent walking backwards the other way. Therefore, if 0 is the position where one starts,  $|x + y|$  represents the distance one stands from 0 after some combination of walking forwards and backwards, while  $|x| + |y|$  represents the *total* distance walked. The distance from 0 can only ever be as large as the total distance walked (by walking only forwards or backwards), so  $|x + y| \leq |x| + |y|$ .

Returning to the limit proof, the two values involved in the triangle inequality are  $f(x) - L$  and  $g(x) - M$ . (3) substitutes both  $|f(x) - L|$  and  $|g(x) - M|$  for  $\frac{1}{2}\varepsilon$ . Since  $|f(x) - L| < \frac{1}{2}\varepsilon$  and  $|g(x) - M| < \frac{1}{2}\varepsilon$ , it follows that  $|f(x) - L| + |g(x) - M| < \frac{1}{2}\varepsilon + \frac{1}{2}\varepsilon$ . The theorem is ultimately proven, because the difference between the function,  $f(x) + g(x)$ , and the desired limit,  $L + M$ , was shown to be less than any  $\varepsilon > 0$  given an appropriate  $\delta$ .

$$(ii) \lim_{x \rightarrow a} [f(x) - g(x)] = L - M$$

The proof of (ii) is similar to that of (i). We once again allow  $\delta_1, \delta_2 > 0$  where

$$0 < |x - a| < \delta_1 \Rightarrow |f(x) - L| < \frac{1}{2}\varepsilon$$

and

$$0 < |x - a| < \delta_2 \Rightarrow |f(x) - M| < \frac{1}{2}\varepsilon.$$

Let  $\delta = \min(\delta_1, \delta_2)$ . If  $0 < |x - c| < \delta$ , then

$$\begin{aligned} |[f(x) - g(x)] - (L - M)| &= |[f(x) - L] + [M - g(x)]| \\ &\leq |f(x) - L| + |M - g(x)| \\ &= |f(x) - L| + |g(x) - M| \\ &< \frac{1}{2}\varepsilon + \frac{1}{2}\varepsilon = \varepsilon, \end{aligned}$$

proving (ii).

$$(iii) \lim_{x \rightarrow a} f(x)g(x) = LM$$

Proving (iii) is more complicated. We begin by adding and subtracting  $f(x)M$  to help relate the quantity  $f(x)g(x) - LM$  to the differences  $f(x) - L$  and  $g(x) - M$ :

$$\begin{aligned} |f(x)g(x) - LM| &= |[f(x)g(x) - f(x)M] + [f(x)M - LM]| \\ &\leq |f(x)g(x) - f(x)M| + |f(x)M - LM| \\ &= |f(x)||g(x) - M| + |M||f(x) - L| \\ &\leq |f(x)||g(x) - M| + (|M| + 1)|f(x) - L|. \end{aligned} \quad (4)$$

Provided some  $\varepsilon > 0$ , it is certain that  $\delta_1, \delta_2, \delta_3 > 0$  all exist where

$$0 < |x - a| < \delta_1 \Rightarrow |f(x) - L| < \varepsilon \Rightarrow |f(x)| < |L| + \varepsilon; \quad (5)$$

$$0 < |x - a| < \delta_2 \Rightarrow |g(x) - M| < \frac{1}{2}\varepsilon \left( \frac{1}{|L| + 1} \right); \quad (6)$$

$$0 < |x - a| < \delta_3 \Rightarrow |f(x) - L| < \frac{1}{2}\varepsilon \left( \frac{1}{|M| + 1} \right). \quad (7)$$

(5) comes from the fact that  $\lim_{x \rightarrow a} f(x) = L$ , so a  $\delta_1 > 0$  exists for every  $\varepsilon > 0$ . In the case of (5),  $\varepsilon = 1$ . While (6) and (7) may look confusing, they once again stem from the definition of the limit. For instance, since  $\lim_{x \rightarrow a} g(x) = M$ , a  $\delta_2 > 0$  exists for every  $\varepsilon > 0$ .  $\varepsilon$  is fundamentally a positive value,

which makes  $\frac{1}{2}\varepsilon \left( \frac{1}{|L| + 1} \right)$  also positive, justifying (6).

