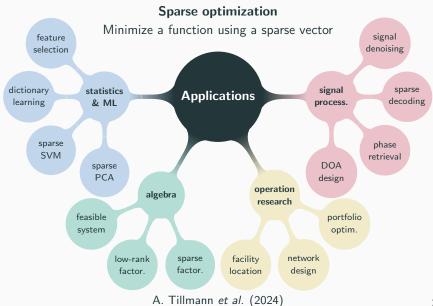
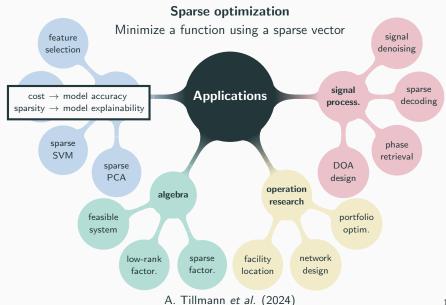
Théo Guyard JOPT, HEC Montréal, Canada - May 12th, 2025

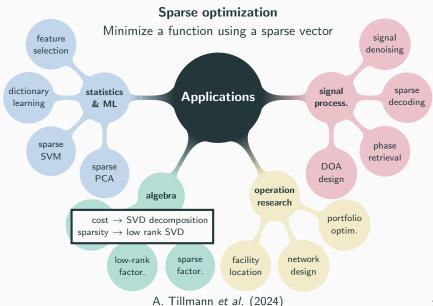
Optimization methods for ℓ_0 -problems

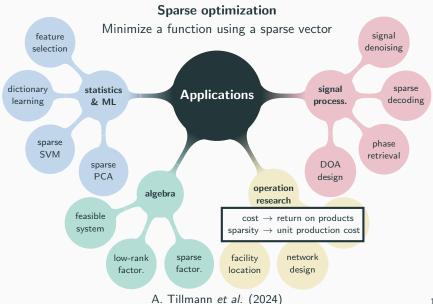
Sparse optimization

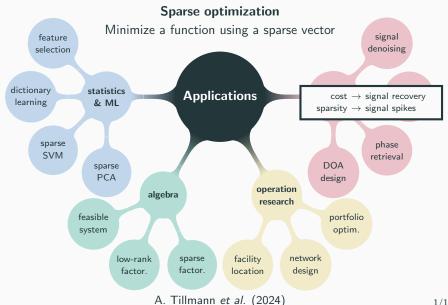
Minimize a function using a sparse vector











Sparse optimization

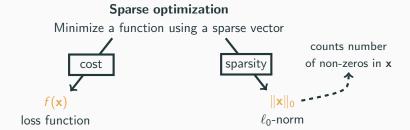
Minimize a function using a sparse vector

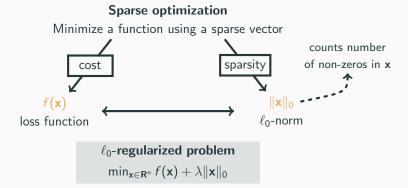
Sparse optimization

Minimize a function using a sparse vector



loss function





 $f(\mathbf{x})$

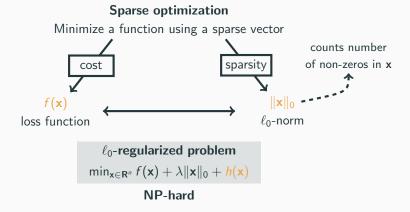
loss function

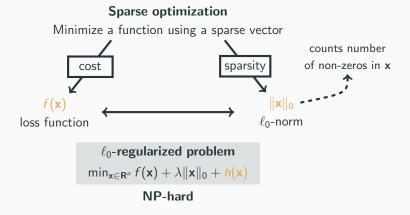


 $\|\mathbf{x}\|_0$

 ℓ_0 -norm

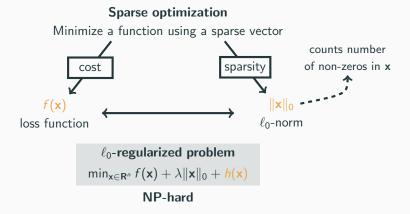
 ℓ_0 -regularized problem $\min_{\mathbf{x} \in \mathbf{R}^n} f(\mathbf{x}) + \lambda \|\mathbf{x}\|_0 + h(\mathbf{x})$





