# Homework #7

# 

October 20, 2021

### Problem 1

Given the real and symmetric matrix A, we can apply the eigenvalue decomposition such that  $A = O\Lambda O^T$ , where O is an orthogonal matrix whose column vectors are the eigenvectors of A and where  $\Lambda$  is a diagonal matrix whose entries are the eigenvalues of A:

$$A = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & 1 \\ 0 & 1 & 2 \end{bmatrix}$$

The eigenvalues and respective eigenvectors of A are computed using MATLAB:

$$\lambda_1 = 2$$
 and  $v_1 = \begin{bmatrix} 1 & 0 & 1 \end{bmatrix}^T$ 

$$\lambda_2 = 2 - \sqrt{2} \text{ and } v_2 = \begin{bmatrix} -1 & -\sqrt{2} & 1 \end{bmatrix}^T$$

$$\lambda_3 = 2 + \sqrt{2} \text{ and } v_3 = \begin{bmatrix} -1 & \sqrt{2} & 1 \end{bmatrix}^T$$

We can now form the orthogonal and diagonal matrices as such:

$$O = [v_1|v_2|v_3] = \begin{bmatrix} 1 & -1 & -1 \\ 0 & -\sqrt{2} & \sqrt{2} \\ 1 & 1 & 1 \end{bmatrix} \quad \text{and} \quad O^T = \begin{bmatrix} 1 & 0 & 1 \\ -1 & -\sqrt{2} & 1 \\ -1 & \sqrt{2} & 1 \end{bmatrix}$$
$$\Lambda = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 - \sqrt{2} & 0 \\ 0 & 0 & 2 + \sqrt{2} \end{bmatrix}$$

We can check the results by computing the matrix multiplication:

$$O\Lambda O^{T} = \begin{bmatrix} 1 & -1 & -1 \\ 0 & -\sqrt{2} & \sqrt{2} \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 - \sqrt{2} & 0 \\ 0 & 0 & 2 + \sqrt{2} \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 \\ -1 & -\sqrt{2} & 1 \\ -1 & \sqrt{2} & 1 \end{bmatrix} = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & 1 \\ 0 & 1 & 2 \end{bmatrix} = A$$

$$\Longrightarrow \boxed{A = O\Lambda O^{T}}$$

## Problem 2

#### Part a

$$Av^{1} = \begin{bmatrix} 1 & 0 & \sqrt{2} \\ 0 & 2 & 0 \\ \sqrt{2} & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \\ 0 \end{bmatrix} = 2 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = 2v^{1}$$

### Part b

By inspection, we choose  $v^2$  and  $v^3$  as such:

$$v^2 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad \text{and} \quad v^3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

We get:

$$V = [v^{1}|v^{2}|v^{3}] = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

#### Part c

We have:

$$V = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad \text{and} \quad V^T = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} = V$$

We can compute the following matrix multiplication:

$$VAV^{T} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & \sqrt{2} \\ 0 & 2 & 0 \\ \sqrt{2} & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 2 & 0 \\ 1 & 0 & \sqrt{2} \\ \sqrt{2} & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & \sqrt{2} \\ 0 & \sqrt{2} & 0 \end{bmatrix}$$

Now, we notice that  $VAV^T$  can be written as:

$$VAV^T = \begin{bmatrix} 2 & 0_{1\times 2} \\ 0_{2\times 1} & A_2 \end{bmatrix}$$
 where  $A_2 = \begin{bmatrix} 1 & \sqrt{2} \\ \sqrt{2} & 0 \end{bmatrix}$ 

#### Part d

The eigenvalues and respective eigenvectors of  ${\cal A}_2$  are computed using MATLAB:

$$\lambda_1 = 2$$
 and  $v_1 = \begin{bmatrix} \sqrt{2} & 1 \end{bmatrix}^T$ 

$$\lambda_2 = -1$$
 and  $v_2 = \begin{bmatrix} -\frac{\sqrt{2}}{2} & 1 \end{bmatrix}^T$ 

We can now form the orthogonal matrix  $U_2$ , whose columns are the eigenvectors of  $A_2$ , as such:

$$U_2 = \begin{bmatrix} v_1 | v_2 \end{bmatrix} = \begin{bmatrix} \sqrt{2} & -\frac{\sqrt{2}}{2} \\ 1 & 1 \end{bmatrix}$$
 and  $U_2^T = \begin{bmatrix} \sqrt{2} & 1 \\ -\frac{\sqrt{2}}{2} & 1 \end{bmatrix}$ 

We check if the matrix multiplication results in a diagonal matrix:

$$U_2^T A_2 U_2 = \begin{bmatrix} \sqrt{2} & 1 \\ -\frac{\sqrt{2}}{2} & 1 \end{bmatrix} \begin{bmatrix} 1 & \sqrt{2} \\ \sqrt{2} & 0 \end{bmatrix} \begin{bmatrix} \sqrt{2} & -\frac{\sqrt{2}}{2} \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 2\sqrt{2} & 2 \\ \frac{\sqrt{2}}{2} & -1 \end{bmatrix} \begin{bmatrix} \sqrt{2} & -\frac{\sqrt{2}}{2} \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 6 & 0 \\ 0 & -\frac{3}{2} \end{bmatrix}$$

#### Part e

To check whether U is orthogonal or not, we compute its transpose and check that  $UU^T = I$ :

$$UU^{T} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \sqrt{2} & -\frac{\sqrt{2}}{2} \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & \sqrt{2} & 1 \\ 0 & -\frac{\sqrt{2}}{2} & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = I$$

