HMM project: application to genetics

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Overview

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Introduction

Our study is based on the article of "Parseq: reconstruction of microbial transcription landscape from RNA-Seq read counts using state-space models".

It develops a way to reconstruct the transcription level accross the genom (hidden variable) based on the read counts (observed variable) produced by modern RNA-sequencing techniques.

Project organization

- Implement the model and generate data
- Implement a FK and use the bootstrap filter
- Use the PMMH algorithm to perform bayesian inference





The variables

To model contains 3 main variables:

- $(y_t)_{t>0}$ is the sequence of observations, the read counts.
- $(u_t)_{t>0}$ is the underlying expression level.
- $(s_t)_{t>0}$ is a local scaling variable.

The hidden variable X_t is a vetor (u_t, s_t) . It is deterministically initizalied at (0,0).



Markov chains for s_t

A piecewise constant Gamma:

$$k_s(s_{t+1}|s_t) = \alpha_s \times \delta_{s_t}(s_{t+1}) + (1-\alpha_s) \times \Gamma(s_{t+1}; shape = \kappa_s, scale = \kappa_s)$$



Markov chain for u_t

A complicated mixture with seven types of moves:

$$k_{u}(u_{t+1}|u_{t}) = \mathbb{1}_{\{u_{t}=0\}} \times \left[(1-\eta) \times \delta_{0}(u_{t+1}) + \eta \times \mathcal{E}(u_{t+1};\zeta) \right]$$

$$+ \mathbb{1}_{\{u_{t}>0\}} \times \left[\alpha \times \delta_{u_{t}}(u_{t+1}) + \beta \times \mathcal{E}(u_{t+1};\zeta) + \beta_{0} \times \delta_{0}(u_{t+1}) \right]$$

$$+ \gamma_{u} \mathbb{1}_{\{u_{t+1}>u_{t}\}} \left(u_{t} + \mathcal{E}(Z;\frac{\lambda_{u}}{u_{t}}) \right) + \gamma_{d} \mathbb{1}_{\{u_{t+1}$$

With $\alpha + \beta + \beta_0 + \gamma_u + \gamma_d = 1$.



Emission model - First version

Two intermediary variables:

- $a_t \sim \Gamma(\kappa, \theta)$ (the amplification coefficient)
- $x_t \sim \mathcal{P}(\frac{u_t s_t}{\kappa \theta})$ (the number of molecules)

Then the emission model has density:

$$e(y_t|x_t, a_t) = (1 - \epsilon_b - \epsilon_0) \times \mathcal{P}(y_t; x_t \times a_t)$$

$$+ \epsilon_b \times \mathcal{P}_{-\{0\}}(y_t; a_t) + \epsilon_0 \times \mathcal{U}(y_t; 0...b)$$

This version was useful for generating the data.



Emission model - Second version

Without those intermediary variable, it writes:

$$\begin{aligned} e(y_t|u_t, s_t) &= (1 - \epsilon_b - \epsilon_0) \times \sum_{x_t=0}^{\infty} \mathcal{P}(x_t; \frac{u_t s_t}{\kappa \theta}) \times \mathcal{NB}(y_t; \kappa, \frac{x_t \theta}{x_t \theta + 1}) \\ &+ \epsilon_b \times \mathcal{NB}_{-\{0\}}(y_t; \kappa, \frac{\theta}{\theta + 1}) \\ &+ \epsilon_0 \times \mathcal{U}(y_t; 0 ... b) \end{aligned}$$

This version was used to compute the log likelihood.



Hidden variable and observations

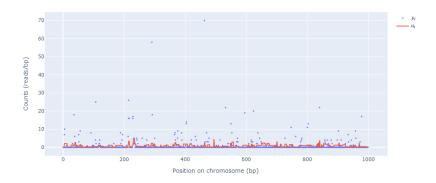


Figure: The expression level (u_t) and the observations (y_t) in the generated data



Zoom on the hidden variable

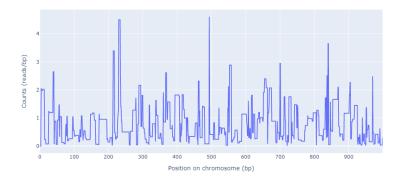
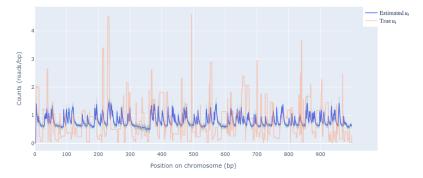


Figure: The expression level u_t in the generated data



Results obtained with 10 runs

100 particles were used in each bootstrap filter.







On a subset of parameters

The model includes **16 parameters** but we used PMMH on only two, because:

- Some of them can be estimated on the data.
- A lot of them are probabilities, and would require a Dirichlet distribution.

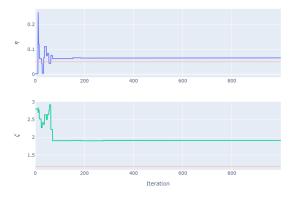
Priors:

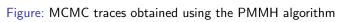
$$\eta \sim \textit{Beta}(1,100)$$
 $\zeta \sim \mathcal{E}(1)$



Results for η and ζ

1000 iterations and 20 particles (about 6 hours of running time).







Conclusion

- Successful implementation of the bootstrap filter and the PMMH algorithm (using the particles package)
- But we did not have the time for the tuning of the algorithm
- It would be interesting to do the bayesian inference on the parameters representing probabilities



The end

Thank you for your attention !