Off-the-shelf MIP solvers

- X Poor numerical performances
- Need standardized expressions



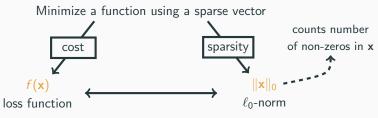
Off-the-shelf MIP solvers

- X Poor numerical performances
- X Need standardized expressions

Specialized Branch-and-Bound

- ✓ Better numerical performances
 - ✓ Greater flexibility





ℓ_0 -regularized problem

$$\min_{\mathbf{x} \in \mathbf{R}^n} f(\mathbf{x}) + \lambda \|\mathbf{x}\|_0 + \frac{h(\mathbf{x})}{h(\mathbf{x})}$$

NP-hard

Off-the-shelf MIP solvers

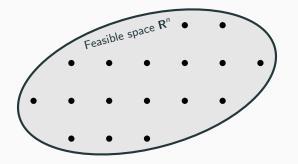
- X Poor numerical performances
- X Need standardized expressions

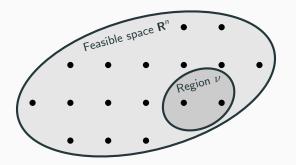
Topic of this talk —

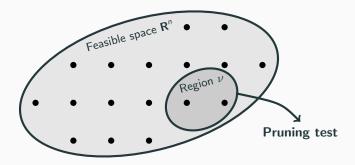
Specialized Branch-and-Bound

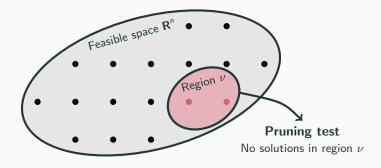
- ✓ Better numerical performances
 - ✓ Greater flexibility

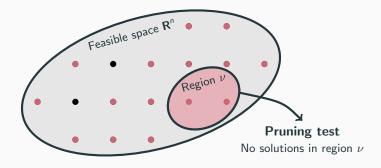
Branch-and-Bound Algorithms



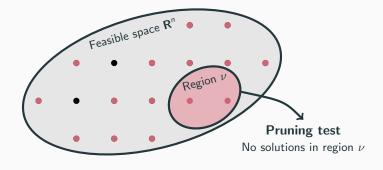








Explore regions in the feasible space and prune those that cannot contain any optimal solution.



Branching step – Region design and exploration **Bounding step** – Pruning test evaluation

Problem

$$\min_{\mathbf{x} \in \mathbf{R}^n} f(\mathbf{x}) + \lambda \|\mathbf{x}\|_0 + h(\mathbf{x})$$

Problem

$$\min_{\mathbf{x} \in \mathbf{R}^n} f(\mathbf{x}) + \lambda \|\mathbf{x}\|_0 + h(\mathbf{x})$$

Observation

Solutions are expected to be sparse

Problem

 $\min_{\mathbf{x} \in \mathbf{R}^n} f(\mathbf{x}) + \lambda \|\mathbf{x}\|_0 + h(\mathbf{x})$

Observation

Solutions are expected to be sparse

Method

Drive the sparsity of the optimization variable

Problem $\min_{\mathbf{x} \in \mathbf{R}^n} f(\mathbf{x}) + \lambda \|\mathbf{x}\|_0 + h(\mathbf{x})$

