0.1 σ Estimation Method

Usually, when back-diffusing a depth series, some amplitude is regained on the signal, and some peaks and troughs, that might have been washed out from the diffusion might emerge when restoring the signal. These two properties thus makes it possible to connect the diffusion length to the years counted in that section (i.e. the number of peaks and troughs). Due to the knowledge of time passed from the Laki to the Tambora event, the data, along with the restoration techniques, permits a further investigation of the diffusion length in the given section. Thus, when back-diffusing, instead of just using the diffusion length estimate from the spectra, it is possible to examine which diffusion length that results in the correct number of years counted in that section. This property is what will be utilized in the following section, which focuses on finding the optimal diffusion length of a given section.

The general idea of the method is to back diffuse a depth series defined on an interval where the time span (i.e. the number of peaks and troughs expected in that section) is known. The focus is then to find the diffusion length estimate which generates the right number of peaks and troughs in the back diffused depth series. If more than one diffusion length meet these constraints, the largest diffusion length to still fulfill the constraints is sought after.

The algorithm consists of two modules, where one module describes the numerical back diffusion, given and inputted depth series, core specification and specific σ_0 estimate (which is either manually inputted or estimated from the spectral analysis). The flowchart describing the processes carried out in this module can be seen in Figure 0.1. Many of the sections in this module are only necessary in the initialization of the algorithm as these parts do not change if the inputted diffusion length estimate is changed. In Figure 0.1 anything carried out above the *Frequency Filters* block to the left is only computed once, and the same with anything to the right of it, except the σ_0 estimate. The density and diffusion profile calculations, the spectral analysis and the Wiener filter construction is inherent to the depth series alone, and these analyses are carried out as previously described in this thesis.

The second module is responsible for the optimization. This module examines the parameter space containing the diffusion length estimates, and utilizes a direct search method to find the optimal diffusion length estimate.

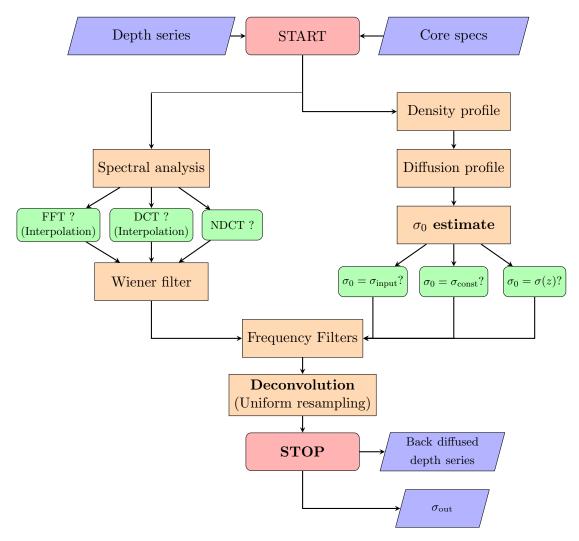


Figure 0.1: Flowchart of initialization method for back diffusion of a depth series given a diffusion length estimate.

0.1.1 Corrections on the Computed σ estimate

As mentioned in Section ??, the estimated diffusion length needs to be corrected for a number of different influences: the sampling diffusion, the ice diffusion at a given depth and the thinning function at a given drill site.

This section will describe how each of these influences have been taken care of in the work.

0.1.1.1 Ice Diffusion, σ_{ice}

0.1.1.2 Sampling Diffusion, $\sigma_{\rm dis}$

0.1.1.3 Thinning Function S(z)

0.1.2 Constraints

This section will contain a walk through of the general differences between constrained and non-constrained optimization of the diffusion length. In Figure 0.2 an example of the results of the optimization with and without constraints can be seen.

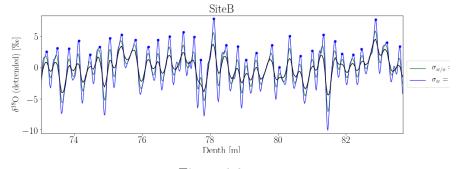


Figure 0.2:

0.2 Method Testing and Stability

Throughout this section a number of different tests of the algorithm will be presented. The tests are performed to examine the stability of the method, the accuracy of the Laki and Tambora positions and how the choice of parameters (interpolation, spectral transform type, ALT estimation, peak prominence and peak distance) changes the resulting diffusion length estimate.

