

Stepper Motors

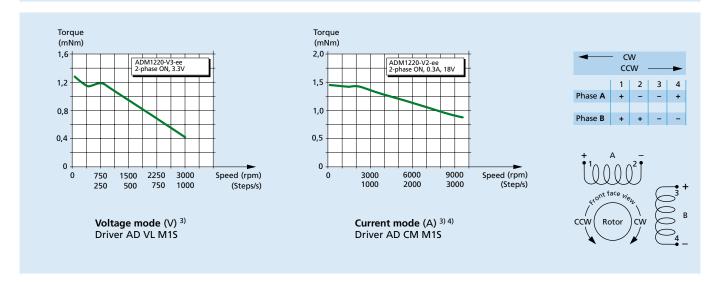
2,4 mNm

Two phase, 20 steps per revolution PRECIstep® Technology

ADM1220-ww-ee

	ww =		V2		V3		V6		V12	
		Voltage	Current	Voltage	Current		Current	Voltage	Current	
1	Nominal voltage	2	-	3	-	6	-	12	-	V DC
2	Nominal current per phase (both phases ON)	_	0,3	-	0,2	-	0,09	-	0,055	Α
	Phase resistance (at 20°C)	5,4		13		48		164		Ω
	Phase inductance (1kHz)	1,4		4,1		11,8		49,1		mH
5	Back-EMF amplitude	1,5		2,5		4,5		9,1		V/k step/s
6	Holding torque 1) (at nominal current in both phases)	2,4								mNm
7	Holding torque 1) (at twice the nominal current)	4,1								mNm
8	Step angle (full step)	18						degree		
	Angular accuracy ²⁾	± 5							% of full step	
	Residual torque		0,3						mNm	
11	Rotor inertia	7,6							·10 ⁻⁹ kgm ²	
	Resonance frequency (at no load)	187						Hz		
13	Electrical time constant	0,28								ms
1.1	A male la mata de mana a made mana mana ma	25 . 7	'A							0.0
	Ambient temperature range	-35 +70 130						°C		
	Winding temperature tolerated, max. Thermal resistance winding-ambient air	62						°C/W		
	Thermal time constant	205								
17	mermai time constant	203								S
12	Shaft bearings	sintered	sintered bronze sleeves			ball bearings, preloaded				
10	Shart bearings	(standard)				(optional)				
19	Shaft load, max.:	(Starraur	(Staridard)			(optional)				
	- radial (3 mm from bearing)	0,5				6,0				N
	- axial	0,5				3,0				N
	aria.					-,-				
20	Shaft play, max.:									
	- radial (0,2N)	15				12				μm
	- axial (0,2N)	~0				~0				μm
21	Isolation test voltage	200	200							
	- J									
22	Weight	9								q

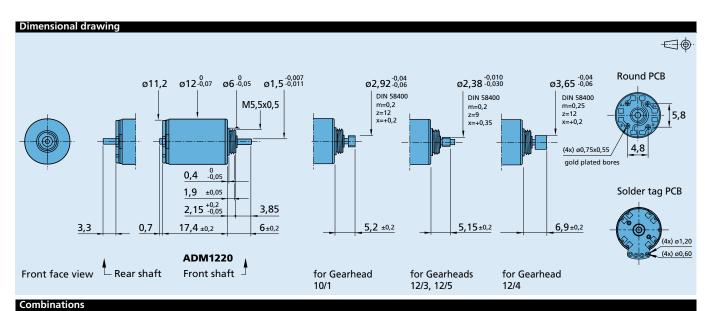
⁴⁾ Testing the motor at lower supply voltages in current mode will result in a decrease in torque at higher speed, even with the same current setting



¹⁾ with bipolar driver

^{2) 2} phases ON, balanced phase currents
3) Curves measured with a load inertia of 10 ·10·9 kgm²





Drive Electronics Encoders Stepper Motors Gearheads / Lead screws AD VL M_S AD VM M_S AD CM M_S 12/3 12/4 12/5* Lead screws M2 - M2,5 - M3

Ordering information Example: **ADM1220-2R-V2-01** Bearings (rr) Motor type Winding (ww) Motor execution (ee) ADM = Motor design 12 = Motor diameter (mm) 20 = Steps per revolution Only front output shaft With double output shaft Front output shaft Special lubricant options available -V2 -01 (Round PCB) -00 (Round PCB) **ADM1220** (sleeve bearings) Plain shaft -2R (2 ball bearings) -V3 -05 (Round PCB) **-06** (Round PCB) Pinion 10/1 -V6 -07 (Round PCB) -08 (Round PCB) Pinion 12/3, 12/5 -V12 -09 (Round PCB) **-10** (Round PCB) Pinion 12/4 -23 (Round PCB) -22 (Round PCB) Plain shaft for lead screw M2 - M2,5 - M3 -21 (Solder tag PCB) -20 (Solder tag PCB) Plain shaft -25 (Solder tag PCB) -24 (Solder tag PCB) Pinion 10/1 -27 (Solder tag PCB) -26 (Solder tag PCB) Pinion 12/3, 12/5 -29 (Solder tag PCB) -28 (Solder tag PCB) Pinion 12/4 -43 (Solder tag PCB) -42 (Solder tag PCB) Plain shaft for lead screw M2 - M2,5 - M3

^{*} Zero Backlash Gearheads