#### Part f

$$O = VU = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & \sqrt{2} & -\frac{\sqrt{2}}{2} \\ 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 0 & \sqrt{2} & -\frac{\sqrt{2}}{2} \\ 1 & 0 & 0 \\ 0 & 1 & 1 \end{bmatrix}$$

Verifying that O is orthogonal:

$$OO^{T} = \begin{bmatrix} 0 & \sqrt{2} & -\frac{\sqrt{2}}{2} \\ 1 & 0 & 0 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ \sqrt{2} & 0 & 1 \\ -\frac{\sqrt{2}}{2} & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = I$$

## Part g

We verify that the matrix multiplication results in a diagonal matrix:

$$O^{T}AO = \begin{bmatrix} 0 & 1 & 0 \\ \sqrt{2} & 0 & 1 \\ -\frac{\sqrt{2}}{2} & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & \sqrt{2} \\ 0 & 2 & 0 \\ \sqrt{2} & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & \sqrt{2} & -\frac{\sqrt{2}}{2} \\ 1 & 0 & 0 \\ 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 6 & 0 \\ 0 & 0 & -\frac{3}{2} \end{bmatrix}$$

## Problem 3

#### Part a

For  $1 \le k \le 500$ , we denote the matrices  $A_k \in \mathbb{R}^{km \times n}$  and  $C_k \in \mathbb{R}^{3 \times 100}$  as well as the vectors  $x \in \mathbb{R}^{100}$  and  $y_i \in \mathbb{R}^3$ :

$$A_k = \begin{bmatrix} C_1 \\ C_2 \\ \vdots \\ C_k \end{bmatrix}$$

Thus, for each bach k, we have:

$$\dim(A_k) = km \times n = 3k \times 100$$

For  $A_k$  to have  $\dim(x) = 100$  independent column vectors, we require that number of rows of  $A_k$  is greater than or equal to the number of columns of  $A_k$ :

$$3k \ge 100 \implies k \ge \mathbb{Z}(\frac{100}{3}) = 34$$

Thus, the least n is equal to 34.