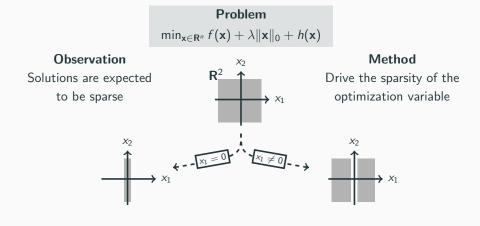
Observation

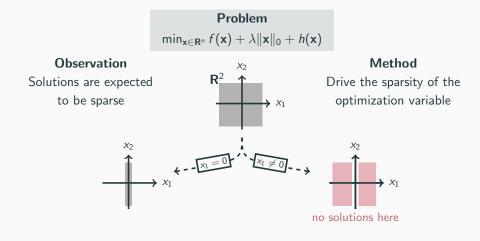
Solutions are expected to be sparse

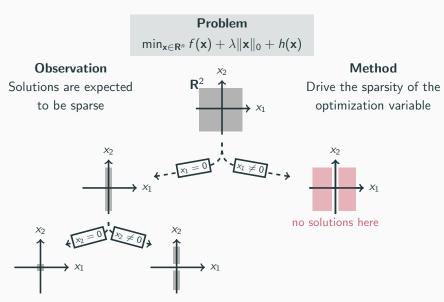


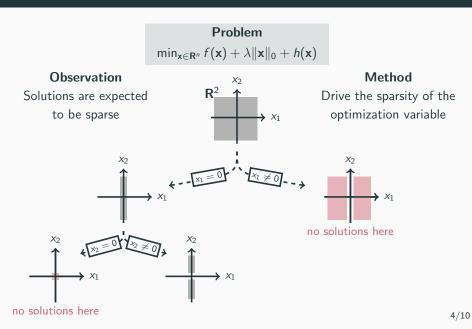
Method

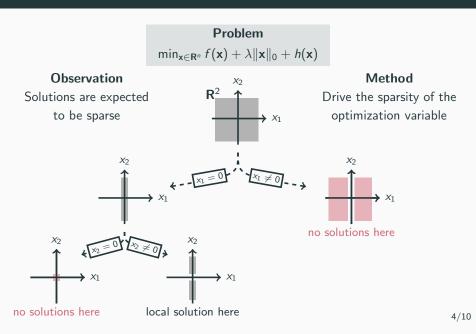
Drive the sparsity of the optimization variable

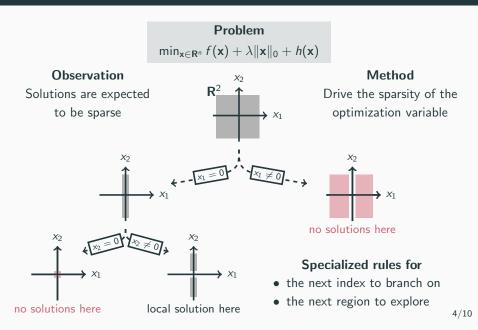












BnB – **Bounding** step



Does region $\boldsymbol{\nu}$ contains optimal solutions ?

BnB – Bounding step



Does region $\boldsymbol{\nu}$ contains optimal solutions ?

Problem

$$p^{\star} = \min_{\mathbf{x} \in \mathbf{R}^n} f(\mathbf{x}) + \lambda \|\mathbf{x}\|_0 + h(\mathbf{x})$$



Does region ν contains optimal solutions ?

$\begin{aligned} & \textbf{Problem} \\ p^{\star} &= \min_{\mathbf{x} \in \mathbf{R}^n} f(\mathbf{x}) + \lambda \|\mathbf{x}\|_0 + h(\mathbf{x}) \end{aligned}$



Restriction to region ν

$$p^{\nu} = \min_{\mathbf{x} \in \nu} f(\mathbf{x}) + \lambda \|\mathbf{x}\|_0 + h(\mathbf{x})$$



Does region ν contains optimal solutions ?

Problem

$$p^{\star} = \min_{\mathbf{x} \in \mathbf{R}^n} f(\mathbf{x}) + \lambda \|\mathbf{x}\|_0 + h(\mathbf{x})$$



Restriction to region ν

$$p^{\nu} = \min_{\mathbf{x} \in \boldsymbol{\nu}} f(\mathbf{x}) + \lambda \|\mathbf{x}\|_{0} + h(\mathbf{x})$$

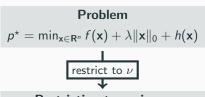


Pruning test

$$p^{\nu} > p^{\star}$$



Does region ν contains optimal solutions ?



Restriction to region ν

$$p^{\nu} = \min_{\mathbf{x} \in \nu} f(\mathbf{x}) + \lambda \|\mathbf{x}\|_0 + h(\mathbf{x})$$



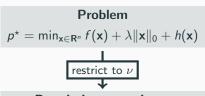
Pruning test

$$p^{\nu} > p^{\star}$$





Does region ν contains optimal solutions ?



Restriction to region ν

$$p^{\nu} = \min_{\mathbf{x} \in \boldsymbol{\nu}} f(\mathbf{x}) + \lambda \|\mathbf{x}\|_{0} + h(\mathbf{x})$$



Pruning test

$$p_{
m lb}^{
u}>p_{
m ub}^{\star}$$





Does region ν contains optimal solutions ?

