Node-screening pour le problème des moindres carrés avec pénalité ℓ_0

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 ℓ_0 -penalized problems

Ingredients of the problem

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Rough formulation

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Find x sparse such that $y \simeq Model(Ax)$

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Remark : Entries of x weight each atom in the linear combination.

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$$p^* = \begin{cases} \min & f(Ax) + \lambda ||x||_0 \\ \text{s.t.} & ||x||_{\infty} \le M \end{cases}$$
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where $\lambda > 0$ is a tuning parameter and M is a big-enough constant.

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$$\xrightarrow{\text{reformulation}}$$
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Problem
$$(P)$$
 reformulation Mixed-Integer Program

Properties:

- Continuous and integer variables
- Combinatorial problem
- Can be addressed with Branch-and-Bound (BnB) algorithms

Branch-and-bound algorithms

Idea:

• Enumerate all feasible solutions

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Node $\nu = (\mathcal{S}_0, \mathcal{S}_1, \bar{\mathcal{S}})$ where :

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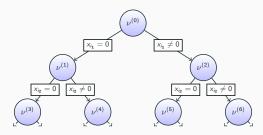
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Sub-problem at node ν $p^{\nu} = \left\{ \begin{array}{ll} \min & f(\mathsf{Ax}) + \lambda \|\mathbf{x}\|_0 \\ \mathrm{s.t.} & \|\mathbf{x}\|_{\infty} \leq M \end{array} \right\} \bigcap \left\{ \begin{array}{ll} \mathsf{x}_{\mathcal{S}_0} &= 0 \\ \mathsf{x}_{\mathcal{S}_1} & \neq 0 \end{array} \right\} \qquad (P^{\nu})$ If $p^{\star} < p^{\nu}$, then node ν can be pruned from the BnB tree.

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Neither p^* nor p^{ν} are accessible in practice :

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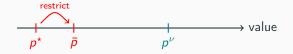
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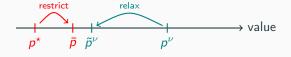


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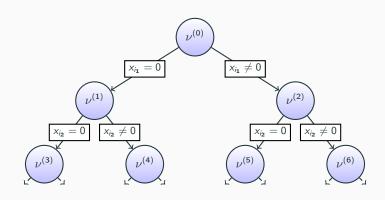
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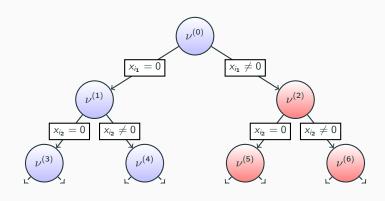
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Exploration and pruning process



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BnB efficiency

The efficiency of the BnB algorithm depends on :

- The number of nodes processed
- The ability to process nodes quickly

Node-screening improves both of these things !

Node-screening

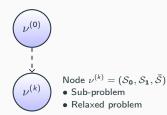
Main idea

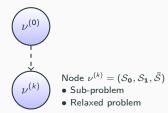
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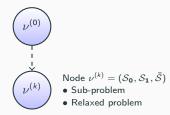
Question: How to detect prunable nodes in a more economic way?





Dual problem at node ν

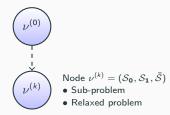
$$\max_{\mathsf{u}\in\mathbb{R}^m} \left\{ \mathrm{D}^{\nu}(\mathsf{u}) \triangleq -f^*(-\mathsf{u}) - \sum_{i\in\bar{\mathcal{S}}} [\gamma(\mathsf{a}_i^\mathsf{T}\mathsf{u})]_+ - \sum_{i\in\mathcal{S}_1} \gamma(\mathsf{a}_i^\mathsf{T}\mathsf{u}) \right\} \qquad (D^{\nu})$$



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- Terms depending on the current node constraints
- The pivot function is defined as $\gamma(t) = M|t| \lambda$

Direct consequence : The dual objective at two consecutive nodes differs from only one term.

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Dual objective link

At node
$$\nu=(\mathcal{S}_0,\mathcal{S}_1,\bar{\mathcal{S}})$$
, let $i\in\bar{\mathcal{S}}.$ Then $\forall \mathsf{u},$

$$D^{\nu \cap \{x_i = 0\}}(u) = D^{\nu}(u) + [\gamma(a_i^T u)]_+$$

$$D^{\nu \cap \{x_i \neq 0\}}(u) = D^{\nu}(u) - [\gamma(a_i^T u)]_-$$

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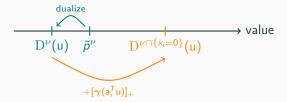
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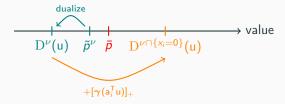
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Node-screening test

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Given some point u,

$$D^{\nu}(\mathbf{u}) + [\gamma(\mathbf{a}_{i}^{\mathsf{T}}\mathbf{u})]_{+} > \bar{p} \implies \text{Fix } x_{i} \neq 0 \text{ at node } \nu$$

$$D^{\nu}(\mathbf{u}) - [\gamma(\mathbf{a}_{i}^{\mathsf{T}}\mathbf{u})]_{-} > \bar{p} \implies \text{Fix } x_{i} = 0 \text{ at node } \nu$$

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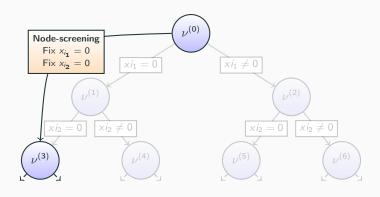
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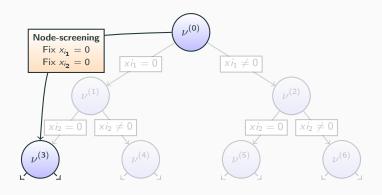
$$\begin{split} \mathrm{D}^{\nu}(\mathsf{u}) + [\gamma(\mathsf{a}_i^\mathsf{T}\mathsf{u})]_+ > \bar{p} &\implies \mathsf{Fix} \ x_i \neq 0 \ \mathsf{at} \ \mathsf{node} \ \nu \\ \mathrm{D}^{\nu}(\mathsf{u}) - [\gamma(\mathsf{a}_i^\mathsf{T}\mathsf{u})]_- > \bar{p} &\implies \mathsf{Fix} \ x_i = 0 \ \mathsf{at} \ \mathsf{node} \ \nu \end{split}$$

Nesting property : If multiple node-screening tests are passed, the corresponding variables can be fixed simultaneously.

Consequence of passing a node-screening test



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Consequence: Less nodes are explored by the BnB algorithm.

Synthetic setups:

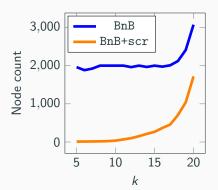
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