

COMBINAZIONE LINEARE DEI MODI NATURALI PER RADII COMPLESSI

$$P(\lambda) = 0 \rightarrow \alpha_n \lambda^n + \alpha_{n-1} \lambda^{n-1} + \dots + \alpha_1 \lambda + \alpha_0 = 0$$

$$\lambda \in \mathbb{C} \quad (\lambda_e) \rightarrow e^{2\pi i t}, te^{2\pi i t}, \dots, t^{k-1} e^{2\pi i t} \rightarrow C_{\lambda_e}(t)$$

$$\lambda^* \in \mathbb{C} \quad (\lambda_e^* = \bar{\lambda}) \rightarrow e^{2\pi i t}, \bar{t}e^{2\pi i t}, \dots, \bar{t}^{k-1} e^{2\pi i t} \rightarrow C_{\lambda_e^*}(t)$$

$$\rightarrow C_{\lambda_e}(t) + C_{\lambda_e^*}(t) = \sum_{k=0}^{n-1} t^k [A_{ek} e^{2\pi i t} + A_{ek}^* e^{2\pi i t}]$$

SUPPONENDO CHE CI SIANO 2S RADICI COMPLESSE CONIUGATE, SI HA:

$$P(\lambda=0) \rightarrow C_{\lambda_1}(t) = e^{\lambda_1 t}, te^{\lambda_1 t}, \dots, t^{s-1} e^{\lambda_1 t}$$

$$C_{\lambda_1^*}(t) = e^{\lambda_1^* t}, \bar{t}e^{\lambda_1^* t}, \dots, \bar{t}^{s-1} e^{\lambda_1^* t}$$

⋮

$$C_{\lambda_s} = e^{\lambda_s t}, te^{\lambda_s t}, \dots, t^{s-1} e^{\lambda_s t}$$

$$C_{\lambda_s^*} = e^{\lambda_s^* t}, \bar{t}e^{\lambda_s^* t}, \dots, \bar{t}^{s-1} e^{\lambda_s^* t}$$

$$\Rightarrow C_s(t) = \sum_{k=1}^s [C_{\lambda_k}(t) + C_{\lambda_k^*}(t)] = \sum_{k=1}^s \sum_{k=0}^{n-1} t^k [A_{ek} e^{2\pi i t} + A_{ek}^* e^{2\pi i t}]$$

COMBINAZIONE LINEARE DEI MODI NATURALI PER RADII REALI E COMPLESSI

$$P(\lambda) = 0 \rightarrow \alpha_n \lambda^n + \alpha_{n-1} \lambda^{n-1} + \dots + \alpha_1 \lambda + \alpha_0 = 0$$

A VEDERNO UN TOTAL DI R RADII REALI E 2S RADII COMPLESSI.

$$\text{DUNQUE } C(t) = C_R(t) + C_S(t) = \left[\sum_{k=1}^R \left(\sum_{k=0}^{n-1} A_{rk} t^k e^{2\pi i t} \right) \right] +$$

$$+ \sum_{k=1}^s \sum_{k=0}^{n-1} t^k [A_{ek} e^{2\pi i t} + A_{ek}^* e^{2\pi i t}] =$$

$$= \left[\sum_{i=1}^R \left(\sum_{k=0}^{r_i-1} A_{i,k} t^k e^{r_i t} \right) \right] + \left[\sum_{i=R+1}^{n+s} \left(\sum_{k=0}^{r_i-1} t^k \left(A_{i,k} t^k [A_{i,k} e^{r_i t} + A_{i,k}] \right) \right) \right]$$

TEOREMA: UNA FUNZIONE REALE $\bar{y}(t)$ È SOLUZIONE DELL'EQUAZIONE

OLOGENEA ASSOCIAТА $\Leftrightarrow \bar{y}(t)$ È UNA COMBINAZIONE LINEARE

DEI MODI NATURALI ASSOCIATI ALLE RADICI DEL POLINOMIO CARATTERISTICO

DEL SISTEMA CONSIDERATO

$\Rightarrow P(\lambda) = 0 \rightarrow "r"$ RADICI $\lambda_1, \dots, \lambda_r$ REALI E/O COMPLESE

$$\begin{aligned} c(t) &= \sum_{i=1}^r c_{r_i}(t) = c_{r_1}(t) + \dots + c_{r_r}(t) = \left(\sum_{k=0}^{r_1-1} A_{1,k} t^k e^{\lambda_1 t} \right) + \dots + \left(\sum_{k=0}^{r_r-1} A_{r,k} t^k e^{\lambda_r t} \right) \\ &= \sum_{i=1}^r \sum_{k=0}^{r_i-1} A_{i,k} t^k e^{\lambda_i t} = \bar{y}(t) \end{aligned}$$

QUESTA DESTRUISE INFETTE SOLUZIONI. OCCHIO! METTIAMO ALLORA UNA

PROPOSIZIONE: LA RISPOSTA LIBERA DEL SISTEMA CONSIDERATO È UNA

PARTICOLARE COMBINAZIONE LINEARE DEI MODI NATURALI ASSOCIATI ALLE

RADICI DEL POLINOMIO CARATTERISTICO $P(\lambda)$

$$\Rightarrow \alpha_n y_e^n(t) + \dots + \alpha_1 y_e^1(t) + \alpha_0 y_e(t) = 0$$

$$y_e(t) = c(t) \Big|_{y(t_0), y'(t_0), \dots, y^{n-1}(t_0)} \Rightarrow \begin{cases} y_e(t_0) = c(t_0) \\ y'_e(t_0) = c'(t_0) \\ \vdots \\ y^{n-1}(t_0) = c^{n-1}(t_0) \end{cases}$$

ESEMPIO: DETERMINARE LA RISPOSTA LIBERA DEL SISTEMA

$$y'''(t) + 8y''(t) + 21y'(t) + 16y(t) = 3u(t) + 5u'(t) - 7u''(t)$$

SAPENDO CHE $y(0)=2$, $y'(0)=1$, $y''(0)=-20$

$$P(\lambda) = \lambda^3 + 8\lambda^2 + 2\lambda + 18 = 0$$

$$\begin{array}{r|rrr} 1 & 1 & 8 & 21 \\ -2 & & -2 & -12 \\ \hline & 1 & 6 & 9 & 0 \end{array}$$

$$(\lambda+2)(\lambda^2+6\lambda+9) = 0$$

$$(\lambda+2)(\lambda+3)^2 = 0$$

$$\cdot \lambda_1 = -2 \quad \lambda_1 = 1 \rightarrow e^{-2t}$$

$$\cdot \lambda_2 = -3 \quad \lambda_2 = 2 \rightarrow e^{-3t}, te^{-3t}$$

$$C(t) = A_1 e^{-2t} + A_{2,1} t e^{-3t} + A_{2,2} t^2 e^{-3t}$$

$$C'(t) = -2A_1 e^{-2t} - 3A_{2,1} t e^{-3t} + A_{2,2} t^2 e^{-3t} - 3A_{2,2} t^2 e^{-3t}$$