Problem $p^* = \min_{\mathbf{x} \in \mathbf{R}^n} f(\mathbf{x}) + \lambda ||\mathbf{x}||_0 + h(\mathbf{x})$

restrict to
$$\nu$$

Restriction to region ν

$$p^{\nu} = \min_{\mathbf{x} \in \nu} f(\mathbf{x}) + \lambda \|\mathbf{x}\|_0 + h(\mathbf{x})$$



Pruning test

$$p_{
m lb}^{
u}>p_{
m ub}^{\star}$$



Easy task

Compute an upper bound on p^*



Does region ν contains optimal solutions ?

$\begin{aligned} & \textbf{Problem} \\ & \rho^{\star} = \min_{\mathbf{x} \in \mathbf{R}^n} f(\mathbf{x}) + \lambda \|\mathbf{x}\|_0 + h(\mathbf{x}) \end{aligned}$

restrict to
$$\nu$$

Restriction to region ν

$$p^{\nu} = \min_{\mathbf{x} \in \nu} f(\mathbf{x}) + \lambda \|\mathbf{x}\|_0 + h(\mathbf{x})$$



Pruning test

$$p^{
u}_{
m lb} > p^{\star}_{
m ub}$$



Easy task

Compute an upper bound on p^*

Construct and evaluate a feasible vector in each region explored to refine p_{ub}^{\star}



Does region ν contains optimal solutions ?



$$p^* = \min_{\mathbf{x} \in \mathbf{R}^n} f(\mathbf{x}) + \lambda ||\mathbf{x}||_0 + h(\mathbf{x})$$



Restriction to region ν

$$p^{\nu} = \min_{\mathbf{x} \in \boldsymbol{\nu}} f(\mathbf{x}) + \lambda \|\mathbf{x}\|_0 + h(\mathbf{x})$$



Pruning test

$$p^{
u}_{
m lb} > p^{\star}_{
m ub}$$



Easy task

Compute an upper bound on p^*

Construct and evaluate a feasible vector in each region explored to refine p_{ub}^*

Main challenge

Compute a lower bound on p^{ν}



Does region ν contains optimal solutions ?

Problem

$$p^{\star} = \min_{\mathbf{x} \in \mathbf{R}^n} f(\mathbf{x}) + \lambda \|\mathbf{x}\|_0 + h(\mathbf{x})$$



Restriction to region ν

$$p^{\nu} = \min_{\mathbf{x} \in \nu} f(\mathbf{x}) + \lambda \|\mathbf{x}\|_0 + h(\mathbf{x})$$



Pruning test

$$p_{
m lb}^{
u}>p_{
m ub}^{\star}$$

 \rightarrow prune ν

Easy task

Compute an upper bound on p^*

Construct and evaluate a feasible vector in each region explored to refine p_{ub}^*

Main challenge

Compute a lower bound on p^{ν}

Construct and solve a relaxation

BnB – Building relaxations

Restriction to region ν

$$p^{\nu} = \min_{\mathbf{x} \in \nu} f(\mathbf{x}) + \lambda \|\mathbf{x}\|_0 + h(\mathbf{x})$$

seek tight/tractable lower bound on p^{ν}

BnB – Building relaxations

Restriction to region ν

$$p^{\nu} = \min_{\mathbf{x} \in \nu} f(\mathbf{x}) + \lambda ||\mathbf{x}||_0 + h(\mathbf{x})$$

reformulation

Restriction to region ν

$$p^{\nu} = \min_{\mathbf{x} \in \mathbf{R}^n} f(\mathbf{x}) + g^{\nu}(\mathbf{x})$$

seek tight/tractable lower bound on p^{ν}

with g^{ν} proper and closed

BnB – Building relaxations

Restriction to region ν

$$p^{\nu} = \min_{\mathbf{x} \in \nu} f(\mathbf{x}) + \lambda ||\mathbf{x}||_0 + h(\mathbf{x})$$

reformulation

Restriction to region ν

$$p^{\nu} = \min_{\mathbf{x} \in \mathbf{R}^n} f(\mathbf{x}) + g^{\nu}(\mathbf{x})$$

$$g_{\mathsf{lb}}^{\nu} \leq g^{\nu}, g_{\mathsf{lb}}^{\nu} \mathsf{convex}$$

Relaxation for region ν

$$p_{\mathsf{lb}}^{\nu} = \mathsf{min}_{\mathsf{x} \in \mathsf{R}^n} f(\mathsf{x}) + g_{\mathsf{lb}}^{\nu}(\mathsf{x})$$

seek tight/tractable lower bound on p^{ν}

with g^{ν} proper and closed

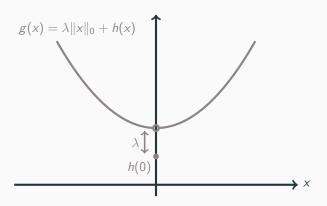
set $g_{\mathrm{lb}}^{\,
u}$ set as the convex envelope of $g^{\,
u}$

