

Recv: FIRMWARE_NAME:Prusa-Firmware 5.0.4-TZB based on Marlin
FIRMWARE_URL:https://github.com/prusa3d/Prusa-Firmware PROTOCOL_VERSION:1.0
MACHINE_TYPE:Prusa i3 MK3 EXTRUDER_COUNT:1 UUID:00000000-0000-0000-0000-000000000000

Recv: ok

Send: N2 M20*19

Recv: Begin file list

Recv: NEMA_E~1.GCO 272345

Recv: NEMA_E~2.GCO 425324

Recv: OZZLOY~1.GCO 47049477

Recv: PHONE_~1.GCO 24640264

Recv: PRUSA_~1.GCO 3515190

Recv: PRUSA~1.GCO 14078317

Recv: SPIRAL~1.GCO 20303835

Recv: TOOL_S~1.GCO 42749989

Recv: 20MM_H~1.GCO 198739

Recv: ECOR_T~1.GCO 273611

Recv: ECOR_T~2.GCO 258460

Recv: FORD_M~1.GCO 1898759

Recv: MK3_PL~1.GCO 3552905

Recv: MK3_PL~2.GCO 2206259

Recv: MK3_PL~3.GCO 23525291

Recv: MK3_PL~4.GCO 224162

Recv: MK6B5B~1.GCO 5966830

Recv: MK31C7~1.GCO 25074366

Recv: MKEB14~1.GCO 9991779

Recv: MK6698~1.GCO 21788066

Recv: MK3CAD~1.GCO 319820

Recv: MK9BA2~1.GCO 1163600

Recv: MK9CAB~1.GCO 11667175

Recv: MKDFE2~1.GCO 3771043

Recv: MKD24A~1.GCO 17819561

Recv: MKD715~1.GCO 7586128

Recv: MK027C~1.GCO 839525

Recv: MK3_PR~1.GCO 409041

Recv: MMU2_1~1.GCO 926712

Recv: End file list

Recv: ok

Send: N3 M117 [] 0%*52

Recv: ok

Send: N4 M117 [] 0%*51

Recv: ok

Send: N0 M110 N0*125

Recv: ok

Send: N1 M73 P0 R317*17

Recv: NORMAL MODE: Percent done: 0; print time remaining in mins: 317

Recv: SILENT MODE: Percent done: 255; print time remaining in mins: -1

Recv: ok

Send: N2 M73 Q0 S319*28

Recv: NORMAL MODE: Percent done: 0; print time remaining in mins: 317

Recv: SILENT MODE: Percent done: 0; print time remaining in mins: 319

Recv: ok

Send: N3 M201 X1000 Y1000 Z1000 E5000*57

Recv: ok

Send: N4 M203 X200 Y200 Z12 E120*8

Recv: ok

Send: N5 M204 P1250 R1250 T1250*80

Recv: ok

Send: N6 M205 X8.00 Y8.00 Z0.40 E2.00*58

Recv: ok

Send: N7 M205 S0 T0*36

Recv: ok

Send: N8 M107*45

Recv: ok

Send: N9 M107*44

Recv: ok

Send: N10 M115 U3.4.0*85

Recv: ok

Send: N11 M83*40

Recv: ok

Send: N12 M140 S60*96

Recv: ok

Send: N13 M109 S160*93

Recv: ok

Send: N14 M117 [] 0%*2

Recv: ok

Send: N15 M190 S60*106

Recv: ok

Send: N16 G28 W*83

Recv: tmc2130_home_enter(axes_mask=0x01)

Recv: 0 step=14 mscnt= 225

Recv: tmc2130_goto_step 0 45 2 1000

Recv: tmc2130_home_exit tmc2130_sg_homing_axes_mask=0x01

Recv: tmc2130_home_enter(axes_mask=0x02)