$$C''(t) = 4A_1 e^{-2t} + 9A_{2,1} t e^{-3t} - 6A_{2,2} t^2 e^{-3t} + 6A_{2,2} t^3 e^{-3t}$$

$$C(0) \left\{ \begin{array}{l} A_1 + A_{2,2} = 2 \end{array} \right.$$

$$C'(0) \left\{ \begin{array}{l} -2A_1 - 3A_{2,1} + A_{2,2} = 1 \end{array} \right.$$

$$C''(0) \left\{ \begin{array}{l} 4A_1 + 9A_{2,1} - 6A_{2,2} = -20 \end{array} \right.$$

$$\left\{ \begin{array}{l} A_1 = 2 - A_{2,2} \\ -4 - A_{2,1} + A_{2,2} = 1 \end{array} \right.$$

$$8 + 5A_{2,2} - 6A_{2,2} = -20$$

$$\left\{ \begin{array}{l} A_1 = 2 - A_{2,2} \end{array} \right.$$

$$\left\{ \begin{array}{l} 8 + 5A_{2,2} - 6A_{2,2} - 24 = -20 \end{array} \right.$$

$$\left\{ \begin{array}{l} A_{2,2} = 1 + A_{2,1} + 4 \end{array} \right.$$

$$\left\{ \begin{array}{l} A_1 = 4 \\ A_{2,1} = -2 \\ A_{2,2} = 3 \end{array} \right.$$

$$\Rightarrow Y_e(t) = 4e^{-2t} - 2e^{-3t} + 3te^{-3t}$$

ESEMPIO: TROVARE LA Y(t) DEL SEGUENTE SISTEMA

DARE LE CONDIZIONI INIZIALI

$$(y'''(t) + 2y''(t) + 5y'(t) = u(t) - 3u(t))$$

$$\left\{ \begin{array}{l} y(0) = 3 \\ y'(0) = 2 \\ y''(0) = 1 \end{array} \right.$$

$$A_{1,0} = \operatorname{Re}[A_{1,0}] + i \operatorname{Im}[A_{1,0}]$$

$$A_{1,0}^* = \operatorname{Re}[A_{1,0}] - i \operatorname{Im}[A_{1,0}]$$

$$\lambda(\lambda) = \lambda^3 + 2\lambda^2 + 5\lambda$$

$$\lambda(\lambda) = 0 \quad \lambda(\lambda^2 + 2\lambda + 5) = 0 \quad \lambda = -1 \quad \lambda_1 = 0 \quad \lambda_2 = -1 + 2i \quad \lambda_2^* = -1 - 2i$$

$$\rightarrow C(t) = A_0 + A_{1,0} e^{(-1+2i)t} + A_{1,0}^* e^{(-1-2i)t}$$

$$C'(t) = (-1+2i)A_{1,0} e^{(-1+2i)t} + (-1-2i)A_{1,0}^* e^{(-1-2i)t}$$

$$\begin{aligned} C''(t) &= (-1+2i)^2 A_{1,0} e^{(-1+2i)t} + (-1-2i)^2 A_{1,0}^* e^{(-1-2i)t} \\ &= (-3-4i)A_{1,0} e^{(-1+2i)t} + (-3+4i)A_{1,0}^* e^{(-1-2i)t} \end{aligned}$$

$$\left\{ \begin{array}{l} A_0 + A_{1,0} + A_{1,0}^* = 3 \end{array} \right.$$

$$\left\{ \begin{array}{l} (-1+2i)A_{1,0} + (-1-2i)A_{1,0}^* = 2 \end{array} \right.$$

$$\left\{ \begin{array}{l} (-3-4i)A_{1,0} + (-3+4i)A_{1,0}^* = 1 \end{array} \right.$$

$$A_{1,0} = V_{1,0} + i U_{1,0}$$

$$\gamma = -\frac{1}{2}$$

$$A_{1,0}^* = V_{1,0} - i U_{1,0}$$

$$U = \frac{1}{4}$$

$$\left\{ \begin{array}{l} A_0 = 4 \\ A_{1,0} = \frac{1}{2} + \frac{1}{4}i \end{array} \right.$$

$$A_{1,0}^* = \frac{1}{2} - \frac{1}{4}i$$

$$\Rightarrow Y_e(t) = 4 + \left(\frac{1}{2} + \frac{1}{4}i \right) e^{(-2+2i)t} + \left(\frac{1}{2} - \frac{1}{4}i \right) e^{(-2-2i)t}$$

$$= 4 + \left[-e^{-t} \cos(2t) - \frac{1}{2} e^{-t} \sin(2t) \right]$$

$$B_{e,n} = 2 \cdot \frac{-1}{2} = -1$$

$$= 4 + \left[\frac{\sqrt{5}}{2} e^{-t} \cos\left(2t + \arccos\left(\frac{1}{2}\right)\right) \right]$$

$$C_{e,n} = 2 \cdot \frac{1}{4} = \frac{1}{2}$$

$$M_{e,n} = 2\sqrt{\frac{1}{4} + \frac{1}{2}} = \frac{\sqrt{5}}{2}$$

$$\phi_{e,n} = \arctan\left(\frac{-1/2}{1/4}\right) = \arctan\left(\frac{1}{2}\right)$$

I MODI NATURALI

SI FACCIANO DELLE IMPORTANTI CONSIDERAZIONI SU MODI NATURALI. NE DISCRIMINIAMO DUE DIVERSE FORME:

MODI APERIODICI
 $\lambda_i \in \mathbb{R} \setminus \{0\}$

$$\lambda_i \in \mathbb{R} \setminus \{0\}$$

$$t^i e^{\lambda_i t} \quad i=0, 1, \dots, N-1$$

MODI MISURABILI
 $\lambda_i \in \mathbb{C}$

$$\begin{aligned} & \lambda_i = \alpha + j\beta \quad \alpha \in \mathbb{R}, \beta \in \mathbb{R} \\ & t^i e^{\alpha t} \cos(\beta t) \\ & t^i e^{\alpha t} \sin(\beta t) \end{aligned}$$

CONSIDERAZIONI:
 $\text{Im}[\lambda_i] = \beta$

APERIODICO

① $\text{Im}[\lambda_i] = \beta$

② $t^i e^{\alpha t} \cos(\beta t)$ FORMA COMPOSSIBILE

③ $t^i e^{\alpha t} \sin(\beta t)$ FORMA COMPOSSIBILE

I MODI APERIODICI

COME VISTO POCO FA, RIGUARDANDO IL CASO DI RADICI REALI E QUINDI UN MODO DEL TIPO $M_i(t) = t^k e^{\lambda_i t}$, $k=1, \dots, \chi_i - 1$

DEFINIAMO LA COSTANTE DI TEMPO DEL MODO NATURALE

$$m_i \text{ come } \tau_i = -\frac{1}{\lambda_i} \Rightarrow M_i(t) = \delta^k e^{-\frac{1}{\tau_i} t}$$

STUDIAMO, AD ESEMPIO, IL COMPORTAMENTO DI m_i NEL CASO

DI RADICI NEGATIVE $\lambda_i < 0 \Rightarrow \tau_i > 0$

t	≈ 0	$= \tau_i = 3\tau_i \dots$
$e^{-\frac{t}{\tau_i}}$	$= 1$	$= 0,37 \ 0,05 \ \dots$