Convex envelope of $g(\mathbf{x}) = \lambda \|\mathbf{x}\|_0 + h(\mathbf{x})$ with $\mathbf{x} \in \mathbf{R}^n$

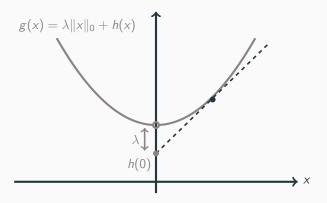
Convex envelope of
$$g(\mathbf{x}) = \lambda ||\mathbf{x}||_0 + h(\mathbf{x})$$
 with $\mathbf{x} \in \mathbf{R}^n$

$$\begin{array}{c} \uparrow \\ \hline h \text{ separable} \\ \downarrow \end{array}$$

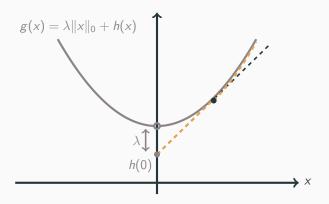
Convex envelope of $g(\mathbf{x}) = \lambda \|\mathbf{x}\|_0 + h(\mathbf{x})$ with $\mathbf{x} \in \mathbf{R}^n$ h separable



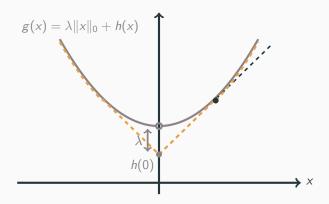
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Convex envelope of $g(\mathbf{x}) = \lambda \|\mathbf{x}\|_0 + h(\mathbf{x})$ with $\mathbf{x} \in \mathbf{R}^n$ h separable



Convex envelope of $g(\mathbf{x}) = \lambda \|\mathbf{x}\|_0 + h(\mathbf{x})$ with $\mathbf{x} \in \mathbf{R}^n$ h separable



Overall solve time

pruning test time \times number of regions processed

Overall solve time

Relaxation for region ν

$$p_{\mathsf{lb}}^{\nu} = \mathsf{min}_{\mathbf{x} \in \mathsf{R}^n} \, f(\mathbf{x}) + g_{\mathsf{lb}}^{\nu}(\mathbf{x})$$

Overall solve time

Relaxation for region ν

$$p_{\mathsf{lb}}^{\nu} = \mathsf{min}_{\mathsf{x} \in \mathsf{R}^n} f(\mathsf{x}) + g_{\mathsf{lb}}^{\nu}(\mathsf{x})$$

 $\textit{g}^{\nu}_{\text{lb}}$ is proper, closed, convex, separable, and non-smooth at x=0

Overall solve time

pruning test time × number of regions processed

Relaxation for region ν

$$p_{\mathsf{lb}}^{\nu} = \mathsf{min}_{\mathsf{x} \in \mathsf{R}^n} f(\mathsf{x}) + g_{\mathsf{lb}}^{\nu}(\mathsf{x})$$

 $g^{
u}_{
m lb}$ is proper, closed, convex, separable, and non-smooth at ${f x}={f 0}$

This is a convex sparse optimization problem

Overall solve time

pruning test time × number of regions processed

Relaxation for region ν

$$p_{\mathsf{lb}}^{\nu} = \mathsf{min}_{\mathsf{x} \in \mathsf{R}^n} \, f(\mathsf{x}) + g_{\mathsf{lb}}^{\nu}(\mathsf{x})$$

 $g^{
u}_{ ext{lb}}$ is proper, closed, convex, separable, and non-smooth at $\mathbf{x}=\mathbf{0}$



- \rightarrow first-order methods proximal gradient, coordinate descent, ... $\rightarrow \text{ acceleration strategies}$
 - working set, screening tests, ...