## Part b

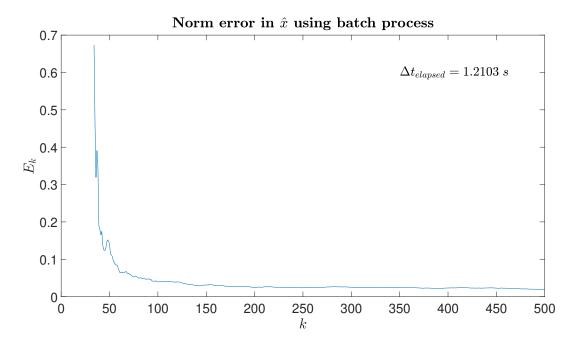


Figure 1: Error  $E_k$  Decay over time using a batch process

# Part c

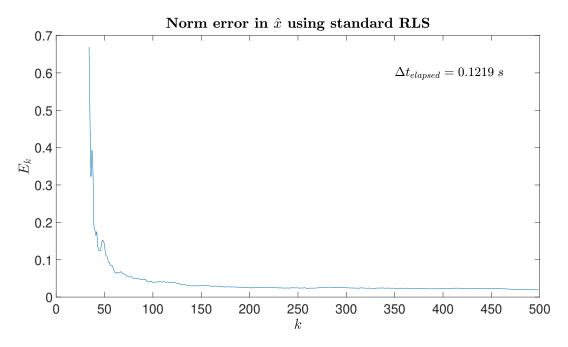


Figure 2: Error  $E_k$  Decay over time using standard Recursive Least Squares

## Part d

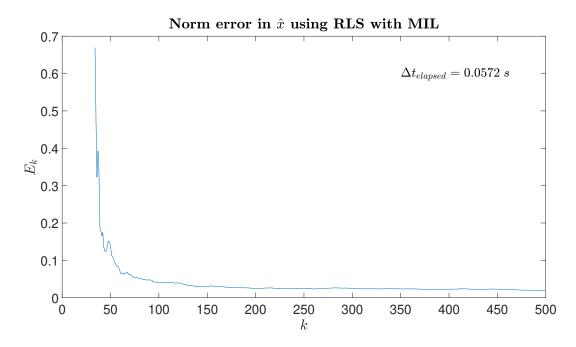


Figure 3: Error  $E_k$  Decay over time using RLS with Matrix Inversion Lemma

The matlab code used to solve this part is displayed below:

```
%% Initialize
1
   clear all
3
   clc
   load DataHW07_Prob3.mat
4
   %% Part b
   A_k = [];
6
   Y_k = [];
   R_k = [];
8
9
   E_k = [];
10
   tic
   for i = 1 : ceil(length(x_actual{1})/rank(C{1}))-1
11
       A_k = [A_k; C\{i\}];
12
       Y_k = [Y_k; y\{i\}];
13
14
   for i = ceil(length(x_actual{1})/rank(C{1})) : length(x_actual)
15
       A_k = [A_k; C\{i\}];
16
17
       R_k = eye(3*i);
       Y_k = [Y_k;y{i}];
18
       x_hat = (A_k'*R_k*A_k)\A_k'*R_k*Y_k;
19
20
       E_k = [E_k norm(x_actual{i}-x_hat)];
   end
22
   toc
   figure(1)
23
^{24}
   plot(ceil(length(x_actual{1}))/rank(C{1})) : length(x_actual),E_k);
   title('\textbf{Norm error in $\hat{x}$ using batch process}','Interpreter','latex')
25
   xlabel('$k$','Interpreter','latex')
27
   ylabel('$E_k$','Interpreter','latex')
   text(350,0.6,'$\Delta t_{elapsed}=1.2103 \; s$','FontSize',40,'Interpreter','latex')
28
29
   set(gca,'fontsize',40)
   %% Part c
30
   Q_n = [];
31
   E_k = [];
32
33
   S_k = eye(3);
   K_n = [];
34
   Q_n = zeros(100);
35
   Gamma = zeros(100,1);
37
   tic
   for i = 1 : ceil(length(x_actual{1})/rank(C{1}))
38
       Q_n = Q_n + C\{i\}, *S_k*C\{i\};
39
       Gamma = Gamma + C{i}'*S_k*y{i};
40
41
   end
   x_hat = Q_n\backslash Gamma;
42
   for k = i : length(x_actual)-1
^{43}
       Q_n = Q_n + C\{k\}'*S_k*C\{k\};
44
       K_n = inv(Q_n)*C\{k\}'*S_k;
45
46
       x_hat = x_hat + K_n*(y\{k\}-C\{k\}*x_hat);
       E_k = [E_k norm(x_actual{k}-x_hat)];
47
   end
48
49
   toc
   figure(2)
50
51
   plot(ceil(length(x_actual{1}))/rank(C{1})) : length(x_actual)-1,E_k);
   title('\textbf{Norm error in $\hat{x}$ using standard RLS}','Interpreter','latex')
52
   xlabel('$k$','Interpreter','latex')
   ylabel('$E_k$','Interpreter','latex')
54
   text(350,0.6,'$\Delta t_{elapsed}=0.1219 \; s$','FontSize',40,'Interpreter','latex')
   set(gca,'fontsize',40)
56
   %% Part d
57
   Q_n = [];
58
   P_n = [];
59
   E_k = [];
   S_k = eye(3);
61
   K_n = [];
62
   Q_n = zeros(100);
63
  Gamma = zeros(100,1);
64
65 tic
```

```
for i = 1 : ceil(length(x_actual{1})/rank(C{1}))
        Q_n = Q_n + C\{i\}, *S_k*C\{i\};
67
        Gamma = Gamma + C{i}'*S_k*y{i};
68
69
   end
70
   P_n = inv(Q_n);
71
   x_hat = P_n*Gamma;
   for k = i : length(x_actual)-1
72
        P_n = P_n - P_n * C\{k\}' * inv((inv(S_k) + C\{k\} * P_n * C\{k\}')) * C\{k\} * P_n;
73
        K_n = P_n * C\{k\}' * S_k;
74
        x_hat = x_hat + K_n*(y\{k\}-C\{k\}*x_hat);
75
76
        E_k = [E_k norm(x_actual\{k\}-x_hat)];
   end
77
78
   figure(3)
79
   plot(ceil(length(x_actual{1})/rank(C{1})) : length(x_actual)-1,E_k);
80
   title('\textbf{Norm error in $\hat{x}$ using RLS with MIL}','Interpreter','latex')
81
   xlabel('$k$','Interpreter','latex')
   ylabel('$E_k$','Interpreter','latex')
   text(350,0.6, '$\Delta t_{elapsed}=0.0572 \; s$', 'FontSize',40, 'Interpreter', 'latex')
84
   set(gca,'fontsize',40)
```

### Problem 4

#### Part a

For  $1 \le k \le 500$ , we denote the matrices  $A_k \in \mathbb{R}^{km \times n}$  and  $C_k \in \mathbb{R}^{3 \times 20}$  as well as the vectors  $x_i \in \mathbb{R}^{20}$  and  $y_i \in \mathbb{R}^3$ :

$$A_k = \begin{bmatrix} C_1 \\ C_2 \\ \vdots \\ C_k \end{bmatrix}$$

Thus, for each bach k, we have:

$$\dim(A_k) = km \times n = 3k \times 20$$

For  $A_k$  to have  $\dim(x) = 20$  independent column vectors, we require that number of rows of  $A_k$  is greater than or equal to the number of columns of  $A_k$ :

$$3k \ge 20 \implies k \ge \mathbb{Z}(\frac{20}{3}) = 7$$

Thus, the least n is equal to 7.

# Part b

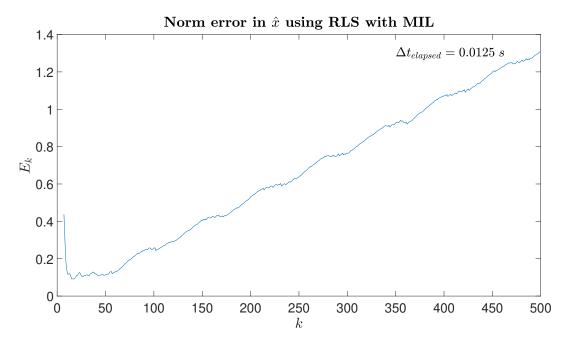


Figure 4: Error  $E_k$  Decay over time using RLS with Matrix Inversion Lemma

# Part c

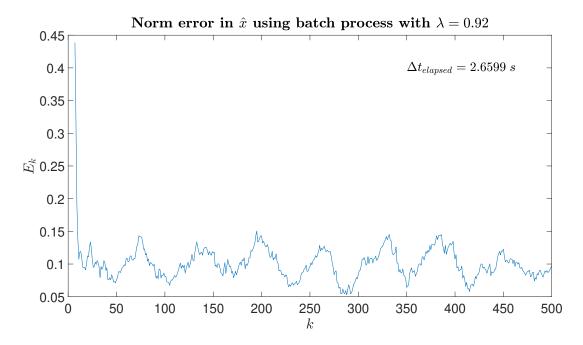


Figure 5: Error  $E_k$  Decay over time using a batch process with a forgetting factor  $\lambda = 0.92$ 

