

$$\cdot \frac{dp}{d\theta} = -\gamma \cdot \frac{p}{V} \frac{dV}{d\theta} + (\gamma-1) \frac{1}{V} \cdot \frac{dQ}{d\theta}$$

$$\cdot Q = \frac{Q_{rot}}{2} \left[ 1 - \cos \left( \pi \left( \frac{\theta - \theta_d}{\Delta\theta_{contr}} \right) \right) \right]$$

$$\Rightarrow \frac{dQ}{d\theta} = \frac{Q_{rot}}{2} \cdot \left[ \frac{\pi}{\Delta\theta_{contr}} \sin \left( \frac{\theta - \theta_d}{\Delta\theta_{contr}} \right) \right]$$

$$\cdot V = \frac{V_c}{2} \left[ 1 - \cos \theta + \beta - \sqrt{\beta^2 - \sin^2 \theta} \right] + \frac{1}{\gamma-1} \cdot V_c$$

$$\hookrightarrow V_c = \frac{\pi D^2}{4} \cdot 2R \quad ; \quad \gamma = \frac{V_{max}}{V_{min}} \quad ; \quad \beta = \frac{L}{R}$$

$$\Rightarrow \frac{dV}{d\theta} = \frac{V_c}{2} \left[ \sin \theta - \left( \frac{-2 \sin \theta \cdot \cos \theta}{2 \sqrt{\beta^2 - \sin^2 \theta}} \right) \right]$$

$$= \frac{V_c}{2} \sin \theta \left[ \frac{\cos \theta}{\sqrt{\beta^2 - \sin^2 \theta}} + 1 \right]$$

Méthode de Runge-Kutta d'ordre 2 :

$$\begin{cases} p_{i+1} = p_i + \frac{h}{2} (K_1 + K_2) \\ K_1 = f(\theta_i, p_i) \\ K_2 = f(\theta_i + h, p_i + h K_1) \end{cases}$$

$$\cdot f(\theta_i, p_i) = -\gamma \cdot \frac{p_i}{V(\theta_i)} \cdot \frac{dV}{d\theta}(\theta_i) + (\gamma-1) \frac{1}{V(\theta_i)} \cdot \frac{dQ}{d\theta}(\theta_i)$$