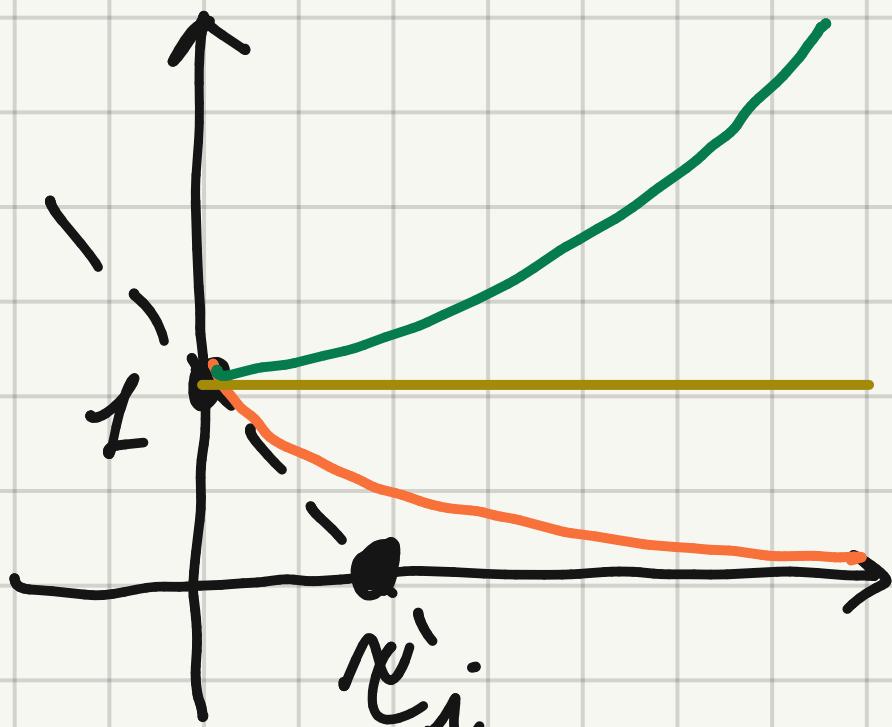
SI OSSERVA, DUNQUE, CHE COL PASSARE DEL TEMPO IL MODO È SEMPRE meno (NFLUEGTE), UOÈ $M_i(t)$ È UN MODO APERIODICO

CHE SI ESAURISCE

MODI APERIODICI ASSOCIATI A RADICI REALI DI MOLTAURO $\lambda_i = 1$

$$M_i(t) = C e^{\lambda_i t} \quad \lambda_i = 1 \Rightarrow M_i(t) = e^{\lambda_i t}$$

- $\lambda_i < 0 \rightarrow$ MODO STABILE (O ASINTOMATICAMENTE STABILE)
NISTOSM LIBERA CONVERGENTE
- $\lambda_i = 0 \rightarrow$ MODO AL CENTRO DI STABILITÀ (O SEMPRELLAMENTE STABILE)
- $\lambda_i > 0 \rightarrow$ MODO INSTABILE DISADDA LIBERA DIVERGENTE



$$\left\{ \begin{array}{l} M_i(t) = e^{\lambda_i t} \Rightarrow M'_i(t) = \lambda_i e^{\lambda_i t} \\ M'_i(0) = \lambda_i \end{array} \right.$$

$$\left\{ \begin{array}{l} h_i(t) = at + b = \lambda_i t + b \Rightarrow h_i(0) = 1 = b \Rightarrow b = 1 \end{array} \right.$$

$$\rightarrow \lambda_i t + 1 = 0 \Rightarrow t = -\frac{1}{\lambda_i} = \tau_i$$

MODI APERIODICI ASSOCIATI A MASSI NEGLIGIBILI DI MOLtepLICITÀ > 1

$$M_i(t) = t^K e^{-\frac{1}{\lambda_i} t} \quad K=0, 1, \dots, \tau_i - 1$$

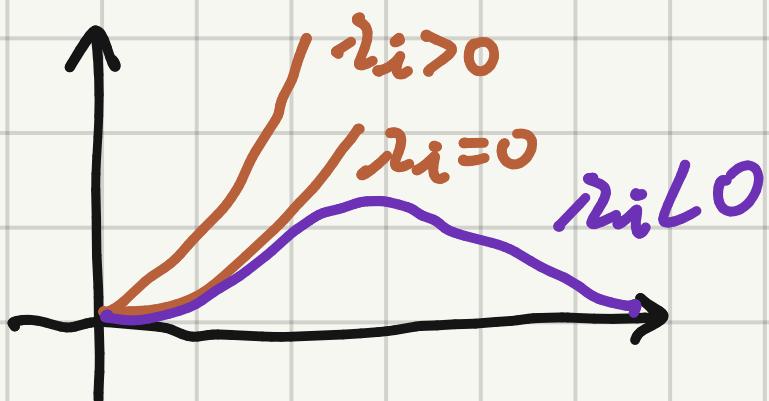
STUDIAMO IL COMPORTAMENTO DEL MODO ALL'AUMENTARE DI K

PER K=0, ABBIAMO IL CASO VISTO IN PRECEDENZA

$$\text{PER } K>0, \text{ ABBIAMO } M_i(t) = t^K e^{\lambda_i t}$$

- $\lambda_i < 0 \Rightarrow M \text{ DECRESE} \Rightarrow \text{MODO STABILE}$

- $\lambda_i > 0 \Rightarrow M \text{ DIVERGE} \Rightarrow \text{MODO INSTABILE}$



CARTOLO PER UN GENERICO
K > 1

I MODI PSEUDOPERIODICI

RIVARDA MEDI DEL TPO $M_e(t) = \cos(\operatorname{Im}[\lambda_e]t) \cdot t^k \cdot e^{[\operatorname{Re}[\lambda_e]t]}$