# Part d

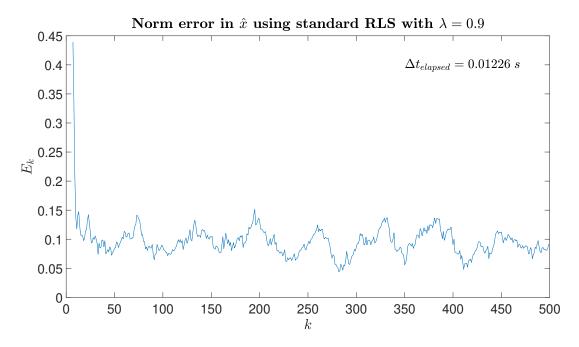


Figure 6: Error  $E_k$  Decay over time using Recursive Least Squares with a forgetting factor  $\lambda=0.9$ 

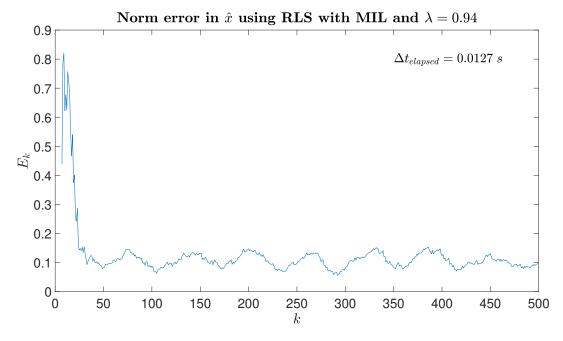


Figure 7: Error  $E_k$  Decay over time using RLS and MIL with a forgetting factor  $\lambda = 0.94$ The matlab code used to solve this part is displayed below:

```
%% Initialize
1
   clear all
3
   clc
   load DataHW07_Prob4.mat
   %% Part b
5
   Q_n = [];
6
   P_n = [];
   E_k = [];
8
   S_k = eye(3);
10
   K_n = [];
   Q_n = zeros(20);
11
   Gamma = zeros(20,1);
12
13
   tic
   for i = 1 : ceil(length(x_actual{1})/rank(C{1}))
15
       Q_n = Q_n + C\{i\}'*S_k*C\{i\};
       Gamma = Gamma + C{i}'*S_k*y{i};
16
17
   end
   P_n = inv(Q_n);
18
   x_hat = P_n*Gamma;
20
   for k = i : length(x_actual)-1
21
       P_n = P_n - P_n * C(k) * inv((inv(S_k) + C(k) * P_n * C(k) *)) * C(k) * P_n;
       K_n = P_n * C\{k\}' * S_k;
22
       x_hat = x_hat + K_n*(y\{k\}-C\{k\}*x_hat);
23
       E_k = [E_k norm(x_actual\{k\}-x_hat)];
24
   end
25
26
27
   figure(1)
   plot(ceil(length(x_actual{1}))/rank(C{1})) : length(x_actual)-1,E_k);
28
   title('\textbf{Norm error in $\hat{x}$ using RLS with MIL}','Interpreter','latex')
   xlabel('$k$','Interpreter','latex')
30
   ylabel('$E_k$','Interpreter','latex')
   text(350,1.3,'$\Delta t_{elapsed}=0.0125 \; s$','FontSize',40,'Interpreter','latex')
32
   set(gca,'fontsize',40)
33
34
   %% Part c
   A_k = [];
35
   Y_k = [];
   R_k = eye(3);
37
   E_k = [];
39
   lambda = 0.92;
40
   A_k = [A_k; C\{1\}];
41
   Y_k = [Y_k; y{1}];
42
   tic
   for i = 2 : ceil(length(x_actual{1})/rank(C{1}))-1
       A_k = [A_k; C\{i\}];
44
       Y_k = [Y_k; y\{i\}];
45
46
       R_k = [lambda*R_k zeros(3*(i-1),3); zeros(3,3*(i-1)) eye(3)];
   end
47
   for i = ceil(length(x_actual{1})/rank(C{1})) : length(x_actual)
48
       A_k = [A_k; C\{i\}];
49
       R_k = [lambda*R_k zeros(3*(i-1),3); zeros(3,3*(i-1)) eye(3)];
50
       Y_k = [Y_k; y\{i\}];
51
       x_hat = inv(A_k'*R_k*A_k)*A_k'*R_k*Y_k;
52
       E_k = [E_k norm(x_actual{i}-x_hat)];
   end
54
55
56
   figure(2)
   plot(ceil(length(x_actual{1}))/rank(C{1})) : length(x_actual),E_k);
57
   title('\textbf{Norm error in $\hat{x}$ using batch process with $\lambda=0.92$}','
       Interpreter','latex')
   xlabel('$k$','Interpreter','latex')
60
   ylabel('$E_k$','Interpreter','latex')
   text(350,0.4,'$\Delta t_{elapsed}=2.6599 \; s$','FontSize',40,'Interpreter','latex')
61
   set(gca,'fontsize',40)
   %% Part d RLS with MIL
63
64
   Q_n = [];
65 P_n = [];
66 E_k = [];
```

```
lambda = 0.94;
 67
         0 n = zeros(20):
 68
         Gamma = zeros(20,1);
 69
         tic
 70
         for i = 1 : ceil(length(x_actual{1})/rank(C{1}))
 71
                   Q_n = Q_n + C\{i\}'*lambda^(ceil(length(x_actual\{1\})/rank(C\{1\}))-1)*C\{i\};
 72
                   Gamma = Gamma + C{i}'*lambda^(ceil(length(x_actual{1})/rank(C{1}))-1)*y{i};
 73
 74
 75
         P_n = inv(Q_n);
         x_hat = P_n*Gamma;
 76
 77
         for k = i : length(x_actual)-1
                    P_n = P_n/lambda - P_n*C\{k\}'*inv(lambda*eye(size(C\{k\}*P_n*C\{k\}')) + C\{k\}*P_n*C\{k\}')*C\{k\}*P_n*C\{k\}*P_n*C\{k\}') + C\{k\}*P_n*C\{k\}')*C\{k\}*P_n*C\{k\}') + C\{k\}*P_n*C\{k\}') + C\{k\}*P_n
 78
                       P_n = MIL(P_n,C\{k\}',1/lambda,C\{k\});
 79
                   K_n = P_n * C\{k\}';
 80
                   x_hat = x_hat + K_n*(y\{k\}-C\{k\}*x_hat);
 81
                   E_k = [E_k norm(x_actual\{k\}-x_hat)];
