



# Theara SENG

Lecturer



03 September 1996



Cambodia



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## Programming Skills

MATLAB

C++

Python

## Skills

CAD Design

ROS1 & ROS2

Circuit Design (Kicad)

STM32, Arduino, ESP32, 8051

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## Language

French

English

Khmer

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## Education

2012-2015	High School 10 January 1979 High School	Cambodia
2015-2020	Bachelor (Electronics and Automation) Institute of Technology of Cambodia (ITC)	Cambodia
2021-2022	Master MARS (Mobile, Autonomous, and Robotic Systems) Grenoble INP-ENSE3	France

## Working Experiences

2018-2019	Ministry of Public Works and Transport Traffic Solving in Phnom Penh City	Software Simulator
2019-2020	Sabaicode Teaching Electronics and Robotics	Mentor
2020-2021	Institute of Technology of Cambodia Sensor Fusion of a Mobile Robot In Agriculture	Assistance Lecturer
2020-2021	Cushybots Mobile Robot to remove the Land Mine	Programming and Electronics
2021-2022	Visual Behavior Navigation of a Mobile base on the depth Camera	Robotics Engineer
2022-2024	Institute of Technology of Cambodia Teaching various Subject related to Robotics and Embedded System	Lecturer
2024-2025	American University of Phnom Penh Teaching Robotics and IOTs	Lecturer

## Achievements

2012	3 <sup>rd</sup> Place Physic Outstanding Student Grade 9
2015	3 <sup>rd</sup> Place Physic Outstanding Student Grade 12
2018	1 <sup>st</sup> Place Lego Mindstorm Competition for the Exchange Program with Japan Universities
2018	1 <sup>st</sup> Place of the 5 <sup>th</sup> Cambodia Robocon Competition
2018	3 <sup>rd</sup> Place of Asia Pacific Robocon Contest 2018
2019	3 <sup>rd</sup> Place of the Robotics Underwater Competition
2023	1 <sup>st</sup> Place of the MRC competition (Rainfall) at Vientiane, Laos.

## Experiences

2017	Autonomous Mobile Robot with Four-Wheels with a French Volunteer (Ecole Central de Paris)
2018	Two Mobile Robot to Participate in the ABU Robocon 2018 in Vietnam
2019	Autonomous Four-Legged Robot to Participate in the National Robotics Competition in Cambodia
2020	Navigation of an Autonomous Robot Based on Robot Operating System (ROS)
2021	Mobile Robot (using ROS) to Remove the Landmine from the Landmine field in Siem Reap Province
2022	Depth Estimation and Navigation of the Mobile Robot based on RealSense Camera
2023	Develop Navigation Package on ROS2 using A* Algorithm and P Controller for Turtlebot3
2023	Leading students to work on two autonomous mobile robot for the ABU Robocon
2024	Exploring navigation of the Turtlebot3 based on Raspberry pi 5
2025	Leading students to work on autonomous Car (Depth Estimation for wall following and Yolo for the color detection) to participate in the World Robot Olympiad

## Reference

Dr. Am Sok Chea : Deputy Head the Department of Electrical Engineering  
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