E QUINDI DANI COMPLESSI $\lambda_e \in \mathbb{C}$ RISPETTIVO CONVATO λ_e^*

$$\lambda_e = \operatorname{Re}[\lambda_e] + i \operatorname{Im}[\lambda_e]$$

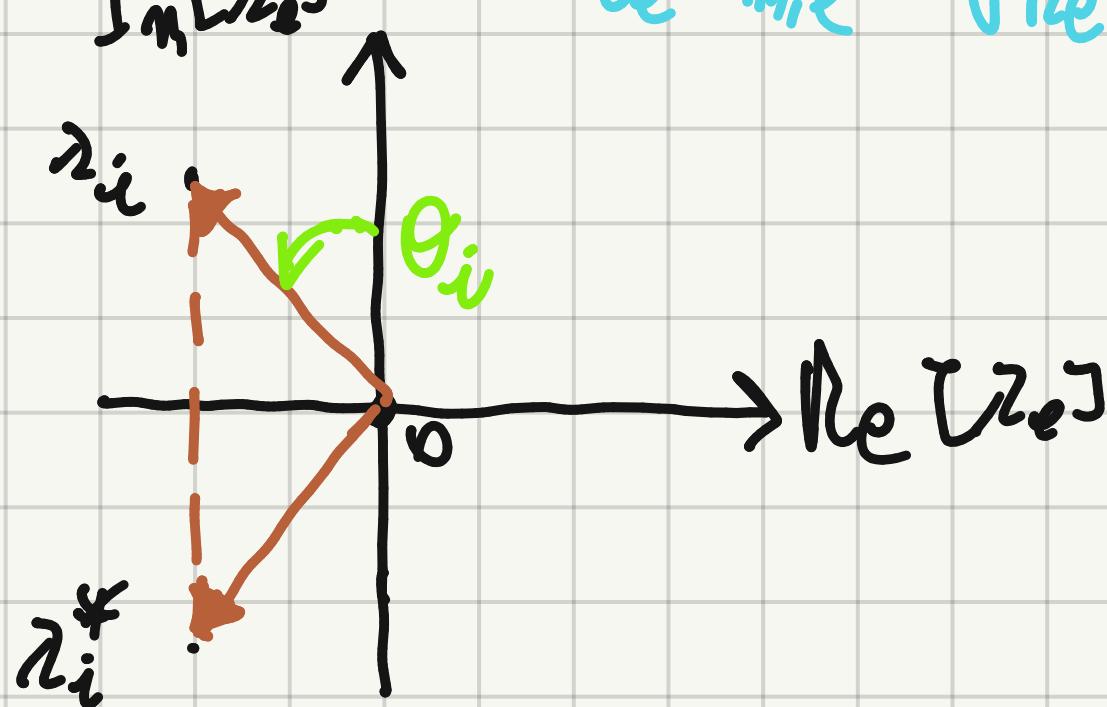
$$\lambda_e^* = \operatorname{Re}[\lambda_e] - i \operatorname{Im}[\lambda_e] \quad \left\{ \begin{array}{l} \rightarrow M_e(t) = \cos(\operatorname{Im}[\lambda_e]t) \cdot t^k \cdot e^{[\operatorname{Re}[\lambda_e]t]} \\ k=0,1,\dots, \chi_{e-1} \end{array} \right.$$

DEFINIAMO LA COSTANTE DI TEMPO NEL MODO NATURALE

MI COME $\gamma_e = -\frac{1}{\lambda_e}$ LA PULSAZIONE NATURALE

$$w_{m,e} = \sqrt{\operatorname{Re}[\lambda_e]^2 + \operatorname{Im}[\lambda_e]^2} \quad \text{E IL COEFFICIENTE DI}$$

$$\text{SMORZAMENTO } \xi_e = \frac{1}{\operatorname{Re} \cdot w_{m,e}} = -\frac{\operatorname{Re}[\lambda_e]}{\sqrt{\operatorname{Re}[\lambda_e]^2 + \operatorname{Im}[\lambda_e]^2}}$$



IMMAGINARIO PURO
REALE PURO

$$\operatorname{sm}(\theta_e) = -\frac{\operatorname{Re}[\lambda_e]}{\sqrt{\operatorname{Re}[\lambda_e]^2 + \operatorname{Im}[\lambda_e]^2}} = \xi_e \Rightarrow 0 \leq \xi_e \leq 1$$

$$\theta_e = \operatorname{arctan}(\operatorname{sm}(\xi_e)) \quad w_{m,e} = \sqrt{\operatorname{Re}[\lambda_e]^2 + \operatorname{Im}[\lambda_e]^2}$$

$$\Rightarrow w_{m,e}^2 = \operatorname{Re}[\lambda_e]^2 + \operatorname{Im}[\lambda_e]^2 \Rightarrow \operatorname{Re}[\lambda_e]^2 = w_{m,e}^2 - \operatorname{Im}[\lambda_e]^2$$

$$\text{DA CI } \operatorname{Re}[\lambda_e] = \xi_e^2 \cdot w_{m,e}^2$$

$$\rightarrow \Im_e^2 \cdot w_{m,e}^2 = I_m [\lambda_e]^2 - w_{m,e}^2 \quad I_m [\lambda_e]^2 = w_{m,e}^2 (1 - \Im_e^2)$$

$$\text{Da } w_1 \quad I_m [\lambda_e] = w_{m,e} \cdot \sqrt{1 - \Im_e^2}$$

MODI PSEUDOPERIODICI ASSOCIATI A RADICI COMPLESSI DI MATEMATICA =

$$\lambda_e \in \{(\lambda_e = f) \rightarrow \lambda_e = \Re[\lambda_e] + i \Im[\lambda_e]$$

$$\lambda_e^* \in \{(\lambda_e^* = \bar{\lambda}_e) \rightarrow \lambda_e^* = \Re[\lambda_e] - i \Im[\lambda_e]$$

$$\begin{cases} M_e(t) = e^{\Re[\lambda_e]t} \cos(\Im[\lambda_e]t) \end{cases}$$

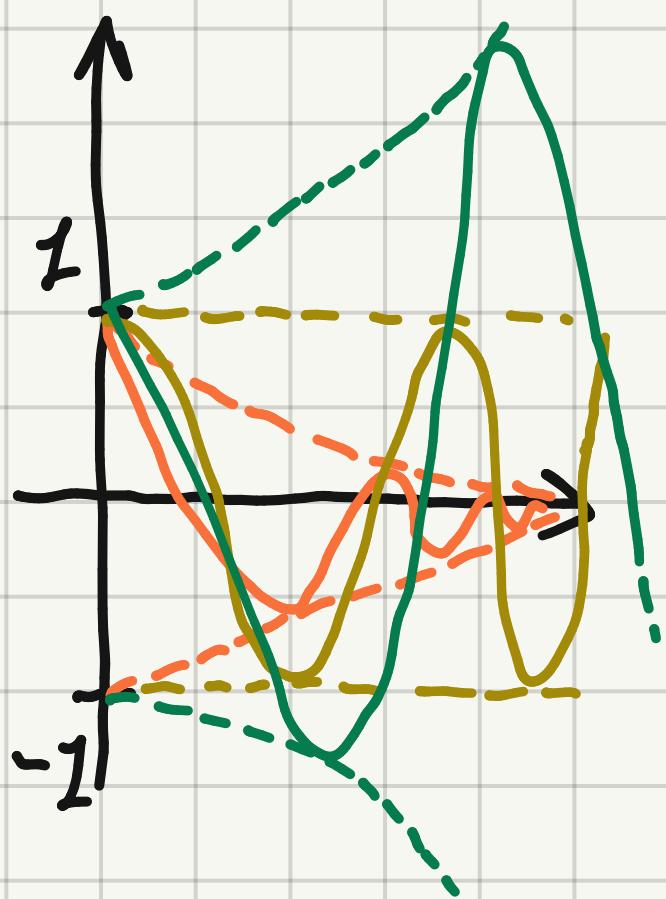
$$\begin{cases} M_e^*(t) = e^{\Re[\lambda_e^*]t} \sin(\Im[\lambda_e]t) \end{cases}$$

$$\rightarrow M_e(t) = e^{\Re[\lambda_e]t} \cos(\Im[\lambda_e]t) = \begin{cases} e^{\Re[\lambda_e]t}, t = (2k+1) \cdot \frac{\pi}{\Im[\lambda_e]} \\ \text{Re}[\lambda_e] < 0 \\ e^{\Re[\lambda_e^*]t}, t = 2k \cdot \frac{\pi}{\Im[\lambda_e]} \\ \text{Re}[\lambda_e^*] < 0 \end{cases}$$