Overall solve time

pruning test time × number of regions processed

Relaxation for region ν

$$p_{\mathsf{lb}}^{\nu} = \mathsf{min}_{\mathsf{x} \in \mathsf{R}^n} \, f(\mathsf{x}) + g_{\mathsf{lb}}^{\nu}(\mathsf{x})$$

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ightarrow first-order methods proximal gradient, coordinate descent, ... ightarrow acceleration strategies working set, screening tests, ...

Simultaneous pruning

Overall solve time

Relaxation for region ν

$$p_{\mathsf{lb}}^{\nu} = \min_{\mathbf{x} \in \mathsf{R}^n} f(\mathbf{x}) + g_{\mathsf{lb}}^{\nu}(\mathbf{x})$$

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Simultaneous pruning



processing region ...

Overall solve time

Relaxation for region ν

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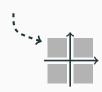
This is a convex sparse optimization problem

ightarrow first-order methods proximal gradient, coordinate descent, ... ightarrow acceleration strategies working set, screening tests, ...

Simultaneous pruning



processing region ...



perform degraded but low-cost pruning test

Overall solve time

pruning test time × number of regions processed

Relaxation for region ν

$$p_{\mathsf{lb}}^{\nu} = \mathsf{min}_{\mathsf{x} \in \mathsf{R}^n} f(\mathsf{x}) + g_{\mathsf{lb}}^{\nu}(\mathsf{x})$$

 $g_{\text{lb}}^{\,
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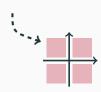
This is a convex sparse optimization problem

ightarrow first-order methods proximal gradient, coordinate descent, ... ightarrow acceleration strategies working set, screening tests, ...

Simultaneous pruning



processing region ...



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Overall solve time

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Relaxation for region ν

$$p_{\mathsf{lb}}^{\nu} = \mathsf{min}_{\mathsf{x} \in \mathsf{R}^n} f(\mathsf{x}) + g_{\mathsf{lb}}^{\nu}(\mathsf{x})$$

 $g^{
u}_{ ext{lb}}$ is proper, closed, convex, separable, and non-smooth at $\mathbf{x}=\mathbf{0}$

This is a convex sparse optimization problem

→ first-order methods

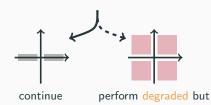
proximal gradient, coordinate descent, ...

ightarrow acceleration strategies working set, screening tests, ...

Simultaneous pruning



processing region ...



processing

low-cost pruning test

Overall solve time

Relaxation for region ν

$$p_{\mathsf{lb}}^{\nu} = \min_{\mathbf{x} \in \mathsf{R}^n} f(\mathbf{x}) + g_{\mathsf{lb}}^{\nu}(\mathbf{x})$$

 $g_{\text{lb}}^{
u}$ is proper, closed, convex, separable, and non-smooth at $\mathbf{x}=\mathbf{0}$

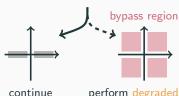
This is a convex sparse optimization problem

- → first-order methods proximal gradient, coordinate descent, ...
 - ightarrow acceleration strategies working set, screening tests, ...

Simultaneous pruning



processing region ...



continue processing

perform degraded but low-cost pruning test

Numerical Illustration

Problem

$$\min_{\mathbf{x} \in \mathbf{R}^n} f(\mathbf{x}) + \lambda \|\mathbf{x}\|_0 + h(\mathbf{x})$$

MIP solvers: → cplex → mosek BnB solver: → elOps

Problem

$$\min_{\mathbf{x} \in \mathbf{R}^n} f(\mathbf{x}) + \lambda \|\mathbf{x}\|_0 + h(\mathbf{x})$$

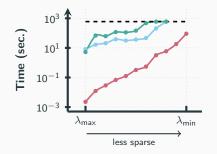
MIP solvers: → cplex → mosek BnB solver: → el0ps

- f : LeastSquares(y, Ax)
- h: ℓ₂-norm + bound constraint on x
- ullet riboflavin: $\mathbf{y} \in \mathbf{R}^{71}$ and $\mathbf{A} \in \mathbf{R}^{71 \times 4088}$

Problem
$$\min_{\mathbf{x} \in \mathbf{R}^n} f(\mathbf{x}) + \lambda \|\mathbf{x}\|_0 + h(\mathbf{x})$$

MIP solvers: → cplex → mosek BnB solver: → el0ps

- f : LeastSquares(y, Ax)
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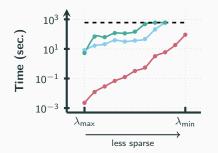