Resuming the proof, we let  $\delta = \min(\delta_1, \delta_2, \delta_3)$ . Then

$$0 < |x - a| < \delta \Rightarrow |f(x)g(x) - LM| < \frac{1}{2}\varepsilon + \frac{1}{2}\varepsilon = \varepsilon,$$

proving (iii). This final step is justified as so: (4) showed that

$$|f(x)g(x) - LM| \leq |f(x)||g(x) - M| + (|M| + 1)|f(x) - L|.$$

Since  $|f(x)| < |L| + 1$  from (5), and  $|g(x) - M| < \frac{1}{2}\varepsilon \left( \frac{1}{|L| + 1} \right)$  from (6),

$$|f(x)||g(x) - M| < (|L| + 1) \left[ \frac{1}{2}\varepsilon \left( \frac{1}{|L| + 1} \right) \right] = \frac{1}{2}\varepsilon.$$

Since  $|f(x) - L| < \frac{1}{2}\varepsilon \left( \frac{1}{|M| + 1} \right)$ ,

$$(|M| + 1)|f(x) - L| < (|M| + 1) \left[ \frac{1}{2}\varepsilon \left( \frac{1}{|M| + 1} \right) \right] = \frac{1}{2}\varepsilon,$$

justifying the final step.

$$\text{(iv)} \lim_{x \rightarrow a} \frac{f(x)}{g(x)} = \frac{L}{M}$$

To prove (iv), we take advantage of the fact that

$$\lim_{x \rightarrow a} \left[ \frac{f(x)}{g(x)} \right] = \lim_{x \rightarrow a} \left[ f(x) \cdot \frac{1}{g(x)} \right]$$

due to (iii), so all that is required is to show that

$$\lim_{x \rightarrow a} \left[ \frac{1}{g(x)} \right] = \left[ \frac{1}{M} \right].$$

If  $g(x) \neq 0$ , then

$$\left| \frac{1}{g(x)} - \frac{1}{M} \right| = \frac{|g(x) - M|}{|M| |g(x)|} \quad (1)$$

Let  $\delta_1 > 0$  where

$$0 < |x - a| < \delta_1 \Rightarrow |g(x) - M| < \frac{1}{2} |M| \quad (2)$$

so that

$$\begin{aligned} |g(x)| &> \frac{1}{2} |M| \\ \frac{1}{|g(x)|} &< \frac{2}{|M|} \end{aligned}$$

which means

$$\left| \frac{1}{g(x)} - \frac{1}{M} \right| < \frac{2}{|M|^2} |g(x) - M|. \quad (3)$$

From (2), we know that the distance between  $g(x)$  and  $M$  is smaller than  $\frac{1}{2} |M|$ . This means that  $\frac{1}{2} |M| < |g(x)| < \frac{3}{2} |M|$ , so  $|g(x)| > \frac{1}{2} |M|$ . (3) is achieved by substituting  $\frac{1}{|g(x)|}$  on the right hand side of (1) with  $\frac{2}{|M|}$ .

Let  $\varepsilon > 0$  be provided and  $\delta_2 > 0$  such that

$$0 < |x - a| < \delta_2 \Rightarrow |g(x) - M| < \frac{|M|^2}{2} \varepsilon.$$

If  $\delta = \min(\delta_1, \delta_2)$ , then

$$0 < |x - a| < \delta \Rightarrow \left| \frac{1}{g(x)} - \frac{1}{M} \right| < \frac{2}{|M|^2} \cdot \frac{|M|^2}{2} \varepsilon = \varepsilon,$$

the final step coming from substituting  $|g(x) - M|$  in (3) with  $\frac{|M|^2}{2} \varepsilon$ . This concludes the proof of (iv) and ultimately Theorem 2 in its entirety. It is interesting seeing how the limit laws are, in essence, results of brief sequences of subtle algebraic manipulations.

The final application of the epsilon-delta limit that will be analyzed is the classic **squeeze theorem**.