 82
         end
 84
         toc
         figure(3)
 85
         plot(ceil(length(x_actual{1}))/rank(C{1})) : length(x_actual)-1,E_k);
 86
         title('\textbf{Norm error in $\hat{x}$ using RLS with MIL and $\lambda=0.94$}', 'Interpreter'
 87
         xlabel('$k$','Interpreter','latex')
 88
 89
         ylabel('$E_k$','Interpreter','latex')
         text(350,0.8,'$\Delta t_{elapsed}=0.0127 \; s$','FontSize',40,'Interpreter','latex')
 90
         set(gca,'fontsize',40)
 91
         %% Part d RLS
 92
         Q_n = [];
 93
 94
         P_n = [];
         E_k = [];
 95
         K_n = [];
 97
         lambda = 0.9;
 98
         Q_n = zeros(20);
         Gamma = zeros(20,1);
 99
100
         tic
         for i = 1 : ceil(length(x_actual{1})/rank(C{1}))
101
                   Q_n = Q_n + C\{i\}'*lambda^(ceil(length(x_actual\{1\})/rank(C\{1\}))-1)*C\{i\};
102
                   Gamma = Gamma + C{i}'*lambda^(ceil(length(x_actual{1})/rank(C{1}))-1)*y{i};
103
104
         end
         P_n = inv(Q_n);
105
         x_hat = P_n*Gamma;
106
107
         for k = i : length(x_actual)-1
108
                   Q_n = lambda*Q_n+C\{k\}'*C\{k\};
109
                   K_n = inv(Q_n)*C\{k\}';
                   x_hat = x_hat + K_n*(y\{k\}-C\{k\}*x_hat);
110
111
                   E_k = [E_k norm(x_actual\{k\}-x_hat)];
         end
112
113
114
         plot(ceil(length(x_actual{1}))/rank(C{1})) : length(x_actual)-1,E_k);
115
         title('\textbf{Norm error in $\hat{x}$ using standard RLS with $\lambda=0.9$}','Interpreter'
                   .'latex')
         xlabel('$k$','Interpreter','latex')
         ylabel('$E_k$','Interpreter','latex')
118
         text(350,0.4,'$\Delta t_{elapsed}=0.01226 \; s$','FontSize',40,'Interpreter','latex')
119
         set(gca,'fontsize',40)
```

## Problem 5

A symmetric matrix is positive definite if and only if all its eigenvalues are positive. It is positive semi-definite if and only if all eigenvalues are non-negative. Thus, we compute the eigenvalues for each matrix and classify them accordingly:

#### Part a

Define the pumpkin matrix below:

We compute the eigenvalues of ( $\circlearrowleft$ ) as follows:

$$\det(\underbrace{\Box} -\lambda I) = \begin{vmatrix} 1 - \lambda & 3 \\ 3 & 9 - \lambda \end{vmatrix} = (1 - \lambda)(9 - \lambda) - 9 = 0$$

$$\det(\underbrace{\Box} -\lambda I) = \lambda^2 - 10\lambda = 0 \quad \Rightarrow \quad \lambda_1 = 0 \quad \text{and} \quad \lambda_2 = 10$$

Thus 3 is symmetric positive semi-definite since all its eigenvalues are non-negative, i.e.  $\lambda_{1,2} \geq 0$ . Therefore, 3 is invertible and we can split it as such:

$$\underbrace{\overset{\mathtt{T}}{\overset{\bullet}{\smile}}}_{=} = (\underbrace{\overset{\mathtt{T}}{\overset{\bullet}{\smile}}}_{=})^T \underbrace{\overset{\mathtt{T}}{\overset{\bullet}{\smile}}}_{=} \overset{1}{\overset{1}{\smile}} = \underbrace{\overset{\mathtt{T}}{\overset{\bullet}{\smile}}}_{=} \overset{1}{\overset{1}{\smile}} \underbrace{\overset{\mathtt{T}}{\overset{\bullet}{\smile}}}_{=} \underbrace{\overset{1}{\overset{\bullet}{\smile}}}_{=} \underbrace{\overset{\mathtt{T}}{\overset{\bullet}{\smile}}}_{=} \underbrace{\overset{\mathtt{T}}{\overset{\mathtt{T}}{\smile}}}_{=} \underbrace{\overset{\mathtt{T}}{\overset{\mathtt{T}}}}_{=} \underbrace{\overset{\mathtt{T}}}_{=} \underbrace{\overset{\mathtt{T}}}_{=} \underbrace{\overset{\mathtt{T}}{\overset{\mathtt{T}}}}_{=} \underbrace{\overset{\mathtt{T}}}_{=} \underbrace{\overset{\mathtt{T}}}_{=}$$