Recv: echo:busy: processing

Recv: 0 step=18 mscnt= 288

Recv: tmc2130_goto_step 1 17 2 1000

Recv: tmc2130_home_exit tmc2130_sg_homing_axes_mask=0x02

Recv: ok

Send: N17 M117 [] 0%*1

Recv: ok

Send: N18 G80*40

Recv: echo:busy: processing

Recv: echo:busy: processing

Recv: echo:busy: processing

Recv: echo:busy: processing

Recv: echo:busy: processing

Recv: echo:busy: processing

Recv: echo:busy: processing

Recv: echo:busy: processing

Recv: echo:busy: processing

Recv: echo:busy: processing

Recv: echo:busy: processing

Recv: echo:busy: processing

Recv: ok

Send: N19 M105*31

Recv: ok T:160.2 /160.0 B:61.2 /60.0 T0:160.2 /160.0 @:19 B@:0 P:38.2 A:38.4

Send: N20 M109 S215*92

Recv: ok

Send: N21 G21*41

Recv: Unknown G code: \$21 G21

Recv: ok

Send: N22 M403 E0 F0*23

Recv: MMU <= 'F0 0'

Recv: ok

Send: N23 M403 E1 F0*23

Recv: MMU <= 'F1 0'

Recv: ok

Send: N24 M403 E2 F0*19

Recv: MMU <= 'F2 0'

Recv: ok

Send: N25 M403 E3 F0*19

Recv: MMU <= 'F3 0'

Recv: ok

Send: N26 M403 E4 F0*23

Recv: MMU <= 'F4 0'

Recv: ok
Send: N27 G1 Y-3.0 F1000.0*29
Recv: ok
Send: N28 G1 Z0.4 F1000.0*59
Recv: ok
Send: N29 T0*1
Recv: E-axis disabled
Recv: MK3 => MMU 'T0 @toolChange:1'
Recv: echo:busy: processing
Recv: echo:busy: processing
Recv: echo:busy: processing
Recv: echo:busy: processing
Recv: MMU => MK3 'waiting for filament @ MK3 Sensor'
Recv: MK3 => MMU 'Filament seen at extruder'
Recv: E-axis enabled
Recv: echo:busy: processing
Recv: MMU => MK3 'ok :)'
Recv: ok
Recv: MK3 => MMU 'C0'
Send: N30 M105*20
Recv: ok T:212.1 /215.0 B:60.5 /60.0 T0:212.1 /215.0 @:68 B@:33 P:39.2 A:38.3
Send: N31 G1 X55.0 E32.0 F1073.0*123
Recv: ok
Send: N32 M73 Q0 S319*47
Recv: NORMAL MODE: Percent done: 0; print time remaining in mins: 317
Recv: SILENT MODE: Percent done: 0; print time remaining in mins: 319
Recv: ok
Send: N33 M73 P0 R317*32
Recv: NORMAL MODE: Percent done: 0; print time remaining in mins: 317
Recv: SILENT MODE: Percent done: 0; print time remaining in mins: 319
Recv: ok

Send: N34 M105*16

Recv: ok T:212.1 /215.0 B:60.5 /60.0 TO:212.1 /215.0 @:68 B@:33 P:39.2 A:38.3

Send: N35 G1 X5.0 E32.0 F1800.0*70

Recv: ok

Send: N36 G1 X55.0 E8.0 F2000.0*66

Recv: ok

Send: N37 G1 Z0.3 F1000.0*50

Recv: ok

Send: N38 G92 E0.0*98

Recv: ok

Send: N39 G1 X240.0 E25.0 F2200.0*102

Recv: ok

Send: N40 G1 Y-2.0 F1000.0*29

Recv: ok

Send: N41 G1 X55.0 E25 F1400.0*100

Recv: MMU => MK3 'ok'

Recv: echo:busy: processing

Recv: echo:busy: processing

Recv: ok

Send: N42 M105*17

Recv: ok T:215.1 /215.0 B:60.4 /60.0 TO:215.1 /215.0 @:25 B@:22 P:39.3 A:38.3

Send: N43 G1 Z0.20 F1000.0*0

Recv: ok

Send: N44 G1 X5.0 E4.0 F1000.0*125

Recv: ok

Send: N45 G92 E0.0*104

Recv: ok

Send: N46 M221 S95*111

Recv: ok

Send: N47 G90*35

Recv: ok

Send: N48 M83*36

Recv: ok

Send: N49 G92 E0.0*100

Recv: ok

Send: N50 G21*47

Recv: Unknown G code: \$50 G21

Recv: ok

Send: N51 G90*36

Recv: ok

Send: N52 M83*47

Recv: ok

Send: N53 T0*12

Recv: echo:busy: processing

Recv: echo:busy: processing

Recv: echo:busy: processing

Recv: echo:busy: processing

Recv: echo:busy: processing

Recv: echo:busy: processing

Recv: echo:busy: processing

Recv: echo:busy: processing