- $\Re[\lambda_e] < 0 \Rightarrow$ MODO STABILE

- $\Re[\lambda_e] = 0 \Rightarrow$ MODO ALIMENTE DI STABILITÀ

- $\Re[\lambda_e] > 0 \Rightarrow$ MODO INSTABILE



MODI PSEUDOPLICONI ASSOCIATI A RADICI COMPLESSI CON MULTEZZA = 1

$$\lambda_e \in \mathbb{C} (\lambda_e \neq 0) \rightarrow \lambda_e = \operatorname{Re}[\lambda_e] + i \operatorname{Im}[\lambda_e]$$

$$\lambda_e^* \in \mathbb{C} (\lambda_e^* = \bar{\lambda}_e) \rightarrow \lambda_e^* = \operatorname{Re}[\lambda_e] - i \operatorname{Im}[\lambda_e]$$

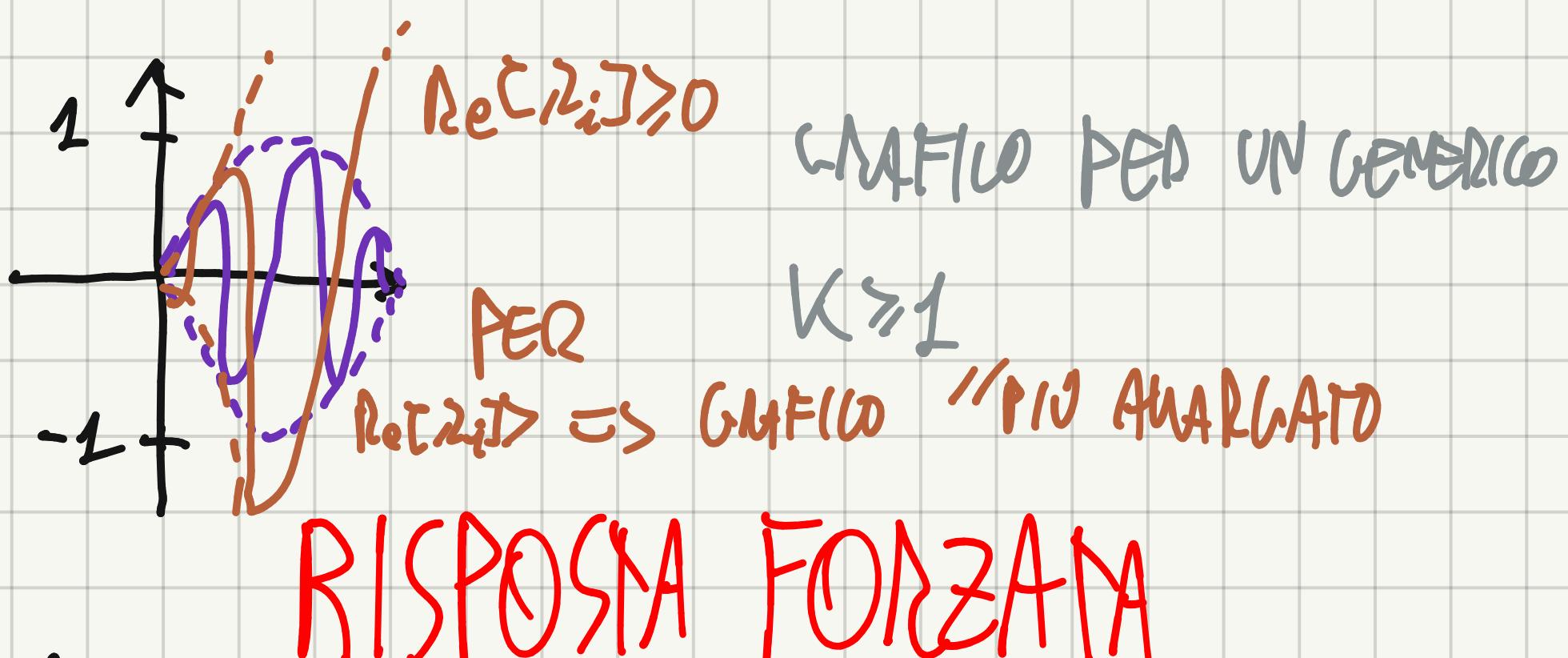
$$\left\{ \begin{array}{l} M_e(t) = t^k e^{\operatorname{Re}[\lambda_e]t} \cos(\operatorname{Im}[\lambda_e]t) \\ M_e^*(t) = t^k e^{\operatorname{Re}[\lambda_e^*]t} \cos(\operatorname{Im}[\lambda_e^*]t) \end{array} \right.$$

$$\left\{ \begin{array}{l} M_e(t) = t^k e^{\operatorname{Re}[\lambda_e]t} \sin(\operatorname{Im}[\lambda_e]t) \\ M_e^*(t) = t^k e^{\operatorname{Re}[\lambda_e^*]t} \sin(\operatorname{Im}[\lambda_e^*]t) \end{array} \right.$$

$$\rightarrow M_e(t) = t^k e^{\operatorname{Re}[\lambda_e]t} \cos(\operatorname{Im}[\lambda_e]t) = \begin{cases} t^k e^{\operatorname{Re}[\lambda_e]t}, & t = (2k+1) \cdot \frac{\pi}{\operatorname{Im}[\lambda_e]} \\ t^k e^{\operatorname{Re}[\lambda_e]t}, & t = 2k \cdot \frac{\pi}{\operatorname{Im}[\lambda_e]} \end{cases}$$

- $\operatorname{Re}[\lambda_e] < 0 \Rightarrow M_e$ DECRESCE \Rightarrow MODO STABILE

- $\operatorname{Re}[\lambda_e] > 0 \Rightarrow M_e$ DIVERGE \Rightarrow MODO INSTABILE



RISPOSA FORZATA

$U(t) \neq 0$, $M(t)$ constante (NOLTA)