Applying the eigenvalue decomposition where O is and orthogonal matrix whose column vectors are the eigenvectors of 2 and  $\Lambda$  is a diagonal matrix whose entries are the eigenvalues of 2:

$$\mathbf{C}^{\mathbf{T}} = O\Lambda O^T$$

From MATLAB, we obtain:

$$O = \begin{bmatrix} -3 & \frac{1}{3} \\ 1 & 1 \end{bmatrix} \quad \text{and} \quad \Lambda = \begin{bmatrix} 0 & 0 \\ 0 & 10 \end{bmatrix} = (\Lambda^{\frac{1}{2}})^T \Lambda^{\frac{1}{2}} = \Lambda^{\frac{1}{2}} \Lambda^{\frac{1}{2}} \quad \text{where} \quad \Lambda^{\frac{1}{2}} = \begin{bmatrix} 0 & 0 \\ 0 & \sqrt{10} \end{bmatrix}$$

Thus, we can write:

$$( \overset{\bullet}{ } ) = O \Lambda^{\frac{1}{2}} \Lambda^{\frac{1}{2}} O^T = N^T N \quad \text{where} \quad N = \Lambda^{\frac{1}{2}} O^T$$

Finally:

$$N = \Lambda^{\frac{1}{2}}O^{T} = \begin{bmatrix} 0 & 0 \\ 0 & \sqrt{10} \end{bmatrix} \begin{bmatrix} -3 & 1 \\ \frac{1}{3} & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 1 & 3 \end{bmatrix}$$
$$N^{T}N = \begin{bmatrix} 0 & 1 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 1 & 3 \end{bmatrix} = \begin{bmatrix} 1 & 3 \\ 3 & 9 \end{bmatrix} = \underbrace{ \vdots }$$

#### Part b

Define the skull matrix below:

We compute the eigenvalues of  $\overline{\omega}$  as follows:

$$\det(\bigcirc -\lambda I) = \begin{vmatrix} 6 - \lambda & 10 & 11\\ 10 & 19 - \lambda & 19\\ 11 & 19 & 21 - \lambda \end{vmatrix} = 0$$

Then:

$$(6 - \lambda)((19 - \lambda)(21 - \lambda) - 19^{2}) - 10(10(21 - \lambda) - 19 * 11) + 11(10 * 19 - 11(19 - \lambda)) = 0$$

$$(6 - \lambda)(\lambda^{2} - 40\lambda + 38) - 10(1 - 10\lambda) + 11(11\lambda - 19) = 0$$

$$\lambda^{3} - 46\lambda^{2} + 57\lambda - 9 = 0$$

$$\lambda^{3} - 46\lambda^{2} + 57\lambda - 9 = 0$$

$$\lambda^{3} - 46\lambda^{2} + 57\lambda - 9 = 0$$

Thus  $\odot$  is positive definite since all its eigenvalues are positive, i.e.  $\lambda_{1,2,3} > 0$ . Therefore,  $\odot$  is invertible and we can split it as such:

Applying the eigenvalue decomposition where O is and orthogonal matrix whose column vectors are the eigenvectors of  $\underline{\omega}$  and  $\Lambda$  is a diagonal matrix whose entries are the eigenvalues of  $\underline{\omega}$ :

$$\bigcirc \hspace{-0.5cm} = O\Lambda O^T$$

From MATLAB, we obtain:

$$O = \begin{bmatrix} -0.8745 & 0.3270 & 0.3583 \\ -0.0244 & -0.7674 & 0.6407 \\ 0.4845 & 0.5515 & 0.6791 \end{bmatrix} \quad \text{and} \quad \Lambda = \begin{bmatrix} 0.1856 & 0 & 0 \\ 0 & 1.0842 & 0 \\ 0 & 0 & 44.7302 \end{bmatrix} = (\Lambda^{\frac{1}{2}})^T \Lambda^{\frac{1}{2}} = \Lambda^{\frac{1}{2}} \Lambda^{\frac{1}{2}}$$

Where:

$$\Lambda^{\frac{1}{2}} = \begin{bmatrix} 0.4308 & 0 & 0\\ 0 & 1.0413 & 0\\ 0 & 0 & 6.6881 \end{bmatrix}$$

Thus, we can write:

$$\bigcirc = O \Lambda^{\frac{1}{2}} \Lambda^{\frac{1}{2}} O^T = N^T N \quad \text{where} \quad N = \Lambda^{\frac{1}{2}} O^T$$