Problem $\min_{\mathbf{x} \in \mathbf{R}^n} f(\mathbf{x}) + \lambda ||\mathbf{x}||_0 + h(\mathbf{x})$

MIP solvers: → cplex → mosek BnB solver: → elOps

Instance 1

- f : LeastSquares(y, Ax)
- $h: \ell_2$ -norm + bound constraint on \mathbf{x}
- riboflavin: $\mathbf{y} \in \mathbf{R}^{71}$ and $\mathbf{A} \in \mathbf{R}^{71 \times 4088}$



- f : Logistic(y, Ax)
- $h: \ell_1$ -norm + bound constraint on x
- leukemia: $\mathbf{y} \in \mathbf{B}^{38}$ and $\mathbf{A} \in \mathbf{R}^{38 \times 7129}$

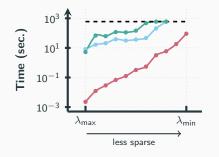
Problem $\min_{\mathbf{x} \in \mathbf{R}^n} f(\mathbf{x}) + \lambda \|\mathbf{x}\|_0 + h(\mathbf{x})$

MIP solvers: → cplex → mosek

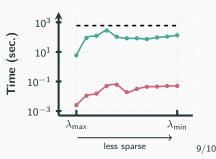
BnB solver: → el0ps

Instance 1

- f : LeastSquares(y, Ax)
- $h: \ell_2$ -norm + bound constraint on \mathbf{x}
- riboflavin: $\mathbf{y} \in \mathbf{R}^{71}$ and $\mathbf{A} \in \mathbf{R}^{71 \times 4088}$



- f : Logistic(y, Ax)
- $h: \ell_1$ -norm + bound constraint on \mathbf{x}
- \bullet leukemia: $\textbf{y} \in \textbf{B}^{38}$ and $\textbf{A} \in \textbf{R}^{38 \times 7129}$



Take-home messages

- ℓ_0 -problems are of great practical interest but NP-hard
- Off-the-shelf MIP solvers
 - X Poor numerical performances
 - Need standardized expressions
- Specialized BnB solvers
 - ✓ Better numerical performances
 - ✓ Greater flexibility
- Structure-exploitation is key
 - \rightarrow Sparsity-driven branching strategy
 - \rightarrow Convexification-based bounding strategy
 - → Efficient convex solver for lower bounds
 - → Dedicated simultaneous pruning strategy

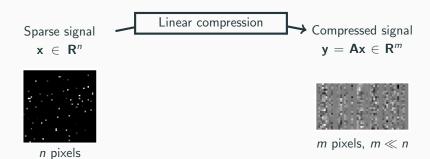
Question time!

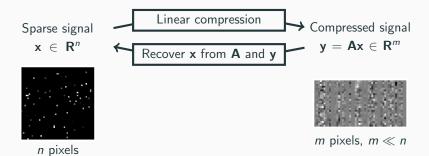


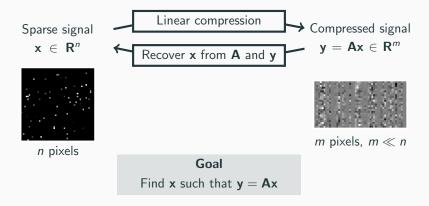
Sparse signal

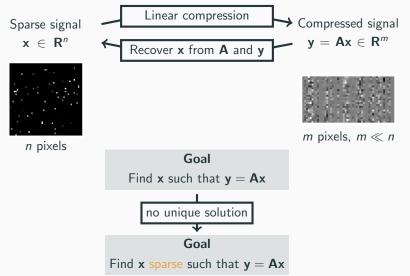
 $x \in R^n$











	Feature 1	Feature 2		Feature n	Target
Sample 1	a _{1,1}			$a_{1,n}$	
Sample 2	a _{2,1}			$a_{2,n}$	
Sample 3	a _{3,1}	$A \in R^{m}$	×n	a _{3,n}	$y \in R^m$
Sample m	$a_{m,1}$			$a_{m,n}$	Ут

	Feature 1	Feature 2		Feature n	Target
Sample 1	a _{1,1}			$a_{1,n}$	
Sample 2	a _{2,1}			$a_{2,n}$	
Sample 3	a _{3,1}	$A \in R^{m}$	×n	a _{3,n}	$y \in R^m$
Sample m	$a_{m,1}$			$a_{m,n}$	Ут