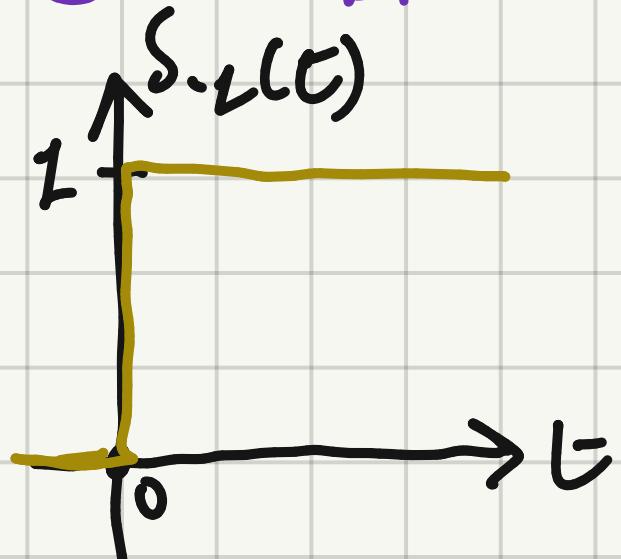
$$a_n Y^n(t) + \dots + a_1 Y'(t) + a_0 Y(t) = 0$$

$$Y(t_0) = Y'(t_0) = \dots = Y^n(t_0) = 0$$

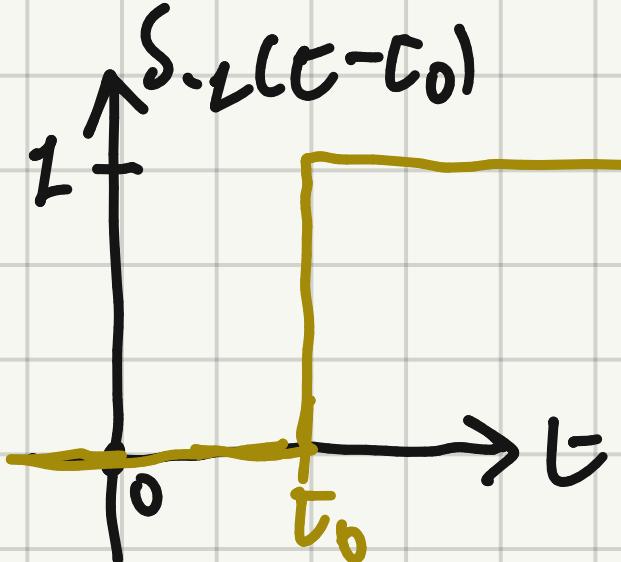
$$V(t) \leq \sum_{i=1}^P V_i(t) = V_1(t) + V_2(t) + \dots + V_P(t) = \sum_{k_1} V_{k_1}(t) + \sum_{k_2} V_{k_2}(t) + \dots + \sum_{k_n} V_{k_n}(t)$$

(NU INGRESSI) CANONICO

① GRADINO UNIMODO $\delta_{-1}(t)$

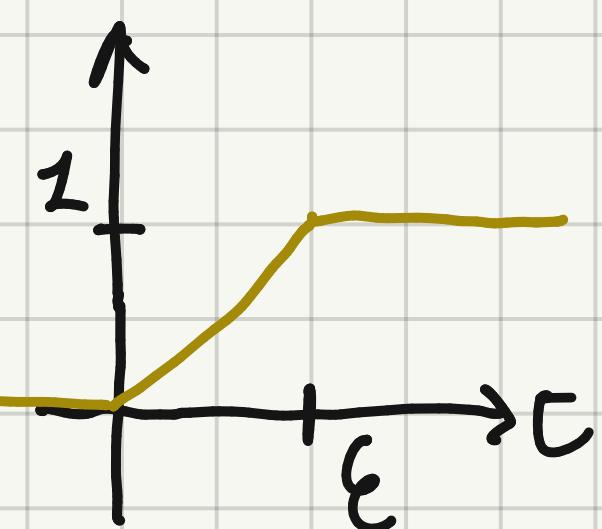


$$\delta_{-1}(t) = \begin{cases} 0 & t < 0 \\ 1 & t \geq 0 \end{cases}$$



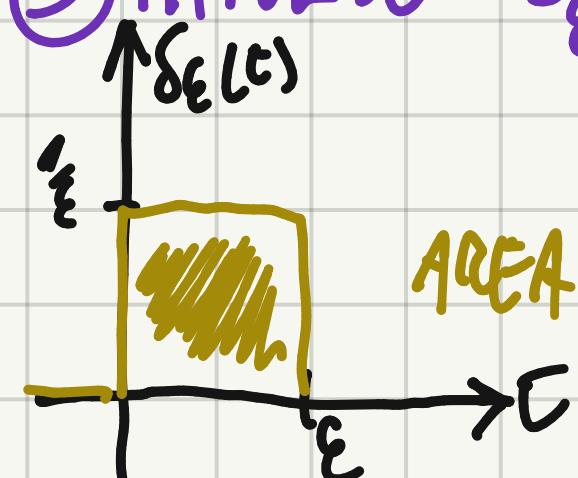
$$\delta_{-1}(t) = \begin{cases} 0 & t < t_0 \\ 1 & t \geq t_0 \end{cases}$$

② GRADINO + RAMPA $\delta_{-1,\epsilon}(t)$



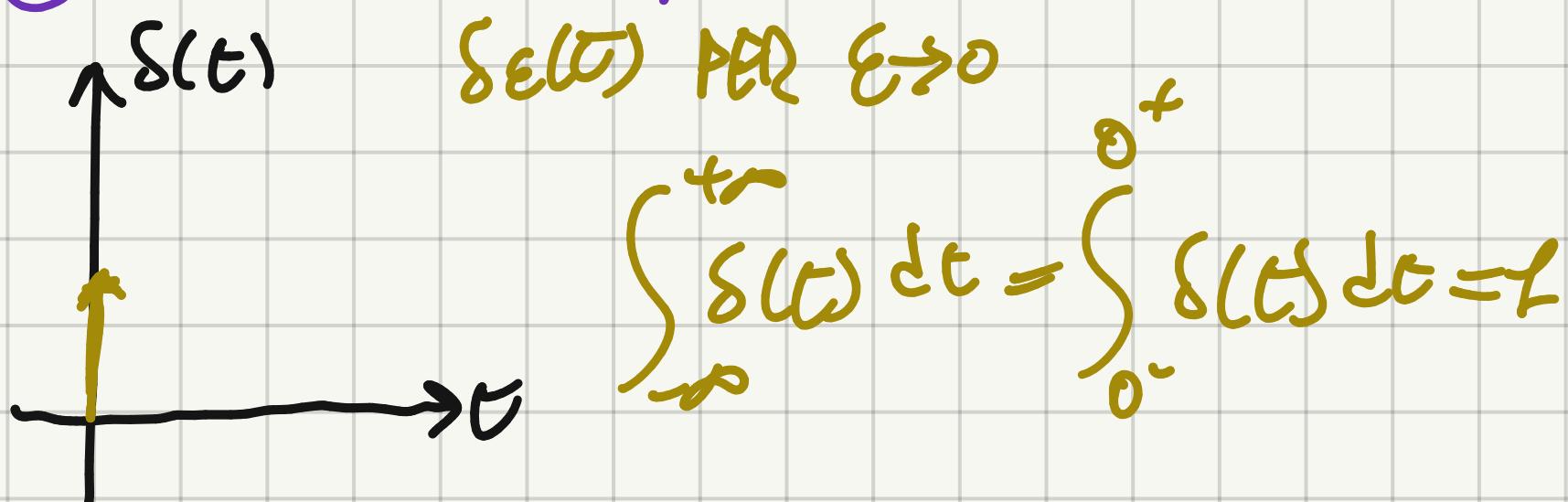
$$\delta_{-1,\epsilon}(t) = \begin{cases} 0 & t < 0 \\ \frac{t}{\epsilon} & 0 \leq t \leq \epsilon \\ 1 & t > \epsilon \end{cases}$$