Finally:

$$N = \Lambda^{\frac{1}{2}}O^{T} = \begin{bmatrix} 0.4308 & 0 & 0 \\ 0 & 1.0413 & 0 \\ 0 & 0 & 6.6881 \end{bmatrix} \begin{bmatrix} -0.8745 & -0.0244 & 0.4845 \\ 0.3270 & -0.7674 & 0.5515 \\ 0.3583 & 0.6407 & 0.6791 \end{bmatrix} = \begin{bmatrix} -0.3767 & -0.0105 & 0.2087 \\ 0.3405 & -0.7991 & 0.5743 \\ 2.3963 & 4.2850 & 4.5417 \end{bmatrix}$$

$$N^T N = \begin{bmatrix} -0.3767 & 0.3405 & 2.3963 \\ -0.0105 & -0.7991 & 4.2850 \\ 0.2087 & 0.5743 & 4.5417 \end{bmatrix} \begin{bmatrix} -0.3767 & -0.0105 & 0.2087 \\ 0.3405 & -0.7991 & 0.5743 \\ 2.3963 & 4.2850 & 4.5417 \end{bmatrix} = \begin{bmatrix} 6 & 10 & 11 \\ 10 & 19 & 19 \\ 11 & 19 & 21 \end{bmatrix} = \bigcirc$$

#### Part c

Define the ghost matrix below:

We compute the eigenvalues of  $\widehat{\mathcal{L}}$  as follows:

$$\det(\mathbf{C} - \lambda I) = \begin{vmatrix} 2 - \lambda & 6 & 10 \\ 6 & 10 - \lambda & 14 \\ 10 & 14 & 18 - \lambda \end{vmatrix} = 0$$

Then:

$$(2 - \lambda)((10 - \lambda)(18 - \lambda) - 14^{2}) - 6(6(18 - \lambda) - 14 * 10) + 10(6 * 14 - 10(10 - \lambda)) = 0$$

$$(2 - \lambda)(\lambda^{2} - 28\lambda - 16) + 6(6\lambda + 32) + 10(10\lambda - 16) = 0$$

$$\lambda^{3} - 30\lambda^{2} + 96\lambda = 0$$

$$\lambda^{3} - 30\lambda^{2} + 96\lambda = 0$$

$$\lambda^{3} - 30\lambda^{2} + 96\lambda = 0$$

Thus  $\widehat{\Omega}$  is neither positive definite nor positive semi-definite since  $\lambda_2 < 0$ .

# Problem 6

#### Part a

Define the pumpkin matrix below:

We can write ( in the following form:

In this form, we can determine if s is PD using Schur's complement. In fact, the following two conditions should be satisfied:

1. 
$$A \succ 0$$

2. 
$$C - B^T A^{-1} B > 0$$

Then:

$$A = 1 > 0$$
$$8 - 3 * 1 * 3 = -1 < 0$$

Thus, (🗓) is not positive definite.

#### Part b

Define the skull matrix below:

We can write  $\odot$  in the following form:

In this form, we can determine if  $\odot$  is PD using Schur's complement. In fact, the following two conditions should be satisfied:

- 1.  $A \succ 0$
- 2.  $C B^T A^{-1} B > 0$

Then, we have:

$$A = 1 > 0$$

$$C - B^{T} A^{-1} B = \begin{bmatrix} 4 & 7 \\ 7 & 10 \end{bmatrix} - \begin{bmatrix} 0 \\ 6 \end{bmatrix} \begin{bmatrix} 0 & 6 \end{bmatrix} = \begin{bmatrix} 4 & 7 \\ 7 & -26 \end{bmatrix}$$

Recursively for the schur complement of , we check the above conditions for the following form:

$$C - B^T A^{-1} B = \begin{bmatrix} m & n \\ n & p \end{bmatrix}$$
 where  $m = 4$ ,  $n = 7$  and  $p = -26$ 

Then:

- 1. m = 4 > 0
- 2.  $p \frac{n^2}{m} = -26 \frac{49}{4} < 0$

Thus, we is not positive definite since its Schur complement of is not PD.

#### Part c

Define the ghost matrix below:

We can write  $\Omega$  in the following form:

In this form, we can determine if  $\widehat{\square}$  is PD using Schur's complement. In fact, the following two conditions should be satisfied:

1. 
$$A \succ 0$$

2. 
$$C - B^T A^{-1} B > 0$$

Then, we have:

$$A = 1 > 0$$

$$C - B^{T} A^{-1} B = \begin{bmatrix} 5 & 7 \\ 7 & a \end{bmatrix} - \begin{bmatrix} 2 \\ 6 \end{bmatrix} \begin{bmatrix} 2 & 6 \end{bmatrix} = \begin{bmatrix} 1 & -5 \\ -5 & a - 36 \end{bmatrix}$$

Recursively for the schur complement of  $\Omega$ , we check the above conditions for the following form:

$$C - B^T A^{-1} B = \begin{bmatrix} m & n \\ n & p \end{bmatrix}$$
 where  $m = 1$ ,  $n = -5$  and  $p = a - 36$ 

Then:

1. 
$$m = 1 > 0$$

2. 
$$p - \frac{n^2}{m} = a - 36 - 25 = a - 61 > 0$$
  $\Rightarrow$   $a > 61$ 

Thus, for  $\bigcap$  to be PD, we require the following bounds on a:

$$a \in \left]61, +\infty\right[$$

# Problem 7

#### Part a

Since we have an under-determined system, we can find an approximate solution as such:

$$\hat{x} = A^{T} (AA^{T})^{-1}b$$

$$= \begin{bmatrix} 1 & 3 \\ 3 & 8 \\ 2 & 4 \end{bmatrix} \begin{pmatrix} \begin{bmatrix} 1 & 3 & 2 \\ 3 & 8 & 4 \end{bmatrix} \begin{bmatrix} 1 & 3 \\ 3 & 8 \\ 2 & 4 \end{bmatrix} \end{pmatrix}^{-1} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 3 \\ 3 & 8 \\ 2 & 4 \end{bmatrix} \begin{pmatrix} \begin{bmatrix} 14 & 35 \\ 35 & 89 \end{bmatrix} \end{pmatrix}^{-1} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 3 \\ 3 & 8 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} 4.23 & -1.67 \\ -1.67 & 0.67 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 3 \\ 3 & 8 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} 0.905 \\ -0.33 \end{bmatrix}$$

$$\Rightarrow \hat{x} = \begin{bmatrix} -0.095 \\ 0.048 \\ 0.4762 \end{bmatrix}$$