**Theorem 3 - Squeeze Theorem**

If there exists a  $p > 0$  where

$$g(x) \leq f(x) \leq h(x)$$

for all  $x$  satisfying the inequalities  $0 < |x - a| < p$ , and if  $\lim_{x \rightarrow a} g(x) = L$  and

$\lim_{x \rightarrow a} h(x) = L$ , then

$$\lim_{x \rightarrow a} f(x) = L$$

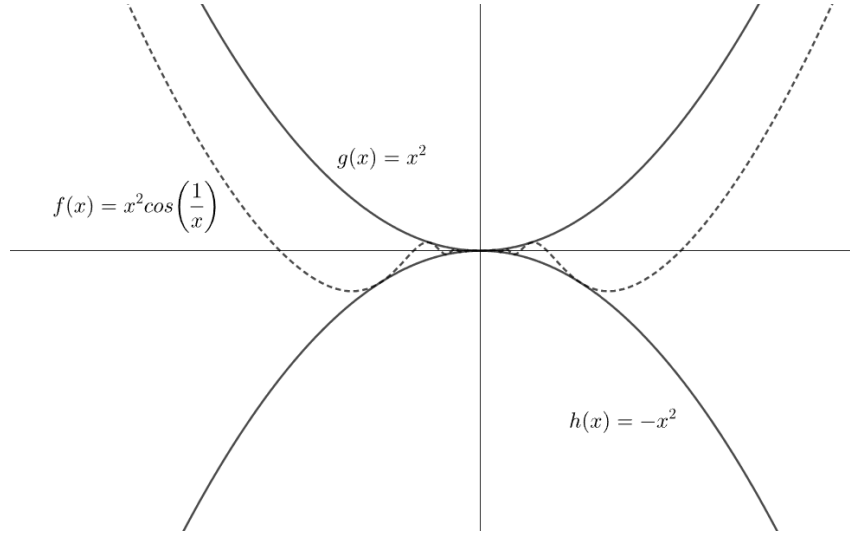


Figure 3: Squeeze theorem visualized

If a function  $f(x)$  is bounded between two other functions  $g(x)$  and  $h(x)$ , and  $g(x)$  and  $h(x)$  both approach the same limit  $L$  as  $x \rightarrow a$ , then  $f(x)$  is “squeezed” toward  $L$ . For example, consider the functions  $f(x) = x^2 \cos\left(\frac{1}{x^2}\right)$ ,  $g(x) = x^2$ , and  $h(x) = -x^2$  displayed in Figure 3. We can show that  $x^2 \cos\left(\frac{1}{x^2}\right)$  lies in between  $x^2$  and  $-x^2$  like so:

$$\begin{aligned} -1 &\leq \cos\left(\frac{1}{x^2}\right) \leq 1 \\ -x^2 &\leq x^2 \cos\left(\frac{1}{x^2}\right) \leq x^2. \end{aligned}$$

Since  $\lim_{x \rightarrow 0} -x^2 = \lim_{x \rightarrow 0} x^2 = 0$ , the squeeze theorem tells us that  $\lim_{x \rightarrow 0} x^2 \cos\left(\frac{1}{x^2}\right) = 0$ .

To prove the theorem, let  $\varepsilon > 0$  be provided, and choose  $\delta_1, \delta_2 > 0$  where

$$0 < |x - a| < \delta_1 \Rightarrow L - \varepsilon < g(x) < L + \varepsilon$$

and

$$0 < |x - a| < \delta_2 \Rightarrow L - \varepsilon < h(x) < L + \varepsilon$$

Let  $\delta = \min(p, \delta_1, \delta_2)$ . Then

$$0 < |x - a| < \delta \Rightarrow L - \varepsilon < g(x) \leq f(x) \leq h(x) < L + \varepsilon$$

$$L - \varepsilon < f(x) < L + \varepsilon$$

$$|f(x) - L| < \varepsilon$$

and thus the theorem is proven.

As a whole, we see how real analysis employs a delicate system of distances and algebraic manipulations in order to concisely define what exactly a limit is and how its definition can be used to prove related theorems. This system is then used as a base to build up toward various other ideas in calculus including differentiation and integration. Such details will not be covered, as 1) the goal here is to merely gain a baseline understanding of the nature of the argumentation present in real analysis and 2) they warrant a deeper level of study far beyond the scope of my efforts. We will, however, get to see how the next field of analysis approaches various ideas of calculus without the concept of limits.