③ IMPULSO $\delta_\epsilon(t)$

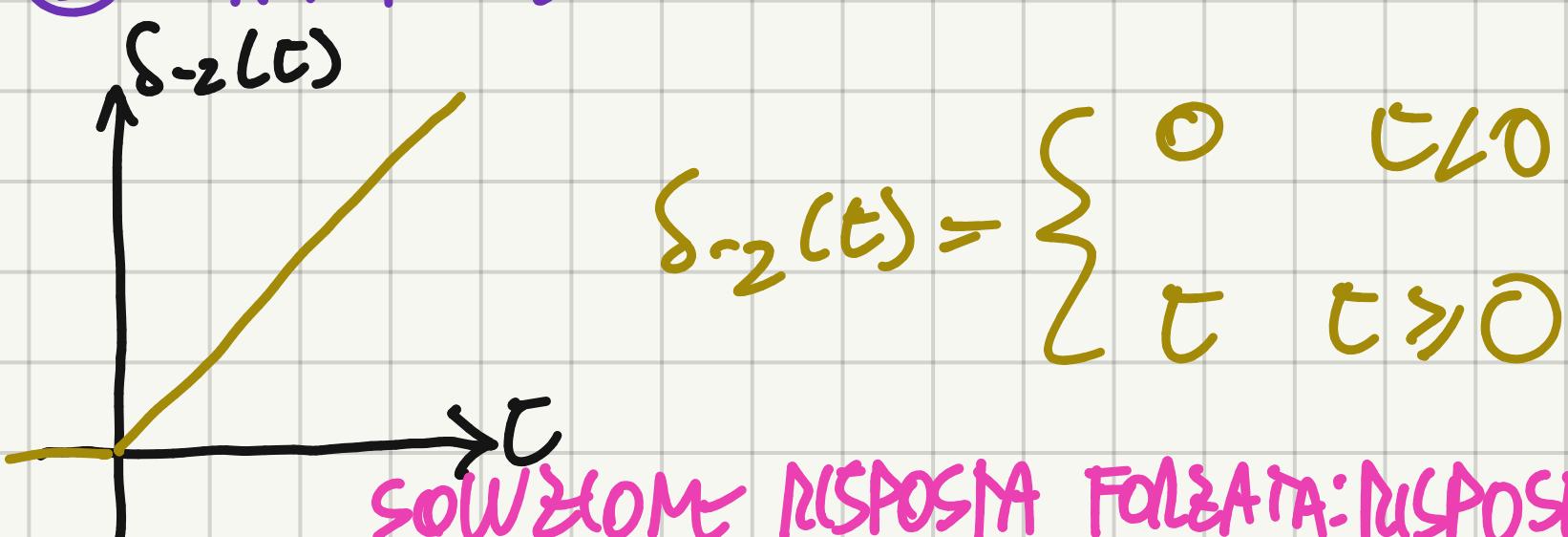


$$\delta_\epsilon(t) = \begin{cases} 0 & t < 0 \\ \epsilon & 0 \leq t \leq \epsilon \\ 0 & t > \epsilon \end{cases}$$

④ IMPULSO UNITARIO $\delta(t)$



⑤ RAMPA $\delta_2(t)$



- $a_n Y^n(t) + \dots + a_1 Y'(t) + a_0 Y(t) = b_0 U(t) + b_1 U'(t) + \dots + b_m U^m(t)$
- $Y(0) = Y'(0) = \dots = Y^{n-1}(0) = 0$
- $U(t) = \delta(t)$

PROPOSIZIONE: LA RISPOSTA FORZATA DEL SISTEMA AD UN INGRESSO

$$U(t) = \delta(t) \text{ È UGUALE A } Y_F(t) = Y_g(t) = \begin{cases} 0 & t < 0 \\ C(t) \cdot \delta_2(t) + A_0 \delta(t) & t \geq 0 \end{cases}$$

$$A_0 = \begin{cases} 0 & n > m \\ \frac{b_m}{a_m} = \frac{b_n}{a_n} & n = m \end{cases}$$

COME CALCOLARE LA RISPOSTA IMPULSIVA $y_g(t)$?

$$y_f(t) = y_g(t) = C(t) \cdot \delta_{-1}(t) + A_0 \cdot \delta(t)$$

$$y'_f(t) = C'(t) \delta_{-1}(t) + C(t) \delta(t) + A_0 \cdot \delta_1(t) = C'(t) \delta_{-1}(t) + C(t) \delta(t) + A_0 \delta_1(t)$$

$$y''_f(t) = C''(t) \delta_{-1}(t) + C'(t) \delta(t) + C(t) \delta_1(t) + A_0 \delta_2(t) = C''(t) \delta_{-1}(t) + C(t) \delta(t) + C(t) \delta_1(t) + A_0 \delta_2(t)$$

⋮

$$y^n_f(t) = C^n(t) \delta_{-1}(t) + C^{n-1}(t) \delta(t) + C^{n-2}(t) \delta_1(t) + \dots + A_0 \delta_n(t)$$

$$\alpha_n y^n(t) + \dots + \alpha_1 y^1(t) + \alpha_0 y(t) = b_0 U(t) + b_1 V(t) + \dots + b_m V^m(t)$$

$U(t) = \delta(t)$

$$\alpha_n y^n(t) + \dots + \alpha_1 y^1(t) + \alpha_0 y(t) = b_0 \delta(t) + b_1 \delta_1(t) + \dots + b_m \delta_m(t)$$

$$\alpha_n y^n(t) + \dots + \alpha_1 y^1(t) + \alpha_0 y(t) = b_0 \delta(t) + \dots + b_m \delta_m(t) + b_{m+1} \delta_{m+1}(t) + \dots + b_n \delta_n(t)$$

$$y(t) = y_f(t) \rightarrow \alpha_n [C^n(t) \delta_{-1}(t) + C^{n-1}(t) \delta(t) + C^{n-2}(t) \delta_1(t) + \dots + A_0 \delta_n(t)]$$

$$+ \dots + \alpha_1 [C(t) \delta_{-1}(t) + C(t) \delta(t) + A_0 \delta_1(t)] + \alpha_0 [C(t) \delta_{-1}(t) + A_0 \delta(t)] =$$

$$= b_0 \delta(t) + \dots + b_m \delta_m(t) + b_{m+1} \delta_{m+1}(t) + \dots + b_n \delta_n(t)$$

- CASO $n = m$

EGCUA GUAMO | $\delta_i, i = 1, \dots, n$

$$\delta \Rightarrow b_0 = \alpha_n C^{n-1}(0) + \dots + \alpha_1 C(0) + \alpha_0 A_0$$

$$\delta_1 \Rightarrow b_1 = \alpha_n C^{n-1}(0) + \dots + \alpha_2 A_0$$

$$\vdots$$

$$\delta_{n-1} \Rightarrow b_{n-1} = \alpha_n C(0) + \alpha_{n-1} A_0$$

$$\delta_n \Rightarrow b_n = \alpha_n A_0 \longrightarrow A_0 = \frac{b_n}{\alpha_n}$$

$$\begin{vmatrix} b_0 \\ b_1 \\ \vdots \\ b_n \end{vmatrix} = \begin{vmatrix} a_0 & a_1 & \dots & a_n \\ a_1 & a_2 & \dots & 0 \\ \vdots & \vdots & \ddots & 0 \\ a_n & 0 & \dots & 0 \end{vmatrix} \cdot \begin{vmatrix} A_0 \\ C(0) \\ C'(0) \\ \vdots \\ C^{n-1}(0) \end{vmatrix}$$