#### Part b

Denote the symmetric matrix Q:

$$Q = \begin{bmatrix} 5 & 1 & 9 \\ 1 & 2 & 1 \\ 9 & 1 & 17 \end{bmatrix}$$

From MATLAB, we compute the eigenvalues of Q and obtain:

$$\begin{bmatrix} \lambda_1 \\ \lambda_2 \\ \lambda_3 \end{bmatrix} = eig(Q) = \begin{bmatrix} 0.0913 \\ 2 \\ 21.9087 \end{bmatrix}$$

Since the eigenvalues of Q are positive and real, then Q is a hermitian matrix and we can utilize the following property:

$$Q^T = Q \quad \text{and} \quad y^T Q = y^T Q^T = (Qy)^T \tag{1}$$

We define the orthogonal nullspace of A as follows:

$$\mathcal{N}(A)^{\perp} = \{ y \mid y^T Q x = 0 , \forall x \in \mathcal{N}(A) \}$$

Thus, from (1):

$$\mathcal{N}(A)^{\perp} = \{ y \mid (Qy)^T x = 0 , \ \forall x \in \mathcal{N}(A) \}$$

Thus, Qy is orthogonal to all x in the  $\mathcal{N}(A)$  and we can write:

$$\mathcal{N}(A)^{\perp} = \{ y \mid Qy = A^T \alpha , \ \alpha \in \mathbb{R}^m \}$$

Rearranging, we obtain:

$$Qy = A^{T}\alpha$$
$$y = Q^{-1}A^{T}\alpha$$
$$y = (AQ^{-1})^{T}\alpha$$

We define the new matrix  $\tilde{A}$  as follows:

$$\tilde{A} = AQ^{-1}$$

Since  $\hat{x} \in \mathcal{R}(\tilde{A})$ , we can write:

$$\hat{x} = \tilde{A}^T \alpha$$

$$A\hat{x} = A\tilde{A}^T \alpha$$

$$\alpha = (A\tilde{A}^T)^{-1} A\hat{x}$$

$$\hat{x} = \tilde{A}(A\tilde{A}^T)^{-1} A\hat{x}$$

$$\implies \hat{x} = \tilde{A}(A\tilde{A}^T)^{-1} b$$

For the above expression to be valid, we need to prove that  $A\tilde{A}^T$  is invertible:

$$\tilde{A} = AQ^{-1} = \begin{bmatrix} 1 & 3 & 2 \\ 3 & 8 & 4 \end{bmatrix} \begin{bmatrix} 5 & 1 & 9 \\ 1 & 2 & 1 \\ 9 & 1 & 17 \end{bmatrix}^{-1} = \begin{bmatrix} -6.25 & 3 & 3.25 \\ -8.25 & 6 & 4.25 \end{bmatrix}$$

And:

$$\det(A\tilde{A}^T) = \begin{bmatrix} 1 & 3 & 2 \\ 3 & 8 & 4 \end{bmatrix} \begin{bmatrix} -6.25 & -8.25 \\ 3 & 6 \\ 3.25 & 4.25 \end{bmatrix} = \begin{vmatrix} 9.25 & 18.25 \\ 18.25 & 40.25 \end{vmatrix} = 39.25 > 0$$

Thus  $A\tilde{A}^T$  is invertible and we can find the minimum norm solution as such:

$$\hat{x} = \tilde{A}^{T} (A\tilde{A}^{T})^{-1}b$$

$$= \begin{bmatrix} -6.25 & -8.25 \\ 3 & 6 \\ 3.25 & 4.25 \end{bmatrix} \begin{pmatrix} \begin{bmatrix} 1 & 3 & 2 \\ 3 & 8 & 4 \end{bmatrix} \begin{bmatrix} -6.25 & -8.25 \\ 3 & 6 \\ 3.25 & 4.25 \end{bmatrix} \end{pmatrix}^{-1} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$= \begin{bmatrix} -6.25 & -8.25 \\ 3 & 6 \\ 3.25 & 4.25 \end{bmatrix} \begin{pmatrix} \begin{bmatrix} 9.25 & 18.25 \\ 18.25 & 40.25 \end{bmatrix} \end{pmatrix}^{-1} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$= \begin{bmatrix} -6.25 & -8.25 \\ 3 & 6 \\ 3.25 & 4.25 \end{bmatrix} \begin{bmatrix} 1.0255 & -0.4650 \\ -0.4650 & 0.2357 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$= \begin{bmatrix} -6.25 & -8.25 \\ 3 & 6 \\ 3.25 & 4.25 \end{bmatrix} \begin{bmatrix} 0.0955 \\ 0.0064 \end{bmatrix}$$

$$\Rightarrow \hat{x} = \begin{bmatrix} -0.6497 \\ 0.3249 \\ 0.3376 \end{bmatrix}$$