Features
$$\mathbf{A} \in \mathbf{R}^{m \times n} \longleftrightarrow \mathbf{A} \in \mathbf{R}^m \longleftrightarrow \mathbf{A} \times \mathbf{A} \times \mathbf{A}$$
 Target $\mathbf{y} = \phi(\mathbf{A}\mathbf{x})$

	Feature 1	Feature 2		Feature n	Target
Sample 1	$a_{1,1}$			$a_{1,n}$	
Sample 2	a _{2,1}			$a_{2,n}$	
Sample 3	a _{3,1}	$A \in R^{m}$	≺ n	a _{3,n}	$y \in R^m$
Sample m	$a_{m,1}$			$a_{m,n}$	Ут

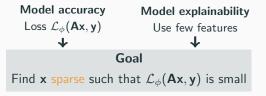
Features
$$\mathbf{A} \in \mathbf{R}^{m \times n} \longleftrightarrow \mathbf{Weights} \ \mathbf{x} \in \mathbf{R}^n \Longrightarrow \mathbf{Target} \ \mathbf{y} = \phi(\mathbf{A}\mathbf{x})$$

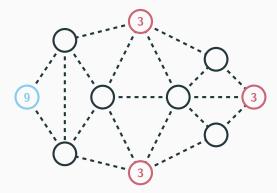
Model accuracy Loss $\mathcal{L}_{\phi}(\mathbf{A}\mathbf{x},\mathbf{y})$

Model explainability
Use few features

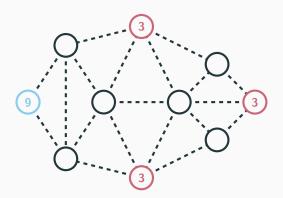
	Feature 1	Feature 2		Feature n	Target
Sample 1	a _{1,1}			$a_{1,n}$	
Sample 2	a _{2,1}			a _{2,n}	
Sample 3	a _{3,1}	$A \in R^{m}$	< n	a _{3,n}	$y \in R^m$
Sample m	$a_{m,1}$	$a_{m,2}$		$a_{m,n}$	Ут

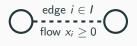
Features
$$\mathbf{A} \in \mathbf{R}^{m \times n} \longleftrightarrow \mathbf{Weights} \ \mathbf{x} \in \mathbf{R}^n$$
 Target $\mathbf{y} = \phi(\mathbf{A}\mathbf{x})$



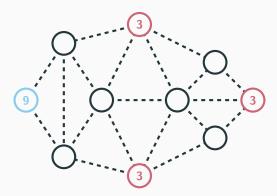


Which edges to build to transport products from source to sink nodes?

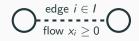




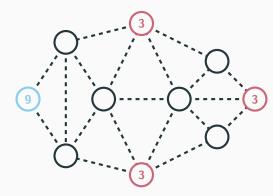
Which edges to build to transport products from source to sink nodes?



Which edges to build to transport products from source to sink nodes?



construct edge $i \in I$ if $x_i > 0$ pay construction cost c



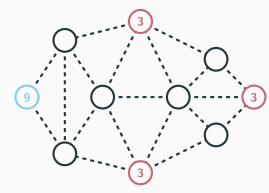
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Question

How to construct the least number of edges to satisfy transportation needs?



Which edges to build to transport products from source to sink nodes?



construct edge $i \in I$ if $x_i > 0$ pay construction cost c

Question

How to construct the least number of edges to satisfy transportation needs?



such that $Q(\mathbf{x}) = 0$

Balancing solution quality and problem hardness

Riboflavin dataset -	Ρ.	Bühlmann	et	al. ((2014))
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Colony AADK		AAPA	ABFA	ABH	 ZUR	B2 prod.
#1	8.49	8.11	8.32	10.28	 7.42	-6.64 -5.43
#71	6.85	8.27	7.98	8.04	 6.65	 -7.58

4,088 genes

Balancing solution quality and problem hardness

Riboflavin dataset - P. Bühlmann et al. (2014)

Colony	AADK	AAPA	ABFA	ABH		ZUR	B2 prod.
#1 #2	8.49 7.29	8.11 6.39	8.32 11.32	10.28 9.42		7.42 6.99	-6.64 -5.43
							 -7.58

4,088 genes