CASO $n > m$

CON ALGEBRA ANALOGA,

$$\begin{vmatrix} b_0 \\ b_1 \\ \vdots \\ b_n \\ 0 \\ \vdots \\ 0 \end{vmatrix} = \begin{vmatrix} a_0 & a_1 & \dots & a_n \\ a_1 & a_2 & \dots & 0 \\ \vdots & \vdots & \ddots & 0 \\ a_n & 0 & \dots & 0 \end{vmatrix} \cdot \begin{vmatrix} A_0 \\ C(0) \\ \vdots \\ C^{n-1}(0) \end{vmatrix}$$

$0 = A_0 \cdot a_n$, COME GIÀ VISTO
 PER SISTEMI SINGOLARMENTE
 PROPRI

ESEMPIO: TROVARE LA RISPOSTA IMPULSIVA DEL SISTEMA

$$2y''(t) + 6y'(t) + 4y(t) = 3v(t) + v'(t)$$

$$y_s(t) = C(t) \cdot \delta_{-1}(t) + A_0 \cdot \delta(t)$$

$$C(t) = ?$$

$$P(\lambda) = 0 \rightarrow 2\lambda^2 + 6\lambda + 4 = 0 \quad \lambda^2 + 3\lambda + 2 = 0 \quad (\lambda+1)(\lambda+2)=0$$

$$\lambda_1 = -1 \quad t_1 = 1 \Rightarrow e^{-t}$$

$$\lambda_2 = -2 \quad t_2 = 1 \Rightarrow e^{-2t} \Rightarrow C(t) = A_1 e^{-t} + A_2 e^{-2t}$$

$$C(t) = -A_1 e^{-t} - 2A_2 e^{-2t}$$

$$C(0) = A_1 + A_2 \quad C'(0) = -A_1 - 2A_2$$

$$\begin{vmatrix} 3 \\ 1 \\ 0 \end{vmatrix} = \begin{vmatrix} 2 & 6 & 4 \\ 6 & 4 & 0 \\ 4 & 0 & 0 \end{vmatrix} \cdot \begin{vmatrix} A_0 \\ A_1 + A_2 \\ -A_1 - 2A_2 \end{vmatrix}$$

$$\begin{vmatrix} 3 \\ 1 \\ 0 \end{vmatrix} = \begin{vmatrix} 2 & 6 & 4 \\ 6 & 4 & 0 \\ 0 & 0 & 0 \end{vmatrix} \cdot \begin{vmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & -1 & -2 \end{vmatrix} \cdot \begin{vmatrix} A_0 \\ A_1 \\ A_2 \end{vmatrix}$$

Da cui $A_0=0$ (come da aspettativa), $A_1=1, A_2=-\frac{1}{2}$

$$\rightarrow y(t) = \left(e^t - \frac{1}{2} e^{-2t} \right) \delta_1(t) \quad (1^a \text{ FORMA})$$

ESEMPIO: PROVARE LA RISPOSTA IMPULSIVA DI $y'''(t) + 2y''(t) +$
 $+ 5y'(t) = u(t) + 4u'(t)$ SAPENDO CHE L'IMPULSO È UNIFORMI

$$P(\lambda) = 0 \quad \lambda^3 + 2\lambda^2 + 5\lambda = 0 \quad \lambda(\lambda^2 + 2\lambda + 5) = 0$$

$$\lambda_1 = 0 \quad \xi_1 = 1$$

$$\frac{-1 \pm \sqrt{-16}}{2} = \frac{-1 \pm 4i}{2}$$

$$\lambda_2 = -1+2i \quad \xi_2 = 1$$

$$\lambda_2^* = -1-2i \quad \xi_2^* = \xi_2 = 1$$

$$\rightarrow C(t) = A_1 + A_2 e^{(-1+2i)t} + A_2^* e^{(-1-2i)t}$$

$$C'(t) = (-1+2i)A_2 e^{(-1+2i)t} + (-1-2i)A_2^* e^{(-1-2i)t}$$

$$C''(t) = (-1+2i)^2 A_2 e^{(-1+2i)t} + (-1-2i)^2 A_2^* e^{(-1-2i)t}$$

$$= (-3-4i)A_2 e^{(-1+2i)t} + (-3+4i)A_2^* e^{(-1-2i)t}$$

$$C(0) = A_1 + A_2 + A_2^* = A_1 + 2\operatorname{Re}[A_2]$$

$$C(0) = (-1+2i)A_2 + (-1-2i)A_2^* = -(A_2 + A_2^*) + 2i(A_2 - A_2^*)$$

$$= -2\operatorname{Re}[A_2] - 4\operatorname{Im}[A_2]$$

$$C^1(0) = (-3 - 4i)A_2 + (-3 + 4i)A_2^* = -3(A_2 + A_2^*) - 4i(A_2 - A_2^*)$$

$$= -6\operatorname{Re}[A_2] + 8\operatorname{Im}[A_2]$$

$$\left| \begin{array}{c|c|ccccc|c} 1 & | & 0 & 5 & 2 & 1 & | & A_0 \\ 4 & | & 5 & 2 & 1 & 0 & | & A_1 + 2\operatorname{Re}[A_2] \\ 0 & | & 2 & 1 & 0 & 0 & | & -2\operatorname{Re}[A_2] - 4\operatorname{Im}[A_2] \\ 0 & | & 1 & 0 & 0 & 0 & | & -6\operatorname{Re}[A_2] + 8\operatorname{Im}[A_2] \end{array} \right.$$

$$\left| \begin{array}{c|c|ccccc|c} 1 & | & 0 & 5 & 2 & 1 & | & A_0 \\ 4 & | & 5 & 2 & 1 & 0 & | & A_1 \\ 0 & | & 2 & 1 & 0 & 0 & | & \operatorname{Re}[A_2] \\ 0 & | & 1 & 0 & 0 & 0 & | & \operatorname{Im}[A_2] \end{array} \right.$$

$\Delta_A \neq 0$

$$\left| \begin{array}{c|c|c} A_0 & | & 0 \\ A_1 & | & 1/5 \\ \operatorname{Re}[A_2] & | & -1/10 \\ \operatorname{Im}[A_2] & | & -7/20 \end{array} \right.$$

$$\Rightarrow y_s(t) = \left(\frac{1}{5} + \left(-\frac{1}{10} - \frac{7}{20}i \right) e^{(-1+2i)t} + \left(-\frac{1}{10} + \frac{7}{20}i \right) e^{(-1-2i)t} \right) \delta_{y_s}(t)$$