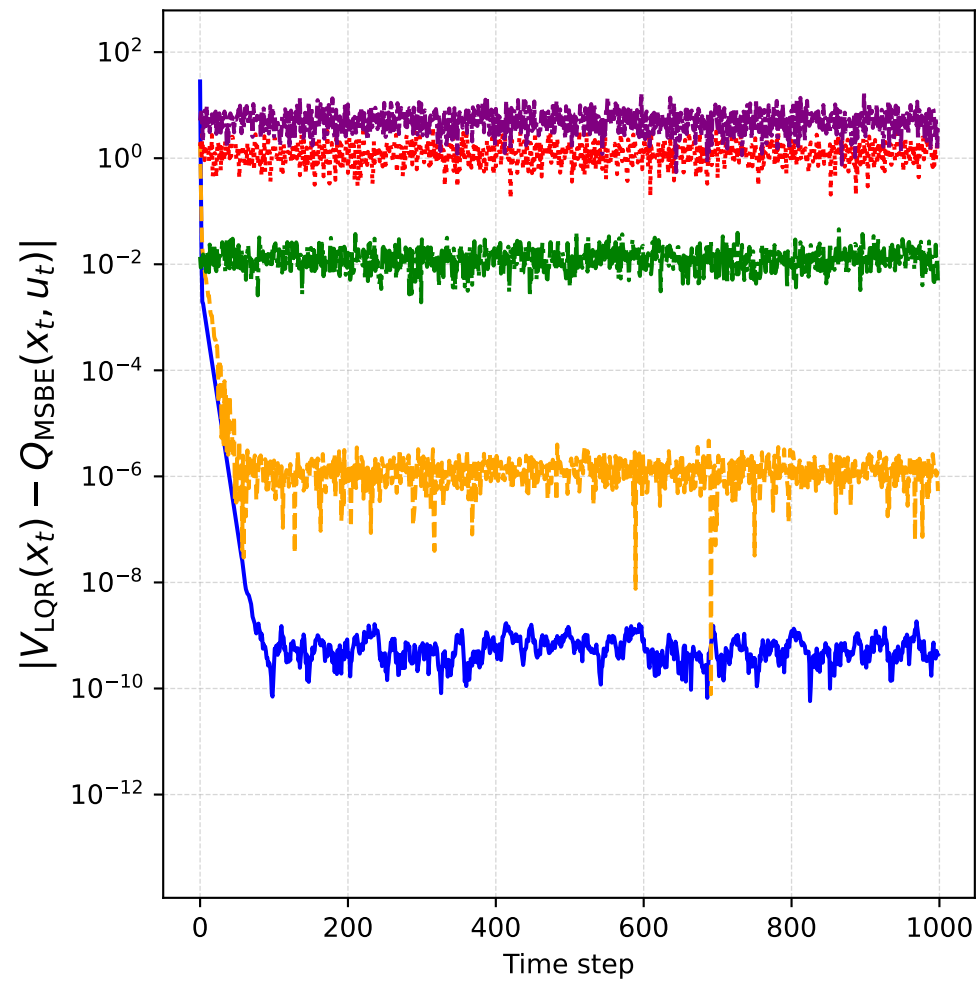


Training trajectory ($x_0 = [5, 0, 0, 0, 0]$)



Test trajectory ($x_0 = [2, 1, 1, 3, 1]$)