0.2.1 No constraints versus constraints

0.2.2 Annual Layer Thickness Estimations

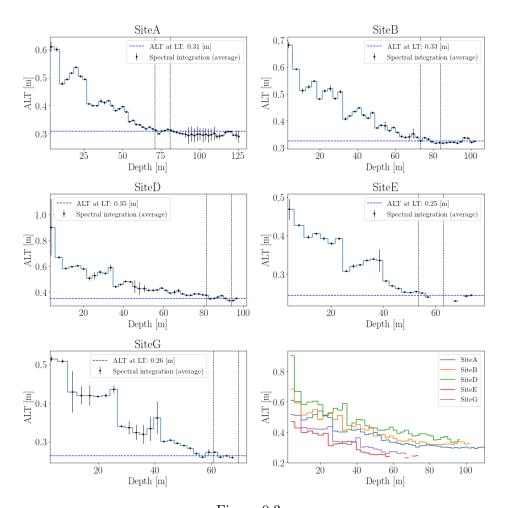


Figure 0.3:

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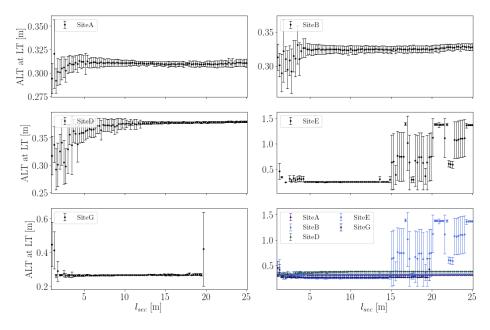


Figure 0.4:

- 0.2.2.1 Change in section length
- 0.2.2.2 Change in shift length
- 0.2.3 Spectral Transform's Effect on Diffusion Length
- 0.2.3.1 Visual Inspection
- 0.2.3.2 Speed Examination
- 0.2.4 Laki and Tambora as Gaussian Distributions
- 0.2.4.1 Varying both Laki and Tambora Position
- 0.2.4.2 Varying only Tambora Position
- 0.2.4.3 Varying only Laki Position
- 0.2.4.4 Variation Corresponding to 2 Months

0.3 Possible Algorithms Upgrades

This section will discuss ideas on how to improve on both the method and the algorithm

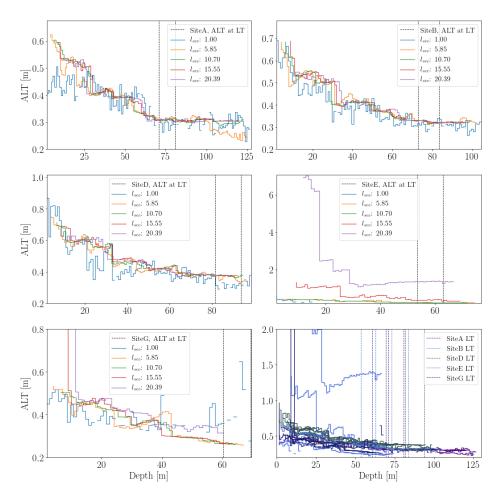


Figure 0.5:

0.3.1 Peak Detection

0.3.2 Optimization Routine

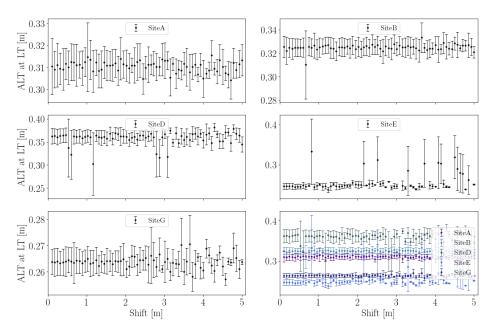


Figure 0.6:

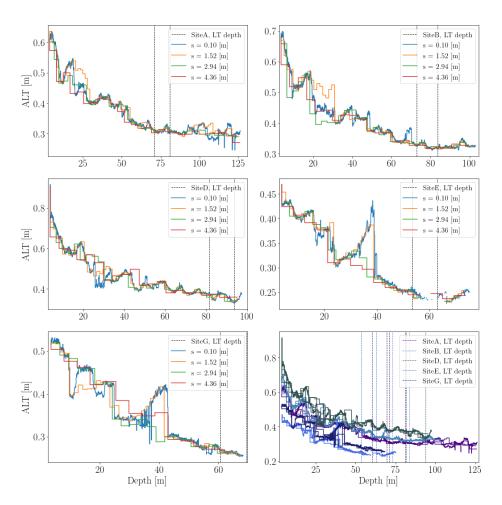


Figure 0.7:

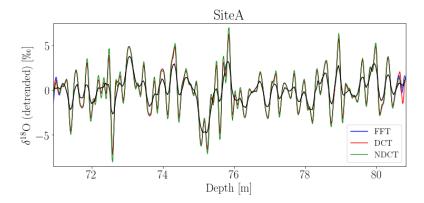


Figure 0.8:

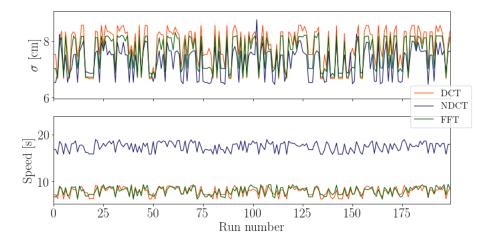


Figure 0.9:

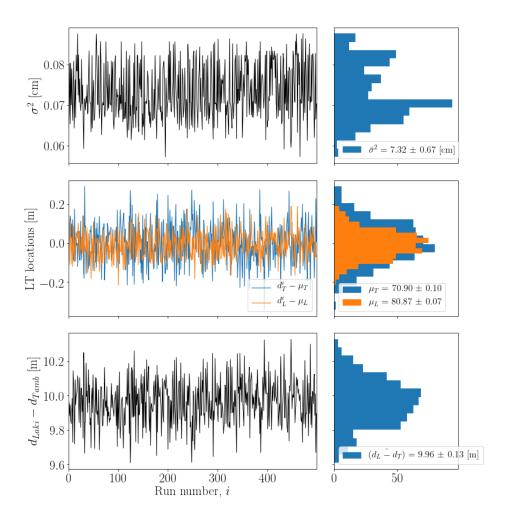


Figure 0.10:

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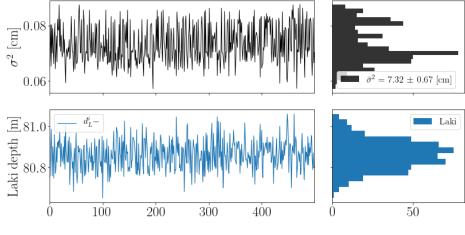


Figure 0.11:

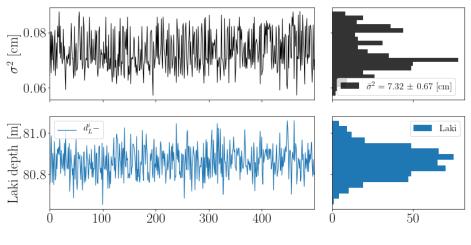


Figure 0.12:

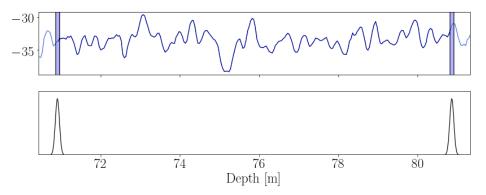


Figure 0.13:

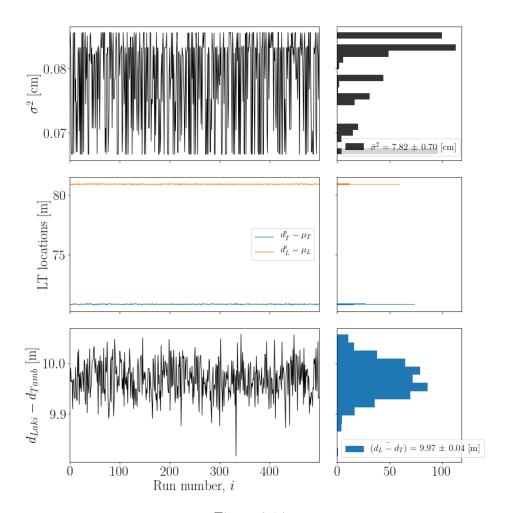


Figure 0.14:

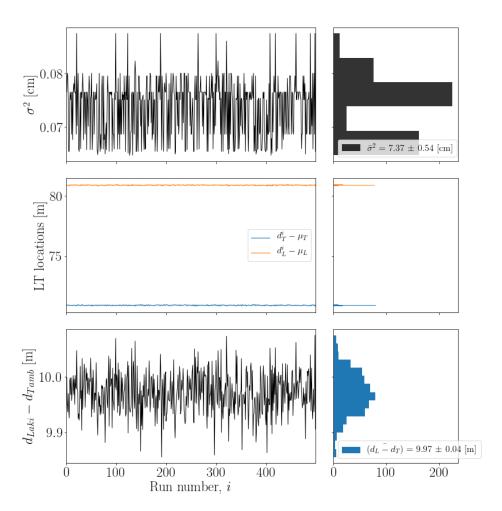


Figure 0.15: